

Foundations of Computer Graphics (Spring 2012)

CS 184, Lecture 22: Global Illumination

<http://inst.eecs.berkeley.edu/~cs184>

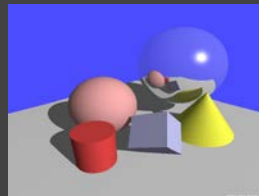
Illumination Models

So far considered mainly local illumination

- Light directly from light sources to surface

Global Illumination: multiple bounces

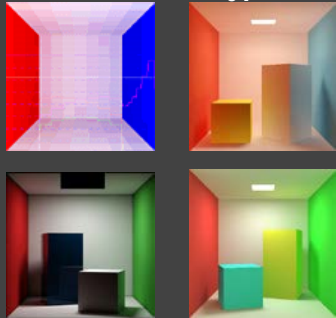
- Already ray tracing: reflections/refractions



Some images courtesy Henrik Wann Jensen

Global Illumination

Diffuse interreflection, color bleeding [Cornell Box]



Global Illumination

Caustics: Focusing through specular surface



Major research effort in 80s, 90s till today

Overview of lecture

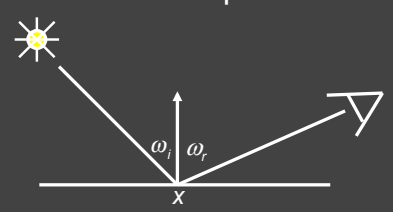
- **Theory** for all methods (ray trace, radiosity)
- We derive **Rendering Equation** [Kajiya 86]
 - Major theoretical development in field
 - Unifying framework for all global illumination
- Discuss existing approaches as special cases

Fairly theoretical lecture (but important). Not well covered in any of the textbooks. Closest are 2.6.2 in Cohen and Wallace handout (but uses slightly different notation, argument [swaps x , x' among other things])

Outline

- **Reflection Equation (review)**
- **Global Illumination**
- **Rendering Equation**
- As a general Integral Equation and Operator
- Approximations (Ray Tracing, Radiosity)
- Surface Parameterization (Standard Form)

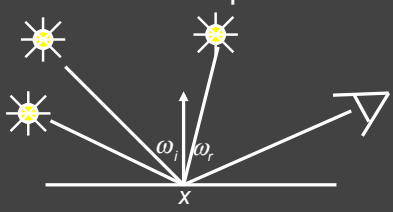
Reflection Equation



$$L_r(x, \omega_r) = L_e(x, \omega_r) + L_i(x, \omega_i) f(x, \omega_i, \omega_r) (\omega_i \cdot n)$$

Reflected Light (Output Image)	Emission	Incident Light (from light source)	BRDF	Cosine of Incident angle

Reflection Equation

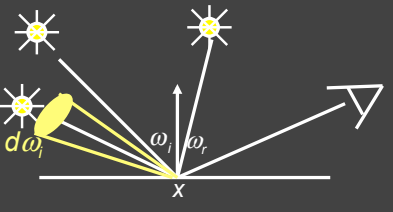


Sum over all light sources

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \sum L_i(x, \omega_i) f(x, \omega_i, \omega_r) (\omega_i \cdot n)$$

Reflected Light (Output Image)	Emission	Incident Light (from light source)	BRDF	Cosine of Incident angle

Reflection Equation



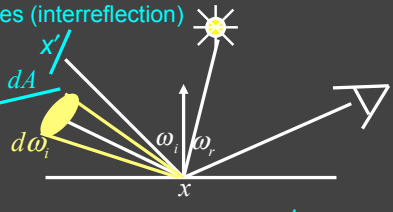
Replace sum with integral

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\Omega} L_i(x, \omega_i) f(x, \omega_i, \omega_r) \cos \theta_i d\omega_i$$

Reflected Light (Output Image)	Emission	Incident Light (from light source)	BRDF	Cosine of Incident angle

Global Illumination

Surfaces (interreflection)



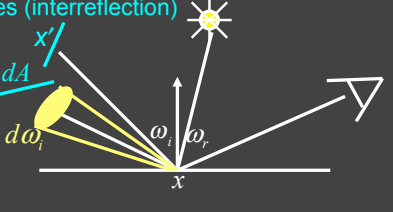
$\omega_i \sim x' - x$

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\Omega} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) \cos \theta_i d\omega_i$$

Reflected Light (Output Image)	Emission	Reflected Light (from surface)	BRDF	Cosine of Incident angle

Rendering Equation

Surfaces (interreflection)



$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\Omega} L_r(x', -\omega_i) f(x, \omega_i, \omega_r) \cos \theta_i d\omega_i$$

Reflected Light (Output Image)	Emission	Reflected Light	BRDF	Cosine of Incident angle
UNKNOWN	KNOWN	UNKNOWN	KNOWN	KNOWN

Rendering Equation (Kajiya 86)




Figure 6. A sample image. All objects are neutral grey. Color on the objects is due to caustics from the green glass balls and color bleeding from the base polygon.

Outline

- Reflectance Equation (review)
- Global Illumination
- Rendering Equation
- *As a general Integral Equation and Operator*
- *Approximations (Ray Tracing, Radiosity)*
- Surface Parameterization (Standard Form)

The material in this part of the lecture is fairly advanced and not covered in any of the texts. The slides should be fairly complete. This section is fairly short, and I hope some of you will get some insight into solutions for general global illumination

Rendering Equation as Integral Equation

$$L_r(x, \omega_r) = L_e(x, \omega_r) + \int_{\Omega} L_r(x', -\omega_r) f(x, \omega_i, \omega_r) \cos \theta_i d\omega_i$$

Reflected Light (Output Image)	Emission	Reflected Light	BRDF	Cosine of Incident angle
UNKNOWN	KNOWN	UNKNOWN	KNOWN	KNOWN

Is a Fredholm Integral Equation of second kind
[extensively studied numerically] with canonical form

$$l(u) = e(u) + \int l(v) K(u, v) dv$$

Kernel of equation

Linear Operator Equation

$$l(u) = e(u) + \int l(v) K(u, v) dv$$

Kernel of equation
Light Transport Operator

$$L = E + KL$$

Can be discretized to a simple matrix equation
[or system of simultaneous linear equations]
(L, E are vectors, K is the light transport matrix)

Solution Techniques

All global illumination methods try to solve
(approximations of) the rendering equation

- Too hard for analytic solution: numerical methods
- General theory of solving integral equations

Radiosity (next lecture; usually diffuse surfaces)

- General class numerical *finite element* methods (divide surfaces in scene into a finite set elements or patches)
- Set up linear system (matrix) of simultaneous equations
- Solve iteratively

Ray Tracing and extensions

- General class numerical **Monte Carlo** methods
- Approximate set of all paths of light in scene

$$L = E + KL$$

$$L - KL = E$$

$$(I - K)L = E$$

$$L = (I - K)^{-1}E$$

Binomial Theorem

$$L = (I + K + K^2 + K^3 + \dots)E$$

$$L = E + KE + K^2E + K^3E + \dots$$

Ray Tracing

$$L = E + KE + K^2E + K^3E + \dots$$

↓

Emission directly
From light sources

↓

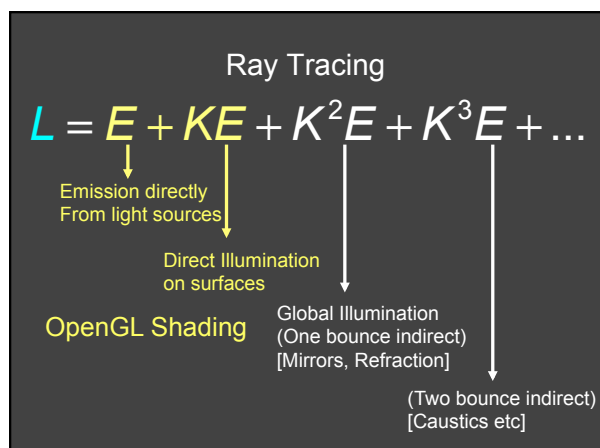
Direct Illumination
on surfaces

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Global Illumination
(One bounce indirect)
[Mirrors, Refraction]

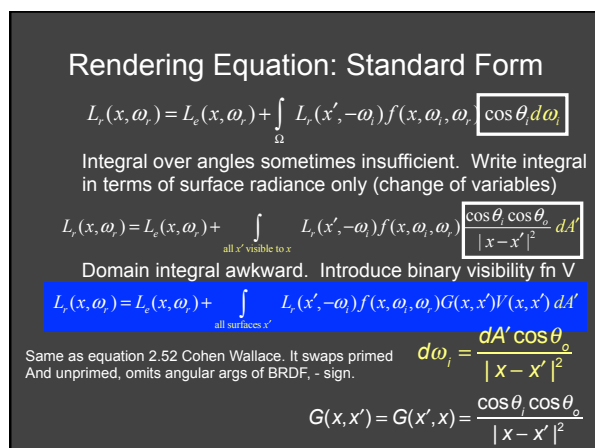
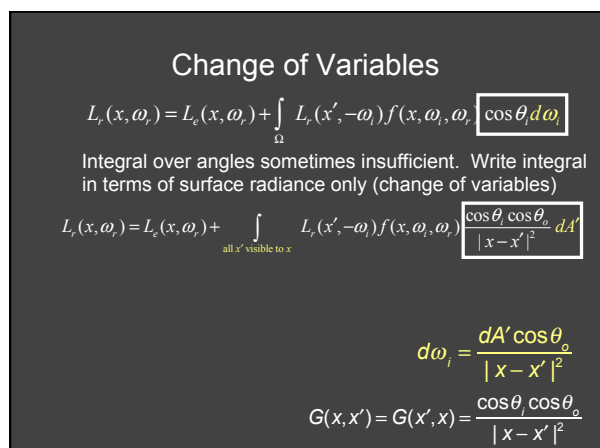
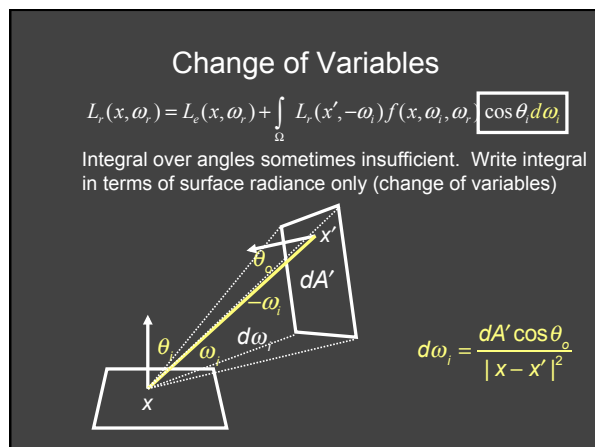
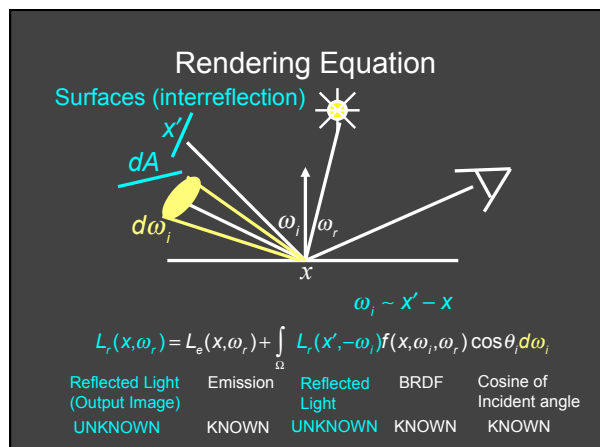
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(Two bounce indirect)
[Caustics etc]



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Overview

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