University of California, Berkeley
College of Engineering
Computer Science Division — EECS
Fall 2015
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Midterm II
April 22 ${ }^{\text {nd }}, 2015$
CS162: Operating Systems and Systems Programming

| Your Name: |  |
| :--- | :--- |
| SID Number: |  |
| Discussion <br> Section: |  |

General Information:
This is a closed book exam. You are allowed 1 page of hand-written notes (both sides). You have 3 hours to complete as much of the exam as possible. Make sure to read all of the questions first, as some of the questions are substantially more time consuming.

Write all of your answers directly on this paper. Make your answers as concise as possible. On programming questions, we will be looking for performance as well as correctness, so think through your answers carefully. If there is something about the questions that you believe is open to interpretation, please ask us about it!

| Problem | Possible | Score |
| :---: | :---: | :---: |
| 1 | 18 |  |
| 2 | 20 |  |
| 3 | 20 |  |
| 4 | 24 |  |
| 5 | 18 |  |
| Total |  |  |

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3.141592653589793238462643383279502884197169399375105820974944

## Problem 1: True/False [18 pts]

In the following, it is important that you EXPLAIN your answer in TWO SENTENCES OR LESS (Answers longer than this may not get credit!). Also, answers without an explanation GET NO CREDIT.

Problem 1a[2pts]: mmap maps memory addresses to portions of files by changing page table entries to map virtual addresses to disk block addresses.

## True / False Explain:

Problem 1b[2pts]: In the Fast File System (FFS), an inode includes all metadata about a file, including its size, permissions, name, and pointer to disk blocks.

## True / False Explain:

Problem 1c[2pts]: Memory mapped I/O devices can be accessed by user-level threads under the right circumstances.

## True / False <br> Explain:

Problem 1d[2pts]: All physical addresses accessed by the CPU correspond to locations in DRAM.

## True / False <br> Explain:

Problem 1e[2pts]: A transactional system that uses two-phase locking (2PL) guarantees that transactions will be conflict serializable.

## True / False <br> Explain:

Problem 1f[2pts]: A fully-associative cache always experiences fewer misses than a direct-mapped cache of the same total size.

## True / False <br> Explain:

Problem $1 \mathrm{~g}[2 \mathrm{pts}]$ : An M/M/1 queue has exponential distributions of both arrivals and service times.

## True / False <br> Explain:

Problem 1h[2pts]: The optimal policy for handling events is to always utilize interrupts for signaling, since this policy adapts well to the unpredictability of event arrival.

## True / False <br> Explain:

Problem 1i[2pts]: Because of the 32-bit IP-V4 address space, it is impossible for more than $2^{32}$ computers to communicate over the internet.

## True / False <br> Explain:

## Problem 2: Short Answer [20pts]

For the following questions, please provide as short an answer as you can that actually answers the question. In most cases, this means one or two sentences. We reserve the right to take off points for answers that are not concise.

Problem 2a[3pts]: What information would an IP router need to allow it to route packets to arbitrary IP addresses? Explain why every router does not need to know about every destination.

Problem 2b[2pts]: Under what conditions are file caches effective for speeding up file reads, i.e. how does the effectiveness the cache depend on the file access patterns of user programs?

Problem 2c[3pts]: What is a precise exception and when are precise exceptions useful?

Problem 2d[3pts]: Suppose you have a RAID-5 system consisting of 4 disks. What must you do to recover data when one disk fails? What must you do to replace the failed disk? Be explicit.

Problem 2e[2pts]: In the context of the ACID transactional semantics, explain how a system can exhibit atomicity, but not consistency.

Problem 2f[3pts]: Explain what copy-on-write is (with respect to the virtual memory system) and explain how the virtual memory system can be used to implement copy-on-write.

Problem 2g[2pts]: Explain how the syscall number and the syscall arguments are passed from the user program to the kernel in Pintos.

Problem 2h[2pts]: Explain what DMA is (don't just say what it stands for) and explain how it helps to improve the performance of a file system.

## Problem 3: File Systems [20pts]

Please keep your answers short (one or two sentences per question-mark). We may not give credit for long answers.

Pintos-inspired file system: Consider the following file system code inspired by Pintos. You may assume all the code is run on Intel x86 32 bit architecture. Instead of inodes, dirents, and data blocks, our file system will be entirely comprised of fnodes. fnodes are constant size structures that will store all the data for the file. The entire disk is composed of fnodes, fnodes are accessed similarly to inodes (via index). The file system only has one directory " $/$ " and all fnodes are under that directory. No more directories will be formed.

```
#define BLOCK_SIZE 4096
/* Block device that contains the file system. */
struct block *fs_device;
/* Reads sector SECTOR from BLOCK into BUFFER */
void block_read(struct block *block, block_sector_t sector,
    void *buffer);
/* Write sector SECTOR to BLOCK from BUFFER, mark block as not free */
void block_write(struct block *block, uint32_t sector,
    const void *buffer) ;
/* Returns one free block */
long get_free_block();
/* Marks given block as free */
void free_block(long bnum);
/* ??? */
int lookup(char* file_name);
/* On-disk fnode. Must be exactly BLOCK_SIZE bytes long. */
struct fnode_disk {
    uint32_t file_name[511]; /* File Name. */
    uint32_t data[512]; /* File Data. */
    unsigned int magic; /* Magic number. */
};
/* In-memory fnode. */
struct fnode {
    struct list_elem elem; /* Element in fnode list. */
    uint32_t sector; /* Sector number of disk location. */
    int open_cnt; /* Number of openers. */
    bool removed; /* True if deleted, false otherwise. */
    int deny_write_cnt; /* 0: writes ok, >0: deny writes. */
    struct fnode_disk data; /* fnode content. */
};
```

Problem 3a[3pts]: Given a disk with 2 GB ( $\mathrm{GB}=2^{30}$ bytes) of usable space (not FS metadata), draw a histogram on the graph below to reflect the optimal usage pattern for this file system. Remember to label the values on each axis so we can interpret your graph properly. Particularly consider the maximum attainable values on either axis. Hint: There is exactly one answer


File Size
Problem 3b[3pts]: Given what you know about this particular file system, in order for file system operations to succeed what do you suppose the function lookup will need to do? Describe one possible way the lookup ( ) function could be implemented. Please limit your answer to twenty words or less!

Problem 3c[6pts]: Suppose that you want to implement hard links in the above file system, and that you want the links to behave identically to other file systems.
a. What changes do you need to make to the fnode structure to make this possible?
b. Describe the necessary modifications to write( ) and read () operations, if any.
c. What are two major disadvantages of this file system with respect to hard links?

Please limit each of your answers ( $a, b, c$ ) to twenty words or less!

Problem 3d[2pts]: You decide to buy storage devices for the file system and have a choice between a 7200 RPM SATA 40 TB ( $\mathrm{TB}=2^{40}$ bytes) hard disk or a 20 TB SSD. If you are looking to maximize both read/write throughput and storage capacity which of the choices is a better option. Why? Please limit your answer to twenty words or less.

Problem 3e[6pts]: Disk requests come in to the driver for cylinders 3, 9, 6, 8, 4, 10, 2, simultaneously, in that order. A seek takes $5 \mu$ s per cylinder. Calculate the sequence of reads and the total seek time for each of the following policies: First In First Out (FIFO), Shortest Seek Time First (SSTF), Elevator Algorithm (SCAN). In all cases, the disk arm is initially at cylinder 8. In case of a tie, pick the option that will minimize total seek time. For the elevator algorithm, assume the arm is initially moving toward decreasing values.

FIFO:

SSTF:

SCAN:

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## Problem 4: Cloud Video Storage Server [24pts]



The above figure illustrates a datacenter network designed to distribute video files locally and over the wide area network (WAN). As shown, multiple local clients interact with local storage servers using TCP/IP. An Ethernet switch connects these two types of elements. Further, a router gives access to the outside world over a WAN connection.

Servers have 12 disks each, divided as 2 separate RAID-6 groups of 6 disks each. Each RAID group has 4 data disks coupled with 2 parity disks. All disks are identical with the same parameters (see the above diagram). Assume that you do not have to account for the difference in bit rate between outer and inner tracks; instead, we have quoted an average transfer rate.

Assume that the file system stripes data across the disks in the RAID group. This means that sequential sectors in the file system are distributed across 4 data disks (one on each disk) before continuing with the next sector on a given disk. Further, keep in mind that it is not possible to read from multiple platters or surfaces on a given disk at the same time. You can switch platters with zero delay, however. It is possible to read from more than one disk at the same time.

Each link is characterized by its Bandwidth, one-way Latency (for the first bit to arrive), and Maximum Transfer Unit (MTU) in bytes. All links are full-duplex (can handle traffic in both directions at full bandwidth). Each switch and router is highly pipelined and will start forwarding bytes from a packet to the next hop immediately after the routing/switching delay has expired. Assume that the bottleneck link for the WAN is described by the parameters of MTU=200 bytes and $\mathrm{BW}=100 \mathrm{Mbits} / \mathrm{sec}$.

Problem 4a[5pts]: Assume that sectors are striped across a RAID stripe (e.g., since the RAID-6 stripe consists of 6 disks, sequential sectors are distributed across 4 data disks before touching the next sector in a given track). How long will it take to read 256 KB of sequential data from the RAID group (starting at a random starting position on the disk), assuming that you can do so by making a single request to the RAID controller? You can assume that the disks are synchronized with one another.

Problem 4b[2pts]: What is the maximum rate in $\mathrm{MB} / \mathrm{sec}$ that data can be read randomly from one RAID group, using 256 K chunks of data as in (4a)? Assume that each request is independent (and uncorrelated) from the previous request.

Problem 4c[3pts]: Assume that clients are reading H.264-encoded video @1080p quality encoded at a $7.68 \mathrm{Mbit} / \mathrm{sec}$ data rate. Further, assume that external clients (over WAN) are using TCP/IP to watch videos. Under ideal circumstances, what is the maximum number of simultaneous video streams that could be submitted over the WAN link? Keep in mind that the TCP/IP header is 40 bytes in size.

Problem 4d[2pts]: Can the incoming request rate calculated in (4c) be handled by a single RAID group using a 256 K request size? Explain. What is the resulting utilization of the single group?

Problem $4 \mathbf{e}[4 \mathbf{p t s}]:$ Under the same assumptions as for (4c), what is the maximum number of simultaneous video streams that a local client could submit over the local link? Would a single RAID group be sufficient to handle this traffic? What about all three servers (six RAID groups)? Explain carefully.

Problem 4f[5pts]: Finally, treat the entire system as an $M / M / m$ queue (that is, a system with $m$ servers rather than one, where each RAID group can be treated as a "server"). Assume that the switch contains a smart load-balancing queue that distributes requests to the least loaded RAID group and that every group can be utilized to serve every request. Also assume that requests are 256 KBytes in size, as in 4 a and 4 b . All requests are placed into a single queue in the load balancer. Assume that a single local client sends a maximum request rate supported by his network (as in 4 e ). What is the average number of requests queued at the load balancer? Ignore any latency in the OS of the storage server. The following equations might be useful:

$$
\begin{aligned}
& \text { M/M/m queue: } \mathrm{T}_{\text {queue }}=\mathrm{T}_{\text {server }} \times\left[\frac{\zeta}{m(1-\zeta)}\right] \text { where: } \zeta=\frac{\lambda}{\frac{1}{\mathrm{~T}_{\text {server }} / m}}=\lambda \times \frac{\mathrm{T}_{\text {server }}}{m} \\
& \text { Little's Law: } \mathrm{L}_{\text {queue }}=\lambda \times \mathrm{T}_{\text {quuue }}
\end{aligned}
$$

Problem 4g[3pts]: Under the same assumptions as (4f), what is the total latency for a request as seen from the standpoint of a local server? Ignore any software latency in the servers.

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## Problem 5: Potpourri [18pts]

Problem 5a[6pts]: For the following problem, assume a hypothetical machine with 4 pages of physical memory and 7 pages of virtual memory. Given the access pattern:

```
A BCDEFCAAFFGABGDFF
```

Indicate in the following table which pages are mapped to which physical pages for each of the following policies. Assume that a blank box matches the element to the left. We have given the FIFO policy as an example.

| Access $\rightarrow$ |  | A | B | C | D | E | F | C | A | A | F | F | G | A | B | G | D | F | F |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| T | 1 | A |  |  |  | E |  |  |  |  |  |  |  |  | B |  |  |  |  |
|  | 2 |  | B |  |  |  | F |  |  |  |  |  |  |  |  |  | D |  |  |
|  | 3 |  |  | C |  |  |  |  | A |  |  |  |  |  |  |  |  | F |  |
|  | 4 |  |  |  | D |  |  |  |  |  |  |  | G |  |  |  |  |  |  |
| $\underset{\sim}{\mathbb{C}}$ | 1 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | 2 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | 3 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | 4 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| $\begin{aligned} & \hat{O} \\ & \underset{\pi}{2} \\ & \underset{\sim}{2} \end{aligned}$ | 1 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | 2 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | 3 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | 4 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

Problem 5b[6pts]: Consider a computer system with the following parameters:

| Measurement | Value |
| :--- | :--- |
| $\mathrm{P}_{\mathrm{T}}=$ =prob of TLB miss | 0.1 |
| $\mathrm{P}_{\mathrm{F}}=$ prob of a page fault when a TLB miss occurs | 0.0002 |
| $\mathrm{P}_{\mathrm{D}}=$ prob page is dirty when replaced | 0.5 |
| $\mathrm{~T}_{\mathrm{T}}=$ time to access TLB | $0 \mu \mathrm{~s}$ |
| $\mathrm{~T}_{\mathrm{M}}=$ time to access memory | $1 \mu \mathrm{~s}$ |
| $\mathrm{~T}_{\mathrm{D}}=$ time to transfer a page to/from disk | $10 \mathrm{~ms}=10000 \mu \mathrm{~s}$ |

The TLB is refilled automatically by the hardware on a miss (the TLB is only accessed once per reference). The page tables are kept in physical memory and are not hierarchical, so looking up a page table entry incurs one memory access. Assume that the costs of the page replacement algorithm and updates to the page table are included in the $\mathrm{T}_{\mathrm{D}}$ measurement.

What is the average memory access time (the time for an application program to do one memory reference) on this computer? Assume physical memory is $100 \%$ utilized and ignore any software overheads in the kernel. Express your answer symbolically and compute the result to two significant digits. Show all steps of the computation!

Problem 5c[6pts]: Some operating systems have the park (void *hint) and unpark (void *hint ) system calls to support user-level implementations of condition variables. When a thread calls park(void *hint), it should yield the CPU. When a thread calls unpark(void *hint ), it should yield the CPU if and only if there are any other threads that had previously called park with the same hint value. Calling unpark(NULL) should match any non-null hint value The return value of park is always 0 . The return value of unpark() is 1 if the thread yielded, otherwise it's 0 .

The function check_pointer(void *ptr) will check that ptr points to valid 4 byte memory location in user memory. Implement the syscalls using the following sketch. You may not need all the blanks (write directly on the following lines):

```
void syscall_park(struct intr_frame *f) {
    uint32_t *args = (uint32_t *) f->esp;
    void *hint =
```

$\qquad$

```
    thread_current()->hint = hint;
    thread_yield();
}
void syscall_unpark(struct intr_frame *f) {
    uint32_t *args = (uint32_t *) f->esp;
    void *hint =
```

$\qquad$

``` ;
    for each struct thread t in ready_list {
        if (t->hint != NULL && (hint == NULL || hint == t->hint)) {
            t->hint = NULL
            thread_yield();
            }
    }
}
```

[ Scratch Page (feel free to remove)]

