

- Lexical analysis
  - Produces tokens
  - Detects & eliminates illegal tokens
- Parsing
  - Produces trees
  - Detects & eliminates ill-formed parse trees
- Static semantic analysis
  - Produces *decorated tree* with additional information attached
  - Detects & eliminates remaining static errors
- Next are the dynamic "back-end" phases:  $\Leftarrow$  *we are here*
  - Code generation (at various semantic levels)
  - Optimization

## Run-time environments

Before discussing code generation, we need to understand what we are trying to generate.

- We'll use the term *virtual machine* to refer to the compiler's target.
- Can be just a bare hardware architecture (small embedded systems).
- Can be an interpreter, as for Java, or an interpreter that does additional compilation at execution, as in modern Java JITs
- For now, we'll stick to hardware + conventions for using it (the *API: application programmer's interface*) + some *runtime-support library*.

## Code Generation Goals and Considerations

- *Correctness*: execution of generated code must be consistent with the programs' specified dynamic semantics.
- In general, however, these semantics do not completely specify behavior, often to allow compiler to accomplish other goals, such as ...
- *Speed*: produce code that executes as quickly as possible, or reliably meets certain timing constraints (as in real-time systems).
- *Size*: minimize size of generated program or of runtime data structures.
- Speed and size optimization can be conflicting goals. Why?
- *Compilation speed*: especially during development or when using JITs.
- Most complications in code generation come from trying to be fast as well as correct, because this requires attention to special cases.

## Subgoals and Constraints

- Subgoals for improving speed and size:
  - Minimize instruction counts.
  - Keep data structure static, known at compilation (e.g., known constant offsets to fields). Contrast Java and Python.
  - Maximize use of registers ("top of the memory hierarchy").
- Subgoals for improving compilation speed:
  - Try to keep analyses as *local* as possible (single statement, block, procedure), because their compilation-time cost tends to be non-linear.
  - Simplify assumptions about control flow: procedure calls "always" return, statements generally execute in sequence. (Where are these violated?)

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## Activations and Lifetimes (Extents)

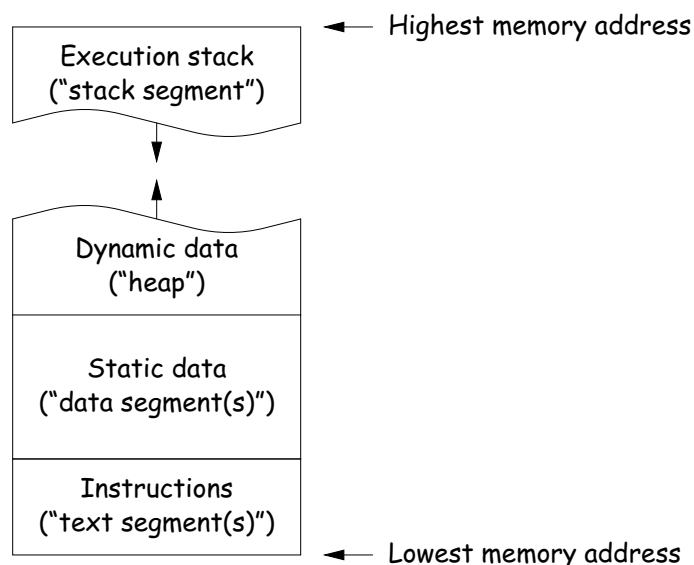
- An invocation of procedure  $P$  is an *activation* of  $P$ .
- The *lifetime of an activation* of  $P$  is all the steps to execute  $P$ , including all the steps in procedures  $P$  calls.
- The *lifetime (extent) of a variable* is the portion of execution during which that variable exists (whether or not the code currently executing can reference it).
- Lifetime is a dynamic (run-time) concept, as opposed to scope, which is static.
- Lifetimes of procedure activations and local variables properly nest (in a single thread), suggesting a *stack* data structure for maintaining their runtime state.
- Other variables have extents that are not coordinated with procedure calls and returns.

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## Memory Layout

Characteristics of procedure activations and variables give rise to the following typical data layout for a (single-threaded) program:



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## Activation Records

- The information needed to manage one procedure activation is called an *activation record (AR)* or *(stack) frame*.
- If procedure  $F$  (the *caller*) calls  $G$  (the *callee*, typically  $G$ 's activation record contains a mix of data about  $F$  and  $G$ ):
  - *Return address* to instructions in  $F$ .
  - *Dynamic link* to the AR for  $F$ .
  - Space to save registers needed by  $F$ .
  - Space for  $G$ 's local variables.
  - Information needed to find non-local variables needed by  $G$ .
  - Temporary space for intermediate results, arguments to and return values from functions that  $G$  calls.
  - Assorted machine status needed to restore  $F$ 's context (signal masks, floating-point unit parameters).
- Depending on architecture and compiler, registers typically hold part of AR (at times), especially parameters, return values, locals, and pointers to the current stack top and frame.

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## Calling Conventions

- Many variations are possible:
  - Can rearrange order of frame elements.
  - Can divide caller/callee responsibilities differently.
  - Don't need to use an array-like implementation of the stack: can use a linked list of ARs.
- An organization is better if it improves execution speed or simplifies code generation
- The compiler must determine, at compile-time, the layout of activation records and generate code that correctly accesses locations in the activation record.
- Furthermore, it is common to compile procedures separately and without access of each other's details, which motivates the the imposition of *calling conventions*.

## Static Storage

- Here, "static storage" refers to variables whose extent is an entire execution and whose size is typically fixed before execution.
- Not generally stored in an activation record, but assigned a fixed address once.
- In C/C++ variables with file scope (declared `static` in C) and with external linkage ("global") are in static storage.
- Java's "static" variables are an odd case: they don't really fit this picture (why?)

## Heap Storage

- Variables whose extent is greater than that of the AR in which they are created can't be kept there:  

```
Bar foo() { return new Bar(); }
```
- Call such storage *dynamically allocated*.
- Typically allocated out of an area called the *heap* (confusingly, not the same as the heap used for priority queues!)

## Achieving Runtime Effects—Functions

- Language design and runtime design interact. Semantics of functions make good example.
- Levels of function features:
  1. Plain: no recursion, no nesting, fixed-sized data with size known by compiler.
  2. Add recursion.
  3. Add variable-sized unboxed data.
  4. Allow nesting of functions, up-level addressing.
  5. Allow function values w/ properly nested accesses only.
  6. Allow general closures.
  7. Allow continuations.
- Tension between these effects and structure of machines:
  - Machine languages typically only make it easy to access things at addresses like  $R + C$ , where  $R$  is an address in a register and  $C$  is a relatively small integer constant.
  - Therefore, fixed offsets *good*, data-dependent offsets *bad*.

## 1: No recursion, no nesting, fixed-sized data

- Total amount of data is bounded, and there is only one instantiation of a function at a time.
- So all variables, return addresses, and return values can go in fixed locations.
- No stack needed at all.
- Characterized FORTRAN programs in the early days.
- In fact, can dispense with call instructions altogether: expand function calls in-line. E.g.,

```
def f (x):
    x *= 42
    y = 9 + x;
    g (x, y)

    x_1 = 3
    x_1 *= 42
    y_1 = 9 + x_1
    g (x_1, y_1)
```

⇒ becomes ⇒

f (3)

- However, program may get bigger than you want. Typically, one in-lines only small, frequently executed functions.

## 1: Calling conventions

- If we don't use function inlining, will need to save return address, parameters.
- There are many options. Here's one example, from the IBM 360, of calling function F from G and passing values 3 and 4:

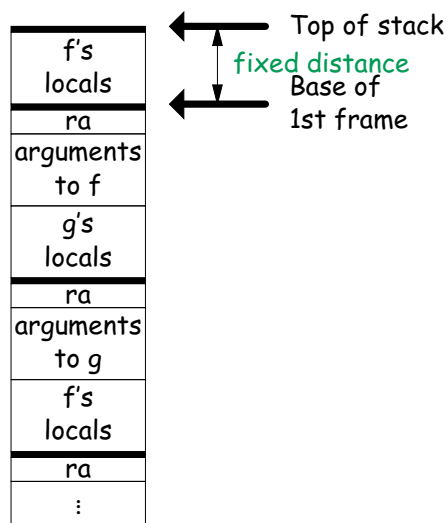
```
GArgs DS 2F          Reserve 2 4-byte words of static storage */
...
ENTRY G
...
G
...
LA R1,GArgs          Load Address of arguments into register 1
LA R0,3               Store 3 and 4 in GArgs+0 and GArgs+4
ST R0,GArgs
LA R0,4
ST R0,GArgs+4
BAL R14,F            Call ("Branch and Link") to F, R14 gets return point
```

and F might contain

```
FRet DS F
ENTRY F
F
ST R14,FRet          Save return address
L R2,0(R1)           Load first argument.
...
L R14,FRet           Get return address
BR R14              Branch to it
```

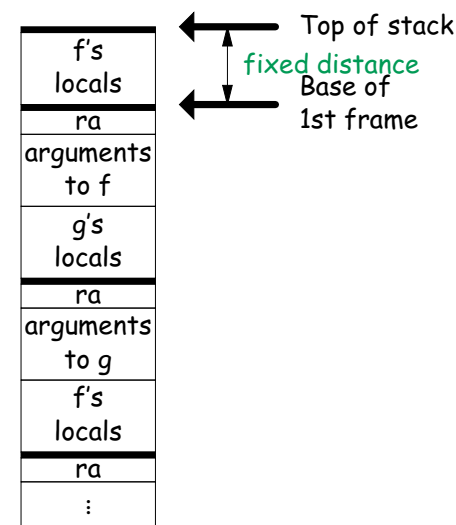
## 2: Add recursion

- Now, total amount of data is unbounded, and several instantiations of a function can be active simultaneously.
- Calls for some kind of expandable data structure: a stack.
- However, variable sizes still fixed, so size of each activation record (stack frame) is fixed.
- All local-variable addresses and the value of dynamic link are known offsets from stack pointer, which is typically in a register.
- (The diagram shows the conventions we use in the ia32, where we'll define a stack frame as starting *after* the return address.)



## 2: Calling Sequence when Frame Size is Fixed

- So dynamic links not really needed.
- Suppose *f* calls *g* calls *f*, as at right.
- When called, the initial code of *g* (its *prologue*) decrements the stack pointer by the size of *g*'s activation record.
- *g*'s exit code (its *epilogue*):
  - increments the stack pointer by this same size,
  - pops off the return address, and
  - branches to address just popped.



## 2: Calling sequence from ia32

### C code:

```
int
f (int x, int y)
{
    int s;
    s = 1;
    while (y > 0) {
        s *= x;
        y -= 1;
    }
    return s;
}

int
g(int q)
{
    return f(q, 5);
}
```

### Assembly excerpt (GNU operand order):

```
/ PRO = Prologue, EPI = Epilogue
f:      / Return address (RA) at SP, x at SP+4, y at SP+8
    subl $4, %esp      / PRO: Decrement SP to make space for s
    movl $1, (%esp)     / s = 1
.L2:
    cmpl $0, 12(%esp)   / compare 0 with y (now at SP+12)
    jle .L3
    movl (%esp), %eax   / tmp = s
    imull 8(%esp), %eax  / tmp *= x
    movl %eax, (%esp)   / s = tmp
    leal 12(%esp), %eax / tmp = &y
    decl (%eax)         / *tmp -= 1
    jmp .L2
.L3:
    movl (%esp), %eax   / return s in EAX
    addl $4, %esp      / EPI: Restore stack pointer so RA on top,
    ret               / EPI: then pop RA and return.

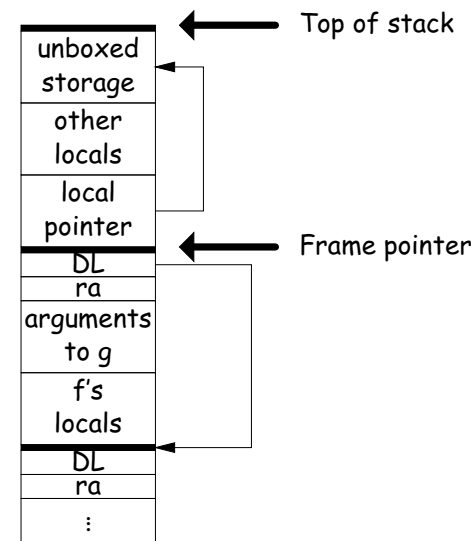
g: ...
    movl $5, 4(%esp)    / Put q and 5 on stack (q on top).
    movl 12(%esp), %eax / tmp = q
    movl %eax, (%esp)   / top of stack = q
    call f              / branch to f and push address of next.
next:
```

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## 3: Add Variable-Sized Unboxed Data

- “Unboxed” means “not on heap.”
- Boxing allows all quantities on stack to have fixed size.
- So Java implementations have fixed-size stack frames.
- But does cost heap allocation, so some languages also provide for placing variable-sized data directly on stack (“heap allocation on the stack”)
- `alloca` in C, e.g.
- Now we do need dynamic link (DL).
- But can still insure fixed offsets of data from frame base (*frame pointer*) using pointers.
- To right, *f* calls *g*, which has variable-sized unboxed array (see right).



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## Other Uses of the Dynamic Link

- Often use dynamic link even when size of AR is fixed.
- Allows use of same strategy for all ARs, simplifies code generation.
- Makes it easier to write general functions that *unwind* the stack (i.e., pop ARs off, thus returning).

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## 3: Calling sequence for the ia32

### Assembly excerpt (GNU operand order):

```
f:      / Return address (RA) at SP, x at SP+4, y at SP+8
    pushl %ebp          / PRO: Save old dynamic link.
    movl %esp, %ebp     / PRO: Set ebp to current frame base.
    subl $4, %esp       / PRO: Decrement SP to make space for s
    movl $1, -4(%ebp)   / s = 1
.L2:
    cmpl $0, 12(%ebp)   / compare 0 with y (now at BP+12)
    jle .L3
    movl -4(%ebp), %eax / tmp = s
    imull 8(%ebp), %eax  / tmp *= x
    movl %eax, -4(%ebp) / s = tmp
    leal 12(%ebp), %eax / tmp = &y
    decl (%eax)         / *tmp -= 1
    jmp .L2
.L3:
    movl -4(%ebp), %eax / return s
    leave              / EPI: Restore %esp to %ebp+4 and %ebp to 0(%ebp)
    ret               / EPI: then pop RA and return.

g: ...
    movl $5, 4(%esp)    / Put q and 5 on stack (q on top).
    movl 8(%ebp), %eax  / tmp = q
    movl %eax, (%esp)   / top of stack = q
    call f              / branch to f and push address of next.
next:
```

### C code:

```
int
f (int x, int y)
{
    int s;
    s = 1;
    while (y > 0) {
        s *= x;
        y -= 1;
    }
    return s;
}

int
g(int q)
{
    return f(q, 5);
}
```

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## 4: Allow Nesting of Functions, Up-Level Addressing

- When functions can be nested, there are three classes of variable:

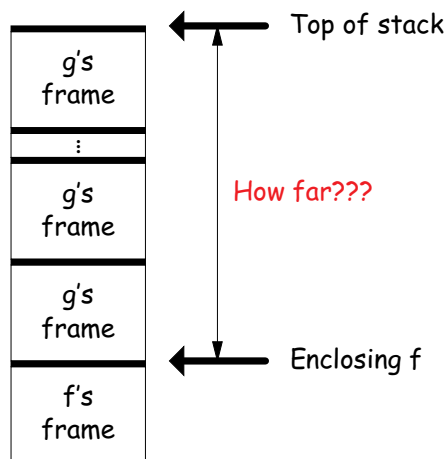
- Local to function.
- Local to enclosing function.
- Global

- Accessing (a) or (c) is easy. It's (b) that's interesting.

- Consider (in Python):

```
def f():
    y = 42 # Local to f
    def g(n, q):
        if n == 0: return q+y
        else: return g(n-1, q*2)
```

- Here, y can be any distance away from top of stack.



## Static Links

- To overcome this problem, go back to environment diagrams!

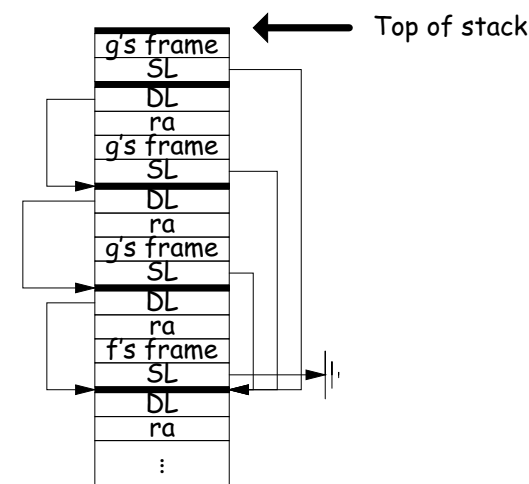
- Each diagram had a pointer to *lexically enclosing environment*

- In Python example from last slide, each 'g' frame contains a pointer to the 'f' frame where that 'g' was defined: the *static link* (SL)

- To access local variable, use frame-base pointer (or maybe stack pointer).

- To access global, use absolute address.

- To access local of nesting function, follow static link once per difference in levels of nesting.



## Calling sequence for the ia32: f0

### C code:

```
int
f0 (int n0)
{
    int s = -n0;
    int g1 () { return s; }
    int f1 (int n1) {
        int f2 () {
            return n0 + n1
                + s + g1 ();
        }
        return f2 (s) + f1 (n0)
            + g1 ();
    }
    f1 (10);
}
```

### Assembly excerpt for f0:

```
f0: / Does not need to be passed a static link
    pushl %ebp / PRO
    movl %esp, %ebp / PRO
    subl $40, %esp / PRO
    movl 8(%ebp), %eax / Fetch n0
    movl %eax, -16(%ebp) / Move n0 to new local variable
    movl -16(%ebp), %eax / Negate n0...
    negl %eax
    movl %eax, -12(%ebp) / ... and store in s
    leal -16(%ebp), %eax / Compute static link to f0's frame
    movl $10, (%esp) / Pass argument 10...
    movl %eax, %ecx / ... and static link ...
    call f1 / ... to f1
    leave / EPI
    ret / EPI
    / Static link into f0's frame points to:
    / int n0' / Copy of n0
    / int s
```

## Calling sequence for the ia32: f1

### C code:

```
int
f0 (int n0)
{
    int s = -n0;
    int g1 () { return s; }
    int f1 (int n1) {
        int f2 () {
            return n0 + n1
                + s + g1 ();
        }
        return f2 (s) + f1 (n0)
            + g1 ();
    }
    f1 (10);
}

/* Static link to f1 points to:
   int n1' Copy of n1
   int SL Static link
           to f0's frame */
```

```
f1: / Static link to f0's frame is in %ecx
    pushl %ebp / PRO
    movl %esp, %ebp / PRO
    pushl %esi / PRO: Save %esi
    pushl %ebx / PRO: Save %ebx
    subl $32, %esp / PRO
    movl %ecx, %ebx / Save link to f0's frame
    movl 8(%ebp), %eax / Move n1 ...
    movl %eax, -16(%ebp) / ... to new local
    movl %ebx, -12(%ebp) / Save static link to f0 in local
    movl 4(%ebx), %edx / Fetch s from f0's frame
    movl %edx, (%esp) / And pass to f2
    leal -16(%ebp), %ecx / Pass static link to my frame to f2
    call f2
    movl %eax, %esi / Save f2(s)
    movl (%ebx), %eax / Fetch n0 from f0's frame...
    movl %eax, (%esp) / ... and pass to f1
    movl %ebx, %ecx / Also pass on my static link
    call f1
    addl %eax, %esi / Compute f2(s) + f1(n0)
    movl %ebx, %ecx / Pass same static link to g1
    call g1
    leal (%esi,%eax), %eax / Compute f2(s)+f1(n0)+g1()
    addl $32, %esp / EPI
    popl %ebx / EPI: restore %ebx
    popl %esi / EPI: restored %esi
    popl %ebp / EPI
    ret / EPI
```

## Calling sequence for the ia32: g1

C code:

```
int
f0 (int n0)
{
    int s = -n0;
    int g1 () { return s; } g1: / Static link (to f0's frame) in %ecx
    int f1 (int n1) {
        return n0 + n1
        + s + g1 ();
    }
    return f2 (s) + f1 (n0)
    + g1 ();
}
f1 (10);
}
```

### Assembly excerpt for g1:

```
pushl %ebp / PRO
movl %esp, %ebp / PRO
movl %ecx, %eax / Fetch s from ...
movl 4(%eax), %eax / ... f0's frame
popl %ebp / EPI
ret / EPI
```

## Calling sequence for the ia32: f2

Assembly excerpt for f2:

C code:

```
int
f0 (int n0)
{
    int s = -n0;
    int g1 () { return s; }
    int f1 (int n1) {
        return n0 + n1
        + s + g1 ();
    }
    return f2 (s) + f1 (n0)
    + g1 ();
}
f1 (10);
}
```

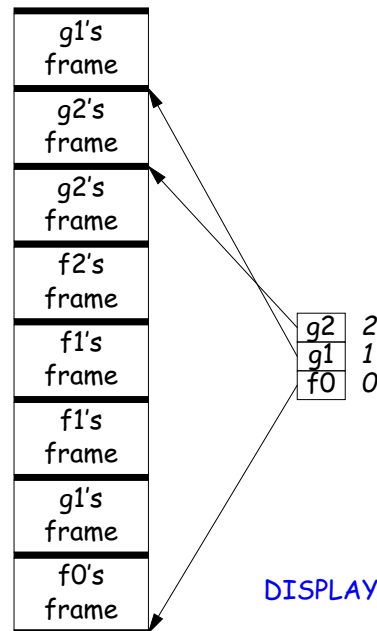
```
f2: / Static link (into f1's frame) in %ecx
pushl %ebp / PRO
movl %esp, %ebp / PRO
pushl %ebx / PRO: Save %ebx
movl %ecx, %eax / Fetch static link to f0
movl 4(%eax), %edx / ... from f1's frame
movl (%edx), %ecx / ... to get n0 from f0's frame
movl (%eax), %edx / Fetch n1 from f1's frame
addl %edx, %ecx / Add n0 + n1
movl 4(%eax), %edx / Fetch static link to f0 again
movl 4(%edx), %edx / Fetch s from f0's frame
leal (%ecx,%edx), %ebx / And add to n0 + n1
movl 4(%eax), %eax / Fetch static link to f0...
movl %eax, %ecx / ... and pass to g1
call g1
leal (%ebx,%eax), %eax / Add g1() to n0 + n1 + s
popl %ebx / EPI: Restore %ebx
popl %ebp / EPI
ret / EPI
```

## The Global Display

- Historically, first solution to nested function problem used an array indexed by call level, rather than static links.

```
def f0 ():
    q = 42; g1 ()
    def f1 ():
        def f2 (): ... g2 () ...
        def g2 (): ... g2 () ... g1 () ...
        ... f2 () ... f1 () ...
    def g1 (): ... f1 () ...
```

- Each time we enter a function at lexical level  $k$  (i.e., nested inside  $k$  functions), save pointer to its frame base in `DISPLAY[k]`; restore on exit.
- Access variable at lexical level  $k$  through `DISPLAY[k]`.
- Relies heavily on scope rules and proper function-call nesting



## Using the global display (sketch)

C code:

```
int
f0 (int n0)
{
    int s = -n0;
    int g1 () { return s; }
    int f1 (int n1) {
        return n0 + n1
        + s + g1 ();
    }
    return f2 (s) + f1 (n0)
    + g1 ();
}
f1 (10);
}
```

```
f0: ...
movl _DISPLAY+0,%eax / PRO: Save old _DISPLAY[0]...
movl %eax,-12(%ebp) / PRO: ...somewhere
movl %ebp,_DISPLAY+0 / PRO: Put my %ebp in _DISPLAY[0]
...
movl -12(%ebp),%ecx / EPI: Restore old _DISPLAY[0]
movl %ecx,_DISPLAY+0 / EPI

f1: ...
movl _DISPLAY+4,%eax / PRO: Save old _DISPLAY[1]...
movl %eax,-12(%ebp) / PRO: ... somewhere
movl %ebp,_DISPLAY+4 / PRO: Put my %ebp in _DISPLAY[1]
... likewise for epilogue.

f2 and g1: no extra code, since they have no nested functions.
```



## 5: Allow Function Values, Properly Nested Access

- In C, C++, no function nesting.
- So all non-local variables are global, and have fixed addresses.
- Thus, to represent a variable whose value is a function, need only to store the address of the function's code.
- But when nested functions possible, function value must contain more.
- When function is finally called, must be told what its static link is.
- Assume first that access is properly nested: variables accessed only during lifetime of their frame.
- So can represent function with address of code + the address of the frame that contains that function's definition.
- It's environment diagrams again!!

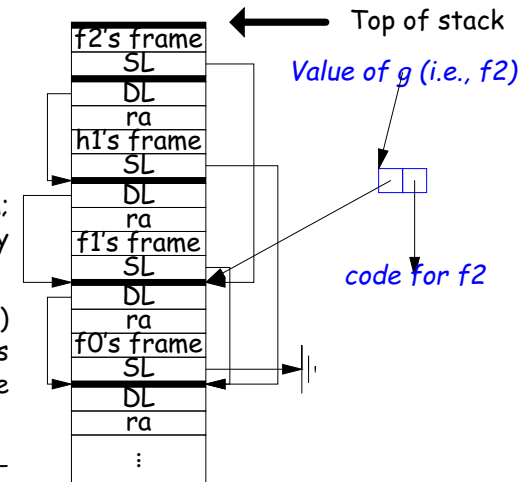
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## Function Value Representation

```
def f0 (x):
  def f1 (y):
    def f2 (z):
      return x + y + z
    print h1 (f2)
  def h1 (g): g (3)
  f1 (42)
```

- Call f0 from the main program; look at the stack when f2 finally is called (see right).
- When f2's value (as a function) is computed, current frame is that of f1. That is stored in the value passed to h1.
- Easy with static links; global display technique does not fare as well [why?]



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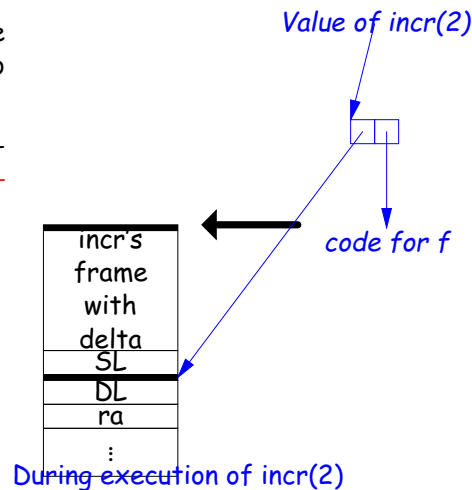
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## 6: General Closures

- What happens when the frame that a function value points to goes away?
- If we used the previous representation (#5), we'd get a **dangling pointer** in this case:

```
def incr (n):
  delta = n
  def f (x):
    return delta + x
  return f
```

```
p2 = incr(2)
print p2(3)
```

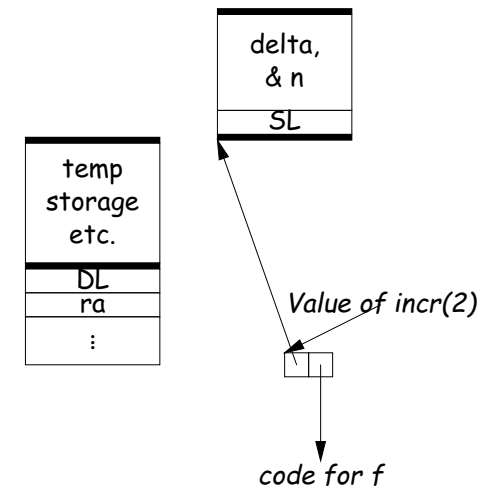


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## Representing Closures

- Could just forbid this case (as some languages do):
  - Algol 68 would not allow pointer to f (last slide) to be returned from incr.
  - Or, one could allow it, and do something random when f (i.e. via delta) is called.
- Scheme and Python allow it and do the right thing.
- But must in general put local variables (and a static link) in a record on the heap, instead of on the stack.



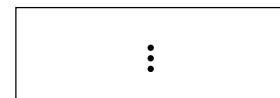
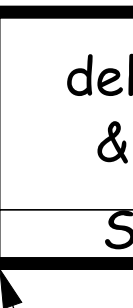
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## Representing Closures

- Could just forbid this case (as some languages do):
  - Algol 68 would not allow pointer to f (last slide) to be returned from incr.
  - Or, one could allow it, and do something random when f (i.e. via delta) is called.
- Scheme and Python allow it and do the right thing.
- But must in general put local variables (and a static link) in a record on the heap, instead of on the stack.
- Now frame can disappear harmlessly.



## 7: Continuations

- Suppose function return were not the end?

```
def f (cont): return cont
x = 1
def g (n):
    global x, c
    if n == 0:
        print "a", x, n,
        c = call_with_continuation (f)
        print "b", x, n,
    else: g(n-1); print "c", x, n,
    g(2); x += 1; print; c()
```

```
# Prints:
# a 1 0 b 1 0 c 1 1 c 1 2
# b 2 0 c 2 1 c 2 2
# b 3 0 c 3 1 c 3 2
...
```

- The *continuation*, *c*, passed to *f* is "the function that does whatever is supposed to happen after I return from *f*."
- Can be used to implement exceptions, threads, co-routines.
- Implementation? Nothing much for it but to put all activation frames on the heap.
- **Distributed cost.**
- However, we can do better on special cases like exceptions.

## Summary

Problem	Solution
1. Plain: no recursion, no nesting, fixed-sized data with size known by compiler, first-class function values.	Use inline expansion or use static variables to hold return addresses, locals, etc.
2. #1 + recursion	Need stack.
3. #2 + Add variable-sized unboxed data	Need to keep both stack pointer and frame pointer.
4. #3 - first-class function values + Nested functions, up-level addressing	Add static link or global display.
5. #4 + Function values w/ properly nested accesses: functions passed as parameters only.	Static link, function values contain their link. (Global display doesn't work so well)
6. #5 + General closures: first-class functions returned from functions or stored in variables	Store local variables and static link on heap.
7. #6 + Continuations	Put everything on the heap.