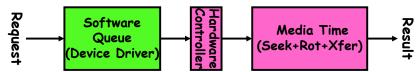
# CS162 Operating Systems and Systems Programming Lecture 18

File Systems, Naming, and Directories

November 2<sup>nd</sup>, 2009
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http://inst.eecs.berkeley.edu/~cs162

#### Review: Disk Performance Model

- · Read/write data is a three-stage process:
  - Seek time: position the head/arm over the proper track (into proper cylinder)
  - Rotational latency: wait for the desired sector to rotate under the read/write head
  - Transfer time: transfer a block of bits (sector) under the read-write head
- Disk Latency = Queueing Time + Controller time + Seek Time + Rotation Time + Xfer Time



- · Highest Bandwidth:
  - Transfer large group of blocks sequentially from one track

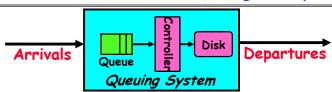
#### Review: Device Drivers

- Device Driver: Device-specific code in the kernel that interacts directly with the device hardware
  - Supports a standard, internal interface
  - Same kernel I/O system can interact easily with different device drivers
  - Special device-specific configuration supported with the ioctl() system call
- · Device Drivers typically divided into two pieces:
  - Top half: accessed in call path from system calls
    - » implements a set of standard, cross-device calls like open(), close(), read(), write(), ioctl(), strategy()
    - » This is the kernel's interface to the device driver
    - » Top half will start I/O to device, may put thread to sleep until finished
  - Bottom half: run as interrupt routine
    - » Gets input or transfers next block of output
    - » May wake sleeping threads if I/O now complete

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# Review: Introduction to Queuing Theory



- · What about queuing time??
  - Let's apply some queuing theory
  - Queuing Theory applies to long term, steady state behavior ⇒ Arrival rate = Departure rate
- · Little's Law:

Mean # tasks in system = arrival rate x mean response time

- Observed by many, Little was first to prove
- Simple interpretation: you should see the same number of tasks in queue when entering as when leaving.
- Applies to any system in equilibrium, as long as nothing in black box is creating or destroying tasks
  - Typical queuing theory doesn't deal with transient behavior, only steady-state behavior

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# Goals for Today

- · Queuing Theory: Continued
- · File Systems
  - Structure, Naming, Directories

Note: Some slides and/or pictures in the following are adapted from slides ©2005 Silberschatz, Galvin, and Gagne. Many slides generated from my lecture notes by Kubiatowicz.

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# Background: Use of random distributions

- · Server spends variable time with customers
  - Mean (Average)  $m1 = \Sigma p(T) \times T$
  - Variance  $\sigma^2 = \Sigma p(T) \times (T-m1)^2 = \Sigma p(T) \times T^2-m1$
  - Squared coefficient of variance:  $C = \sigma^2/m1^2$ Aggregate description of the distribution.



mean

Memoryless

Mean

- · Important values of C:
  - No variance or deterministic  $\Rightarrow$  C=0
  - "memoryless" or exponential  $\Rightarrow$  C=1
    - » Past tells nothing about future
    - » Many complex systems (or aggregates) well described as memoryless
  - Disk response times  $C \approx 1.5$  (majority seeks < avg)
- Mean Residual Wait Time, m1(z):
  - Mean time must wait for server to complete current task
  - Can derive  $m1(z) = \frac{1}{2}m1 \times (1 + C)$ 
    - » Not just ½m1 because doesn't capture variance
  - $-C = 0 \Rightarrow m1(z) = \frac{1}{2}m1; C = 1 \Rightarrow m1(z) = m1$

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#### A Little Queuing Theory: Mean Wait Time



- · Parameters that describe our system:
  - $-\lambda$ : mean number of arriving customers/second
  - T<sub>ser</sub>: mean time to service a customer ("m1")
  - C: squared coefficient of variance =  $\sigma^2/m1^2$
  - $\mu$ : service rate =  $1/T_{se}$
  - u: server utilization ( $0 \le u \le 1$ ):  $u = \lambda/\mu = \lambda \times T_{ser}$
- Parameters we wish to compute:
  - T<sub>q</sub>: Time spent in queue
  - $L_a^{\vee}$ : Length of queue =  $\lambda \times T_a$  (by Little's law)
- Basic Approach:
  - Customers before us must finish mean time  $(L_q \times T_{sep})$
  - If something at server, takes m1(z) to complete on avg » m1(z): mean residual wait time at server=  $T_{ser} \times \frac{1}{2}(1+C)$ 
    - » m1(z): mean residual wait time at server =  $1_{ser} \times \frac{1}{5(1+c)}$ » Chance something at server =  $u \Rightarrow$  mean time is  $u \times m1(z)$
- · Computation of wait time in queue  $(T_a)$ :

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# A Little Queuing Theory: M/G/1 and M/M/1

• Computation of wait time in queue  $(T_q)$ :  $T_q = L_q \times T_{ser} + u \times m1(z)$   $T_q = \lambda \times T_q \times T_{ser} + u \times m1(z)$   $T_q = u \times T_q + u \times m1(z)$ Defin of utilization (u)

$$T_{q}^{q} \times (1 - u) = m1(z) \times u \Rightarrow T_{q} = m1(z) \times u/(1-u) \Rightarrow T_{q} = T_{ser} \times \frac{1}{2}(1+C) \times u/(1-u)$$

- · Notice that as  $u\rightarrow 1$ ,  $T_a\rightarrow \infty$ !
- · Assumptions so far:
  - System in equilibrium; No limit to the queue: works First-In-First-Out
  - Time between two successive arrivals in line are random and memoryless: (M for C=1 exponentially random)
  - Server can start on next customer immediately after prior finishes
- General service distribution (no restrictions), 1 server:
  - Called M/G/1 queue:  $T_q = T_{ser} \times \frac{1}{2}(1+C) \times u/(1-u)$
- Memoryless service distribution (C = 1):
  - Called M/M/1 queue:  $T_q = T_{ser} \times u/(1 u)$

# A Little Queuing Theory: An Example

- · Example Usage Statistics:
  - User requests 10 × 8KB disk I/Os per second
  - Requests & service exponentially distributed (C=1.0)
  - Avg. service = 20 ms (controller+seek+rot+Xfertime)
- Questions:
  - How utilized is the disk?
    - » Ans: server utilization,  $u = \lambda T_{ser}$
  - What is the average time spent in the queue?
  - What is the number of requests in the queue?  $\Rightarrow$  Ans:  $L_a = \lambda T_a$
  - What is the ava response time for disk request? » Ans:  $T_{sys} = T_a + T_{ser}$  (Wait in queue, then get served)
- Computation:

```
'(avg # arriving customers/s) = 10/s
  T_{\text{ser}} (avg time to service customer) = 20 ms (0.02s)
        (server utilization) = \lambda \times T_{ser} = 10/s × .02s = 0.2 (avg time/customer in queue) = T_{ser} \times u/(1 - u)
         \stackrel{\cdot}{=} 20 x 0.2/(1-0.2) = 20 x 0.25 \stackrel{\circ}{=} 5 ms (0 .005s)
        (avg length of queue) = \lambda \times T_a = 10/s \times .005s = 0.05
T<sub>sys</sub> (avg time/customer in system) = T<sub>q</sub> + T<sub>ser</sub> = 25 ms
```

# Administrivia

- · Course Feedback Tomorrow in Section
  - Make sure to go to section!
- · Group Evaluations not Optional
  - You will get a zero for project if you don't fill them out!
  - We use these for grading
- Regrade requests for Midterm I
  - Must be in by next week
- · Check glookup to make sure that we have right grades
  - Make sure that we don't have errors

#### Queuing Theory Resources

- · Handouts page contains Queueing Theory Resources:
  - Scanned pages from Patterson and Hennesey book that gives further discussion and simple proof for general eq.
  - A complete website full of resources
- · Midterms with queueing theory questions:
  - Midterm IIs from previous years that I've taught
- · Assume that Queueing theory is fair game for the final!

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# Disk Scheduling

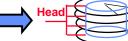
· Disk can do only one request at a time; What order do you choose to do queued requests?

Requests









- FIFO Order
  - Fair among requesters, but order of arrival may be to random spots on the disk  $\Rightarrow$  Very long seeks
- SSTF: Shortest seek time first
  - Pick the request that's closest on the disk
  - Although called SSTF, today must include rotational delay in calculation, since rotation can be as long as seek

- Con: SSTF good at reducing seeks, but may lead to starvation

 SCAN: Implements an Elevator Algorithm: take the closest request in the direction of travel

- No starvation, but retains flavor of SSTF

· C-SCAN: Circular-Scan: only goes in one direction

- Skips any requests on the way back

- Fairer than SCAN, not biased towards pages in middle

#### Building a File System

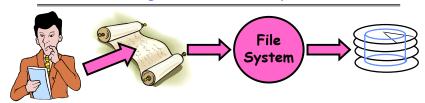
- File System: Layer of OS that transforms block interface of disks (or other block devices) into Files, Directories, etc.
- · File System Components
  - Disk Management: collecting disk blocks into files
  - Naming: Interface to find files by name, not by blocks
  - Protection: Layers to keep data secure
  - Reliability/Durability: Keeping of files durable despite crashes, media failures, attacks, etc.
- · User vs. System View of a File
  - User's view:
    - » Durable Data Structures
  - System's view (system call interface):
    - » Collection of Bytes (UNIX)
    - » Doesn't matter to system what kind of data structures you want to store on disk!
  - System's view (inside OS):
    - » Collection of blocks (a block is a logical transfer unit, while a sector is the physical transfer unit)
    - » Block size ≥ sector size; in UNIX, block size is 4KB

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# Disk Management Policies

- Basic entities on a disk:
  - File: user-visible group of blocks arranged sequentially in logical space
  - Directory: user-visible index mapping names to files (next lecture)
- · Access disk as linear array of sectors. Two Options:
  - Identify sectors as vectors [cylinder, surface, sector]. Sort in cylinder-major order. Not used much anymore.
  - Logical Block Addressing (LBA). Every sector has integer address from zero up to max number of sectors.
  - Controller translates from address ⇒ physical position » First case: OS/BIOS must deal with bad sectors
  - » Second case: hardware shields OS from structure of disk
- Need way to track free disk blocks
  - Link free blocks together ⇒ too slow today
  - Use bitmap to represent free space on disk
- · Need way to structure files: File Header
  - Track which blocks belong at which offsets within the logical file structure
  - Optimize placement of files' disk blocks to match access and usage patterns

# Translating from User to System View



- · What happens if user says: give me bytes 2—12?
  - Fetch block corresponding to those bytes
  - Return just the correct portion of the block
- · What about: write bytes 2—12?
  - Fetch block
  - Modify portion
  - Write out Block
- Everything inside File System is in whole size blocks
  - For example, getc(), putc() ⇒ buffers something like 4096 bytes, even if interface is one byte at a time
- From now on, file is a collection of blocks

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# Designing the File System: Access Patterns

- How do users access files?
  - Need to know type of access patterns user is likely to throw at system
- · Sequential Access: bytes read in order ("give me the next X bytes, then give me next, etc")
  - Almost all file access are of this flavor
- · Random Access: read/write element out of middle of array ("give me bytes i—j")
  - Less frequent, but still important. For example, virtual memory backing file: page of memory stored in file
  - Want this to be fast don't want to have to read all bytes to get to the middle of the file
- · Content-based Access: ("find me 100 bytes starting with KUBI")
  - Example: employee records once you find the bytes, increase my salary by a factor of 2
  - Many systems don't provide this; instead, databases are built on top of disk access to index content (requires efficient random access)

# Designing the File System: Usage Patterns

· Most files are small (for example, .login, .c files)

- A few files are big - nachos, core files, etc.; the nachos executable is as big as all of your class files combined

- However, most files are small' - .class's, .o's, .c's, etc.

- · Large files use up most of the disk space and bandwidth to/from disk
  - May seem contradictory, but a few enormous files are equivalent to an immense # of small files
- · Although we will use these observations, beware usage patterns:
  - Good idea to look at usage patterns: beat competitors by optimizing for frequent patterns
  - Except: changes in performance or cost can alter usage patterns. Maybe UNIX has lots of small files because big files are really inefficient?

· Digression, danger of predicting future:

- In 1950's, marketing study by IBM said total worldwide need for computers was 7!

- Company (that you haven't heard of) called "GenRad" invented oscilloscope; thought there was no market, so sold patent to Tektronix (bet you have heard of them!)

11/02/09 heard of them!)

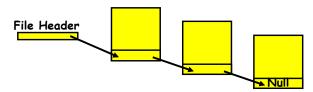
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# How to organize files on disk

- · Goals:
  - Maximize sequential performance
  - Easy random access to file
  - Easy management of file (growth, truncation, etc)
- · First Technique: Continuous Allocation
  - Use continuous range of blocks in logical block space
    - » Analogous to base+bounds in virtual memory
    - » User says in advance how big file will be (disadvantage)
  - Search bit-map for space using best fit/first fit » What if not enough contiguous space for new file?
  - File Header Contains:
    - » First block/LBA in file
    - » File size (# of blocks)
  - Pros: Fast Sequential Access, Easy Random access
  - Cons: External Fragmentation/Hard to grow files
    - » Free holes get smaller and smaller
    - » Could compact space, but that would be really expensive
- · Continuous Allocation used by IBM 360
  - Result of allocation and management cost: People would create a big file, put their file in the middle Lec 18.18

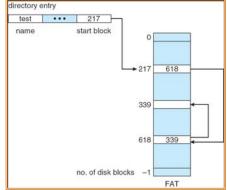
#### Linked List Allocation

- · Second Technique: Linked List Approach
  - Each block, pointer to next on disk



- Pros: Can grow files dynamically, Free list same as file
- Cons: Bad Sequential Access (seek between each block), Unreliable (lose block, lose rest of file)
- Serious Con: Bad random access!!!!
- Technique originally from Alto (First PC, built at Xerox)
  - » No attempt to allocate contiguous blocks

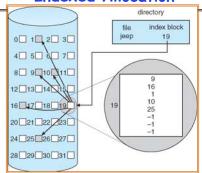
# Linked Allocation: File-Allocation Table (FAT)



- MSDOS links pages together to create a file
  - Links not in pages, but in the File Allocation Table (FAT)
    - » FAT contains an entry for each block on the disk
  - » FAT Entries corresponding to blocks of file linked together - Access properties:
    - » Sequential access expensive unless FAT cached in memory

» Random access expensive always, but really expensive if FAT not cached in memory 11/02/09 Lec 18,20

#### Indexed Allocation



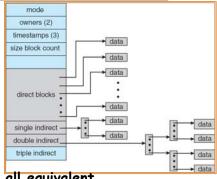
- · Third Technique: Indexed Files (Nachos, VMS)
  - System Allocates file header block to hold array of pointers big enough to point to all blocks
    - » User pre-declares max file size;
  - Pros: Can easily grow up to space allocated for index Random access is fast
  - Cons: Clumsy to grow file bigger than table size

Still lots of seeks: blocks may be spread over disk

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# Multilevel Indexed Files (UNIX 4.1)

- Multilevel Indexed Files: Like multilevel address translation (from UNIX 4.1 BSD)
  - Key idea: efficient for small files, but still allow big files



- · File hdr contains 13 pointers
  - Fixed size table, pointers not all equivalent
  - This header is called an "inode" in UNIX
- · File Header format:
  - First 10 pointers are to data blocks
  - Ptr 11 points to "indirect block" containing 256 block ptrs
  - Pointer 12 points to "doubly indirect block" containing 256 indirect block ptrs for total of 64K blocks
- Pointer 13 points to a triply indirect block (16M blocks)
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# Multilevel Indexed Files (UNIX 4.1): Discussion

- Basic technique places an upper limit on file size that is approximately 16Gbytes
  - Designers thought this was bigger than anything anyone would need. Much bigger than a disk at the time...
  - Fallacy: today, EOS producing 2TB of data per day
- Pointers get filled in dynamically: need to allocate indirect block only when file grows > 10 blocks
  - On small files, no indirection needed

# Example of Multilevel Indexed Files

- Sample file in multilevel indexed format:
  - How many accesses for block #23? (assume file header accessed on open)?
    - » Two: One for indirect block, one for data
  - How about block #5?
    - » One: One for data
  - Block #340?

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- » Three: double indirect block, indirect block, and data
- · UNIX 4.1 Pros and cons
  - Pros: Simple (more or less)

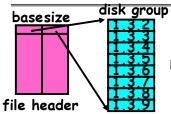
Files can easily expand (up to a point) Small files particularly cheap and easy

- Cons: Lots of seeks

Very large files must read many indirect blocks (four

I/O's per block!)

# File Allocation for Cray-1 DEMOS

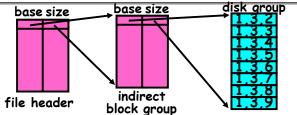


Basic Segmentation Structure: Each segment contiguous on disk

- DEMOS: File system structure similar to segmentation
  - Idea: reduce disk seeks by
    - » using contiguous allocation in normal case
    - » but allow flexibility to have non-contiguous allocation
  - Cray-1 had 12ns cycle time, so CPU: disk speed ratio about the same as today (a few million instructions per seek)
- · Header: table of base & size (10 "block group" pointers)
  - Each block chunk is a contiguous group of disk blocks
  - Sequential reads within a block chunk can proceed at high speed - similar to continuous allocation
- · How do you find an available block group?
  - Use freelist bitmap to find block of 0's.

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# Large File Version of DEMOS



- · What if need much bigger files?
  - If need more than 10 groups, set flag in header: BIGFILE

    » Each table entry now points to an indirect block group
  - Suppose 1000 blocks in a block group  $\Rightarrow$  80GB max file
    - » Assuming 8KB blocks, 8byte entries⇒ (10 ptrs×1024 groups/ptr×1000 blocks/group)\*8K =80GB
- · Discussion of DEMOS scheme
  - Pros: Fast sequential access, Free areas merge simply Easy to find free block groups (when disk not full)
  - Cons: Disk full ⇒ No long runs of blocks (fragmentation), so high overhead allocation/access
- Full disk ⇒ worst of 4.1BSD (lots of seeks) with worst of continuous allocation (lots of recompaction needed)
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# How to keep DEMOS performing well?

- · In many systems, disks are always full
  - CS department growth: 300 GB to 1TB in a year
    - » That's 2GB/day! (Now at 3—4 TB!)
  - How to fix? Announce that disk space is getting low, so please delete files?
    - » Don't really work: people try to store their data faster
  - Sidebar: Perhaps we are getting out of this mode with new disks... However, let's assume disks full for now
- · Solution:
  - Don't let disks get completely full: reserve portion
    - » Free count = # blocks free in bitmap
    - » Scheme: Don't allocate data if count < reserve
  - How much reserve do you need?
    - » In practice, 10% seems like enough
  - Tradeoff: pay for more disk, get contiguous allocation
    - » Since seeks so expensive for performance, this is a very good tradeoff

#### UNIX BSD 4.2

- Same as BSD 4.1 (same file header and triply indirect blocks), except incorporated ideas from DEMOS:
  - Uses bitmap allocation in place of freelist
  - Attempt to allocate files contiguously
  - 10% reserved disk space
  - Skip-sector positioning (mentioned next slide)
- Problem: When create a file, don't know how big it will become (in UNIX, most writes are by appending)
  - How much contiguous space do you allocate for a file?
  - In Demos, power of 2 growth: once it grows past 1MB, allocate 2MB, etc
  - In BSD 4.2, just find some range of free blocks
    - » Put each new file at the front of different range
    - » To expand a file, you first try successive blocks in bitmap, then choose new range of blocks
  - Also in BSD 4.2: store files from same directory near each other

# Attack of the Rotational Delay

 Problem 2: Missing blocks due to rotational delay
 Issue: Read one block, do processing, and read next block. In meantime, disk has continued turning: missed next block! Need 1 revolution/block!



- Solution1: Skip sector positioning ("interleaving")
  - » Place the blocks from one file on every other block of a track: give time for processing to overlap rotation
- Solution2: Read ahead: read next block right after first, even if application hasn't asked for it yet.

  » This can be done either by OS (read ahead)

  » By disk itself (track buffers). Many disk controllers have

  - internal RAM that allows them to read a complete track
- Important Aside: Modern disks+controllers do many complex things "under the covers"
- Track buffers, elevator algorithms, bad block filtering

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#### How do we actually access files?

- · All information about a file contained in its file header
  - UNIX calls this an "inode"
    - » Inodes are global resources identified by index ("inumber")
  - Once you load the header structure, all the other blocks of the file are locatable
- · Question: how does the user ask for a particular file?
  - One option: user specifies an inode by a number (index). » Imagine: open("14553344")
  - Better option: specify by textual name
    - » Have to map name→inumber
  - Another option: Icon
    - » This is how Apple made its money. Graphical user interfaces. Point to a file and click.
- Naming: The process by which a system translates from user-visible names to system resources
  - In the case of files, need to translate from strings (textual names) or icons to inumbers/inodes
- For global file systems, data may be spread over globe need to translate from strings or icons to some combination of physical server location and inumber 11/02/09 Le.

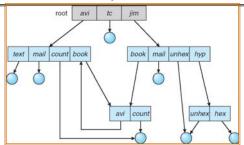
#### Directories

- · Directory: a relation used for naming
  - Just a table of (file name, inumber) pairs
- How are directories constructed?
  - Directories often stored in files
    - » Reuse of existing mechanism
    - » Directory named by inode/inumber like other files
  - Needs to be quickly searchable
    - » Options: Simple list or Hashtable
    - » Can be cached into memory in easier form to search
- How are directories modified?
  - Originally, direct read/write of special file
  - System calls for manipulation: mkdir, rmdir
  - Ties to file creation/destruction
    - » On creating a file by name, new inode grabbed and associated with new file in particular directory

# **Directory Organization**

- · Directories organized into a hierarchical structure
  - Seems standard, but in early 70's it wasn't
  - Permits much easier organization of data structures
- · Entries in directory can be either files or directories
- Files named by ordered set (e.g., /programs/p/list)

# **Directory Structure**



· Not really a hierarchy!

- Many systems allow directory structure to be organized as an acyclic graph or even a (potentially) cyclic graph

- Hard Links: different names for the same file » Multiple directory entries point at the same file

- Soft Links: "shortcut" pointers to other files

» Implemented by storing the logical name of actual file

Name Resolution: The process of converting a logical name into a physical resource (like a file)

- Traverse succession of directories until reach target file

- Global file system: May be spread across the network

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# Directory Structure (Con't)

- How many disk accesses to resolve "/my/book/count"?
  - Read in file header for root (fixed spot on disk)
  - Read in first data bock for root
    - » Table of file name/index pairs. Search linearly ok since directories typically very small
  - Read in file header for "my"
  - Read in first data block for "my"; search for "book"
  - Read in file header for "book"
  - Read in first data block for "book"; search for "count"
  - Read in file header for "count"
- · Current working directory: Per-address-space pointer to a directory (inode) used for resolving file names
  - Allows user to specify relative filename instead of absolute path (say CWD="/my/book" can resolve "count")

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#### Where are inodes stored?

- · In early UNIX and DOS/Windows' FAT file system, headers stored in special array in outermost cylinders
  - Header not stored anywhere near the data blocks. To read a small file, seek to get header, see back to data
  - Fixed size, set when disk is formatted. At formatting time, a fixed number of inodes were created (They were each given a unique number. called an "inumber")

#### Where are inodes stored?

- · Later versions of UNIX moved the header information to be closer to the data blocks
  - Often, inode for file stored in same "cylinder group" as parent directory of the file (makes an Is of that directory run fast).
  - Pros:

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- » Reliability: whatever happens to the disk, you can find all of the files (even if directories might be disconnected)
- » UNIX BSD 4.2 puts a portion of the file header array on each cylinder. For small directories, can fit all data, file headers, etc in same cylinder > no seeks!
- » File headers much smaller than whole block (a few hundred bytes), so multiple headers fetched from disk at same time

#### Summary

- · Queuing Latency:
  - M/M/1 and M/G/1 queues: simplest to analyze
  - As utilization approaches 100%, latency  $\rightarrow \infty$

$$T_q = T_{ser} \times \frac{1}{2}(1+C) \times u/(1-u)$$

- · File System:
  - Transforms blocks into Files and Directories
  - Optimize for access and usage patterns
  - Maximize sequential access, allow efficient random access
- · File (and directory) defined by header
  - Called "inode" with index called "inumber"
- · Multilevel Indexed Scheme
  - Inode contains file info, direct pointers to blocks,
  - indirect blocks, doubly indirect, etc...
- · DEMOS:
  - CRAY-1 scheme like segmentation
  - Emphsized contiguous allocation of blocks, but allowed to use non-contiguous allocation when necessary
- · Naming: the process of turning user-visible names into
- resources (such as files)
  11/02/09 (Such as files)
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