Foundations of Computer Graphics (Spring 2012)

CS 184, Lecture 13: Curves 2 http://inst.eecs.berkeley.edu/~cs184

Outline of Unit

- Bezier curves (last time)
- deCasteljau algorithm, explicit, matrix (last time)
- Polar form labeling (blossoms)
- B-spline curves
- Not well covered in textbooks (especially as taught here). Main reference will be lecture notes. If you do want a printed ref, handouts from CAGD, Seidel

Idea of Blossoms/Polar Forms

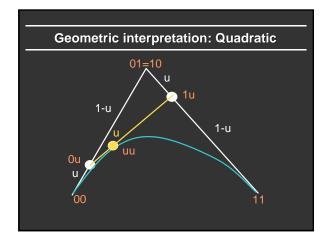
- (Optional) Labeling trick for control points and intermediate deCasteljau points that makes thing intuitive
- E.g. quadratic Bezier curve F(u)
 - Define auxiliary function $f(u_1, u_2)$ [number of args = degree]
 - Points on curve simply have u₁=u₂ so that F(u) = f(u,u)
 And we can label control points and deCasteljau points not
 - on curve with appropriate values of (u₁,u₂)

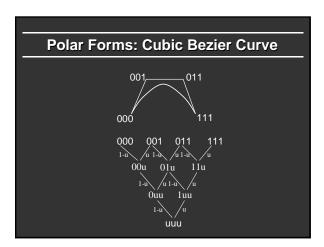


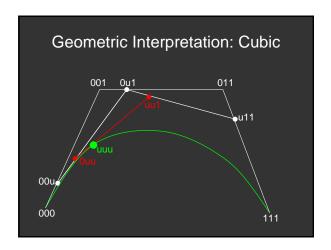
Idea of Blossoms/Polar Forms

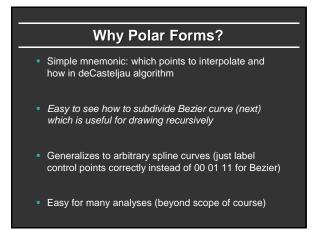
- Points on curve simply have $u_1=u_2$ so that F(u)=f(u,u)
- f is symmetric f(0,1) = f(1,0)
- Only interpolate linearly between points with one arg different
 f(0,u) = (1-u) f(0,0) + u f(0,1) Here, interpolate f(0,0) and f(0,1)=f(1,0)

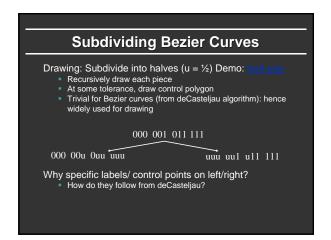


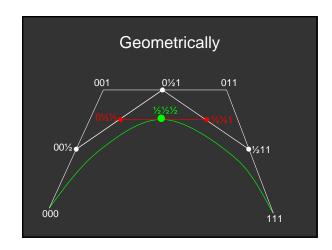


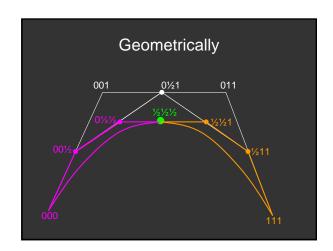


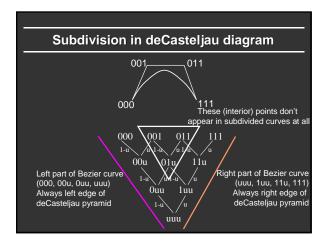












Summary for HW 2

- Bezier2 (Bezier discussed last time)
- Given arbitrary degree Bezier curve, recursively subdivide for some levels, then draw control polygon hw4.exe
- Generate deCasteljau diagram; recursively call a routine with left edge and right edge of this diagram
- You are given some code structure; you essentially just need to compute appropriate control points for left, right

DeCasteljau: Recursive Subdivision

Input: Control points C_i with $0 \le i \le n$ where n is the degree. Output: L_i . R_i for left and right control points in recursion.

```
1 for (level = n ; level \ge 0 ; level - -) {
2          if (level = n) { // Initial control points
3          \forall i : 0 \le i \le n : p_i^{level} = C_i : \text{continue} : \}
4          for (i = 0 : i \le level : i + +)
5          p_i^{level} = \frac{1}{2} * (p_i^{level+1} + p_{i+1}^{level+1}) :
6 }
7 \forall i : 0 < i < n : L_i = p_0^i : R_i = p_i^i :
```

- DeCasteljau (from last lecture) for midpoint
- Followed by recursive calls using left, right parts

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Bezier: Disadvantages

- Single piece, no local control (move a control point, whole curve changes) hw4.exe
- Complex shapes: can be very high degree, difficult
- In practice, combine many Bezier curve segments
 - But only position continuous at join since Bezier curves interpolate end-points (which match at segment boundaries)
 - Unpleasant derivative (slope) discontinuities at end-points
 - Can you see why this is an issue?

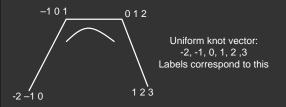
B-Splines

- Cubic B-splines have C² continuity, local control
- 4 segments / control point, 4 control points/segment
- Knots where two segments join: Knotvector
- Knotvector uniform/non-uniform (we only consider uniform cubic B-splines, not general NURBS)



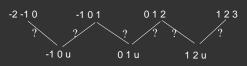
Polar Forms: Cubic Bspline Curve

- Labeling little different from in Bezier curve
- No interpolation of end-points like in Bezier
- Advantage of polar forms: easy to generalize



deCasteljau: Cubic B-Splines

- Easy to generalize using −1 0 1/2 polar-form labels
- Impossible remember without



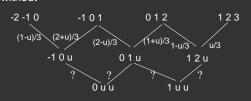
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deCasteljau: Cubic B-Splines

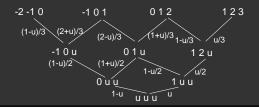
- Easy to generalize using −1 0 ½ polar-form labels
- Impossible remember without



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deCasteljau: Cubic B-Splines

- Easy to generalize using polar-form labels
- Impossible remember without



-2 -1 0

Explicit Formula (derive as exercise)

Summary of HW 2

- BSpline Demo
- Arbitrary number of control points / segments
 - Do nothing till 4 control points / Seg Number of segments = # cpts 3
- Segment A will have control pts A,A+1,A+2,A+3
- Evaluate Bspline for each segment using 4 control points (at some number of locations, connect lines)
- Use either deCasteljau algorithm (like Bezier) or explicit form [matrix formula on previous slide]
- Questions?