| Lecture 21: IL for Arrays | | One-dimensional Arrays | |
|--|-------------------------|--|----------------------|
| | | How do we process retrieval from and assignment to x[i], for an array x? | |
| | | We assume that all items of the array have fixed size—S bytes— and are arranged sequentially in memory (the usual representation). | |
| | | • Easy to see that the address of x[i] must be | |
| | | &x + S · i, where &x is intended to denote the address of the beginning of x. Generically, we call such formulae for getting an element of a data structure access algorithms. The IL might look like this: | |
| | | | |
| | | | |
| | | | |
| | | $cgen(\&A[E], t_0):$ $cgen(\&A, t_1)$ $cgen(E, t_2)$ $\Rightarrow t_3 := t_2 * S$ $\Rightarrow t_0 := t_1 + t_3$ | |
| Last modified: Tue Nov 5 15:53:23 2013 | CS164: Lecture #21 1 | Last modified: Tue Nov 5 15:53:23 2013 | C5164: Lecture #21 2 |
| Multi-dimensional Arrays | | IL for $M \times N$ 2D array | |
| • A 2D array is a 1D array of 1D arrays. | | cgen(&e1[e2,e3], t): | |
| • Java uses arrays of pointers to arrays for >1D arrays. | | <pre>cgen(e1, t1); cgen(e2,t2); cgen(e3,t3) cgen(N, t4) # (N need not be constant) ⇒ t5 := t4 * t2 ⇒ t6 := t5 + t3 ⇒ t7 := t6 * S</pre> | |
| But if row size constant, for faster access and compactness, may prefer to represent an MxN array as a 1D array of 1D rows (not pointers to rows): row-major order | | | |
| Or, as in FORTRAN, a 1D array of 1D columns: column-major order. | | \Rightarrow t := t7 + t1 | |
| So apply the formula for 1D arrays repeatedly—first to compute the beginning of a row and then to compute the column within that row: &A[i][j] = &A + i · S · N + j · S | | | |
| for an M-row by N-column array, where S, a individual element. | gain, is the size of an | | |
| | | | |

Array Descriptors

 \bullet Calculation of element address &e1[e2,e3] has the form

VO + S1 \times e2 +S2 \times e3

, where

- VO (&e1[0,0]) is the virtual origin.
- S1 and S2 are strides.
- All three of these are constant throughout the lifetime of the array (assuming arrays of constant size).
- Therefore, we can package these up into an *array descriptor*, which can be passed in lieu of the array itself, as a kind of "*fat pointer*" to the array:

| &e1[0][0] | S×N | S |
|-----------|-----|---|
|-----------|-----|---|

Array Descriptors (II)

• Assuming that e1 now evaluates to the address of a 2D array descriptor, the IL code becomes:

| Last modified: Tue Nov 5 15:53:23 2013 | CS164: Lecture #21 5 | Last modified: Tue Nov 5 15:53:23 2013 | C5164: Lecture #21 6 |
|--|----------------------|--|----------------------|
| Array Descriptors (III) | | | |
| By judicious choice of descriptor values, can make the same formula work for different kinds of array. | | | |
| For example, if lower bounds of indices are 1 rather than 0, must compute address | | | |
| &e[1,1] + S1 \times (e2-1) + S2 \times (e3-1) | | | |
| But some algebra puts this into the form | | | |
| VO' + S1 \times e2 + S2 \times e3 | | | |
| where | | | |
| VO' = &e[1,1] - S1 - S2 = &e[0,0] (if it e | existed). | | |
| So with the descriptor | | | |
| VO' S×N S | | | |
| we can use the same code as on the last slide. | | | |
| | | | |
| | | | |