

Due: Friday, 30 April 2010

1. A definition (that is, an assignment) of a simple variable is said to *reach* a point in the program if it *might be* the last assignment to that variable executed before execution reaches that point in the program. So for example, definition *A* below reaches points *B* and *C*, but not *D*:

```
x = 3          # A
if a < 2:
    x = 2
    pass      # D
else:
    y = 5
    pass      # B
pass          # C
```

Suppose we want to compute $R(p)$, the set of all definitions that reach point p in a program. Give forward rules (in the style of the lecture) for computing the *reaching definitions*, $R_{\text{Out}}(s)$ for a statement s (the *set* of definitions that reach the point immediately after the statement) as a function of $R_{\text{In}}(s)$ (the definitions that reach the beginning) for each assignment statement s and give the rules for computing $R_{\text{In}}(s)$ as a function of the R_{Out} values of its predecessors.

2. Suppose that L is a set of basic blocks, a subset of some large control-flow graph, G . Suppose also that P is a basic block outside of L with a single successor, that this successor is in L , and that P *dominates* the blocks in L , meaning that all paths from the entrance block of G to a block in L go through P first (typically L is a loop, and we call P a *preheader*). Finally, suppose that you have computed all reaching definitions (see last exercise) at all points in the program. How do you use this information to determine whether the calculation of a certain expression in one of the blocks of L , such as the right-hand side of the assignment statement

```
x := a * b
```

may be moved out of L and to the end of P ?

3. Consider the loop

```
for i := 0 to n-1 do
  for j := 0 to n-1 do
    for k := 0 to n-1 do
      c[i,j] := c[i,j] + a[i,k] * b[k,j]
```

In this nested loop, a , b , and c are two-dimensional arrays of 4-byte integers. Here is a translation into intermediate code (assume that a , b , and c are addresses of static memory, and that all other variables are in registers):

```

Entry:
  i := 0          #1
  goto L6        #2
L1:
  j := 0          #3
  goto L5        #4
L2:
  k := 0          #5
  goto L4        #6
L3:
  t1 := 4 * n     #7
  t2 := t1 * i    #8
  t3 := 4 * j     #9
  t4 := t2 + t3   #10
  t5 := *(t4 + c) #11
  t6 := 4 * n     #12
  t7 := t6 * i    #13
  t8 := 4 * k     #14
  t9 := t7 + t8   #15
  t10 := *(t9 + a) #16
  t11 := 4 * n    #17
  t12 := t11 * k  #18
  t13 := 4 * j    #19
  t14 := t12 + t13 #20
  t15 := *(t14 + b) #21
  t16 := t10 * t15 #22
  t17 := t5 + t16 #23
  t18 := 4 * n    #24
  t19 := t18 * i  #25
  t20 := 4 * j    #26
  t21 := t19 + t20 #27
  *(t21+c) := t17 #28
  k := k + 1      #29
L4:
  if k < n: goto L3 #30
  j := j + 1      #31
L5:
  if j < n: goto L2 #32
  i := i + 1      #33
L6:
  if i < n: goto L1 #34
Exit:

```

To notate accesses to memory, we've used C-like notation:

```

r1 := *(r2+K)
*(r1+K) := r2
*K := r3
r3 := *K

```

K is an integer literal, and L is a static-storage label (a constant address in memory). Unlike C, the additions here are just straight addition: no automatic scaling by word size.

- According to this code, how are the elements of the three two-dimensional arrays laid out in memory (in what order do the elements of the arrays appear)?
- Divide the instructions into basic blocks (feel free to refer to them by number) and show the flow graph.
- The program is almost in SSA form, except for variables i , j , and k . Introduce new variables and ϕ functions as needed to put the program into SSA form (try to minimize ϕ functions).
- Now optimize this code as best you can, moving assignments of invariant expressions out of loops, eliminating common subexpressions, removing dead statements, performing copy propagation, etc.