## CS 188: Artificial Intelligence

## Bayes Nets: Exact Inference



## Bayes Net Semantics

- A Bayes net is an efficient encoding of a probabilistic model of a domain
- A directed, acyclic graph, one node per random variable
- A conditional probability table (CPT) for each node
- A collection of distributions over $X$, one for each combination of parents' values

$$
P\left(X \mid a_{1} \ldots a_{n}\right)
$$



- Bayes' nets implicitly encode joint distributions
- As a product of local conditional distributions
- To see what probability a BN gives to a full assignment, multiply all the relevant conditionals together:

$$
P\left(x_{1}, x_{2}, \ldots x_{n}\right)=\prod_{i=1}^{n} P\left(x_{i} \mid \text { parents }\left(X_{i}\right)\right)
$$



## Size of a Bayes Net

- How big is a joint distribution over N Boolean variables?


## $2^{N}$

- How big is an N -node net if nodes have up to $k$ parents?
$\mathrm{O}\left(\mathrm{N}^{*} 2^{\mathrm{k}+1}\right)$
- Both give you the power to calculate

$$
P\left(X_{1}, X_{2}, \ldots X_{n}\right)
$$

- BNs: Huge space savings!
- Also easier to elicit local CPTs
- Also faster to answer queries (this lecture!)



## Causality?

- BNs need not actually be causal
- Sometimes no causal net exists over the domain (especially if variables are missing)
- E.g. consider the variables Traffic and Rain



## Example: Traffic

- Causal direction


| $P(T, R)$ |
| :---: |
| +r |
| +t $3 / 16$  <br> $+r$ -t $1 / 16$ <br> $-r$ +t $6 / 16$ <br> $-r$ -t $6 / 16$ |

## Example: Reverse Traffic

- Reverse causality?

$P(T, R)$

| $+r$ | +t | $3 / 16$ |
| :---: | :---: | :---: |
| +r | -t | $1 / 16$ |
| -r | +t | $6 / 16$ |
| -r | -t | $6 / 16$ |

## Causality?

- When Bayes' nets reflect the true causal patterns:
- Often simpler (nodes have fewer parents)
- Often easier to think about
- Often easier to estimate probabilities from data
- BNs need not actually be causal
- Sometimes no causal net exists over the domain
 (especially if variables are missing)
- E.g. consider the variables Traffic and Drips
- End up with arrows that reflect correlation, not causation
- What do the arrows really mean?
- Topology may happen to encode causal structure
- Topology really encodes conditional independence

$$
P\left(x_{i} \mid x_{1}, \ldots x_{i-1}\right)=P\left(x_{i} \mid \operatorname{parents}\left(X_{i}\right)\right)
$$

## Inference by Enumeration in Bayes Net

- Reminder of inference by enumeration:
- Any probability of interest can be computed by summing entries from the joint distribution: $\mathrm{P}(\boldsymbol{Q} \mid \boldsymbol{e})=\alpha \sum_{h} \mathrm{P}(\boldsymbol{Q}, \boldsymbol{h}, \boldsymbol{e})$
- Entries from the joint distribution can be obtained from a BN by multiplying the corresponding conditional probabilities
- $P(B \mid j, m)=\alpha \sum_{e, a} P(B, e, a, j, m)$
- $\quad=\alpha \sum_{e, a} P(B) P(e) P(a \mid B, e) P(j \mid a) P(m \mid a)$
- Problem: sums of exponentially many products!



## Variable elimination: The basic ideas

- Move summations inwards as far as possible
- $P(B \mid j, m)=\alpha \sum_{e, a} P(B) P(e) P(a \mid B, e) P(j \mid a) P(m \mid a)$

$$
=\alpha P(B) \sum_{e} P(e) \sum_{a} P(a \mid B, e) P(j \mid a) P(m \mid a)
$$

- Do the calculation from the inside out
- I.e., sum over a first, then sum over $e$

- Challenge: $P(a \mid B, e)$ isn't a single number, it's a table of different numbers (depending on the values of $B$ and $e$ )
- Solution: use arrays of numbers with appropriate operations on them; these are called factors


## Factor Zoo I

- Joint distribution: $\mathrm{P}(\mathrm{X}, \mathrm{Y})$
- Entries $P(x, y)$ for all $x, y$
- $|X| x|Y|$ matrix
- Sums to 1



## Number of variables (capitals) = dimensionality of the table

## Factor Zoo II

- Single conditional: $P(Y \mid x)$
- Entries P(y|x) for fixed $x$, all $y$
- Sums to 1

$P(J \mid a)$

| $\mathrm{A} \backslash \mathrm{J}$ | true | false |
| :---: | :---: | :---: |
| true | 0.9 | 0.1 |

- Family of conditionals: $P(X \mid Y)$
- Multiple conditionals
- Entries $P(x \mid y)$ for all $x, y$
- Sums to $|\mathrm{Y}|$

$P(J \mid A)$
$\left.\begin{array}{|c|c|c|}\hline A \backslash J & \text { true } & \text { false } \\ \hline \text { true } & 0.9 & 0.1 \\ \hline \text { false } & 0.05 & 0.95 \\ \hline\end{array}\right\}-P(J \mid a)$


## Operation 1: Pointwise product

- First basic operation: pointwise product of factors (not matrix multiply!)
- New factor has union of variables of the two original factors

- Each entry is the product of the corresponding entries from the original factors
- Example: $P(J \mid A) \times P(A)=P(A, J)$



## Example: Making larger factors



- Example: $P(A, J) \times P(M \mid A)=P(A, J, M)$
- Factor blowup can make VE very expensive!

| $P(A, J)$ |  |  |
| :---: | :---: | :---: |
| $\mathrm{A} \backslash J$ | true | false |
| true | 0.09 | 0.01 |
| false | 0.045 | 0.855 |


| $P(M \mid A)$ |  |  |
| :---: | :---: | :---: |
| $\mathbf{X}$$A \backslash M$ true false <br> true 0.7 0.3 <br> false 0.01 0.99 |  |  |

$$
P(A, J, M)
$$

$=$|  | $J \backslash M$ | true | false |
| :---: | :---: | :---: | :---: |
| $J \backslash M$ | true | false |  |
| true |  |  | 0.846 |
| false |  | 0.003 |  |

## Operation 2: Summing out a variable

- Second basic operation: summing out (or eliminating) a variable from a factor
- Shrinks a factor to a smaller one
- Example: $\sum_{j} P(A, J)=P(A, j)+P(A, \neg j)=P(A)$

| $P(A, J)$ |  |  |
| :---: | :---: | :---: |
| $A \backslash J$ | true | false |
| true | 0.09 | 0.01 |
| false | 0.045 | 0.855 |



## Variable Elimination



## Variable Elimination

- Query: $P\left(Q \mid E_{1}=e_{1}, . ., E_{k}=e_{k}\right)$
- Start with initial factors:
- Local CPTs (but instantiated by evidence)
- While there are still hidden variables (not Q or evidence):
- Pick a hidden variable $H_{j}$
- Eliminate (sum out) $H_{j}$ from the product of all factors mentioning $\mathrm{H}_{j}$

- Join all remaining factors and normalize

$$
\hat{\rho} \times=\square \times \alpha
$$

## Example

Query $P(B \mid j, m)$

$$
\begin{array}{lllll}
\hline P(B) & P(E) & P(A \mid B, E) & P(j \mid A) & P(m \mid A) \\
\hline
\end{array}
$$

Choose A

$$
\begin{aligned}
& P(A \mid B, E) \\
& P(j \mid A) \\
& P(m \mid A)
\end{aligned} \quad \boxed{x} \quad \sum>P(j, m \mid B, E)
$$

$P(B) \quad P(E) \quad P(j, m \mid B, E)$

## Example

## $\begin{array}{lll}P(B) & P(E) & P(j, m \mid B, E)\end{array}$

Choose E

$$
\begin{array}{ll}
P(E) \\
P(j, m \mid B, E)
\end{array} \stackrel{\times}{\sum>} P(j, m \mid B)
$$

$P(B) \quad P(j, m \mid B)$
Finish with B

$$
\begin{array}{lll}
P(B) \\
P(j, m \mid B)
\end{array} \stackrel{x}{P} \quad P(j, m, B) \underset{\sim}{\text { Normalize }} P P(B \mid j, m)
$$



## Summing out from a product of factors

- Project the factors each way first, then sum the products
- Example: $\sum_{a} P(a \mid B, e) \times P(j \mid a) \times P(m \mid a)$

$$
\begin{aligned}
= & P(a \mid B, e) \times P(j \mid a) \times P(m \mid a)+ \\
& P(\neg a \mid B, e) \times P(j \mid \neg a) \times P(m \mid \neg a)
\end{aligned}
$$



## Order matters

- Order the terms Z, A, B C, D
- $P(D)=\alpha \sum_{z, a, b, c} P(z) P(a \mid z) P(b \mid z) P(c \mid z) P(D \mid z)$
- $\quad=\alpha \sum_{z} P(z) \sum_{a} P(a \mid z) \sum_{b} P(b \mid z) \sum_{c} P(c \mid z) P(D \mid z)$
- Largest factor has 2 variables (D,Z)
- Order the terms A, B C, D, Z
- $P(D)=\alpha \sum_{a, b, c, z} P(a \mid z) P(b \mid z) P(c \mid z) P(D \mid z) P(z)$
- $\quad=\alpha \sum_{a} \sum_{b} \sum_{c} \sum_{z} P(a \mid z) P(b \mid z) P(c \mid z) P(D \mid z) P(z)$
- Largest factor has 4 variables (A,B,C,D)
- In general, with $n$ leaves, factor of size $2^{n}$


## VE: Computational and Space Complexity

- The computational and space complexity of variable elimination is determined by the largest factor (and it's space that kills you)
- The elimination ordering can greatly affect the size of the largest factor.
- E.g., previous slide's example $2^{n}$ vs. 2
- Does there always exist an ordering that only results in small factors?
- No!


## Worst Case Complexity? Reduction from SAT



- Variables: $W, X, Y, Z$
- CNF clauses:

1. $C_{1}=W \vee X \vee Y$
2. $C_{2}=Y \vee Z \vee \neg W$
3. $C_{3}=X \vee Y \vee \neg Z$

- Sentence $S=C_{1} \wedge C_{2} \wedge C_{3}$
- $P(S)>0$ iff $S$ is satisfiable - => NP-hard
- $P(S)=K \times 0.5^{n}$ where $K$ is the number of satisfying assignments for clauses
- =>\#P-hard


## Polytrees

- A polytree is a directed graph with no undirected cycles
- For poly-trees the complexity of variable elimination is linear in the network size if you eliminate from the leave towards the roots



## Bayes Nets

## Part I: Representation

## Part II: Exact inference

- Enumeration (always exponential complexity)
- Variable elimination (worst-case exponential complexity, often better)
- Inference is NP-hard in general

Part III: Independence

Part IV: Approximate Inference

