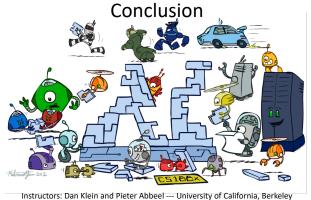
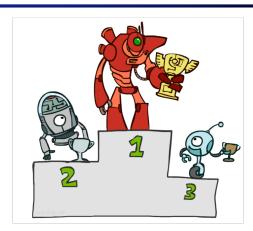
# CS 188: Artificial Intelligence



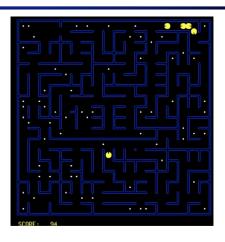
These slides were created by Dan Klein and Pieter Abbeel for CS188 Intro to AI at UC Berkeley.

All CS188 materials are available at http://ai.berkeley.edu.

# **Contest Results**



## P1 Mini-Contest Results!



# P1 Mini-Contest Results

■ 1<sup>st</sup> place:

■ Yunsheng Ma, Ryan Xie

2<sup>nd</sup> place

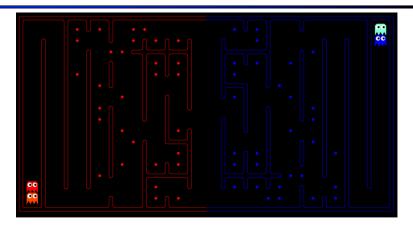
■ JasonL Jingyuan Li

■ 3<sup>rd</sup> place

■ Winnie-the-Pooh Philip Zhao, Winnie Gao

#### P2 Mini-Contest Results!

#### P2 Mini-Contest Results



■ 1<sup>st</sup> place:

■ @\_@ Philip Zhao, Winnie Gao

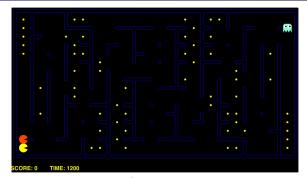
■ 2<sup>nd</sup> place

■ YZWY Yuechen Wu, Yuzishu

■ 3<sup>rd</sup> place

■ DON'T FORGET: REGISTER TO VOTE! Sean Liu, Ham Huang

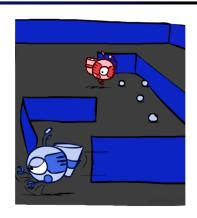
## Final Contest!



A cooperative version of PacMan where you write a bot to coordinate with another bot to gather food and defeat ghosts.

#### **Final Contest Statistics**

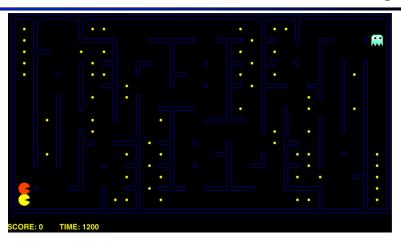
- 32 teams, thousands of matches!
- Great work by everyone!
- Creative Names:
  - pacmantaughtmelife
  - Stupid Pacman is not Ready
  - broken bot
  - Basic bot
  - OôQOô¢Oô>Oô<Oô</li>
  - He never listens
  - SPAM
  - Pacman is READY!!
  - debug\_fixed?
- Final results: now



## Top-10

4 [757]	Watney The Fearful	Alexander Khazatsky
5 [761]	debug_fixed?	mssheldonmao
6 [802]	nine (9) v3	Wilson Wu
7 [812]	DieGhostDie	Shi Mao, Zhibo Fan
8 [813]	openai five candidate	Martin Li
9 [817]	First attempt v4.6	Fredrik Roemming
10 [848]	Mark-??	Winnie Gao, Philip Zha

# 3rd Place – WhenMonaSmiles – Victor Cheng



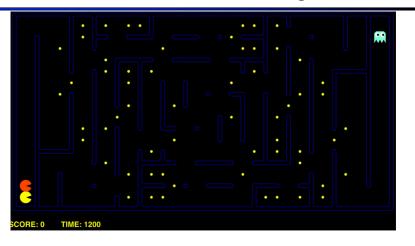
# 3rd Place – WhenMonaSmiles – Victor Cheng

- The bot is based on ReflexCaptureAgent using an using an feature based evaluation function. The features are teammateDistance, distanceToFood, and ghostDistance.
- Basically, the agent aims for the furthest food when it is a certain distance close to the teammate, otherwise it aims for the closest food.
- The agent tries to get away from the ghost when it is close to the ghost.
- The agent values food more than the danger of ghost, as getting the attention of the ghost would potentially help the teammate.
- The thresholds of distances to the teammate and ghost, need to be tuned, like the weights of the feature. Optimally they would be tuned by RL or other learning methods, but they are tuned manually this time.

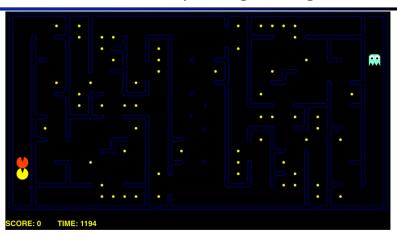
## 2nd Place - Yihe Huang

- Strategy is based on Approximate Q-Learning.
- Features include 3 distances and 2 scores.
- Distances include the maze distance between ghost, teammate, nearest food and my bot.
- Scores include the successor score and a score for exploring and exploiting (to avoid deadlock).

# 2nd Place – Yihe Huang



# 1st Place – Rudy Zhang & Feng Xu

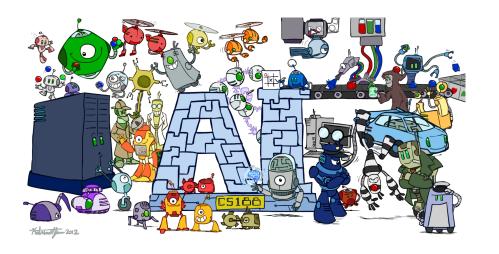


# 1st Place – Rudy Zhang & Feng Xu

- Strategy is based on a map named reward density. It is calculated in the following steps:
  - 1. calculate food density like minesweepers
  - 2. lower the reward of the area if the teammate might approach the area using particle filtering to update teammate position beliefs
  - 3. adjust the reward of a position according to the Pacman's distance to it
  - 4. lower the reward of a position if a ghost is near it
- Using the computed reward density map, we have the following strategy
  - If the ghost is not nearby:
    - go to the position with maximum reward density then collect the food local optimally (both using star search)
  - else if the ghost is close:
    - use minimax strategy to avoid the ghost, award the Pacman for approaching the max reward density position
- Some special calculation:
  - cached actions from the start position to the first position with len(legal actions)>1

## Top-10

1 [711]	Pacman No.70 is READY	Rudy Zhang, Feng Xu
2 [720]	MasterYi	Yihe Huang
3 [748]	WhenMonaSmiles	Victor Cheng
4 [757]	Watney The Fearful	Alexander Khazatsky
5 [761]	debug_fixed?	mssheldonmao
6 [802]	nine (9) v3	Wilson Wu
7 [812]	DieGhostDie	Shi Mao, Zhibo Fan
8 [813]	openai five candidate	Martin Li
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10 [848]	Mark-??	Winnie Gao, Philip Zhao







Ketrina Yim CS188 Artist



# Language Technologies



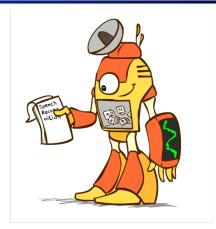


 Requires context, linguistic structure, meanings...



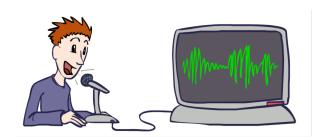
#### **Reality: Shallow Matching**

- Requires robustness and scale
- Amazing successes, but fundamental limitations



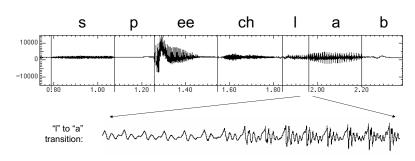


Digitizing Speech



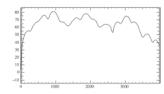
# Speech Input

## Speech input is an acoustic waveform



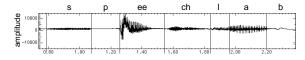
# Part of [ae] from "lab"

- Complex wave repeating nine times
  - Plus smaller wave that repeats 4x for every large cycle
  - Large wave: freq of 250 Hz (9 times in .036 seconds)
  - Small wave roughly 4 times this, or roughly 1000 Hz

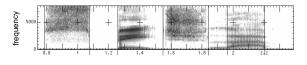


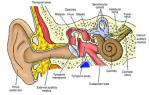
## **Spectral Analysis**

- Frequency gives pitch; amplitude gives volume
  - Sampling at ~8 kHz (phone), ~16 kHz (mic) (kHz=1000 cycles/sec)



- Fourier transform of wave displayed as a spectrogram
  - Darkness indicates energy at each frequency





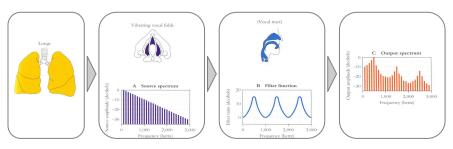


Human ear figure: depion.blogspot.com

# Why These Spectral Peaks?

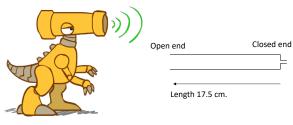
#### Articulator process:

- Vocal cord vibrations create harmonics
- The mouth is an amplifier
- Depending on shape of mouth, some harmonics are amplified more than others



#### Resonances of the Vocal Tract

The human vocal tract as an open tube



- Air in a tube of a given length will tend to vibrate at resonance frequency of tube
- Constraint: Pressure differential should be maximal at (closed) glottal end and minimal at (open) lip end

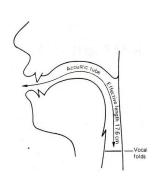
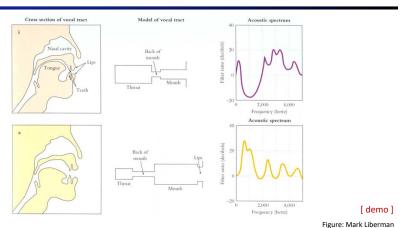
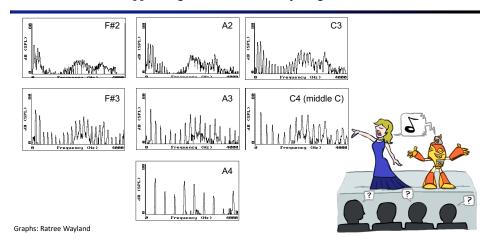


Figure: W. Barry Speech Science slides

# **Spectrum Shapes**

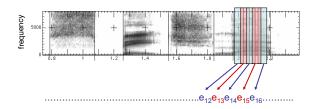


#### Vowel [i] Sung at Successively Higher Pitches



# Speech Recognition as an HMM

■ Evidence: Sequences of acoustic vectors (~39 real numbers per slice)



■ Hidden states: Which words were spoken? Almost!

# Speech Recognition State Space

#### HMM Specification

- P(E|X) models which acoustic vectors match each phoneme (each kind of sound)
- P(X|X') encodes how sounds can be strung together

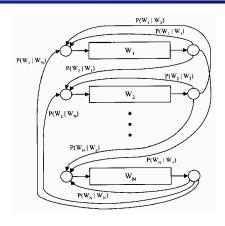
#### State Space

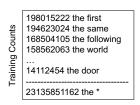
- We will have one state for each sound in each word ("pronunciation cursor")
- Mostly, states advance sound by sound along a word
- We build a little state graph for each word and chain them together to form the state space X

#### States in a Word

#### 

# Transitions with a Bigram Language Model





$$\hat{P}(\text{door}|\text{the}) = \frac{14112454}{23135851162}$$
$$= 0.0006$$

Figure: Huang et al, p. 618

# Increasing N-Gram Order

#### More history captures more correlations

#### Bigram Model

198015222 194623024 168504105 158562063	the same the following
 14112454	the door

23135851162 the \*

P(door | the) = 0.0006

Trigram Model

rrigram wodei			
197302	close the window		
191125	close the door		
152500	close the gap		
116451	close the thread		
87298	close the deal		
3785230	close the *		

P(door | close the) = 0.05

# Decoding

- Finding the words given the acoustics is an HMM inference problem
- Which state sequence  $x_{1:T}$  is most likely given the evidence  $e_{1:T}$ ?

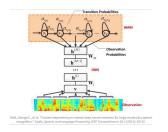
$$x_{1:T}^* = \argmax_{x_{1:T}} P(x_{1:T} | e_{1:T}) \ = \argmax_{x_{1:T}} P(x_{1:T}, e_{1:T})$$

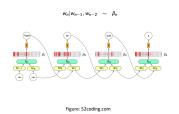
• From the sequence x, we can simply read off the words



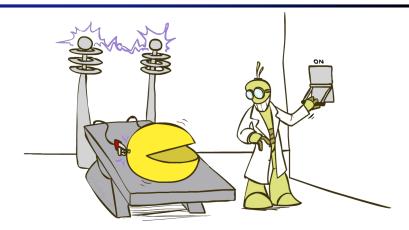
# Neural Nets for Speech

- Major advances in ASR over the last ~5 years due to neural nets
  - Acoustic models P(frequencies | phones) now parameterized with NNs
  - Language models P(word | word history) now parameterized with NNs





# Pac-Man Beyond the Game!



# Pacman: Beyond Simulation?





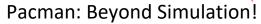






Students at Colorado University: http://pacman.elstonj.com

[VIDEO: Roomba Pacman.mp4]





# Bugman?

#### ■ AI = Animal Intelligence?

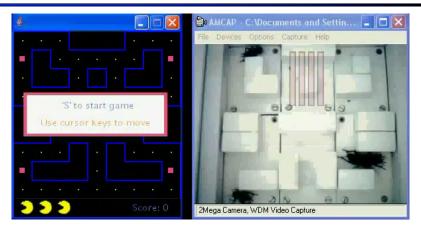
- Wim van Eck at Leiden University
- Pacman controlled by a human
- Ghosts controlled by crickets
- Vibrations drive crickets toward or away from Pacman's location





http://pong.hku.nl/~wim/bugman.htm

## Bugman



# Crawler



# Q-learning with Robot Crawler



#### Where to Go Next?



# Where to go next?

- Congratulations, you've seen the basics of modern AI
  - ... and done some amazing work putting it to use!
- How to continue:
  - Machine learning: cs189, cs182, stat154
  - Intro to Data Science: Data 100
  - Probability: ee126, stat134
  - Optimization: ee127
  - Cognitive modeling: cog sci 131
  - Machine learning theory: cs281a/b
  - Vision: cs280
  - Robotics: cs287
  - Algorithmic Human Robot Interaction: cs294-115
  - Reinforcement Learning: cs285
  - NLP: cs288
  - ... and more; ask if you're interested

#### How about AI Research?



#### That's It!

- Help us out with some course evaluations
- Have a great summer, and always maximize your expected utilities!

