

Project 1 Overview

CS162, 7/1-2/2015

Deadlines

- **Design document:** 7/2/15 *at midnight*
- **Design review:** 7/6/15, sign up by 7/1/15
- **Checkpoint 1:** 7/7/15
- **Project deadline:** 7/13/15

What are *you* building?

1. Timer —> “Alarm Clock”
2. A priority scheduler that implements *priority donation* for locks
3. A BSD4.4 style priority scheduler

What does Pintos already provide?

- Thread creation and completion
- Simple scheduler
- Standard synchronization data structures
 - Locks
 - Semaphores
 - Condition variables
 - Barriers

Task 1:

Sleeping Timer/Alarm Clock

Alarm Clock

- **Your task:** reimplement `timer_sleep`
- What does `timer_sleep` do?
 - Running `timer_sleep(n)` puts the calling thread to sleep until ***at least*** n ticks from now
 - `timer_sleep` currently busy-waits via `yields`. Why is this bad?

What is a timer?

- On many systems, there will be some “clock” that triggers a hardware interrupt at some known rate
- This allows us to implement periodic events
- With this timer, we can implement a variety of `sleep` functions, e.g.:
 - `timer_msleep(...)`
 - `timer_usleep(...)`, etc.

What should your `timer_sleep(...)` do?

- A correct solution will:
 - Put the calling thread to sleep when it calls the `timer_sleep(n)` function, and leave this thread sleeping until *n* ticks from now
 - Not miss any ticks
 - Never “fail” and fall back on busy-waiting
Contemplate: Are there any corner cases that *could* cause your scheduler to fail? Why?

Points to consider/optimize

- If I store information about when to wake sleeping threads, what are efficient data structures and layouts for this information?
- Is it more efficient to store the time *when* a thread should be woken up, or the time *until* a thread should be woken up?
- Will my solution always wake a thread up *exactly* when it should wake up? Will I ever wake a thread up late?

Task 2:

Priority Scheduler

Priority scheduler

- **Your task:** implement a priority scheduler
- Priorities range from 0 (low) to 63 (high)
- A correct implementation will:
 - Always schedule the highest priority thread that is runnable
 - Preempt the current thread if a higher priority thread becomes runnable
 - A thread can change its priority whenever it is running (If a thread changes its priority and is no longer the highest priority thread, what happens?)

What is priority donation, and why is it important?

- Priority donation is a partial solution to the *priority inversion* problem
- Thought question: if t_1 is waiting on t_2 , and t_2 has lower priority than t_1 , what has effectively happened?
- Is priority inversion actually a problem?
 - Yes! Priority inversion led to system instability in the Mars Pathfinder robot. :(

See http://research.microsoft.com/en-us/um/people/mbj/Mars_Pathfinder/.

What we expect from your Priority Donation scheme

- Whenever a thread t_H is waiting on a lock, and another thread t_L has that lock, t_L should inherit t_H 's priority
- Donation should occur if *multiple threads* are waiting on a single thread
- Donation should also occur if there is nested waiting (e.g., t_H waits on t_M and t_M waits on t_L)
- Donations should be *revoked* when a thread unblocks

Important design question:

What is the correct donation
behavior in each multiple
donation case?

Points to consider/optimize

- Is there an upper bound on how many threads a thread can *donate* priority to? If so, what is it?
- Is there an upper bound on how many threads a thread can *receive* priority from? If so, what is it?
- Is there a limit to how deep *nested* priority donation can go? If so, what is it?

A last general comment

- Priority *scheduling* is much less complex than priority *donation*
- Your design should focus more on priority donation and the various corner cases you might encounter
- However, before implementing priority donation, make sure that your priority scheduler works!

Task 3:

Advanced Scheduler

Advanced Scheduler

- **Your task:** implement a 4.4BSD-style scheduler
- 4.4BSD uses a multilevel feedback queue scheduler:
 - This is a type of priority scheduler.
 - However, threads *do not* set their own priority.
 - The scheduler *does not* perform donation.

Note:

We must be able to choose between the basic priority scheduler and multi-level feedback queue scheduler at startup by passing the `-mlfqs` argument.

Multi-level Feedback Queue

- **Multi-level:** The scheduler has multiple queues that correspond to different priority levels
- **Feedback:** Over the lifetime of a thread, the scheduler will dynamically move the thread between different priority levels
- Whenever we need to schedule a thread, we will schedule a thread from the highest priority non-empty queue.
- **Important note:** We expect the individual priority-specific queues to perform round robin scheduling of threads.

How is priority calculated?

- We use the same number of priority levels as in the priority scheduler (64: 0 = low, 63 = high)
 - How many queues does our scheduler have?

- We calculate priority with the equation:

$$\text{priority} = \text{PRI_MAX} - (\text{recent_cpu} / 4) - (\text{nice} * 2)$$

- When do we calculate priority?

How is priority calculated?

- We use the same number of priority levels as in the priority scheduler (64: 0 = low, 63 = high)
 - How many queues does our scheduler have?
- We calculate priority with the equation:
$$\text{priority} = \text{PRI_MAX} - (\text{recent_cpu} / 4) - (\text{nice} * 2)$$
- When do we calculate priority?
 - On thread startup, and every 4th tick thereafter

Niceness

- Although the MLFQS don't allow threads to specify a *priority*, threads are allowed to set their *niceness*
- Niceness exists on a scale between -20 and 20 and parametrizes how likely a thread is to yield time to/take time from another thread.
 - Niceness = 0: No preference
 - Niceness = -20: Prefer to *take* time *from* other threads
 - Niceness = 20: Prefer to *yield* time *to* other threads

Calculating Recent CPU Usage

- General principle: weight calculation of CPU usage to favor *recent* usage
- We can do this by using an exponentially weighted moving average: $x(t) = a \cdot x(t-1) + f(t)$
- On every timer interrupt, we increment `recent_cpu` by 1 *for the running thread*
- Once per second, we update `recent_cpu` for all threads using `load_avg` (see project handout)

Nits: CPU Usage

- The tests assume that the “once per second” updates happen when
`timer_ticks() % TIMER_FREQ == 0`
- Unlike priorities, `recent_cpu` *can* go negative
- If ordered incorrectly, the calculations performed to recalculate CPU usage can lead to overflow