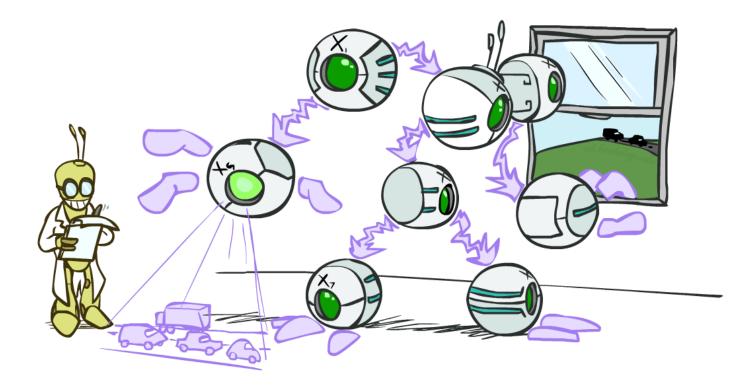
CS 188: Artificial Intelligence

Bayes' Nets: Inference



[Many of these slides were created by Dan Klein and Pieter Abbeel for CS188 Intro to AI at UC Berkeley.]

Announcements

Midterm

- Wednesday March 19, 7-9pm. You will receive an individual email with the location of your exam, probably by Friday. There will be an announcement on Ed when the emails go out. Material up to last week (independence)
- Check Ed and Calendar for more midterm logistics/prep sessions, and see <u>exam logistics page</u> near top of course web site for more info.
- HW6 + HW5 self-assessment
 - Due on Wednesday 3/12/25 at 11:59 PT
- HW6 self-assessment
 - Due on Friday 3/21/25 at 11:59 PT

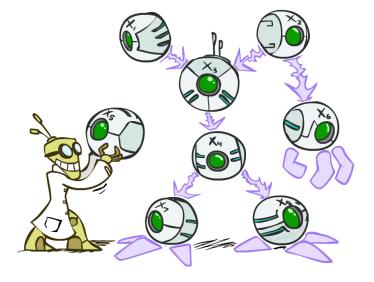
Bayes' Net Representation

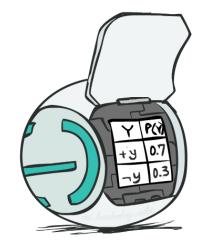
- A directed, acyclic graph, one node per random variable
- A conditional probability table (CPT) for each node
 - A collection of distributions over X, one for each combination of parents' values

 $P(X|a_1\ldots a_n)$

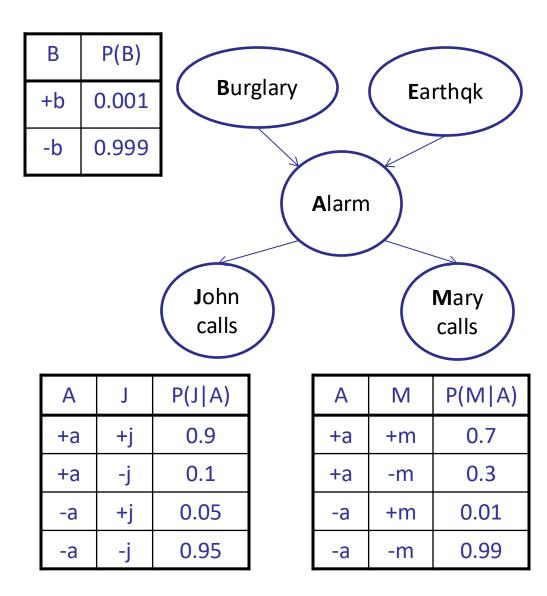
- Bayes' nets implicitly encode joint distributions
 - As a product of local conditional distributions
 - To see what probability a BN gives to a full assignment, multiply all the relevant conditionals together:

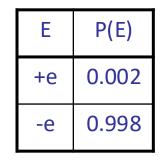
$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | parents(X_i))$$

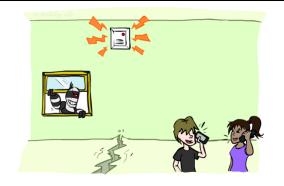




Example: Alarm Network



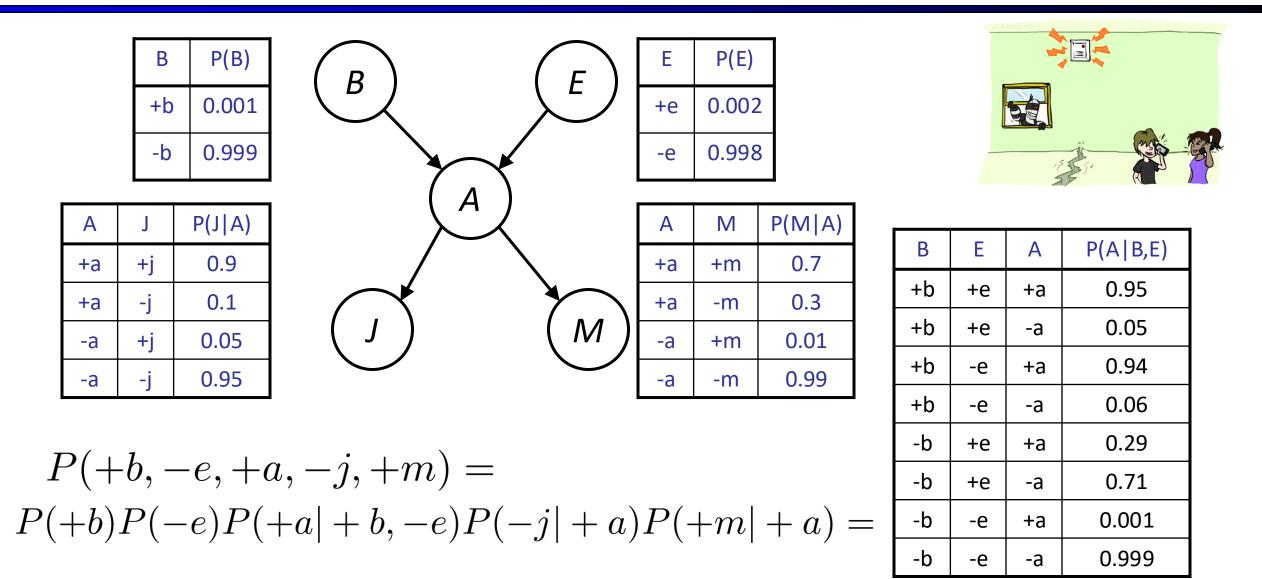




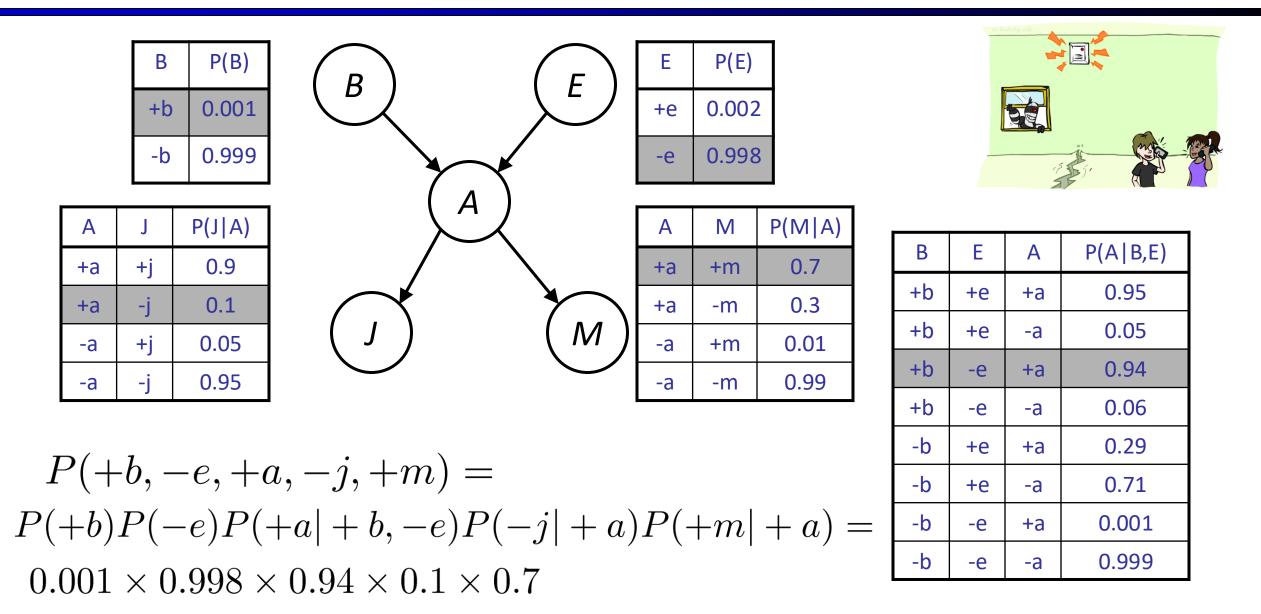
В	Е	Α	P(A B,E)
+b	+e	+a	0.95
+b	+e	-a	0.05
+b	-е	+a	0.94
+b	-е	-a	0.06
-b	+e	+a	0.29
-b	+e	-a	0.71
-b	-е	+a	0.001
-b	-е	-a	0.999

[Demo: BN Applet]

Example: Alarm Network



Example: Alarm Network



Bayes' Nets

Representation

- Conditional Independences
- Probabilistic Inference
 - Enumeration (exact, exponential complexity)
 - Variable elimination (exact, worst-case exponential complexity, often better)
 - Inference is NP-complete
 - Sampling (approximate)
- Learning Bayes' Nets from Data

Inference

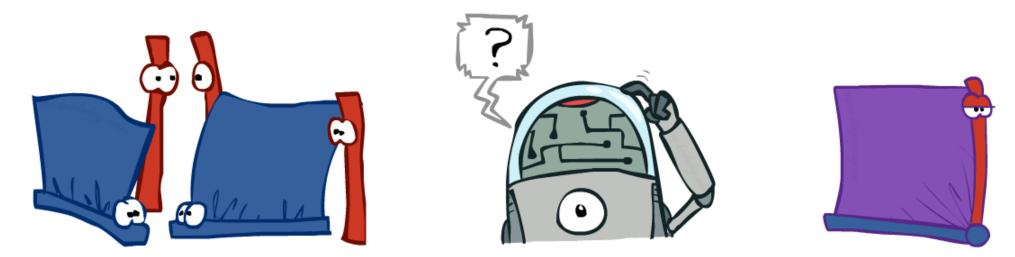
 Inference: calculating some useful quantity from a joint probability distribution

• Examples:

Posterior probability

 $P(Q|E_1 = e_1, \dots E_k = e_k)$

- Most likely explanation:
 - $\operatorname{argmax}_q P(Q = q | E_1 = e_1 \dots)$



Inference by Enumeration

- General case:
 - Evidence variables:
 - Query* variable:
 - Hidden variables:
- $\begin{bmatrix} E_1 \dots E_k = e_1 \dots e_k \\ Q \\ H_1 \dots H_r \end{bmatrix} X_1, X_2, \dots X_n$ All variables
- We want:

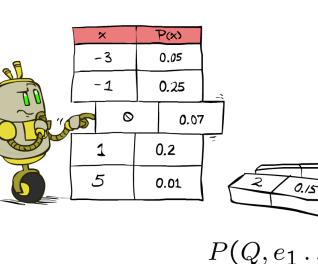
* Works fine with multiple query variables, too

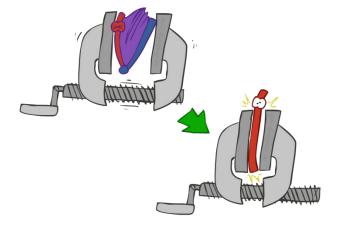
$$P(Q|e_1\ldots e_k)$$

 Step 1: Select the entries consistent with the evidence



Step 3: Normalize





$$P(Q, e_1 \dots e_k) = \sum_{h_1 \dots h_r} P(\underbrace{Q, h_1 \dots h_r, e_1 \dots e_k}_{X_1, X_2, \dots X_n})$$

$$\times \frac{1}{Z}$$

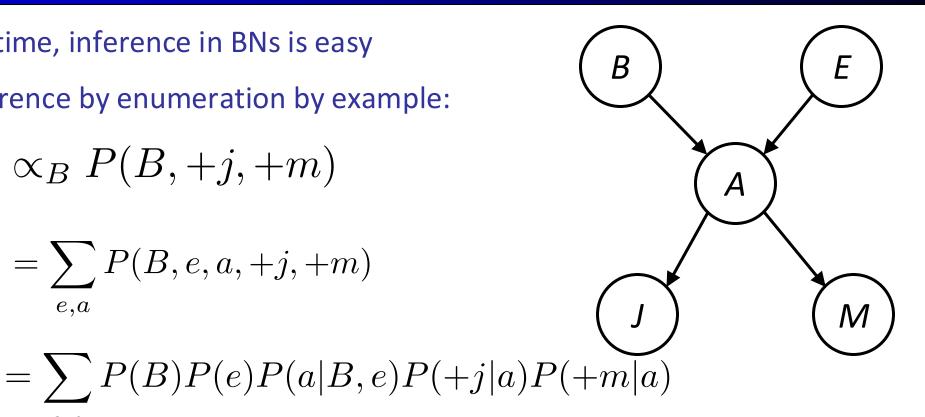
 $Z = \sum_{q} P(Q, e_1 \cdots e_k)$ $P(Q|e_1 \cdots e_k) = \frac{1}{Z} P(Q, e_1 \cdots e_k)$

Inference by Enumeration in Bayes' Net

- Given unlimited time, inference in BNs is easy
- Reminder of inference by enumeration by example:

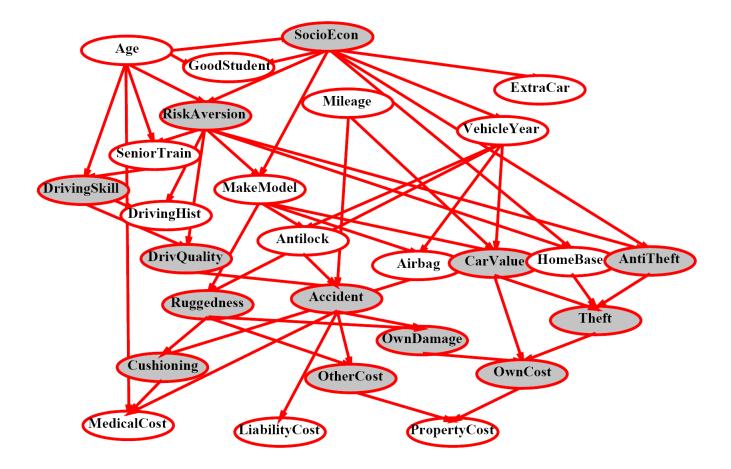
 $P(B \mid +j,+m) \propto_B P(B,+j,+m)$

e,a



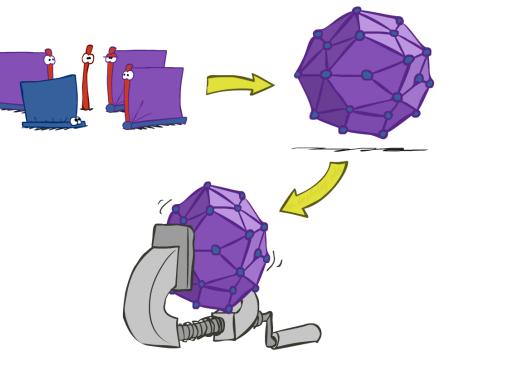
= P(B)P(+e)P(+a|B,+e)P(+j|+a)P(+m|+a) + P(B)P(+e)P(-a|B,+e)P(+j|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)PP(B)P(-e)P(+a|B,-e)P(+j|+a)P(+m|+a) + P(B)P(-e)P(-a|B,-e)P(+j|-a)P(+m|-a)P(+m|-a)P(-a|B,-e)P(+j|-a)P(-a|B,-e)P(+j|-a)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,

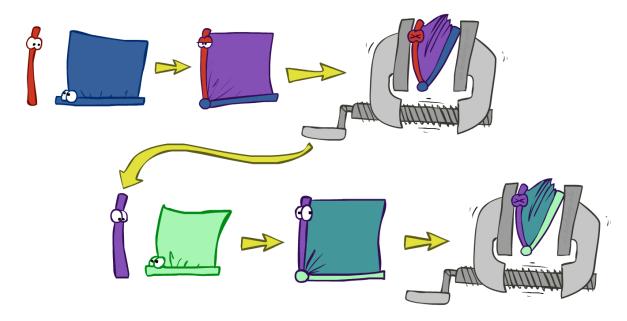
Inference by Enumeration?



Inference by Enumeration vs. Variable Elimination

- Why is inference by enumeration so slow?
 - You join up the whole joint distribution before you sum out the hidden variables
- Idea: interleave joining and marginalizing!
 - Called "Variable Elimination"
 - Still NP-hard, but usually much faster than inference by enumeration

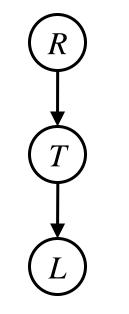




First we'll need some new notation: factors

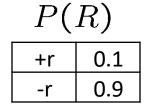
Example: Traffic Domain

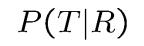
- Random Variables
 - R: Raining
 - T: Traffic
 - L: Late for class!



$$P(L) = ?$$

= $\sum_{r,t} P(r,t,L)$
= $\sum_{r,t} P(r)P(t|r)P(L|t)$





+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9



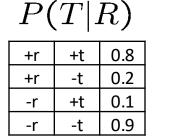
+t	+	0.3
+t	-	0.7
-t	+	0.1
-t	-	0.9

Inference by Enumeration: Procedural Outline

- Track objects called factors
- Initial factors are local CPTs (one per node)

P(R)				
+r	0.1			
-r 0.9				
-1 0.5				

D(D)



P(L T)				
+t	+	0.3		
+t	-	0.7		
-t	+	0.1		
-t	-	0.9		

0.3

0.1

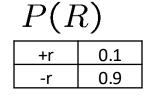
D(T|T)

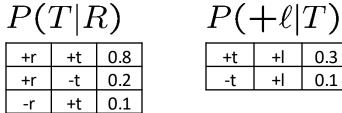
- Any known values are selected
 - E.g. if we know $L = +\ell$, the initial factors are

+r

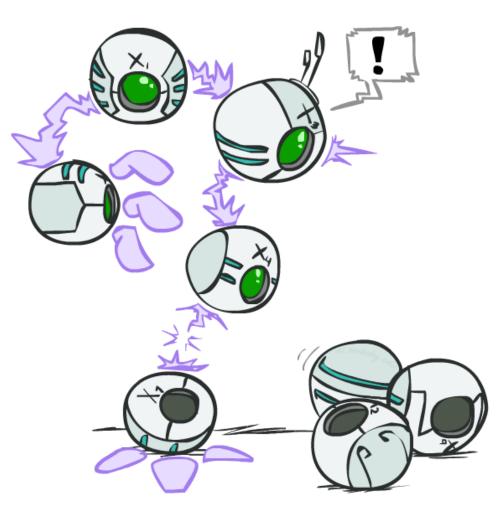
+r

-r





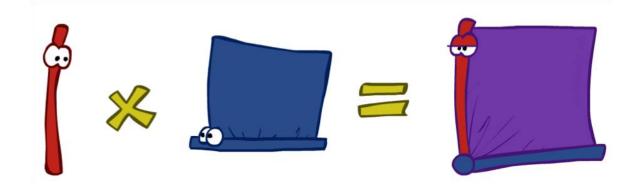
0.9



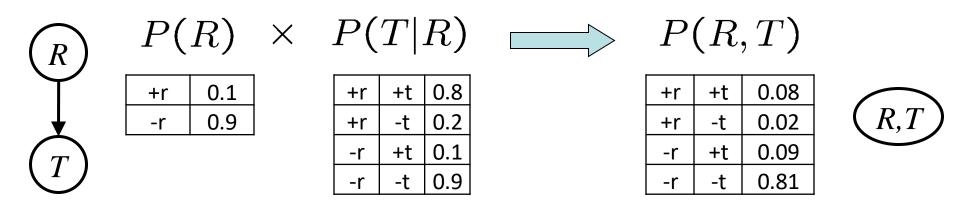
Procedure: Join all factors, eliminate all hidden variables, normalize

Operation 1: Join Factors

- First basic operation: joining factors
- Combining factors:
 - Just like a database join
 - Get all factors over the joining variable
 - Build a new factor over the union of the variables involved

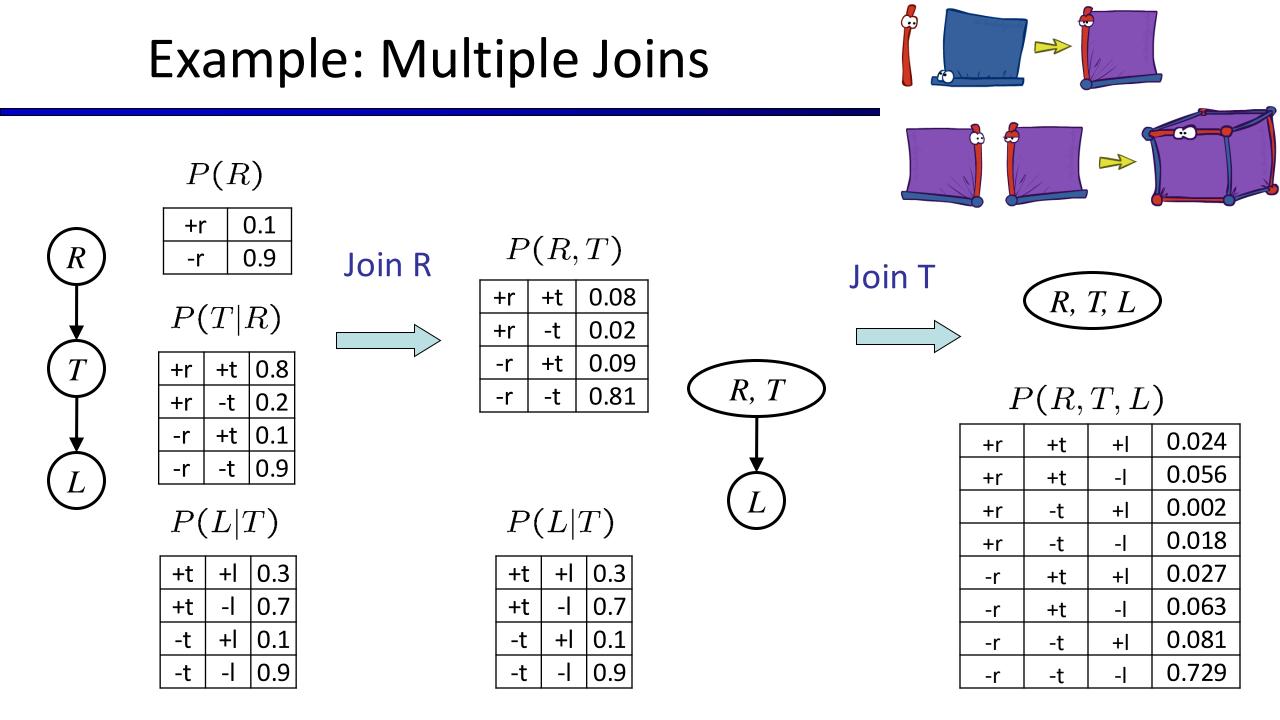


Example: Join on R



• Computation for each entry: pointwise products $\forall r,$

 $\forall r, t : P(r, t) = P(r) \cdot P(t|r)$

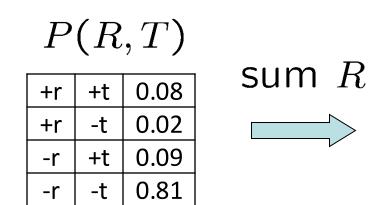


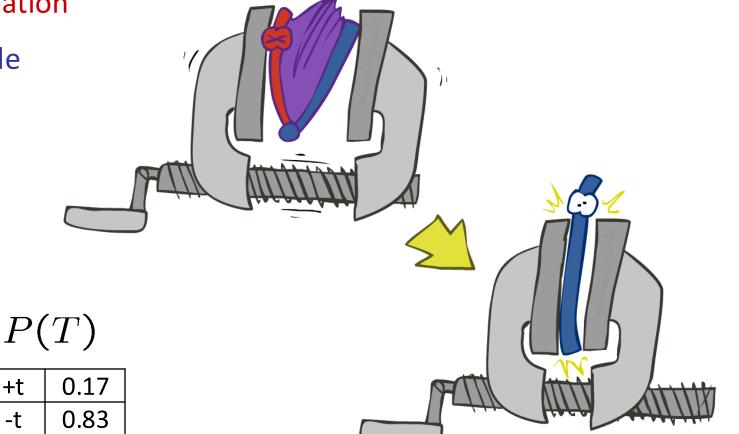
Operation 2: Eliminate

+t

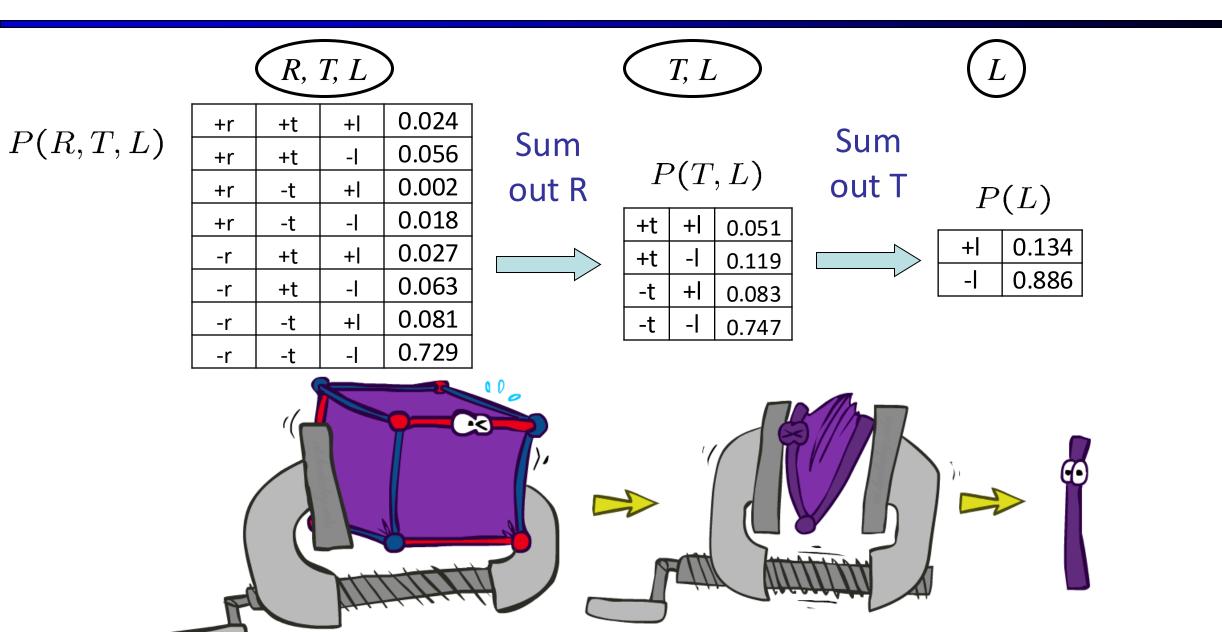
-t

- Second basic operation: marginalization
- Take a factor and sum out a variable
 - Shrinks a factor to a smaller one
 - A projection operation
- Example:

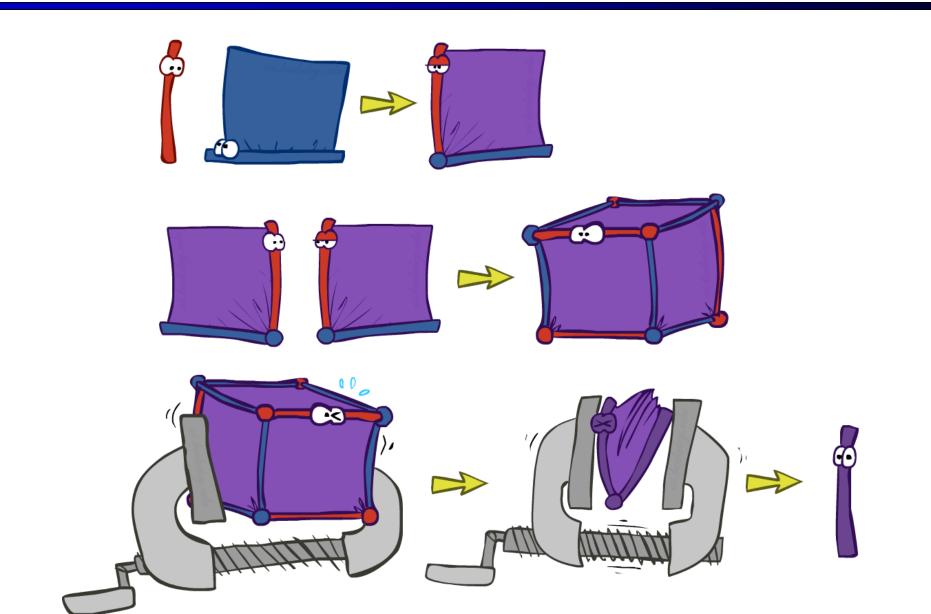




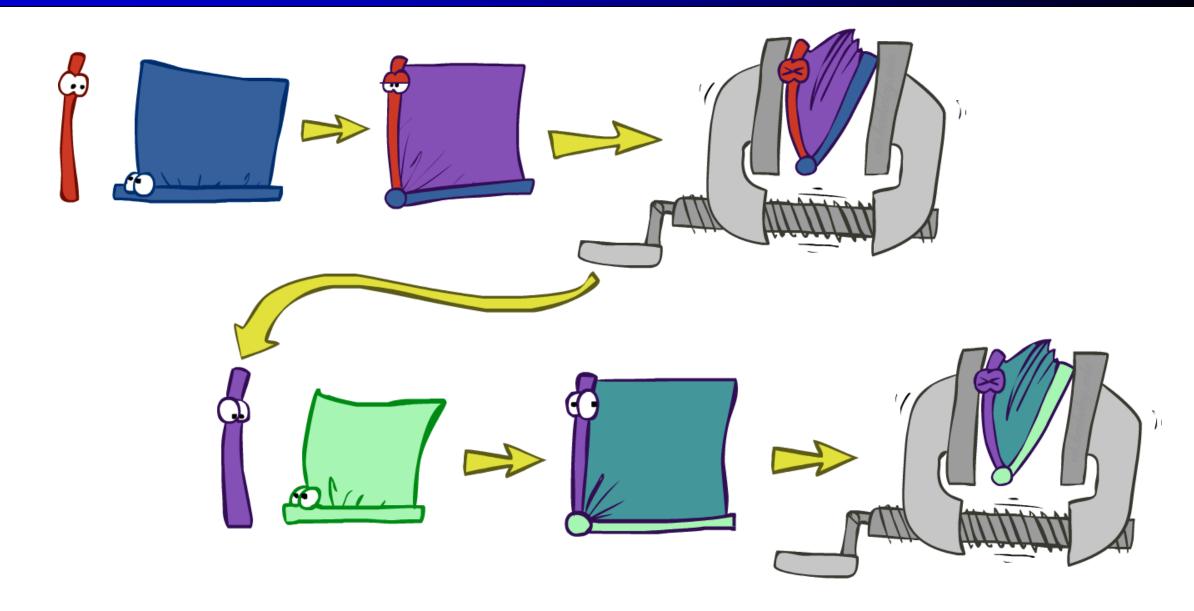
Multiple Elimination



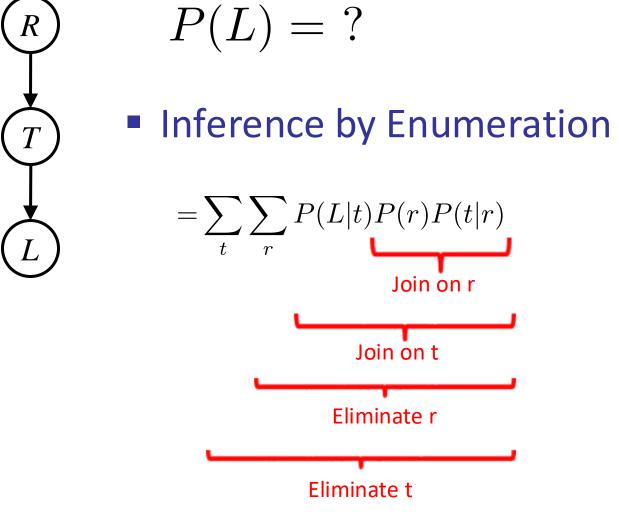
Thus Far: Multiple Join, Multiple Eliminate (= Inference by Enumeration)



Marginalizing Early (= Variable Elimination)



Traffic Domain

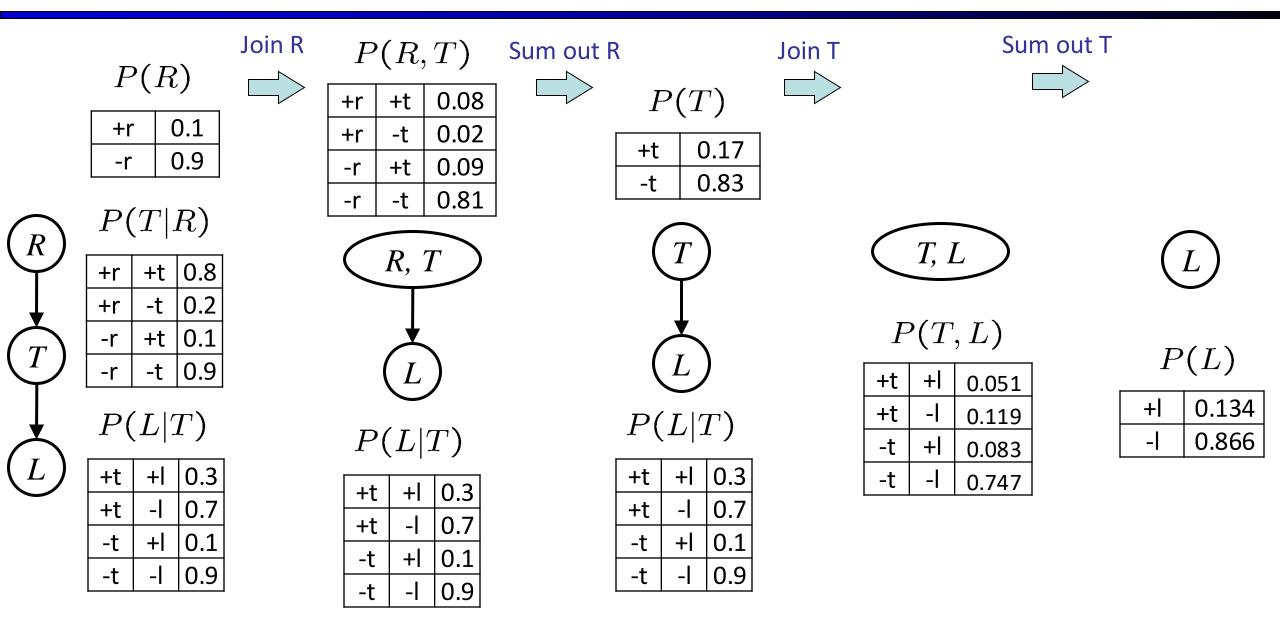


Variable Elimination

$$= \sum_{t} P(L|t) \sum_{r} P(r)P(t|r)$$

Join on r
Eliminate r
Eliminate t

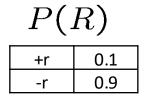
Marginalizing Early! (aka VE)

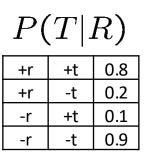


Evidence

If evidence, start with factors that select that evidence

• With no evidence, these are the initial factors:

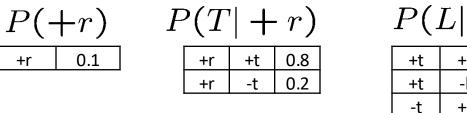


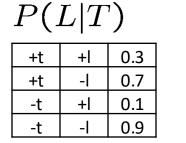


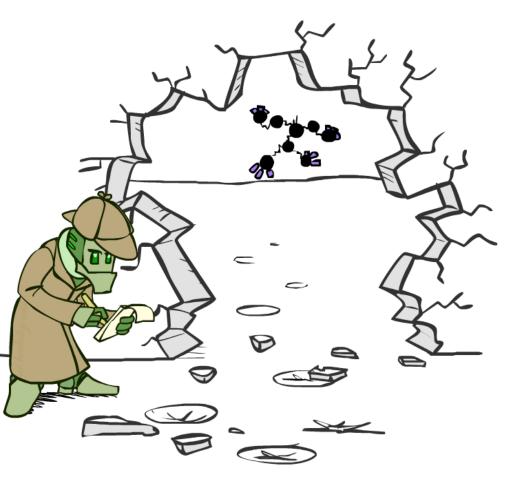
P(L I)				
+t	+	0.3		
+t	-	0.7		
-t	+	0.1		
-t	-	0.9		

D(T|T)

• For computing. P(L| + r), the initial factors become:



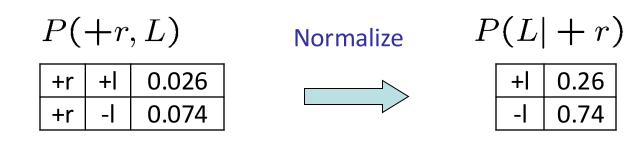




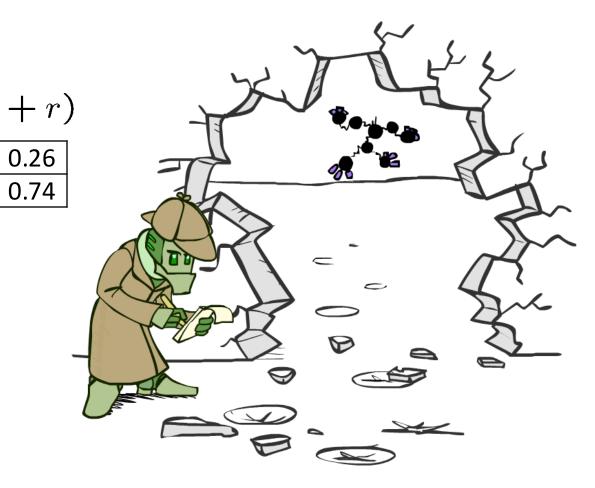
We eliminate all vars other than query + evidence

Evidence II

- Result will be a selected joint of query and evidence
 - E.g. for P(L | +r), we would end up with:

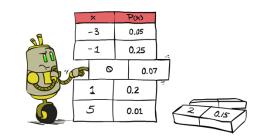


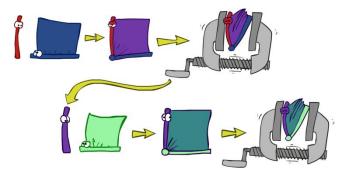
- To get our answer, just normalize this!
- That's it!



General Variable Elimination

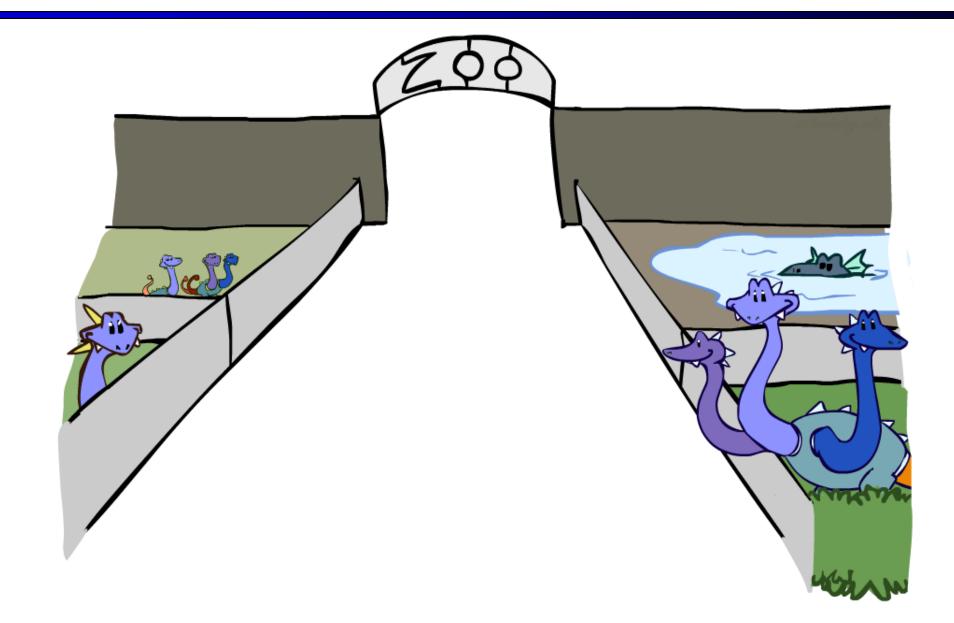
- Query: $P(Q|E_1 = e_1, \dots E_k = e_k)$
- Start with initial factors:
 - Local CPTs (but instantiated by evidence)
- While there are still hidden variables (not Q or evidence):
 - Pick a hidden variable H_i
 - Join all factors mentioning H_i
 - Eliminate (sum out) H_i
- Join all remaining factors and normalize







Factor Zoo



Factor Zoo I

- Joint distribution: P(X,Y)
 - Entries P(x,y) for all x, y
 - Sums to 1

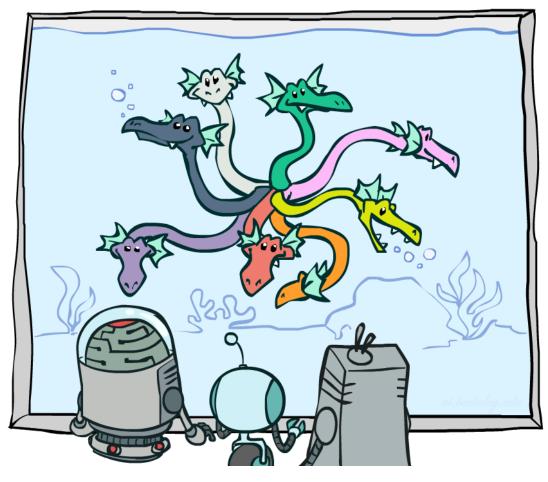
- Selected joint: P(x,Y)
 - A slice of the joint distribution
 - Entries P(x,y) for fixed x, all y
 - Sums to P(x)
- Number of capitals = dimensionality of the table

P(I, W)				
T W P				
hot	hot sun			
hot	rain	0.1		
cold	sun	0.2		
cold	rain	0.3		

D(TT TX)

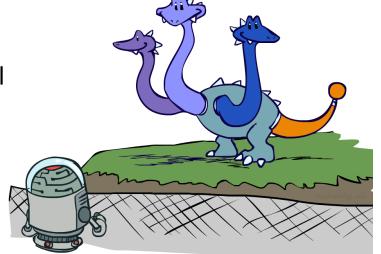
P(cold, W)

Т	W	Р
cold	sun	0.2
cold	rain	0.3



Factor Zoo II

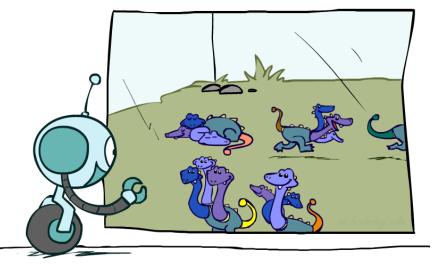
- Single conditional: P(Y | x)
 - Entries P(y | x) for fixed x, all
 - Sums to 1



P(W|cold)

Т	W	Ρ
cold	sun	0.4
cold	rain	0.6

- Family of conditionals:
 P(Y | X)
 - Multiple conditionals
 - Entries P(y | x) for all x, y
 - Sums to |X|



Т	W	Р		
hot	sun	0.8		
hot	rain	0.2	_	
cold	sun	0.4	-	
cold	rain	0.6		

P(W|T)

P(W|hot)

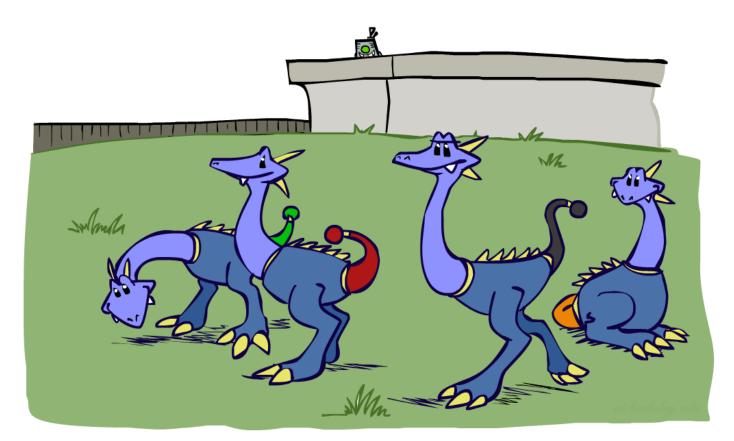
P(W|cold)

Factor Zoo III

- Specified family: P(y | X)
 - Entries P(y | x) for fixed y, but for all x
 - Sums to ... who knows!

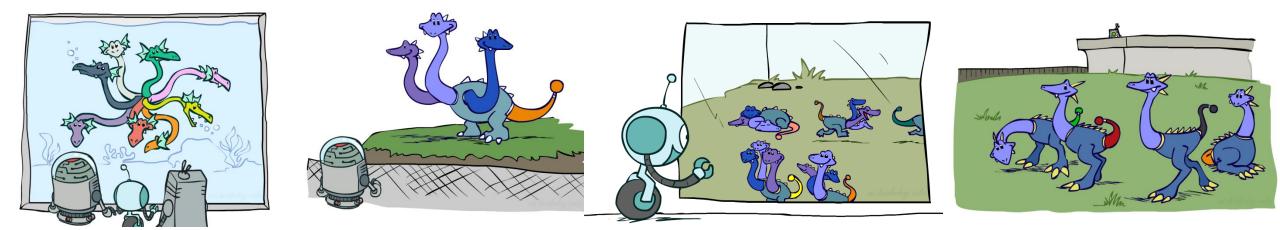
P(rain	T)
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Т	W	Р	
hot	rain	0.2	P(rain hot)
cold	rain	0.6	P(rain cold)

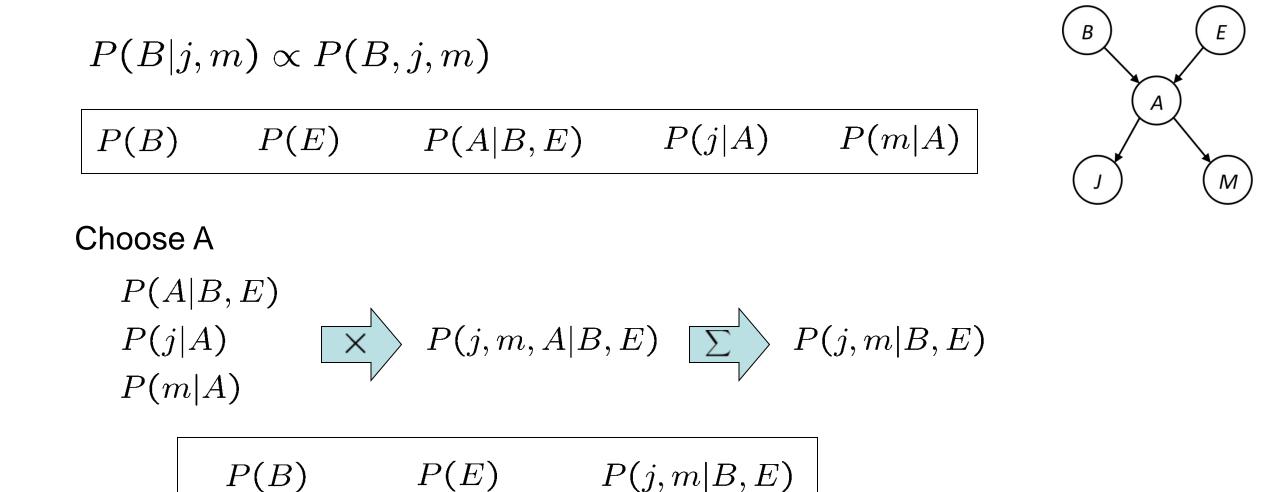


Factor Zoo Summary

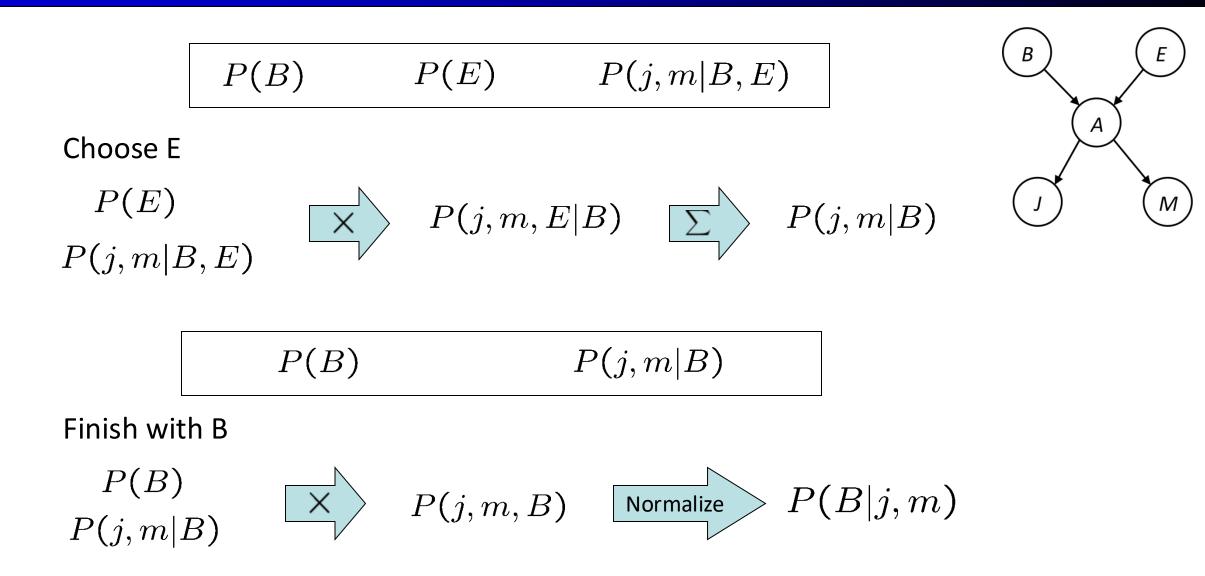
- In general, when we write $P(Y_1 ... Y_N | X_1 ... X_M)$
 - It is a "factor," a multi-dimensional array
 - Its values are $P(y_1 \dots y_N | x_1 \dots x_M)$
 - Any assigned (=lower-case) X or Y is a dimension selected from the array



Example



Example



Same Example in Equations

 $P(B|j,m) \propto P(B,j,m)$

$$P(B)$$
 $P(E)$ $P(A|B,E)$ $P(j|A)$ $P(m|A)$

 $P(B|j,m) \propto P(B,j,m)$

$$=\sum_{e,a}P(B,j,m,e,a)$$

$$= \sum_{e,a} P(B)P(e)P(a|B,e)P(j|a)P(m|a)$$

$$= \sum_{e} P(B)P(e) \sum_{a} P(a|B,e)P(j|a)P(m|a)$$

$$= \sum_{e} P(B)P(e)f_1(B, e, j, m)$$

$$= P(B) \sum_{e} P(e) f_1(B, e, j, m)$$
$$= P(B) f_2(B, j, m)$$

marginal obtained from joint by summing out use Bayes' net joint distribution expression use x*(y+z) = xy + xz

Α

Μ

joining on a, and then summing out gives f_1

use
$$x^*(y+z) = xy + xz$$

joining on e, and then summing out gives f_2

All we are doing is exploiting uwy + uwz + uxy + uxz + vwy + vwz + vxy +vxz = (u+v)(w+x)(y+z) to improve computational efficiency!

Another Variable Elimination Example

Query: $P(X_3|Y_1 = y_1, Y_2 = y_2, Y_3 = y_3)$

Start by inserting evidence, which gives the following initial factors:

 $p(Z)p(X_1|Z)p(X_2|Z)p(X_3|Z)p(y_1|X_1)p(y_2|X_2)p(y_3|X_3)$

Eliminate X_1 , this introduces the factor $f_1(Z, y_1) = \sum_{x_1} p(x_1|Z)p(y_1|x_1)$, and we are left with:

 $p(Z)f_1(Z, y_1)p(X_2|Z)p(X_3|Z)p(y_2|X_2)p(y_3|X_3)$

Eliminate X_2 , this introduces the factor $f_2(Z, y_2) = \sum_{x_2} p(x_2|Z)p(y_2|x_2)$, and we are left with:

 $p(Z)f_1(Z, y_1)f_2(Z, y_2)p(X_3|Z)p(y_3|X_3)$

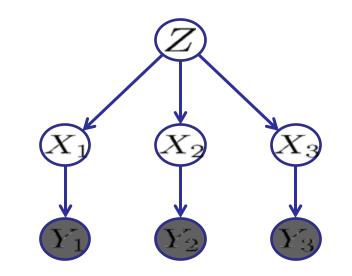
Eliminate Z, this introduces the factor $f_3(y_1, y_2, X_3) = \sum_z p(z) f_1(z, y_1) f_2(z, y_2) p(X_3|z)$, and we are left:

 $p(y_3|X_3), f_3(y_1, y_2, X_3)$

No hidden variables left. Join the remaining factors to get:

 $f_4(y_1, y_2, y_3, X_3) = P(y_3|X_3)f_3(y_1, y_2, X_3).$

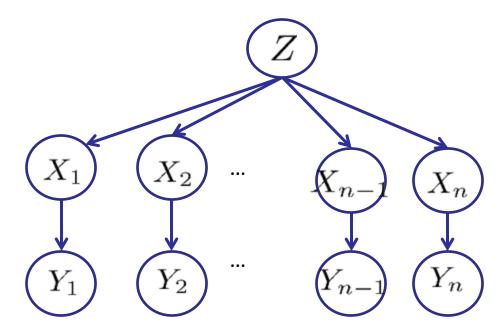
Normalizing over X_3 gives $P(X_3|y_1, y_2, y_3)$.



Computational complexity critically depends on the largest factor being generated in this process. Size of factor = number of entries in table. In example above (assuming binary) all factors generated are of size 2 --- as they all only have one variable (Z, Z, and X₃ respectively).

Variable Elimination Ordering

For the query P(X_n|y₁,...,y_n) work through the following two different orderings as done in previous slide: Z, X₁, ..., X_{n-1} and X₁, ..., X_{n-1}, Z. What is the size of the maximum factor generated for each of the orderings?



- Answer: 2ⁿ⁺¹ versus 2² (assuming binary)
- In general: the ordering can greatly affect efficiency.

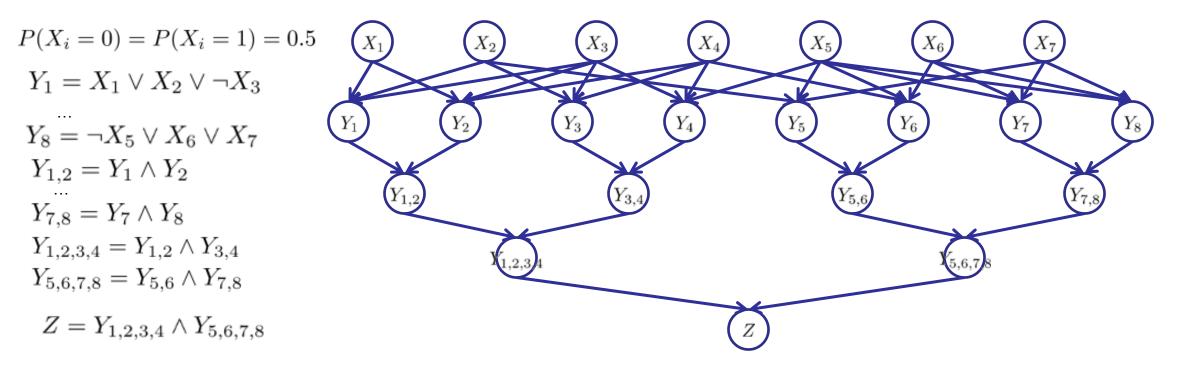
VE: Computational and Space Complexity

- The computational and space complexity of variable elimination is determined by the largest factor
- The elimination ordering can greatly affect the size of the largest factor.
 - E.g., previous slide's example 2ⁿ vs. 2
- Does there always exist an ordering that only results in small factors?
 - No!

Worst Case Complexity?

• CSP:

 $(x_1 \lor x_2 \lor \neg x_3) \land (\neg x_1 \lor x_3 \lor \neg x_4) \land (x_2 \lor \neg x_2 \lor x_4) \land (\neg x_3 \lor \neg x_4 \lor \neg x_5) \land (x_2 \lor x_5 \lor x_7) \land (x_4 \lor x_5 \lor x_6) \land (\neg x_5 \lor x_6 \lor \neg x_7) \land (\neg x_5 \lor \neg x_6 \lor x_7) \land (\neg x_5 \lor \neg x_6 \lor x_7) \land (\neg x_5 \lor \neg x_6 \lor \neg x_7) \land (\neg x_6 \lor \neg x_7) \land$



- If we can answer P(z) equal to zero or not, we answered whether the 3-SAT problem has a solution.
- Hence inference in Bayes' nets is NP-hard. No known efficient probabilistic inference in general.

Polytrees

- A polytree is a directed graph with no undirected cycles
- For poly-trees you can always find an ordering that is efficient
 - Try it!!
- Cut-set conditioning for Bayes' net inference
 - Choose set of variables such that if removed only a polytree remains
 - Exercise: Think about how the specifics would work out!

Bayes' Nets

- Representation
- Conditional Independences
 - Probabilistic Inference
 - Enumeration (exact, exponential complexity)
 - Variable elimination (exact, worst-case exponential complexity, often better)
 - ✓ Inference is NP-complete
 - Sampling (approximate)
 - Learning Bayes' Nets from Data