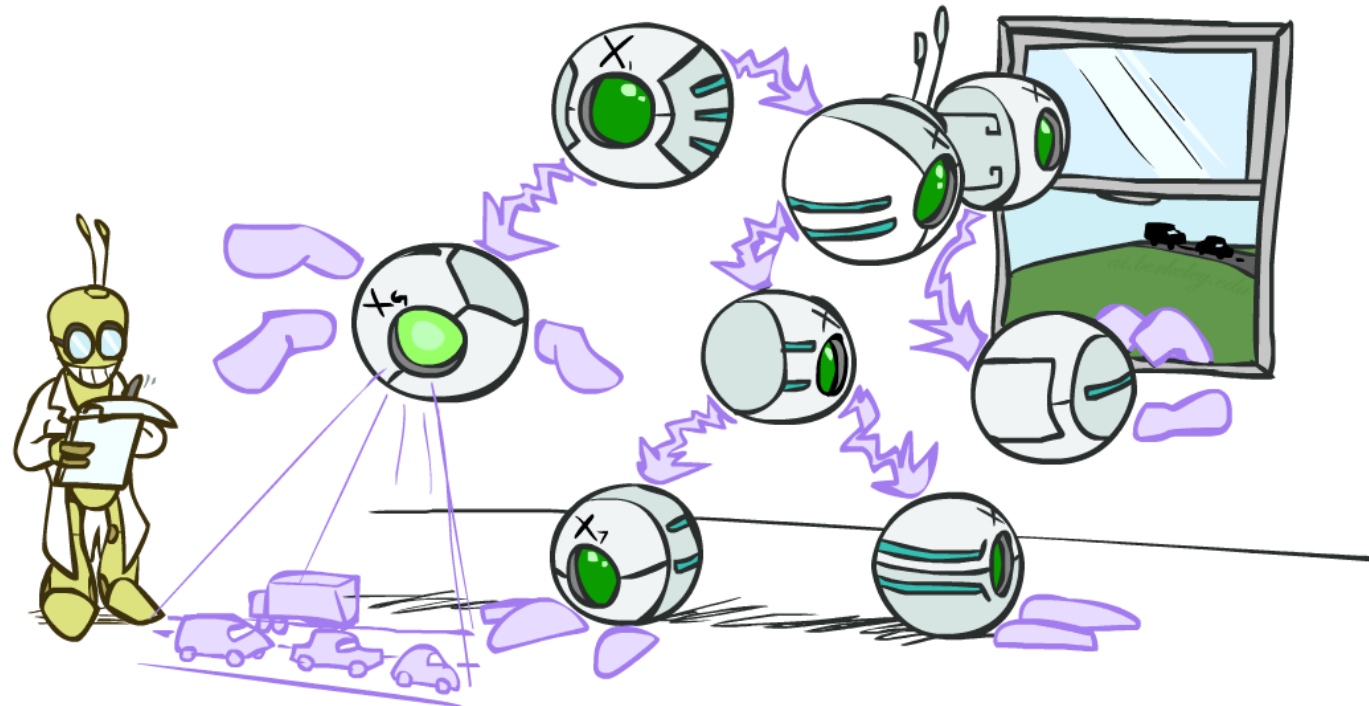


CS 188: Artificial Intelligence

Bayes' Nets: Inference



Instructors: Dan Klein and Pieter Abbeel --- University of California, Berkeley

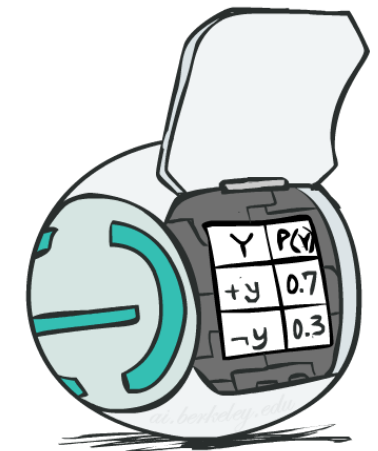
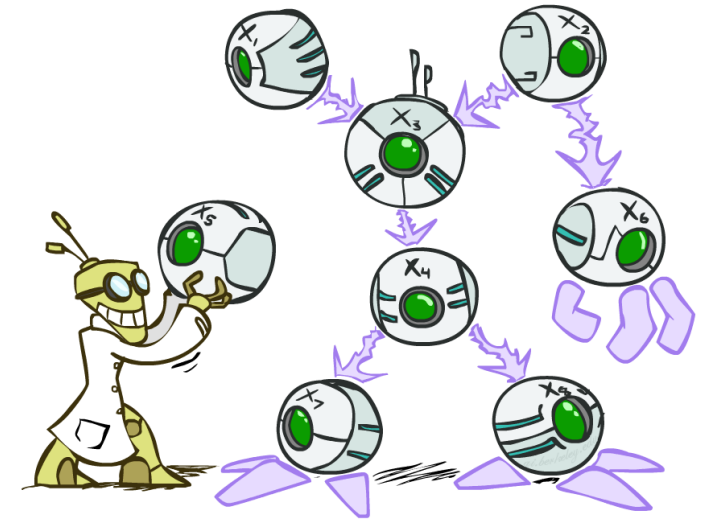
Bayes' Net Representation

- A directed, acyclic graph, one node per random variable
- A conditional probability table (CPT) for each node
 - A collection of distributions over X , one for each combination of parents' values

$$P(X|a_1 \dots a_n)$$

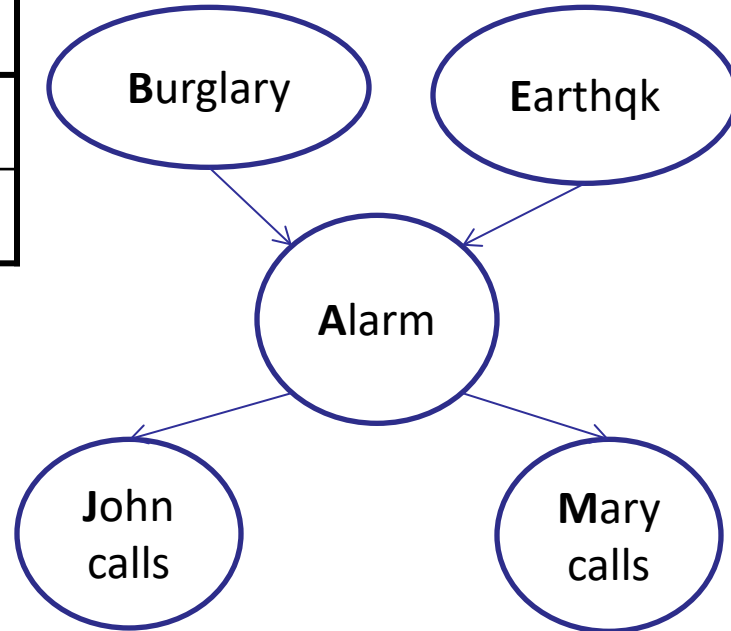
- Bayes' nets implicitly encode joint distributions
 - As a product of local conditional distributions
 - To see what probability a BN gives to a full assignment, multiply all the relevant conditionals together:

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | \text{parents}(X_i))$$

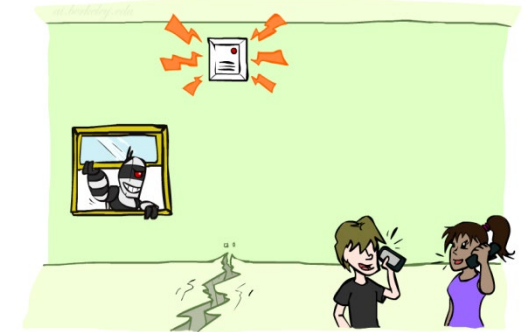


Example: Alarm Network

| B | P(B) |
|----|-------|
| +b | 0.001 |
| -b | 0.999 |



| E | P(E) |
|----|-------|
| +e | 0.002 |
| -e | 0.998 |



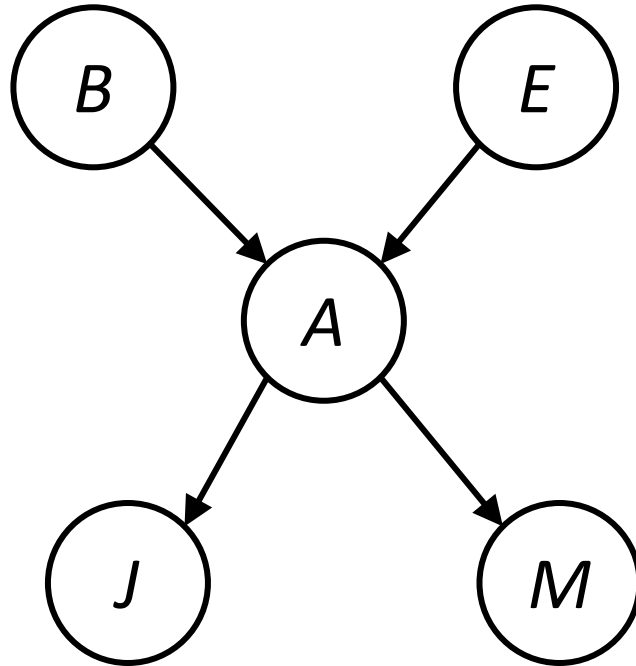
| A | J | P(J A) |
|----|----|--------|
| +a | +j | 0.9 |
| +a | -j | 0.1 |
| -a | +j | 0.05 |
| -a | -j | 0.95 |

| A | M | P(M A) |
|----|----|--------|
| +a | +m | 0.7 |
| +a | -m | 0.3 |
| -a | +m | 0.01 |
| -a | -m | 0.99 |

| B | E | A | P(A B,E) |
|----|----|----|----------|
| +b | +e | +a | 0.95 |
| +b | +e | -a | 0.05 |
| +b | -e | +a | 0.94 |
| +b | -e | -a | 0.06 |
| -b | +e | +a | 0.29 |
| -b | +e | -a | 0.71 |
| -b | -e | +a | 0.001 |
| -b | -e | -a | 0.999 |

Example: Alarm Network

| B | P(B) |
|----|-------|
| +b | 0.001 |
| -b | 0.999 |



| E | P(E) |
|----|-------|
| +e | 0.002 |
| -e | 0.998 |



| A | J | P(J A) |
|----|----|--------|
| +a | +j | 0.9 |
| +a | -j | 0.1 |
| -a | +j | 0.05 |
| -a | -j | 0.95 |

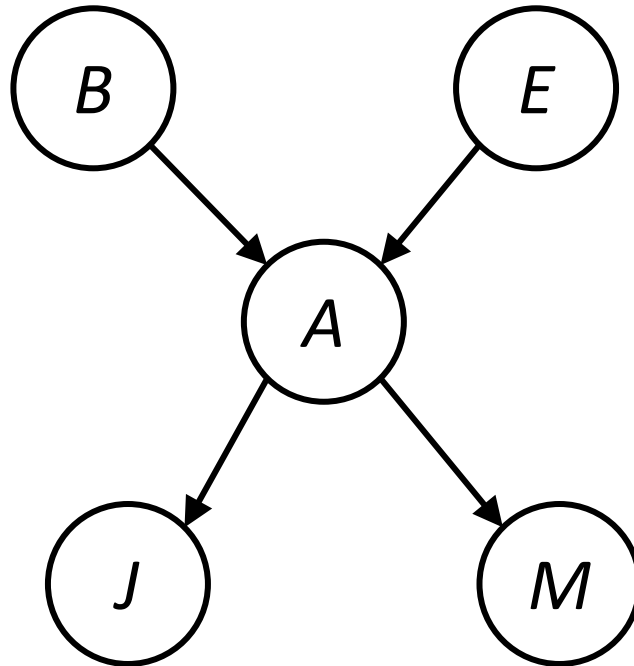
| A | M | P(M A) |
|----|----|--------|
| +a | +m | 0.7 |
| +a | -m | 0.3 |
| -a | +m | 0.01 |
| -a | -m | 0.99 |

| B | E | A | P(A B,E) |
|----|----|----|----------|
| +b | +e | +a | 0.95 |
| +b | +e | -a | 0.05 |
| +b | -e | +a | 0.94 |
| +b | -e | -a | 0.06 |
| -b | +e | +a | 0.29 |
| -b | +e | -a | 0.71 |
| -b | -e | +a | 0.001 |
| -b | -e | -a | 0.999 |

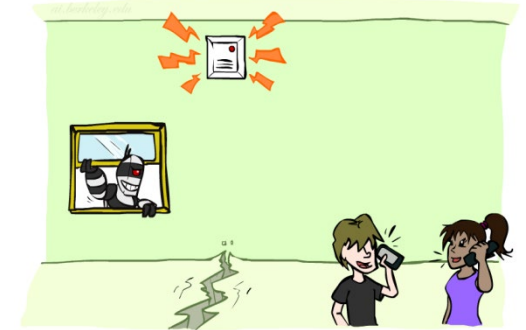
$$P(+b, -e, +a, -j, +m) = P(+b)P(-e)P(+a|+b, -e)P(-j|+a)P(+m|+a) =$$

Example: Alarm Network

| B | P(B) |
|----|-------|
| +b | 0.001 |
| -b | 0.999 |



| E | P(E) |
|----|-------|
| +e | 0.002 |
| -e | 0.998 |



| A | J | P(J A) |
|----|----|--------|
| +a | +j | 0.9 |
| +a | -j | 0.1 |
| -a | +j | 0.05 |
| -a | -j | 0.95 |

| A | M | P(M A) |
|----|----|--------|
| +a | +m | 0.7 |
| +a | -m | 0.3 |
| -a | +m | 0.01 |
| -a | -m | 0.99 |

| B | E | A | P(A B,E) |
|----|----|----|----------|
| +b | +e | +a | 0.95 |
| +b | +e | -a | 0.05 |
| +b | -e | +a | 0.94 |
| +b | -e | -a | 0.06 |
| -b | +e | +a | 0.29 |
| -b | +e | -a | 0.71 |
| -b | -e | +a | 0.001 |
| -b | -e | -a | 0.999 |

$$\begin{aligned}
 P(+b, -e, +a, -j, +m) &= \\
 P(+b)P(-e)P(+a|+b, -e)P(-j|+a)P(+m|+a) &= \\
 0.001 \times 0.998 \times 0.94 \times 0.1 \times 0.7 &
 \end{aligned}$$

Bayes' Nets

- ✓ Representation
- ✓ Conditional Independences
- Probabilistic Inference
 - Enumeration (exact, exponential complexity)
 - Variable elimination (exact, worst-case exponential complexity, often better)
 - Inference is NP-complete
 - Sampling (approximate)
- Learning Bayes' Nets from Data

Inference

- Inference: calculating some useful quantity from a joint probability distribution

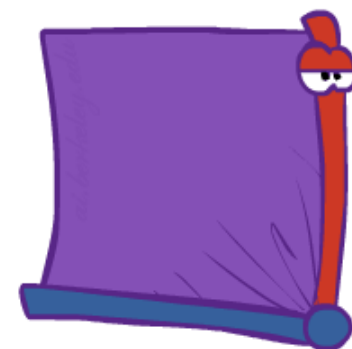
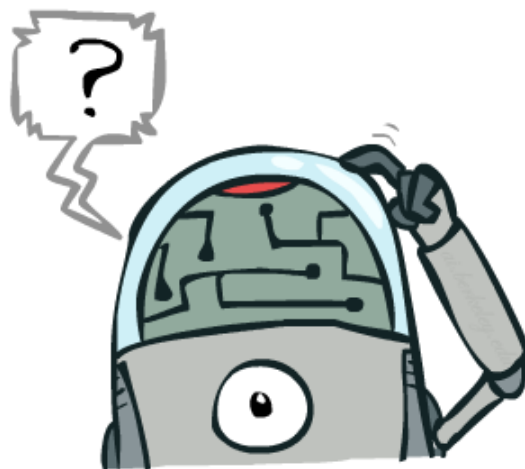
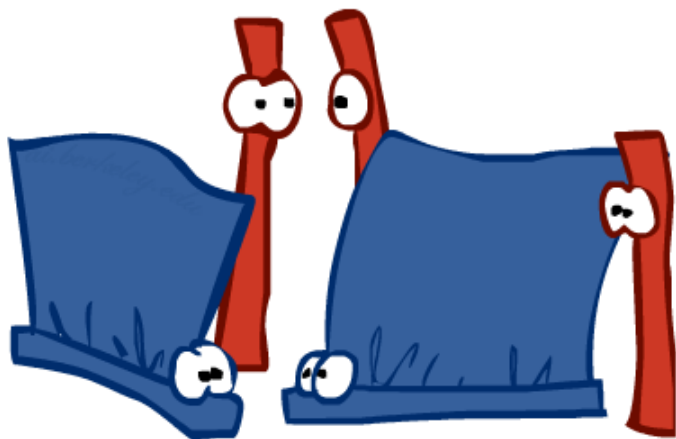
- Examples:

- Posterior probability

$$P(Q|E_1 = e_1, \dots, E_k = e_k)$$

- Most likely explanation:

$$\operatorname{argmax}_q P(Q = q|E_1 = e_1 \dots)$$



Inference by Enumeration

- General case:

- Evidence variables: $E_1 \dots E_k = e_1 \dots e_k$
 - Query* variable: Q
 - Hidden variables: $H_1 \dots H_r$
- } X_1, X_2, \dots, X_n
All variables

- We want:

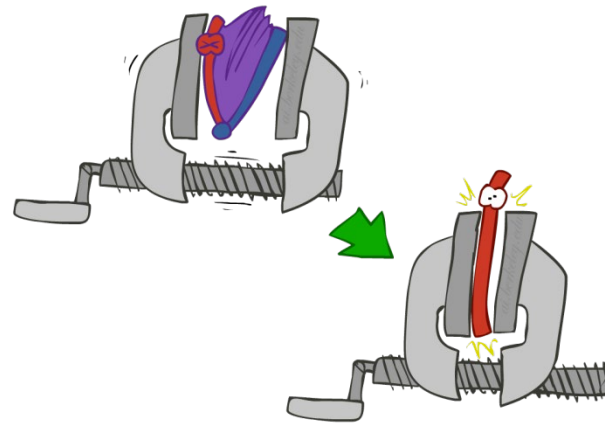
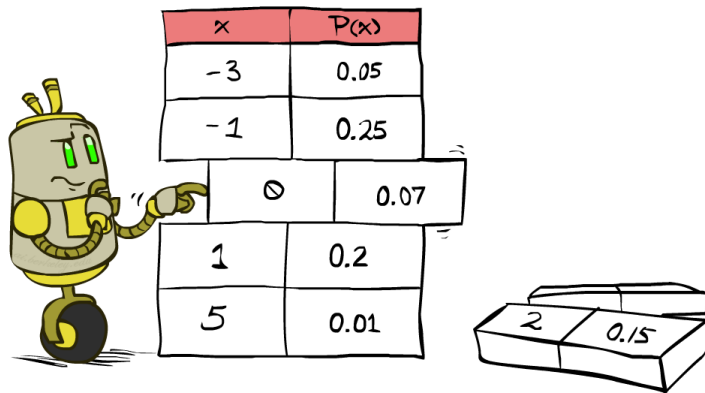
$$P(Q|e_1 \dots e_k)$$

** Works fine with multiple query variables, too*

- Step 1: Select the entries consistent with the evidence

- Step 2: Sum out H to get joint of Query and evidence

- Step 3: Normalize



$$\times \frac{1}{Z}$$

$$P(Q, e_1 \dots e_k) = \sum_{h_1 \dots h_r} \underbrace{P(Q, h_1 \dots h_r, e_1 \dots e_k)}_{X_1, X_2, \dots, X_n}$$

$$Z = \sum_q P(Q, e_1 \dots e_k)$$

$$P(Q|e_1 \dots e_k) = \frac{1}{Z} P(Q, e_1 \dots e_k)$$

Inference by Enumeration in Bayes' Net

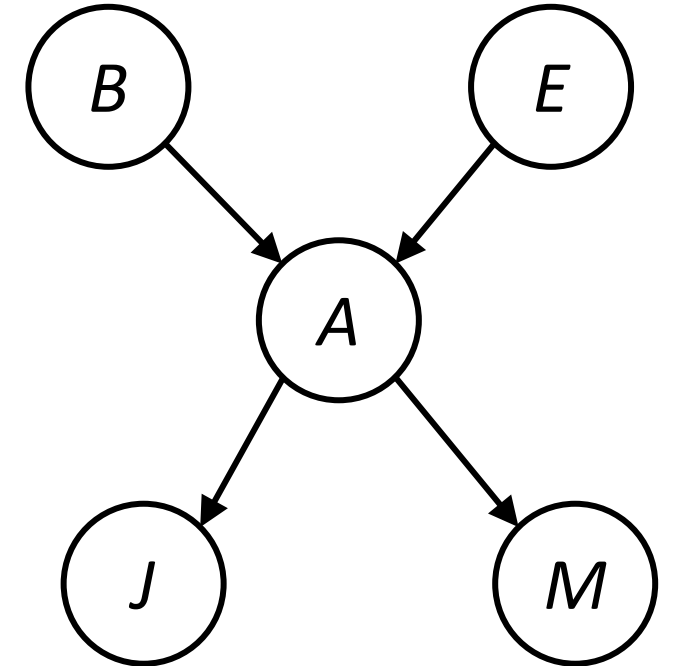
- Given unlimited time, inference in BNs is easy
- Reminder of inference by enumeration by example:

$$P(B \mid +j, +m) \propto_B P(B, +j, +m)$$

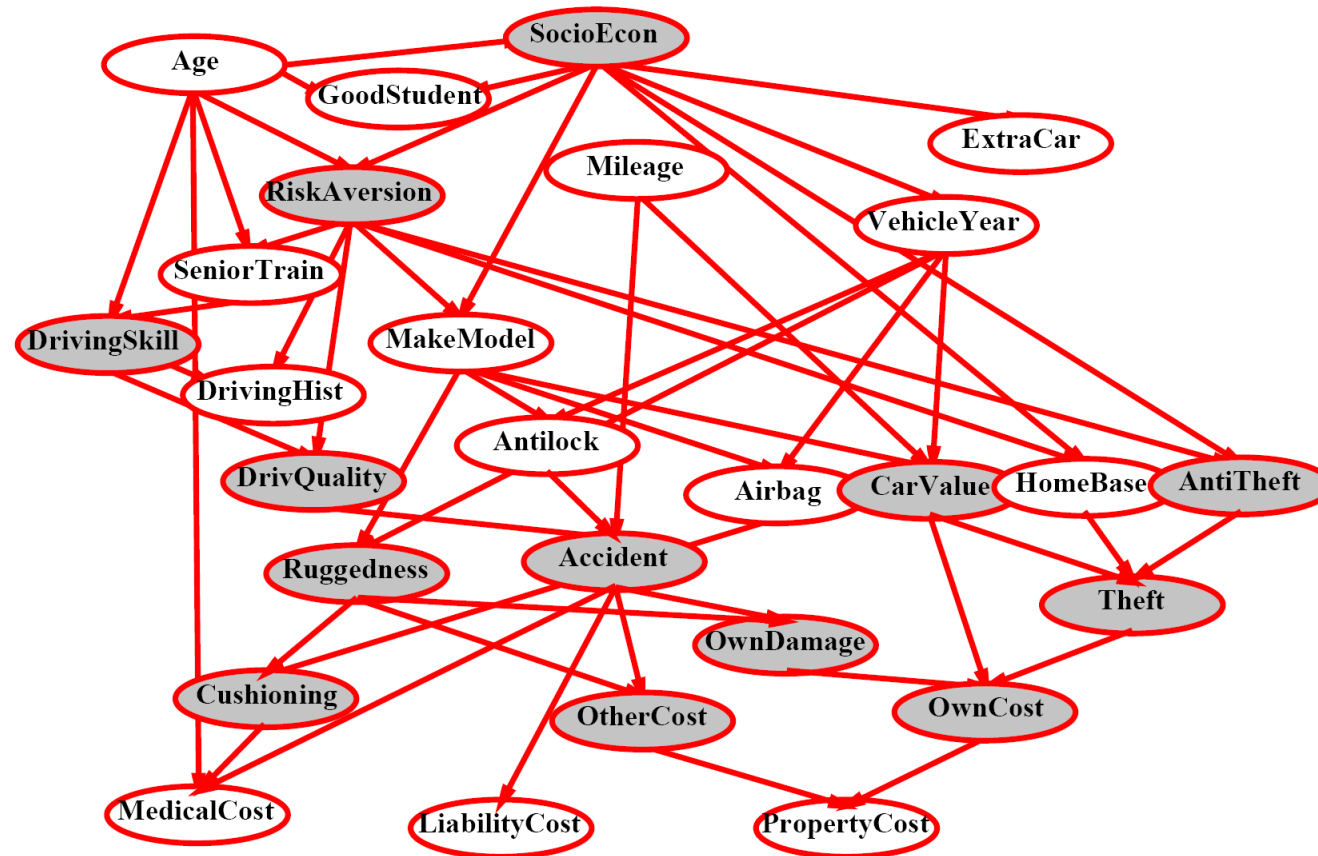
$$= \sum_{e,a} P(B, e, a, +j, +m)$$

$$= \sum_{e,a} P(B)P(e)P(a|B, e)P(+j|a)P(+m|a)$$

$$= P(B)P(+e)P(+a|B, +e)P(+j|+a)P(+m|+a) + P(B)P(+e)P(-a|B, +e)P(+j|-a)P(+m|-a) \\ + P(B)P(-e)P(+a|B, -e)P(+j|+a)P(+m|+a) + P(B)P(-e)P(-a|B, -e)P(+j|-a)P(+m|-a)$$

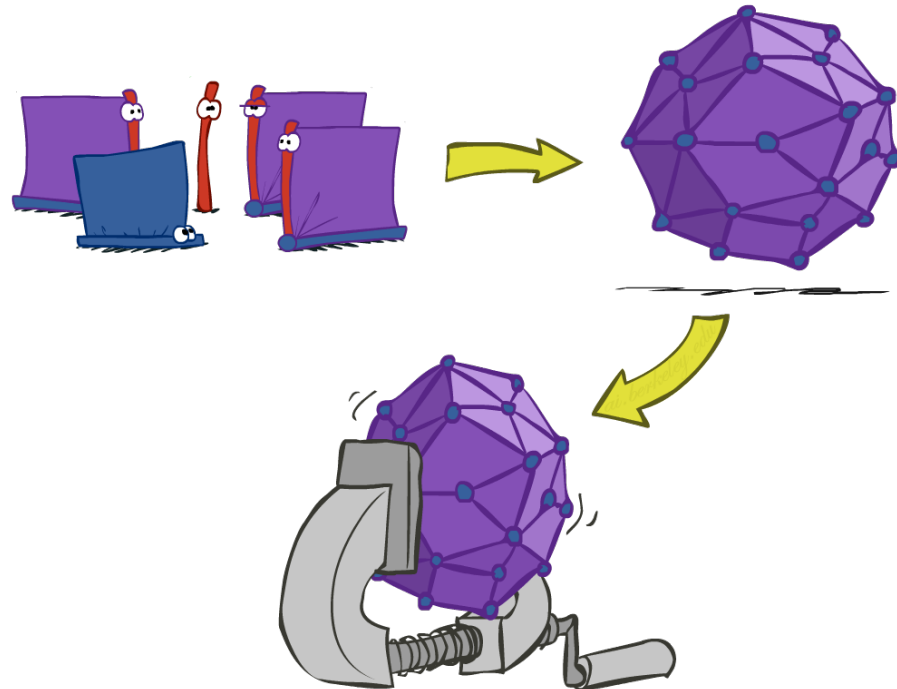


Inference by Enumeration?

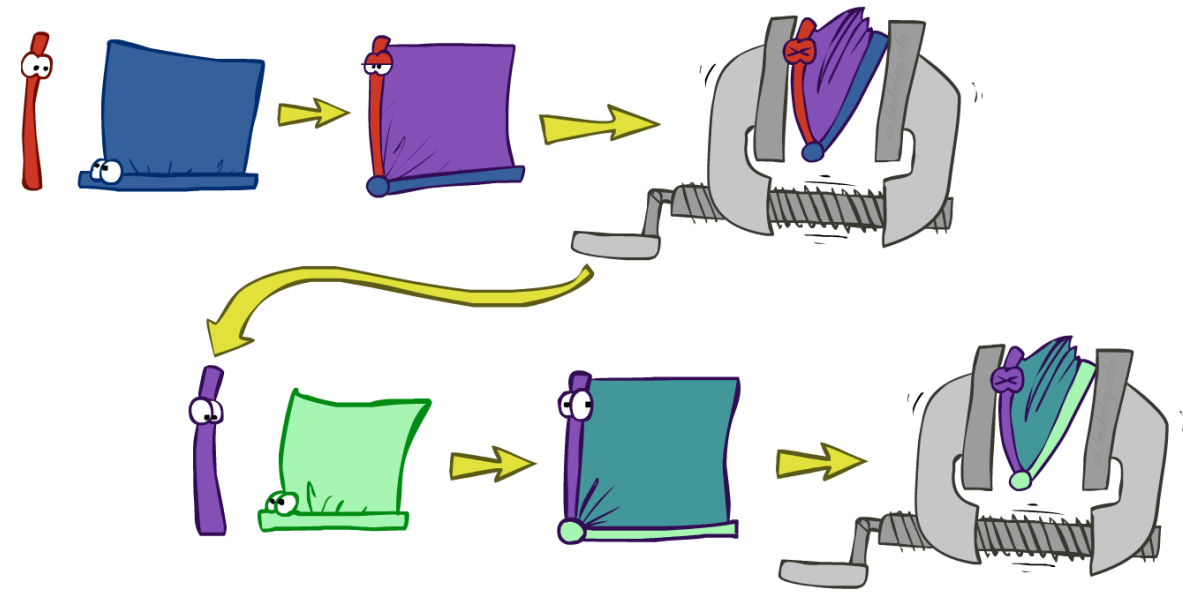


Inference by Enumeration vs. Variable Elimination

- Why is inference by enumeration so slow?
 - You join up the whole joint distribution before you sum out the hidden variables

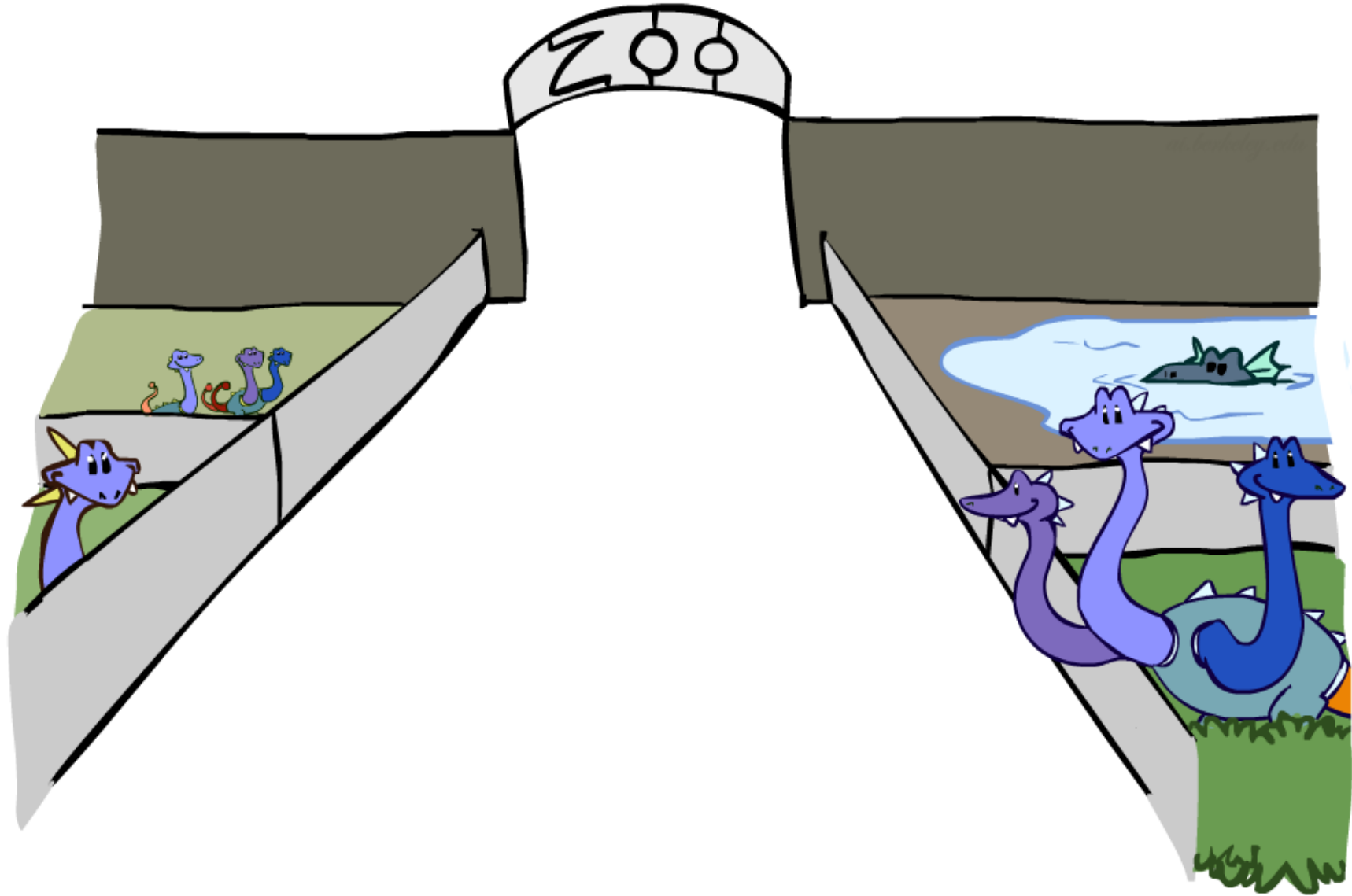


- Idea: interleave joining and marginalizing!
 - Called “Variable Elimination”
 - Still NP-hard, but usually much faster than inference by enumeration



- First we'll need some new notation: factors

Factor Zoo



Factor Zoo I

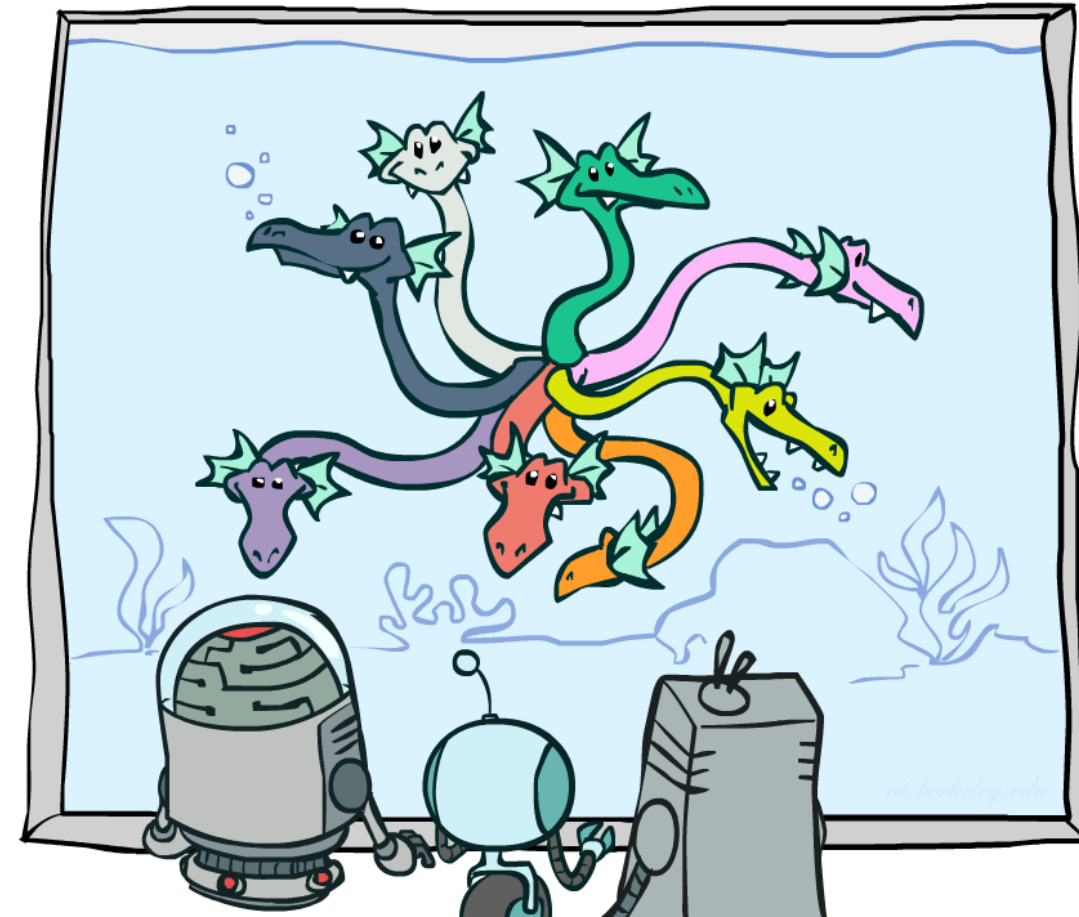
- Joint distribution: $P(X,Y)$
 - Entries $P(x,y)$ for all x, y
 - Sums to 1
- Selected joint: $P(x,Y)$
 - A slice of the joint distribution
 - Entries $P(x,y)$ for fixed x , all y
 - Sums to $P(x)$
- Number of capitals = dimensionality of the table

$$P(T, W)$$

| T | W | P |
|------|------|-----|
| hot | sun | 0.4 |
| hot | rain | 0.1 |
| cold | sun | 0.2 |
| cold | rain | 0.3 |

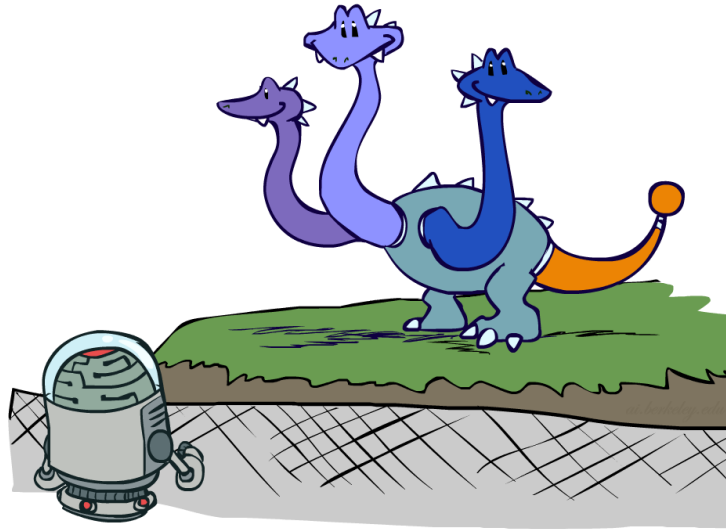
$$P(\text{cold}, W)$$

| T | W | P |
|------|------|-----|
| cold | sun | 0.2 |
| cold | rain | 0.3 |



Factor Zoo II

- Single conditional: $P(Y | x)$
 - Entries $P(y | x)$ for fixed x , all
 - Sums to 1

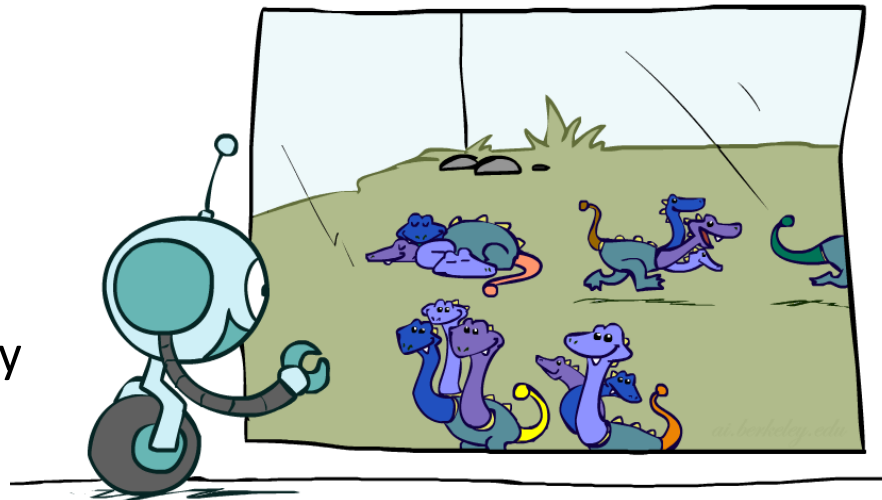


$$P(W|cold)$$

| T | W | P |
|------|------|-----|
| cold | sun | 0.4 |
| cold | rain | 0.6 |

- Family of conditionals:
 $P(Y | X)$

- Multiple conditionals
- Entries $P(y | x)$ for all x, y
- Sums to $|X|$



$$P(W|T)$$

| T | W | P |
|------|------|-----|
| hot | sun | 0.8 |
| hot | rain | 0.2 |
| cold | sun | 0.4 |
| cold | rain | 0.6 |

$$P(W|hot)$$

$$P(W|cold)$$

Factor Zoo III

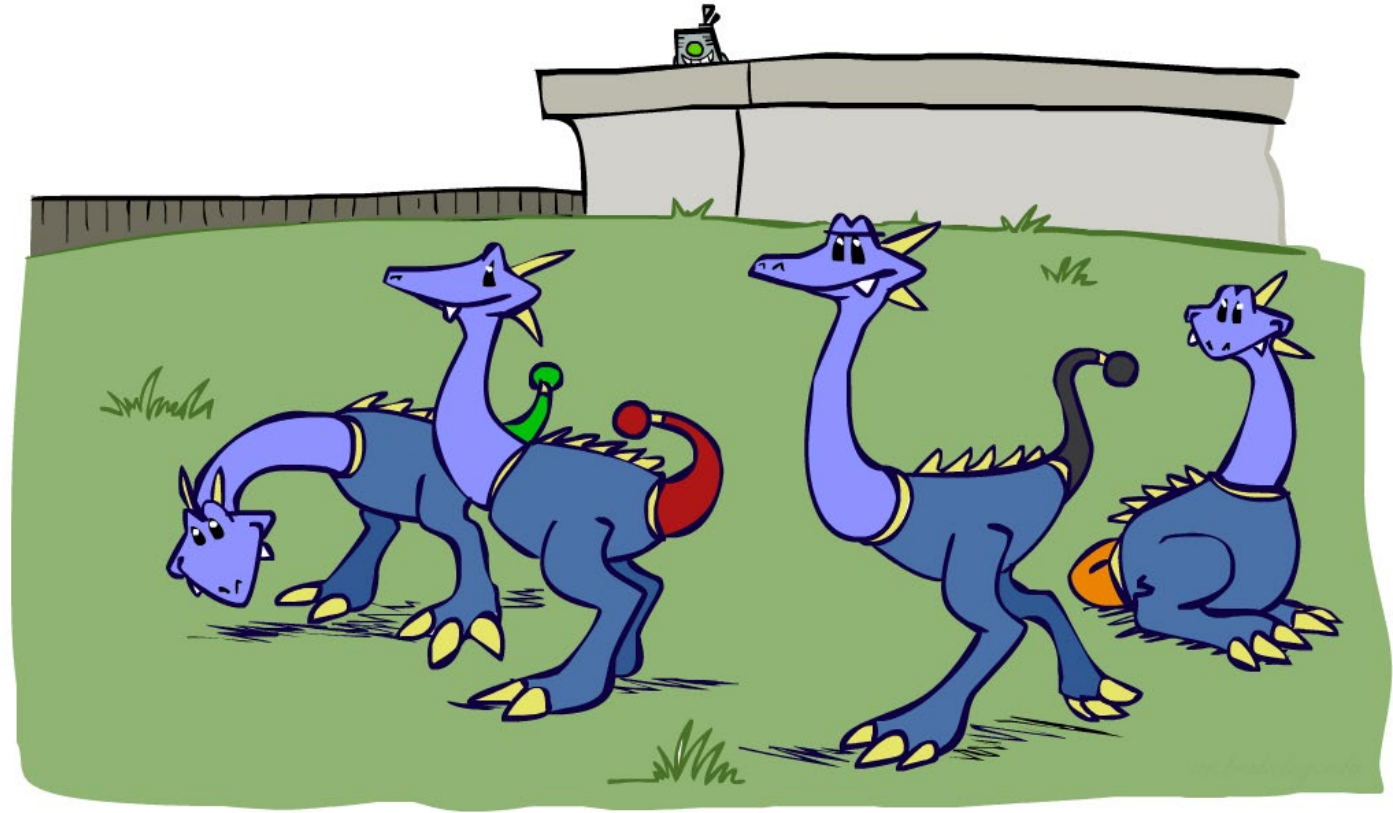
- Specified family: $P(y | X)$
 - Entries $P(y | x)$ for fixed y , but for all x
 - Sums to ... who knows!

$$P(\text{rain}|T)$$

| T | W | P |
|------|------|-----|
| hot | rain | 0.2 |
| cold | rain | 0.6 |

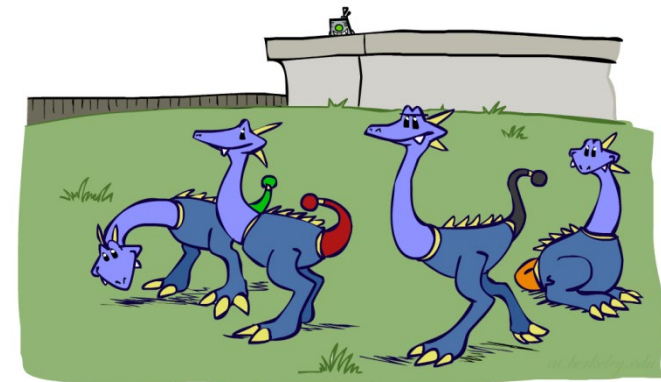
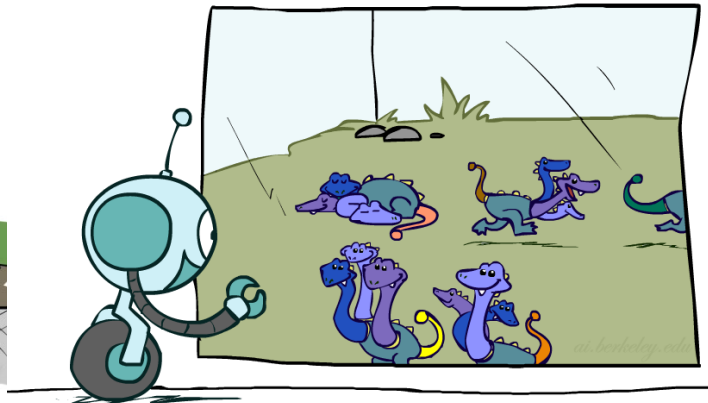
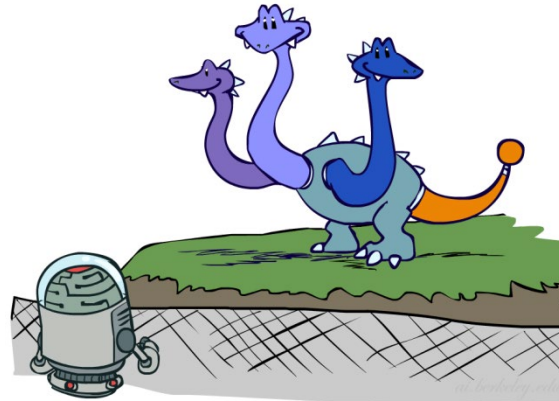
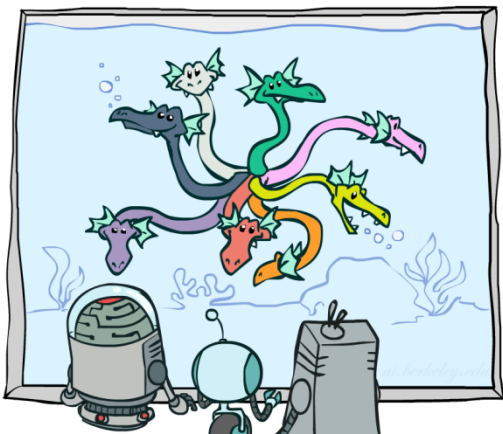
$$P(\text{rain}|hot)$$

$$P(\text{rain}|cold)$$



Factor Zoo Summary

- In general, when we write $P(Y_1 \dots Y_N \mid X_1 \dots X_M)$
 - It is a “factor,” a multi-dimensional array
 - Its values are $P(y_1 \dots y_N \mid x_1 \dots x_M)$
 - Any assigned (=lower-case) X or Y is a dimension missing (selected) from the array



Example: Traffic Domain

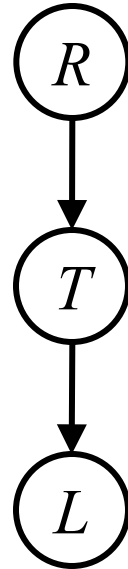
- Random Variables

- R: Raining
- T: Traffic
- L: Late for class!

$$P(L) = ?$$

$$= \sum_{r,t} P(r, t, L)$$

$$= \sum_{r,t} P(r)P(t|r)P(L|t)$$



$$P(R)$$

| | |
|----|-----|
| +r | 0.1 |
| -r | 0.9 |

$$P(T|R)$$

| | | |
|----|----|-----|
| +r | +t | 0.8 |
| +r | -t | 0.2 |
| -r | +t | 0.1 |
| -r | -t | 0.9 |

$$P(L|T)$$

| | | |
|----|----|-----|
| +t | +l | 0.3 |
| +t | -l | 0.7 |
| -t | +l | 0.1 |
| -t | -l | 0.9 |

Inference by Enumeration: Procedural Outline

- Track objects called **factors**
- Initial factors are local CPTs (one per node)

$$P(R)$$

| | |
|----|-----|
| +r | 0.1 |
| -r | 0.9 |

$$P(T|R)$$

| | | |
|----|----|-----|
| +r | +t | 0.8 |
| +r | -t | 0.2 |
| -r | +t | 0.1 |
| -r | -t | 0.9 |

$$P(L|T)$$

| | | |
|----|----|-----|
| +t | +l | 0.3 |
| +t | -l | 0.7 |
| -t | +l | 0.1 |
| -t | -l | 0.9 |

- Any known values are selected
 - E.g. if we know $L = +l$, the initial factors are

$$P(R)$$

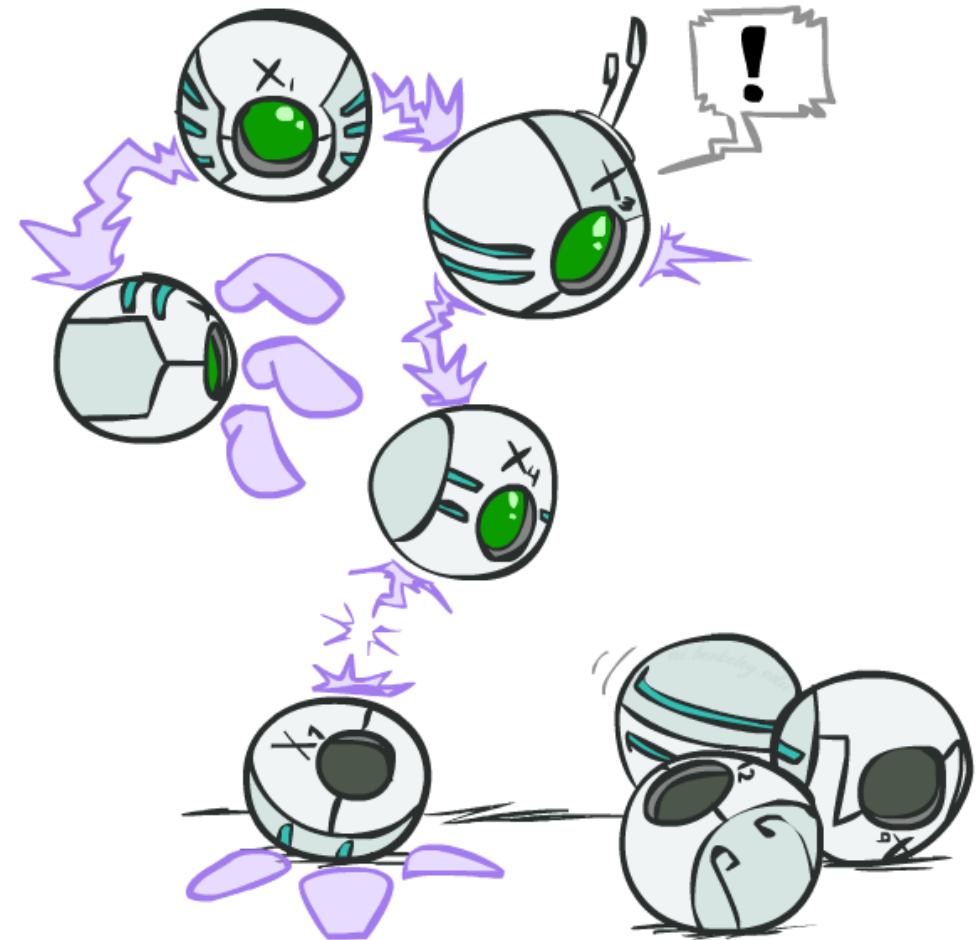
| | |
|----|-----|
| +r | 0.1 |
| -r | 0.9 |

$$P(T|R)$$

| | | |
|----|----|-----|
| +r | +t | 0.8 |
| +r | -t | 0.2 |
| -r | +t | 0.1 |
| -r | -t | 0.9 |

$$P(+l|T)$$

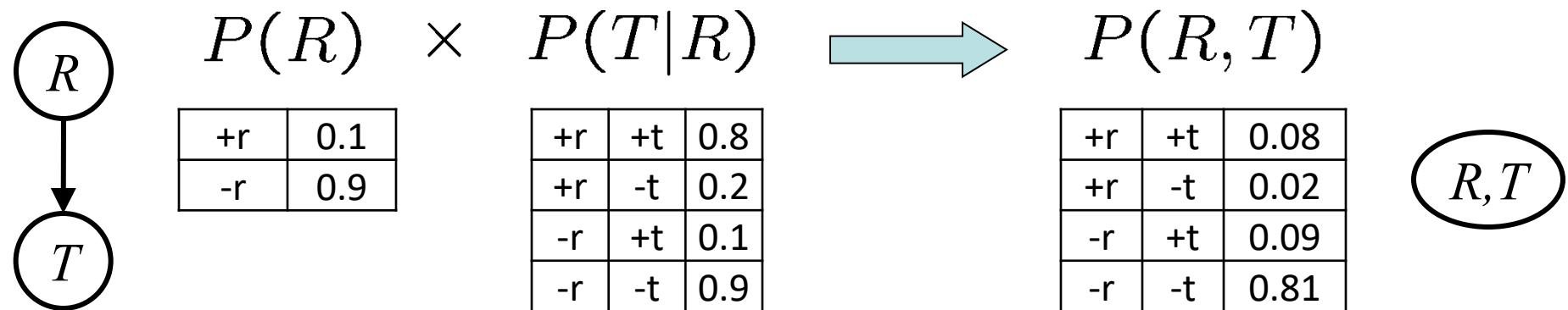
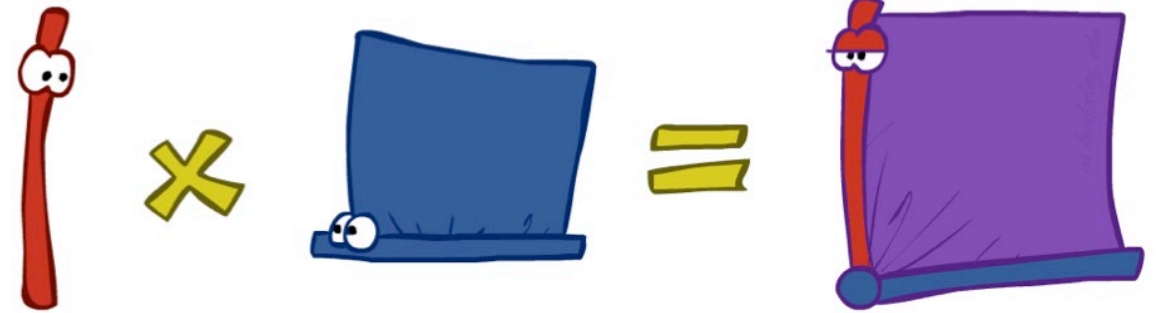
| | | |
|----|----|-----|
| +t | +l | 0.3 |
| -t | +l | 0.1 |



- Procedure: Join all factors, eliminate all hidden variables, normalize

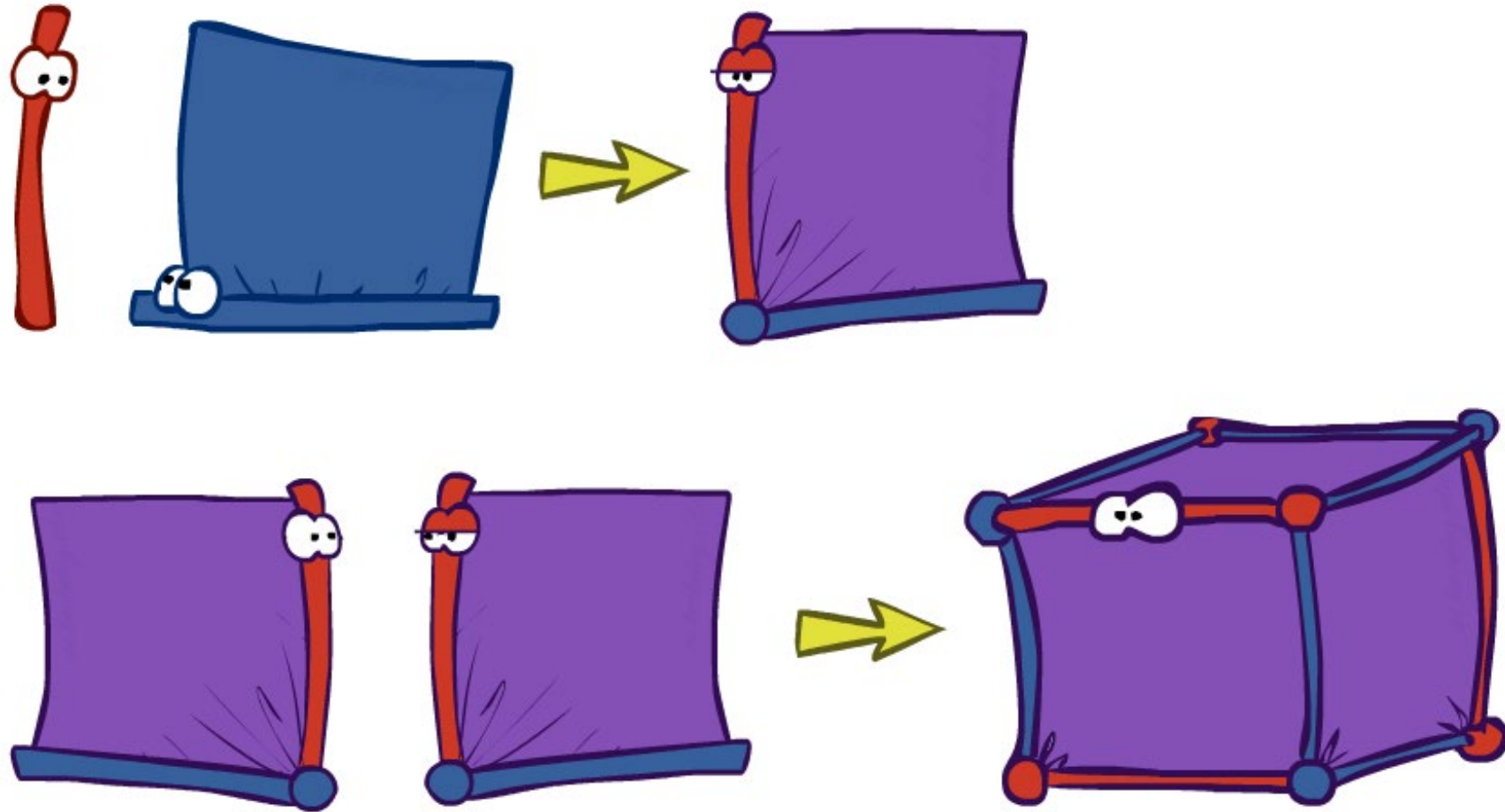
Operation 1: Join Factors

- First basic operation: **joining factors**
- Combining factors:
 - Just like a database join**
 - Get all factors over the joining variable
 - Build a new factor over the union of the variables involved
- Example: Join on R

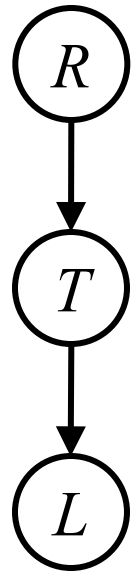
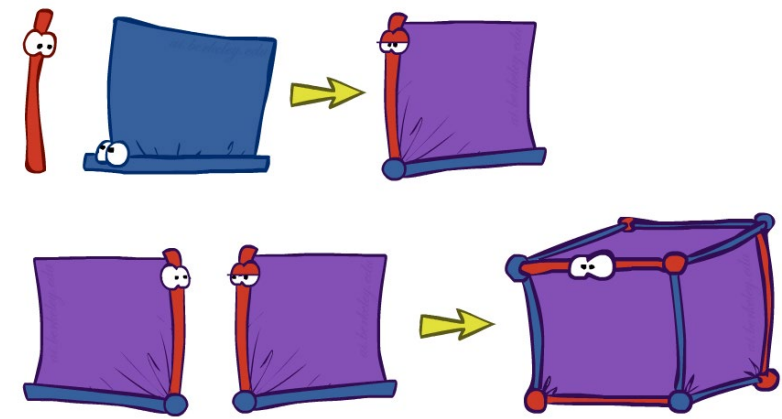


- Computation for each entry: pointwise products $\forall r, t : P(r, t) = P(r) \cdot P(t|r)$

Example: Multiple Joins



Example: Multiple Joins



$P(R)$

| | |
|----|-----|
| +r | 0.1 |
| -r | 0.9 |

Join R

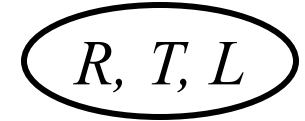
$P(R, T)$

| | | |
|----|----|------|
| +r | +t | 0.08 |
| +r | -t | 0.02 |
| -r | +t | 0.09 |
| -r | -t | 0.81 |

$P(T|R)$

| | | |
|----|----|-----|
| +r | +t | 0.8 |
| +r | -t | 0.2 |
| -r | +t | 0.1 |
| -r | -t | 0.9 |

Join T

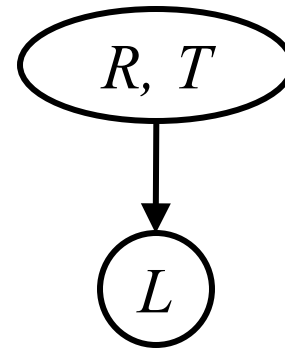


$P(L|T)$

| | | |
|----|----|-----|
| +t | +l | 0.3 |
| +t | -l | 0.7 |
| -t | +l | 0.1 |
| -t | -l | 0.9 |

$P(L|T)$

| | | |
|----|----|-----|
| +t | +l | 0.3 |
| +t | -l | 0.7 |
| -t | +l | 0.1 |
| -t | -l | 0.9 |



$P(R, T, L)$

| | | | |
|----|----|----|-------|
| +r | +t | +l | 0.024 |
| +r | +t | -l | 0.056 |
| +r | -t | +l | 0.002 |
| +r | -t | -l | 0.018 |
| -r | +t | +l | 0.027 |
| -r | +t | -l | 0.063 |
| -r | -t | +l | 0.081 |
| -r | -t | -l | 0.729 |

Operation 2: Eliminate

- Second basic operation: **marginalization**
- Take a factor and sum out a variable
 - Shrinks a factor to a smaller one
 - A **projection** operation
- Example:

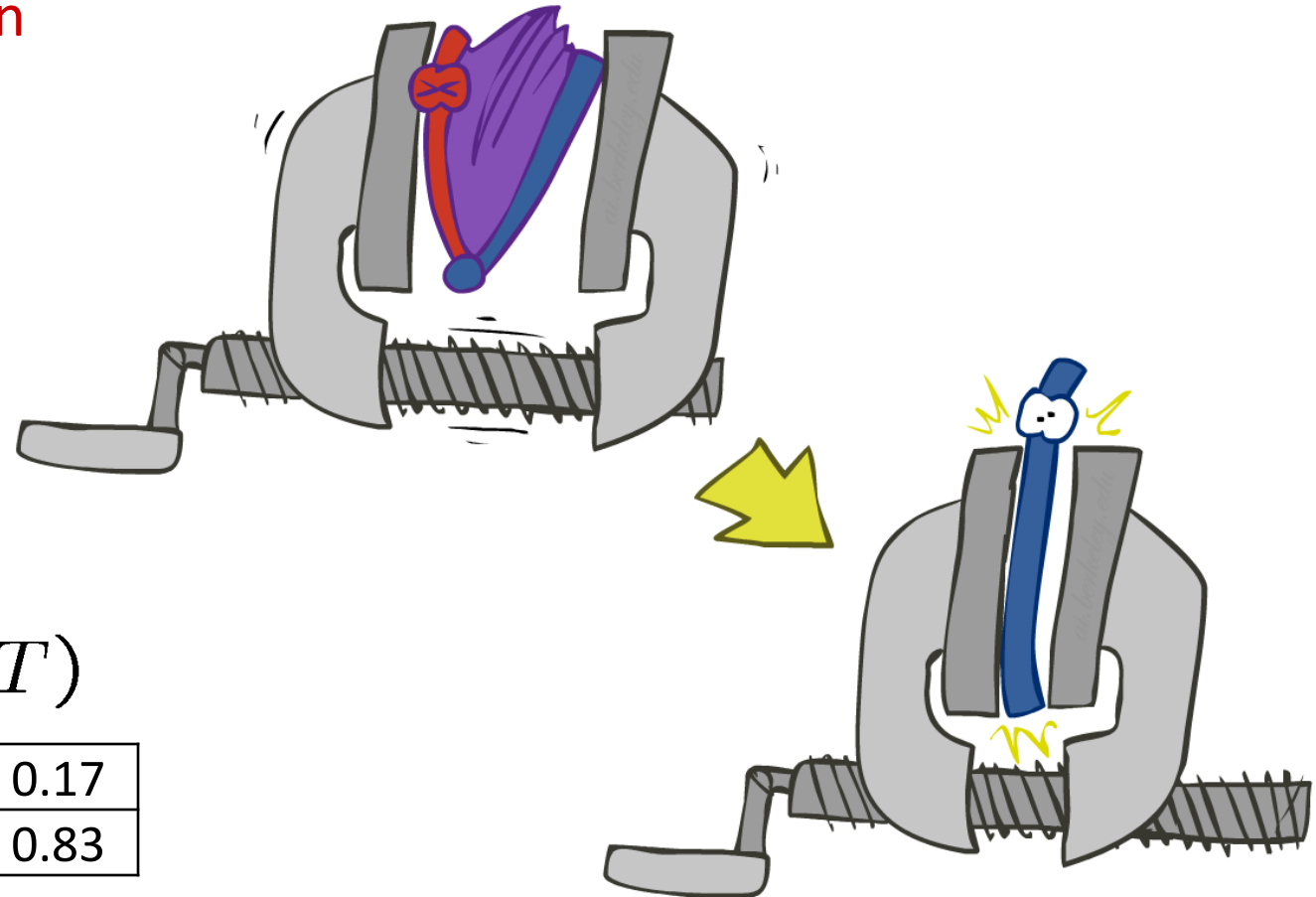
$$P(R, T)$$

| | | |
|----|----|------|
| +r | +t | 0.08 |
| +r | -t | 0.02 |
| -r | +t | 0.09 |
| -r | -t | 0.81 |

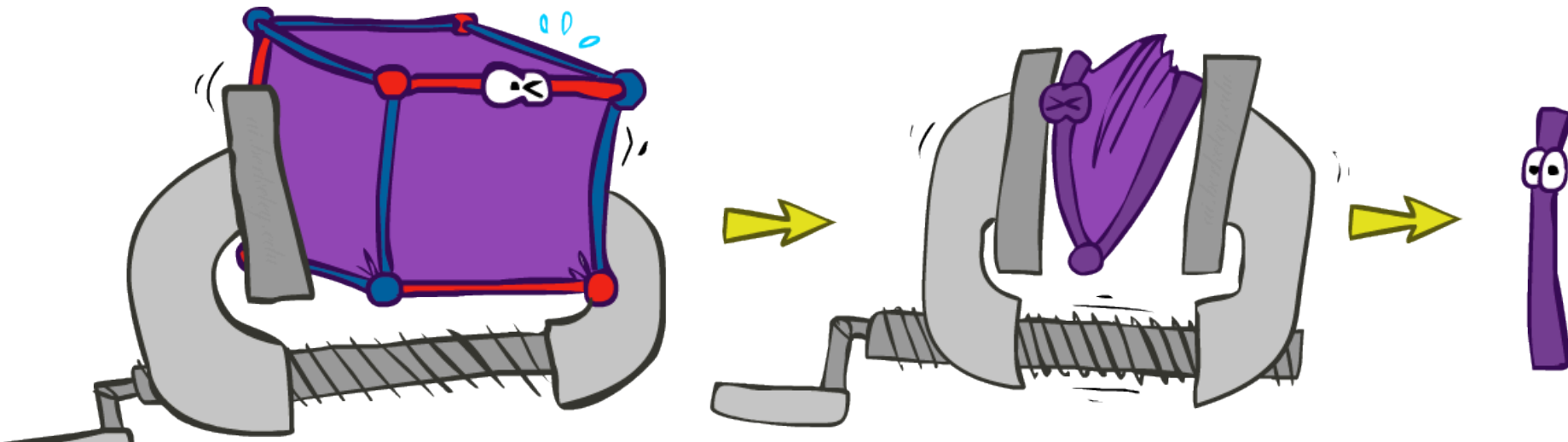
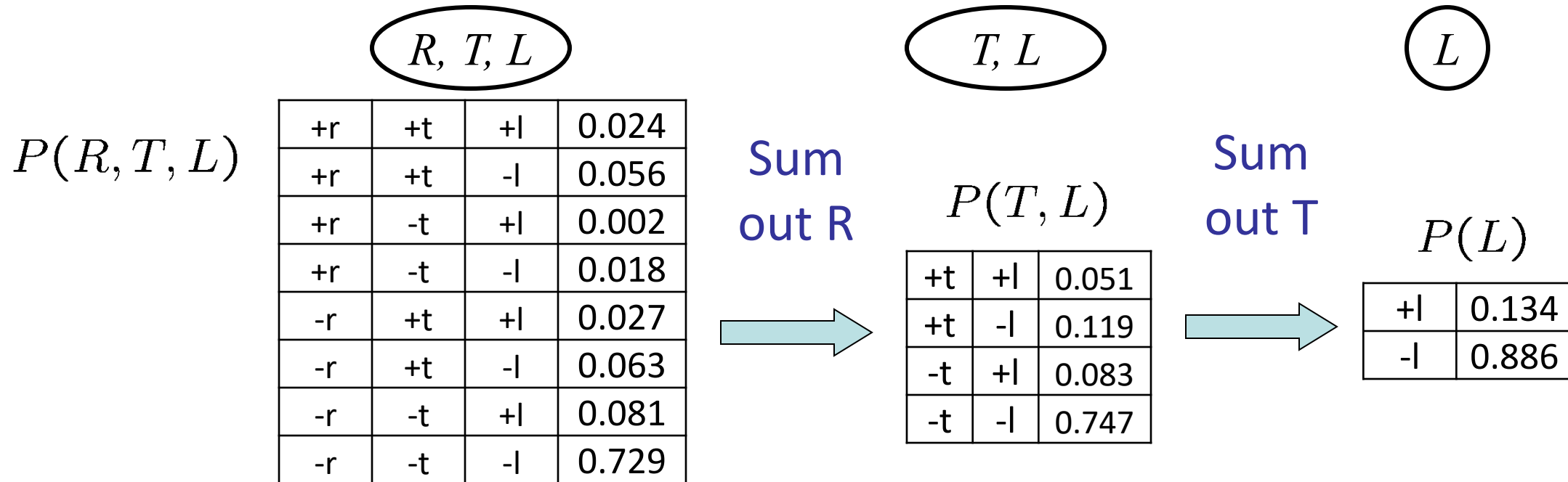
sum R


$$P(T)$$

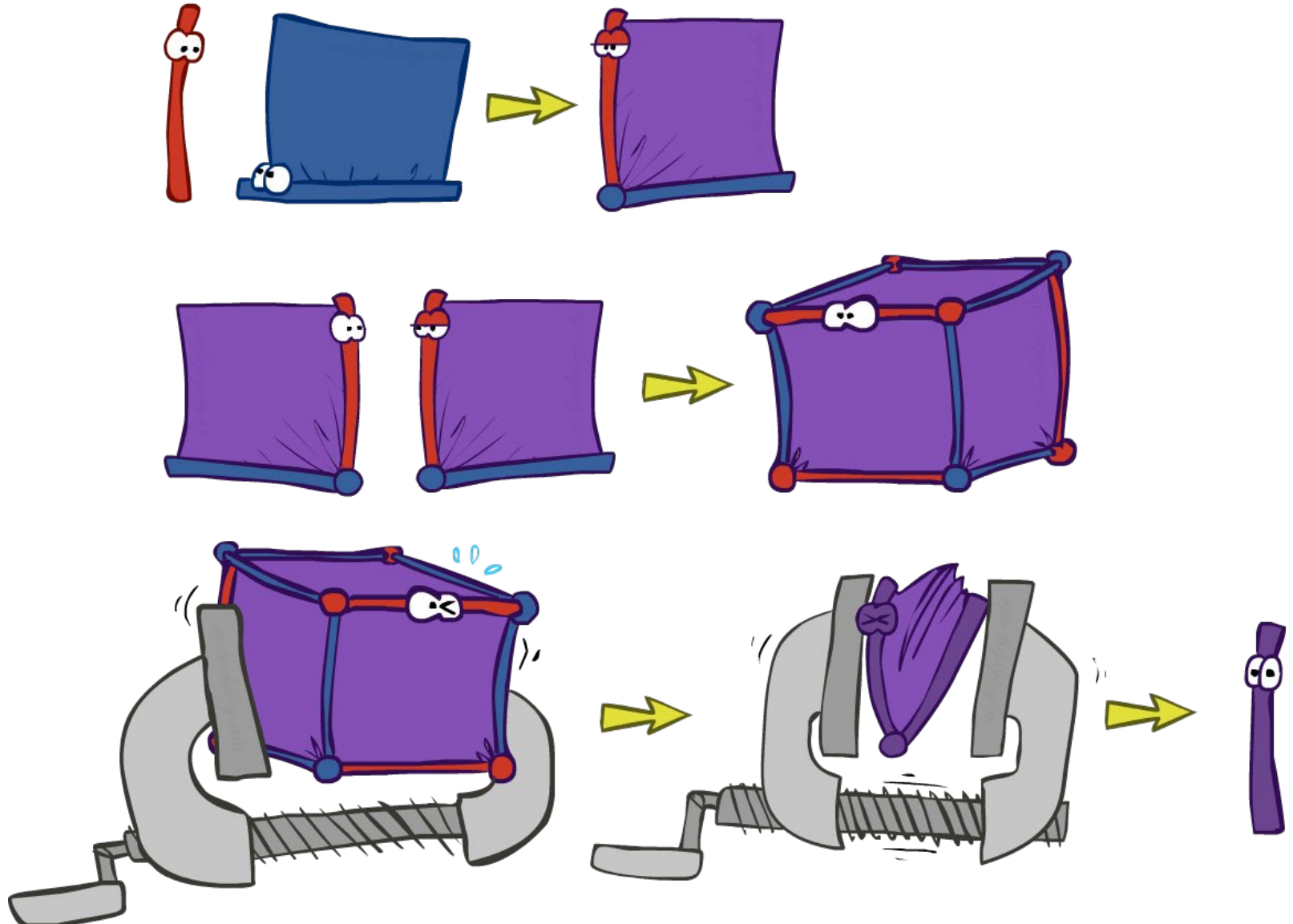
| | |
|----|------|
| +t | 0.17 |
| -t | 0.83 |



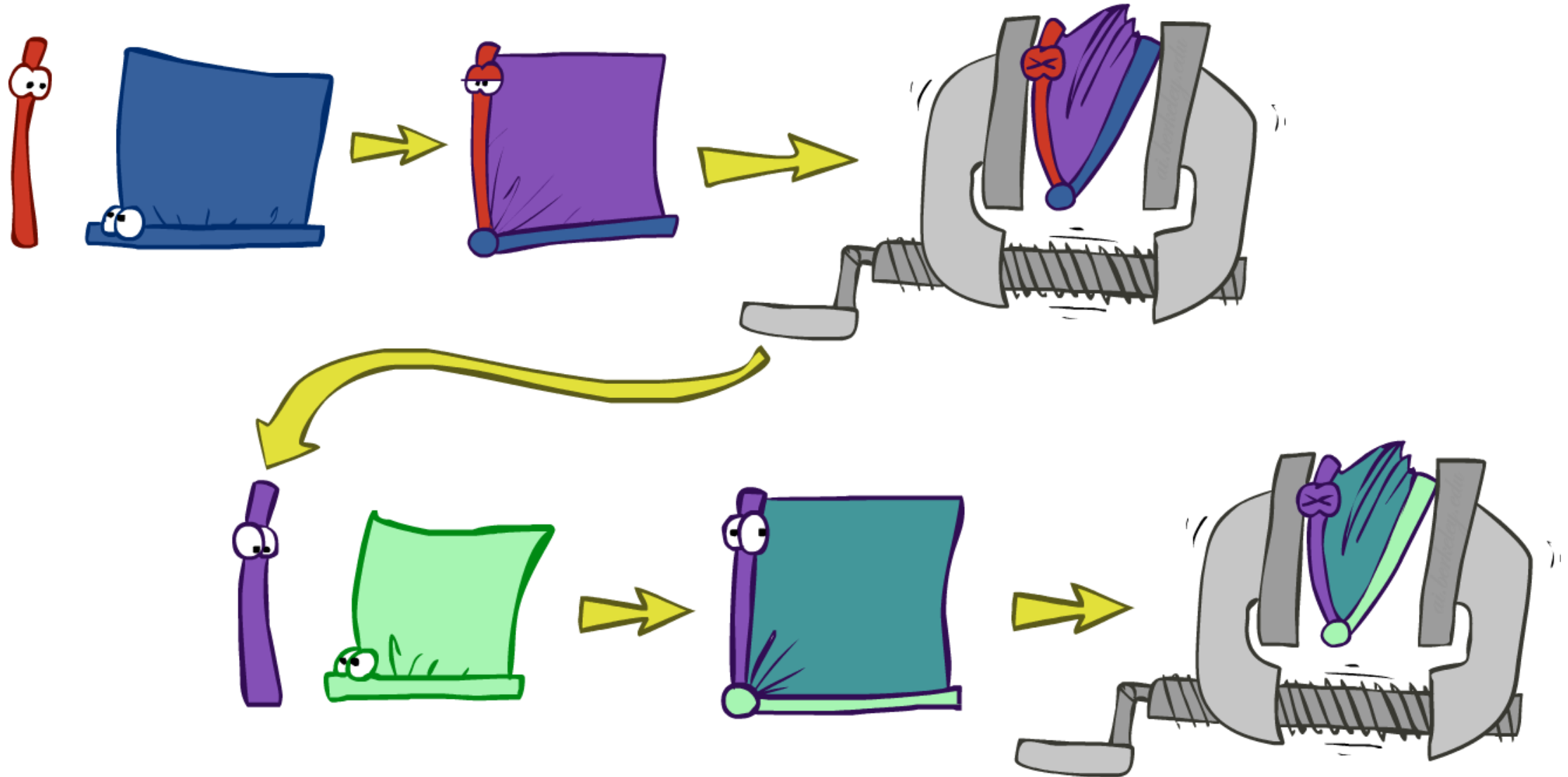
Multiple Elimination



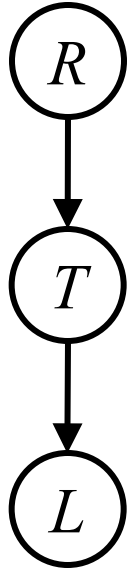
Thus Far: Multiple Join, Multiple Eliminate (= Inference by Enumeration)



Marginalizing Early (= Variable Elimination)



Traffic Domain



$$P(L) = ?$$

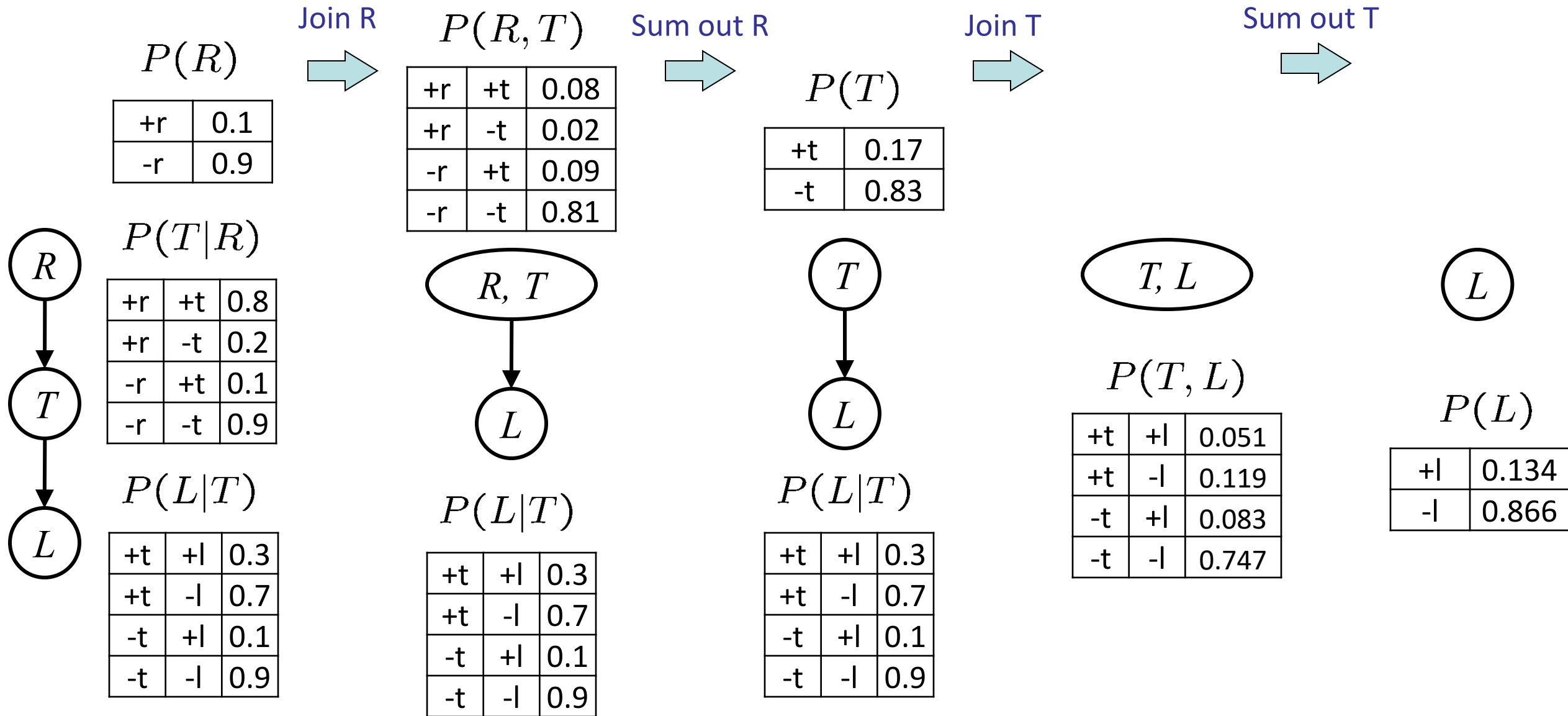
- Inference by Enumeration

$$= \sum_t \sum_r \underbrace{P(L|t)P(r)P(t|r)}_{\text{Join on } r}$$
$$\underbrace{\hspace{10em}}_{\text{Join on } t}$$
$$\underbrace{\hspace{10em}}_{\text{Eliminate } r}$$
$$\underbrace{\hspace{10em}}_{\text{Eliminate } t}$$

- Variable Elimination

$$= \sum_t P(L|t) \underbrace{\sum_r P(r)P(t|r)}_{\text{Join on } r}$$
$$\underbrace{\hspace{10em}}_{\text{Eliminate } r}$$
$$\underbrace{\hspace{10em}}_{\text{Join on } t}$$
$$\underbrace{\hspace{10em}}_{\text{Eliminate } t}$$

Marginalizing Early! (aka VE)



Evidence

- If evidence, start with factors that select that evidence
 - No evidence uses these initial factors:

$$P(R)$$

| | |
|----|-----|
| +r | 0.1 |
| -r | 0.9 |

$$P(T|R)$$

| | | |
|----|----|-----|
| +r | +t | 0.8 |
| +r | -t | 0.2 |
| -r | +t | 0.1 |
| -r | -t | 0.9 |

$$P(L|T)$$

| | | |
|----|----|-----|
| +t | +l | 0.3 |
| +t | -l | 0.7 |
| -t | +l | 0.1 |
| -t | -l | 0.9 |

- Computing $P(L|+r)$ the initial factors become:

$$P(+r)$$

| | |
|----|-----|
| +r | 0.1 |
|----|-----|

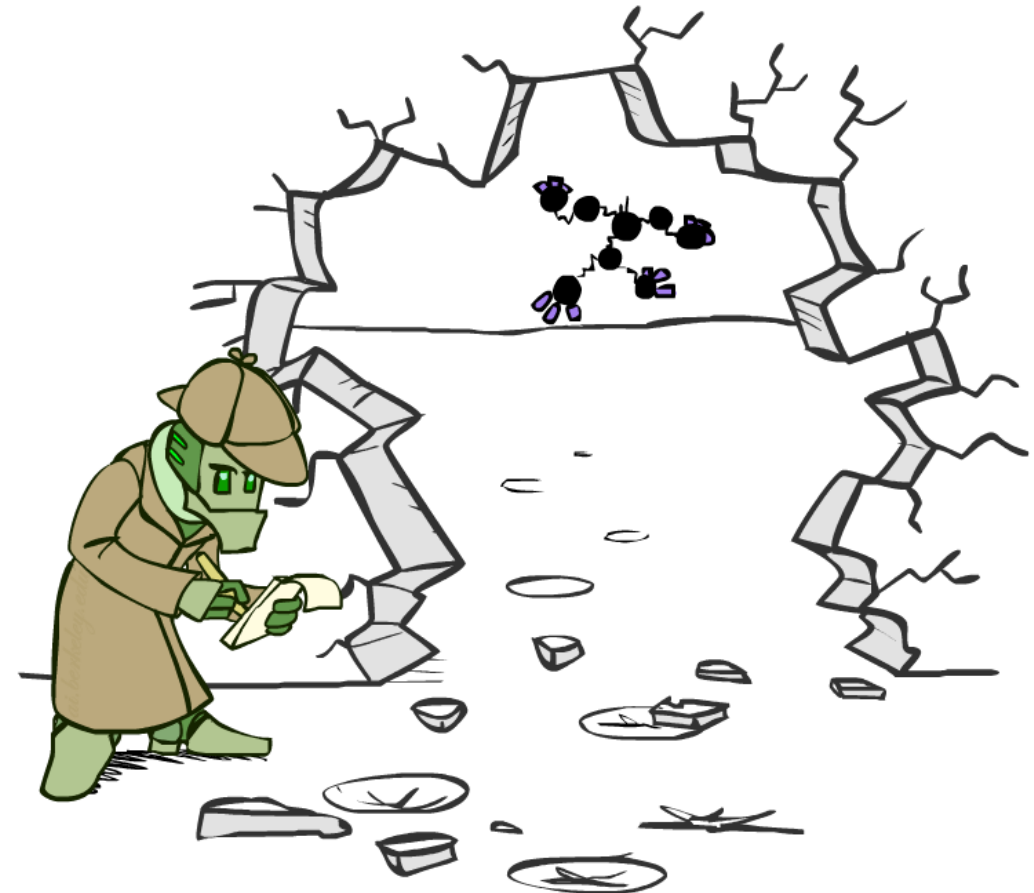
$$P(T|+r)$$

| | | |
|----|----|-----|
| +r | +t | 0.8 |
| +r | -t | 0.2 |

$$P(L|T)$$

| | | |
|----|----|-----|
| +t | +l | 0.3 |
| +t | -l | 0.7 |
| -t | +l | 0.1 |
| -t | -l | 0.9 |

- We eliminate all vars other than query + evidence



Evidence II

- Result will be a selected joint of query and evidence
 - E.g. for $P(L \mid +r)$, we would end up with:

$$P(+r, L)$$

| | | |
|----|----|-------|
| +r | +l | 0.026 |
| +r | -l | 0.074 |

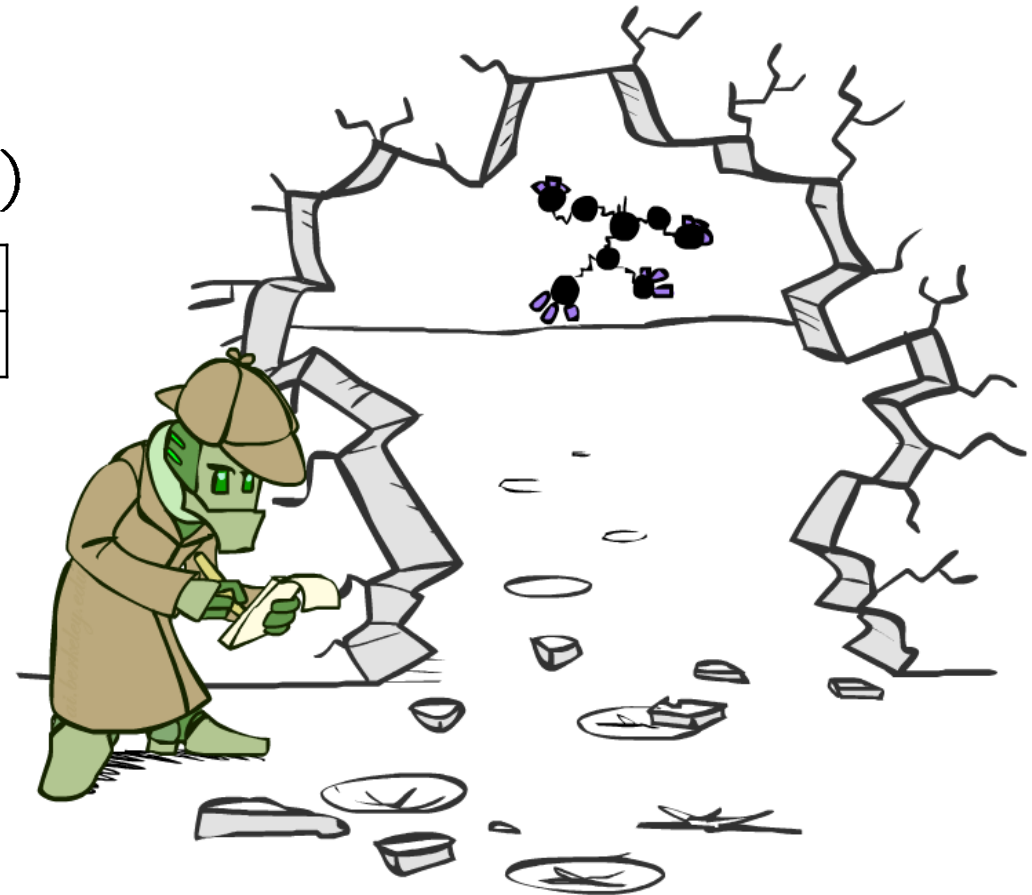
Normalize



$$P(L \mid +r)$$

| | |
|----|------|
| +l | 0.26 |
| -l | 0.74 |

- To get our answer, just normalize this!
- That's it!



General Variable Elimination

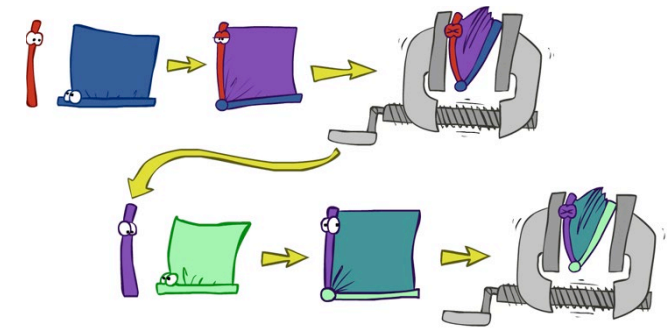
- Query: $P(Q|E_1 = e_1, \dots, E_k = e_k)$

- Start with initial factors:
 - Local CPTs (but instantiated by evidence)

| x | P(x) |
|----|------|
| -3 | 0.05 |
| -1 | 0.25 |
| 0 | 0.07 |
| 1 | 0.2 |
| 5 | 0.01 |

2 0.15

- While there are still hidden variables (not Q or evidence):
 - Pick a hidden variable H
 - Join all factors mentioning H
 - Eliminate (sum out) H



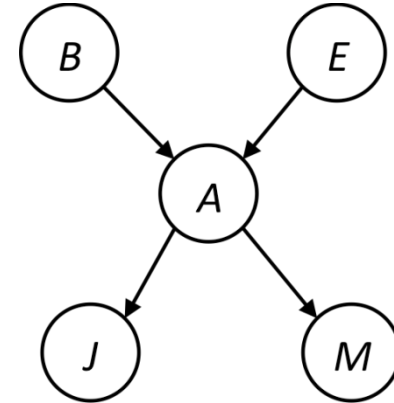
- Join all remaining factors and normalize

$$\text{stick} \times \text{blue square} = \text{purple square} \times \frac{1}{Z}$$

Example

$$P(B|j, m) \propto P(B, j, m)$$

| | | | | |
|--------|--------|-------------|----------|----------|
| $P(B)$ | $P(E)$ | $P(A B, E)$ | $P(j A)$ | $P(m A)$ |
|--------|--------|-------------|----------|----------|

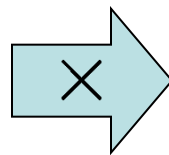


Choose A

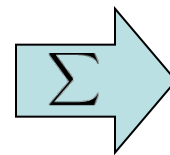
$$P(A|B, E)$$

$$P(j|A)$$

$$P(m|A)$$



$$P(j, m, A|B, E)$$



$$P(j, m|B, E)$$

| | | |
|--------|--------|----------------|
| $P(B)$ | $P(E)$ | $P(j, m B, E)$ |
|--------|--------|----------------|

Example

$$P(B) \quad P(E) \quad P(j, m|B, E)$$

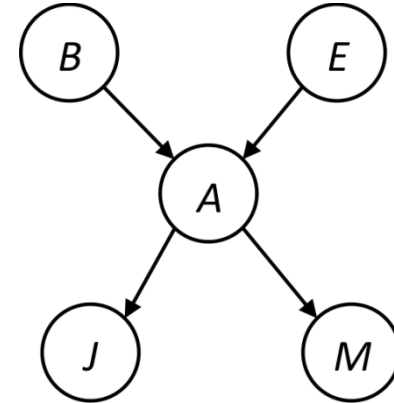
Choose E

$$\begin{array}{l} P(E) \\ P(j, m|B, E) \end{array} \xrightarrow{\times} P(j, m, E|B) \xrightarrow{\Sigma} P(j, m|B)$$

$$P(B) \quad P(j, m|B)$$

Finish with B

$$\begin{array}{l} P(B) \\ P(j, m|B) \end{array} \xrightarrow{\times} P(j, m, B) \xrightarrow{\text{Normalize}} P(B|j, m)$$



Same Example in Equations

$$P(B|j, m) \propto P(B, j, m)$$

| | | | | |
|--------|--------|-------------|----------|----------|
| $P(B)$ | $P(E)$ | $P(A B, E)$ | $P(j A)$ | $P(m A)$ |
|--------|--------|-------------|----------|----------|

$$\begin{aligned}
 P(B|j, m) &\propto P(B, j, m) \\
 &= \sum_{e, a} P(B, j, m, e, a) \\
 &= \sum_{e, a} P(B)P(e)P(a|B, e)P(j|a)P(m|a) \\
 &= \sum_e P(B)P(e) \sum_a P(a|B, e)P(j|a)P(m|a) \\
 &= \sum_e P(B)P(e)f_1(B, e, j, m) \\
 &= P(B) \sum_e P(e)f_1(B, e, j, m) \\
 &= P(B)f_2(B, j, m)
 \end{aligned}$$

marginal obtained from joint by summing out

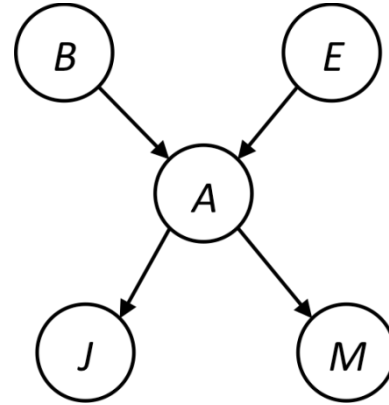
use Bayes' net joint distribution expression

use $x*(y+z) = xy + xz$

joining on a, and then summing out gives f_1

use $x*(y+z) = xy + xz$

joining on e, and then summing out gives f_2



All we are doing is exploiting $uwv + uwz + uxy + uxz + vwy + vwz + vxy + vxz = (u+v)(w+x)(y+z)$ to improve computational efficiency!

Another Variable Elimination Example

Query: $P(X_3|Y_1 = y_1, Y_2 = y_2, Y_3 = y_3)$

Start by inserting evidence, which gives the following initial factors:

$$p(Z)p(X_1|Z)p(X_2|Z)p(X_3|Z)p(y_1|X_1)p(y_2|X_2)p(y_3|X_3)$$

Eliminate X_1 , this introduces the factor $f_1(Z, y_1) = \sum_{x_1} p(x_1|Z)p(y_1|x_1)$, and we are left with:

$$p(Z)f_1(Z, y_1)p(X_2|Z)p(X_3|Z)p(y_2|X_2)p(y_3|X_3)$$

Eliminate X_2 , this introduces the factor $f_2(Z, y_2) = \sum_{x_2} p(x_2|Z)p(y_2|x_2)$, and we are left with:

$$p(Z)f_1(Z, y_1)f_2(Z, y_2)p(X_3|Z)p(y_3|X_3)$$

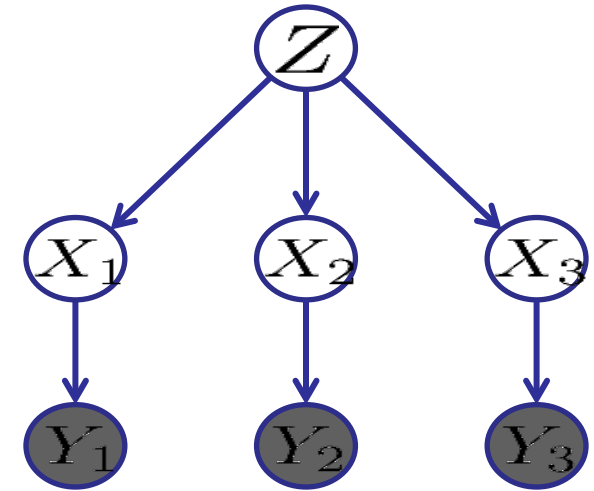
Eliminate Z , this introduces the factor $f_3(y_1, y_2, X_3) = \sum_z p(z)f_1(z, y_1)f_2(z, y_2)p(X_3|z)$, and we are left:

$$p(y_3|X_3), f_3(y_1, y_2, X_3)$$

No hidden variables left. Join the remaining factors to get:

$$f_4(y_1, y_2, y_3, X_3) = P(y_3|X_3)f_3(y_1, y_2, X_3).$$

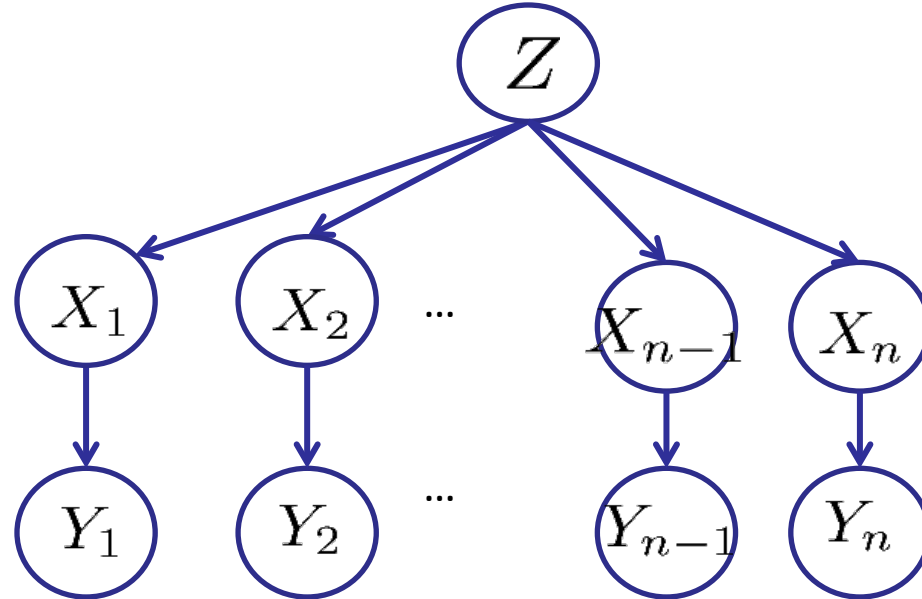
Normalizing over X_3 gives $P(X_3|y_1, y_2, y_3)$.



Computational complexity critically depends on the largest factor being generated in this process. Size of factor = number of entries in table. In example above (assuming binary) all factors generated are of size 2 --- as they all only have one variable (Z , Z , and X_3 respectively).

Variable Elimination Ordering

- For the query $P(X_n | y_1, \dots, y_n)$ work through the following two different orderings as done in previous slide: Z, X_1, \dots, X_{n-1} and X_1, \dots, X_{n-1}, Z . What is the size of the maximum factor generated for each of the orderings?



- Answer: 2^{n+1} versus 2^2 (assuming binary)
- In general: the ordering can greatly affect efficiency.

VE: Computational and Space Complexity

- The computational and space complexity of variable elimination is determined by the largest factor
- The elimination ordering can greatly affect the size of the largest factor.
 - E.g., previous slide's example 2^n vs. 2
- Does there always exist an ordering that only results in small factors?
 - **No!**

Worst Case Complexity?

- CSP:

$$(x_1 \vee x_2 \vee \neg x_3) \wedge (\neg x_1 \vee x_3 \vee \neg x_4) \wedge (x_2 \vee \neg x_2 \vee x_4) \wedge (\neg x_3 \vee \neg x_4 \vee \neg x_5) \wedge (x_2 \vee x_5 \vee x_7) \wedge (x_4 \vee x_5 \vee x_6) \wedge (\neg x_5 \vee x_6 \vee \neg x_7) \wedge (\neg x_5 \vee \neg x_6 \vee x_7)$$

$$P(X_i = 0) = P(X_i = 1) = 0.5$$

$$Y_1 = X_1 \vee X_2 \vee \neg X_3$$

...

$$Y_8 = \neg X_5 \vee X_6 \vee X_7$$

$$Y_{1,2} = Y_1 \wedge Y_2$$

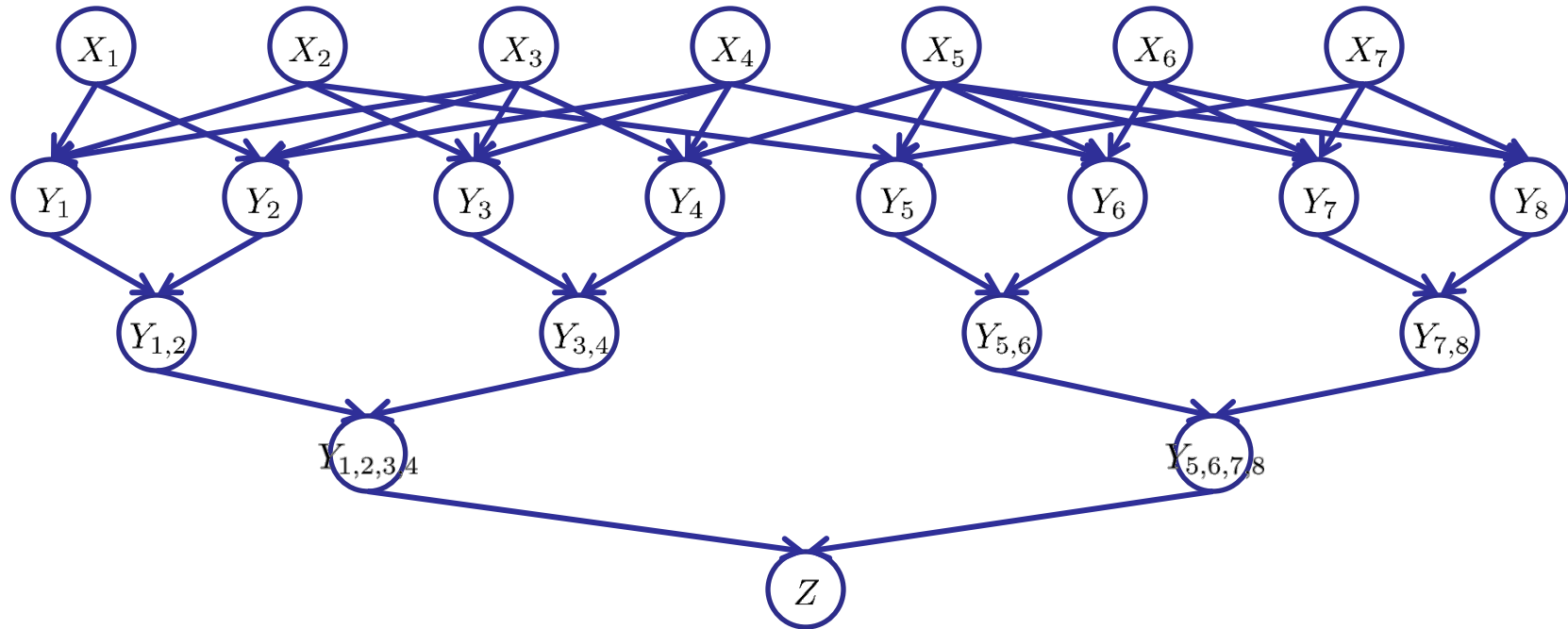
...

$$Y_{7,8} = Y_7 \wedge Y_8$$

$$Y_{1,2,3,4} = Y_{1,2} \wedge Y_{3,4}$$

$$Y_{5,6,7,8} = Y_{5,6} \wedge Y_{7,8}$$

$$Z = Y_{1,2,3,4} \wedge Y_{5,6,7,8}$$



- If we can answer $P(z)$ equal to zero or not, we answered whether the 3-SAT problem has a solution.
- Hence inference in Bayes' nets is NP-hard. No known efficient probabilistic inference in general.

Polytrees

- A polytree is a directed graph with no undirected cycles
- For poly-trees you can always find an ordering that is efficient
 - Try it!!
- Cut-set conditioning for Bayes' net inference
 - Choose set of variables such that if removed only a polytree remains
 - Exercise: Think about how the specifics would work out!

Bayes' Nets

- ✓ Representation
- ✓ Conditional Independences
- Probabilistic Inference
 - ✓ Enumeration (exact, exponential complexity)
 - ✓ Variable elimination (exact, worst-case exponential complexity, often better)
 - ✓ Inference is NP-complete
 - Sampling (approximate)
- Learning Bayes' Nets from Data