Lecture 36: IL for Arrays

One-dimensional Arrays

- How do we process retrieval from and assignment to x[i], for an array x?
- We assume that all items of the array have fixed size—5 bytes— and are arranged sequentially in memory (the usual representation).
- Easy to see that the address of x[i] must be

```
\&x + S \cdot i,
```

where &x is intended to denote the address of the beginning of x.

- Generically, we call such formulae for getting an element of a data structure access algorithms.
- The IL might look like this:

```
cgen(&A[E], t_0):

cgen(&A, t_1)

cgen(E, t_2)

\Rightarrow t_3 := t_2 * S

\Rightarrow t_0 := t_1 + t_3
```

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Multi-dimensional Arrays

- A 2D array is a 1D array of 1D arrays.
- Java uses arrays of pointers to arrays for >1D arrays.
- But if row size constant, for faster access and compactness, may prefer to represent an MxN array as a 1D array of 1D rows (not pointers to rows): row-major order...
- Or, as in FORTRAN, a 1D array of 1D columns: column-major order.
- So apply the formula for 1D arrays repeatedly—first to compute the beginning of a row and then to compute the column within that row:

$$\&A[i][j] = \&A + i \cdot S \cdot N + j \cdot S$$

for an M-row by N-column array, where ${\tt S}$, again, is the size of an individual element.

IL for $M \times N$ 2D array

```
cgen(&e1[e2,e3], t):
    cgen(e1, t1); cgen(e2,t2); cgen(e3,t3)
    cgen(N, t4) # (N need not be constant)
    ⇒ t5 := t4 * t2
    ⇒ t6 := t5 + t3
    ⇒ t7 := t6 * S
    ⇒ t := t7 + t1
```

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Array Descriptors

• Calculation of element address &e1[e2,e3] has the form

$$VO + S1 \times e2 + S2 \times e3$$

, where

- VO (&e1[0,0]) is the virtual origin.
- S1 and S2 are *strides*.
- All three of these are constant throughout the lifetime of the array (assuming arrays of constant size).
- Therefore, we can package these up into an array descriptor, which can be passed in lieu of the array itself, as a kind of "fat pointer" to the array:

&e1[0][0]	$S \times N$	S
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Array Descriptors (III)

- By judicious choice of descriptor values, can make the same formula work for different kinds of array.
- For example, if lower bounds of indices are 1 rather than 0, must compute address

$$\&e[1,1] + S1 \times (e2-1) + S2 \times (e3-1)$$

• But some algebra puts this into the form

VO' + S1
$$\times$$
 e2 + S2 \times e3

where

$$V0' = \&e[1,1] - S1 - S2 = \&e[0,0]$$
 (if it existed).

• So with the descriptor

VO'	$\mathtt{S}{ imes}\mathtt{N}$	S

we can use the same code as on the last slide.

Array Descriptors (II)

Assuming that e1 now evaluates to the address of a 2D array descriptor, the IL code becomes:

```
cgen(&e1[e2,e3], t):
    cgen(e1, t1); cgen(e2,t2); cgen(e3,t3)
    \Rightarrow t4 := *t1;  # The V0
    \Rightarrow t5 := *(t1+4)  # Stride #1
    \Rightarrow t6 := *(t1+8)  # Stride #2
    \Rightarrow t7 := t5 * t2
    \Rightarrow t8 := t6 * t3
    \Rightarrow t9 := t4 + t7
    \Rightarrow t10:= t9 + t8
```

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