Exam Prep 2A

Q1. Search: Algorithms



(a) Consider the search graph and heuristics shown above. Select **all** of the goals that **could** be returned by each of the search algorithms below. For this question, if there is a tie on the fringe, assume the tie is broken **randomly**.

B C S

0 0

7

7

7

0

7

7

1 7

1

1

(i) DFS		$G_1 \bigcirc$	G_2 \bigcirc	G_3 \bigcirc
(ii) BFS		G_1 \bigcirc	G_2 \bigcirc	G_3 \bigcirc
(iii) UCS		G_1 \bigcirc	G_2 \bigcirc	G_3 ()
(iv) Greedy with	H-1	G_1 \bigcirc	G_2 \bigcirc	G_3 ()
(v) Greedy with	H-2	G_1 \bigcirc	G_2 \bigcirc	G_3 \bigcirc
(vi) Greedy with	H-3	G_1 \bigcirc	G_2 \bigcirc	G_3 \bigcirc
(vii) A* with H-2		G_1 \bigcirc	G_2 \bigcirc	G_3 ()
(viii) A* with H-3	3	$G_1 \bigcirc$	G_2 \bigcirc	G_3 ()

(b) For each heuristic, indicate whether it is consistent, admissible, or neither (select more than one option if appropriate):

Neither 🔾	Admissible 🔘	Consistent 🔾	(i) H-1
Neither 🔾	Admissible 🔾	Consistent 🔾	(ii) H-2
Neither 🔾	Admissible 🔾	Consistent 🔾	(iii) H-3
Neither 〇	Admissible 🔘	Consistent ()	(iv) H-4

Q2. Searching with Heuristics

Consider the A* searching process on the connected undirected graph, with starting node S and the goal node G. Suppose the cost for each connection edge is **always positive**. We define $h^*(X)$ as the shortest (optimal) distance to G from a node X.

Answer Questions (a), (b) and (c). You may want to solve Questions (a) and (b) at the same time.

- (a) Suppose h is an admissible heuristic, and we conduct A* tree search using heuristic h' and finally find a solution. Let C be the cost of the found path (directed by h', defined in part (a)) from S to G
 - (i) Choose one best answer for each condition below.
 - 1. If $h'(X) = \frac{1}{2}h(X)$ for all Node X, then
 - 2. If $h'(X) = \frac{h(X) + h^*(X)}{2}$ for all Node X, then $\bigcirc C = h^*(S) \bigcirc C > h^*(S) \bigcirc C \ge h^*(S)$
 - 3. If $h'(X) = h(X) + h^*(X)$ for all Node X, then
 - 4. If we define the set K(X) for a node X as all its neighbor nodes Y satisfying $h^*(X) > h^*(Y)$, and the following always holds

$$h'(X) \le \begin{cases} \min_{Y \in K(X)} h'(Y) - h(Y) + h(X) & \text{if } K(X) \neq \emptyset \\ h(X) & \text{if } K(X) = \emptyset \end{cases}$$

then,

5. If *K* is the same as above, we have

$$h'(X) = \begin{cases} \min_{Y \in K(X)} h(Y) + cost(X, Y) & \text{if } K(X) \neq \emptyset \\ h(X) & \text{if } K(X) = \emptyset \end{cases}$$

where cost(X, Y) is the cost of the edge connecting X and Y, then, $\bigcirc C = h^*(S) \bigcirc C > h^*(S) \bigcirc C \ge h^*(S)$

- 6. If $h'(X) = \min_{Y \in K(X) + \{X\}} h(Y)$ (K is the same as above), $\bigcirc C = h^*(S) \bigcirc C > h^*(S) \bigcirc C \ge h^*(S)$
- (ii) In which of the conditions above, h' is still **admissible** and for sure to dominate h? Check all that apply. Remember we say h_1 dominates h_2 when $h_1(X) \ge h_2(X)$ holds for all X. \Box 1 \Box 2 \Box 3 \Box 4 \Box 5 \Box 6
- (b) Suppose h is a consistent heuristic, and we conduct A^* graph search using heuristic h' and finally find a solution.
 - (i) Answer exactly the same questions for each conditions in Question (a)(i).
 - 1. $\bigcirc C = h^*(S) \bigcirc C > h^*(S) \bigcirc C \ge h^*(S)$ 3. $\bigcirc C = h^*(S) \bigcirc C > h^*(S) \bigcirc C \ge h^*(S)$ 4. $\bigcirc C = h^*(S) \bigcirc C > h^*(S) \bigcirc C \ge h^*(S)$
 - 5. $\bigcirc C = h^*(S) \bigcirc C > h^*(S) \bigcirc C \ge h^*(S)$
- $\begin{array}{cccc} & 4. & \bigcirc & C = h^*(S) & \bigcirc & C > h^*(S) & \bigcirc & C \ge h^*(S) \\ & 6. & \bigcirc & C = h^*(S) & \bigcirc & C > h^*(S) & \bigcirc & C \ge h^*(S) \end{array}$

 $\bigcirc C = h^*(S) \bigcirc C > h^*(S) \bigcirc C \ge h^*(S)$

 $\bigcirc C = h^*(S) \bigcirc C > h^*(S) \bigcirc C > h^*(S)$

 $\bigcirc C = h^*(S) \bigcirc C > h^*(S) \bigcirc C > h^*(S)$

(ii) In which of the conditions above, h' is still **consistent** and for sure to dominate h? Check all that apply.

- (c) Suppose h is an **admissible** heuristic, and we conduct A* **tree search** using heuristic h' and finally find a solution.
 - If $\epsilon > 0$, and X_0 is a node in the graph, and h' is a heuristic such that

$$h'(X) = \begin{cases} h(X) & \text{if } X = X_0\\ h(X) + \epsilon & \text{otherwise} \end{cases}$$

- Alice claims h' can be inadmissible, and hence $C = h^*(S)$ does not always hold.
- Bob instead thinks the node expansion order directed by h' is the same as the heuristic h'', where

$$h''(X) = \begin{cases} h(X) - \epsilon & \text{if } X = X_0 \\ h(X) & \text{if otherwise} \end{cases}$$

Since h'' is admissible and will lead to $C = h^*(S)$, and so does h'. Hence, $C = h^*(S)$ always holds.

The two conclusions (<u>underlined</u>) apparently contradict with each other, and **only exactly one of them are correct and the other is wrong**. Choose the **best** explanation from below - which student's conclusion is wrong, and why are they wrong?

 \bigcirc Alice's conclusion is wrong, because the heuristic h' is always admissible.

Alice's conclusion is wrong, because an inadmissible heuristics does not necessarily always lead to the failure of the optimality when conducting A* tree search.

○ Alice's conclusion is wrong, because of another reason that is not listed above.

 \bigcirc Bob's conclusion is wrong, because the node visiting expansion ordering of h'' during searching might not be the same as h'.

 \bigcirc Bob's conclusion is wrong, because the heuristic h'' might lead to an incomplete search, regardless of its optimally property.

O Bob's conclusion is wrong, because of another reason that is not listed above.