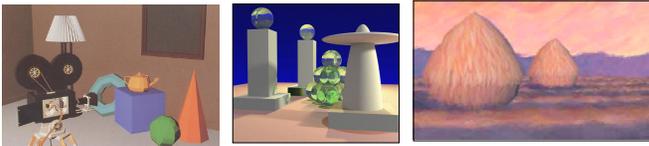


# Advanced Computer Graphics (Fall 2009)

CS 283, Lecture 11: Monte Carlo Integration

Ravi Ramamoorthi

<http://inst.eecs.berkeley.edu/~cs283>



Acknowledgements and many slides courtesy:  
Thomas Funkhouser, Szymon Rusinkiewicz and Pat Hanrahan

## Motivation

Rendering = integration

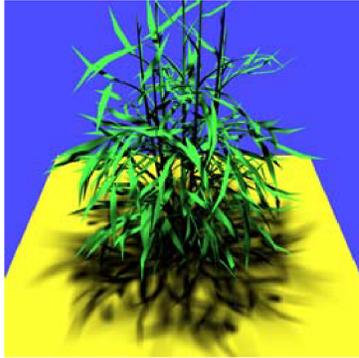
- Reflectance equation: Integrate over incident illumination
- Rendering equation: Integral equation

Many sophisticated shading effects involve integrals

- Antialiasing
- Soft shadows
- Indirect illumination
- Caustics

## Example: Soft Shadows

$$E(x) = \int_{H^2} L_i(x, \omega) \cos \theta d\omega$$



### Challenges

- Visibility and blockers
- Varying light distribution
- Complex source geometry

Source: Agrawala, Ramamoorthi, Heirich, Moll, 2000

## Monte Carlo

- Algorithms based on statistical sampling and random numbers
- Coined in the beginning of 1940s. Originally used for neutron transport, nuclear simulations
  - Von Neumann, Ulam, Metropolis, ...
- Canonical example: 1D integral done numerically
  - Choose a set of random points to evaluate function, and then average (expectation or statistical average)

## Monte Carlo Algorithms

### Advantages

- Robust for complex integrals in computer graphics (irregular domains, shadow discontinuities and so on)
- Efficient for high dimensional integrals (common in graphics: time, light source directions, and so on)
- Quite simple to implement
- Work for general scenes, surfaces
- Easy to reason about (but care taken re statistical bias)

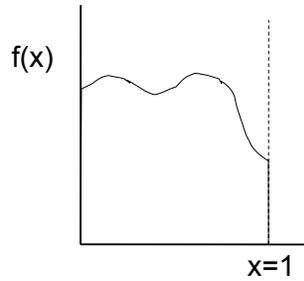
### Disadvantages

- Noisy
- Slow (many samples needed for convergence)
- Not used if alternative analytic approaches exist (but those are rare)

## Outline

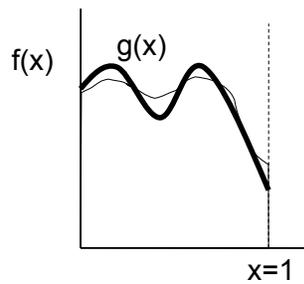
- Motivation
- *Overview, 1D integration*
- Basic probability and sampling
- Monte Carlo estimation of integrals

## Integration in 1D



Slide courtesy of  
Peter Shirley

## We can approximate



Standard integration methods like trapezoidal rule and Simpsons rule

Advantages:

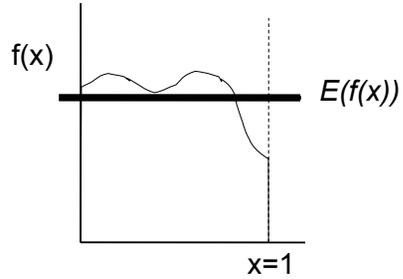
- Converges fast for **smooth** integrands
- Deterministic

Disadvantages:

- Exponential complexity in many dimensions
- Not rapid convergence for discontinuities

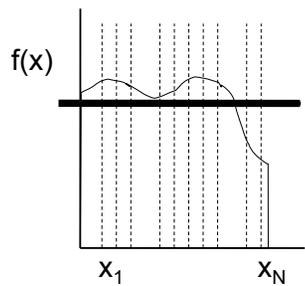
Slide courtesy of  
Peter Shirley

## Or we can average



Slide courtesy of  
Peter Shirley

## Estimating the average



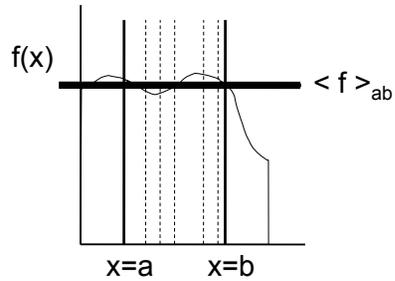
Monte Carlo methods (random choose samples)

Advantages:

- Robust for discontinuities
- Converges reasonably for large dimensions
- Can handle complex geometry, integrals
- Relatively simple to implement, reason about

Slide courtesy of  
Peter Shirley

## Other Domains

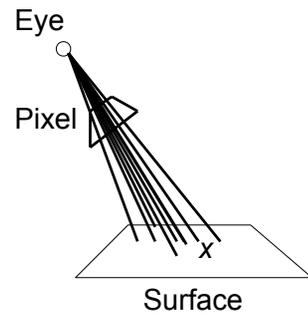


Slide courtesy of  
Peter Shirley

## Multidimensional Domains

Same ideas apply for integration over ...

- Pixel areas
- Surfaces
- Projected areas
- Directions
- Camera apertures
- Time
- Paths



## Outline

- Motivation
- Overview, 1D integration
- *Basic probability and sampling*
- Monte Carlo estimation of integrals

## Random Variables

- Describes possible outcomes of an experiment
- In discrete case, e.g. value of a dice roll [ $x = 1-6$ ]
- Probability  $p$  associated with each  $x$  ( $1/6$  for dice)
- Continuous case is obvious extension

## Expected Value

- Expectation
- For Dice example:

## Continuous Probability Distributions

**PDF**  $p(x)$

$$p(x) \geq 0$$

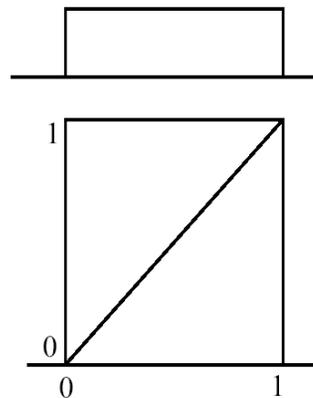
**CDF**  $P(x)$

$$P(x) = \int_0^x p(x) dx$$

$$P(x) = \Pr(X < x) \quad P(1) = 1$$

$$\Pr(\alpha \leq X \leq \beta) = \int_{\alpha}^{\beta} p(x) dx$$
$$= P(\beta) - P(\alpha)$$

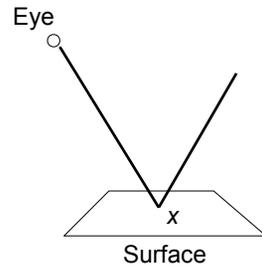
Uniform



## Sampling Techniques

Problem: how do we generate random points/  
directions during path tracing?

- Non-rectilinear domains
- Importance (BRDF)
- Stratified



## Generating Random Points

Uniform distribution:

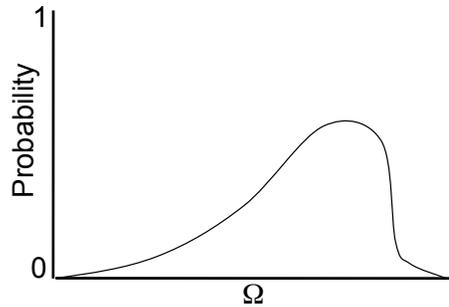
- Use random number generator



## Generating Random Points

Specific probability distribution:

- Function inversion
- Rejection
- Metropolis



## Common Operations

Want to **sample** probability distributions

- Draw samples distributed according to probability
- Useful for integration, picking important regions, etc.

Common distributions

- Disk or circle
- Uniform
- Upper hemisphere for visibility
- Area luminaire
- Complex lighting like an environment map
- Complex reflectance like a BRDF

## Sampling Continuous Distributions

### Cumulative probability distribution function

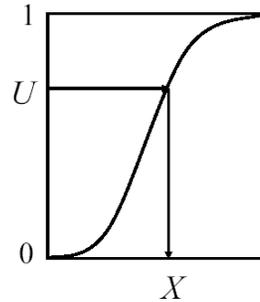
$$P(x) = \Pr(X < x)$$

### Construction of samples

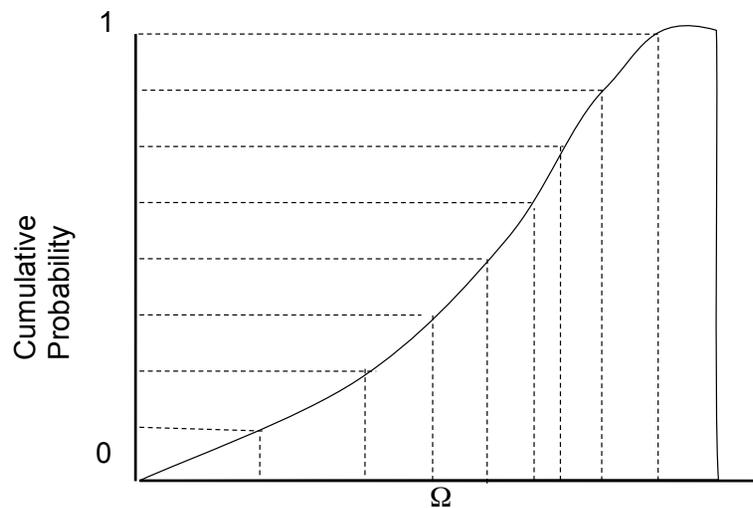
$$\text{Solve for } X = P^{-1}(U)$$

### Must know:

1. The integral of  $p(x)$
2. The inverse function  $P^{-1}(x)$



## Generating Random Points



## Example: Power Function

### Assume

$$p(x) = (n+1)x^n$$

$$\int_0^1 x^n dx = \frac{x^{n+1}}{n+1} \Big|_0^1 = \frac{1}{n+1}$$

$$P(x) = x^{n+1}$$

$$X \sim p(x) \Rightarrow X = P^{-1}(U) = \sqrt[n+1]{U}$$

### Trick

$$Y = \max(U_1, U_2, \dots, U_n, U_{n+1})$$

$$\Pr(Y < x) = \prod_{i=1}^{n+1} \Pr(U_i < x) = x^{n+1}$$

## Sampling a Circle

Unit radius circle

$$A = \int_0^{2\pi} \int_0^1 r dr d\theta = \int_0^1 r dr \int_0^{2\pi} d\theta = \left( \frac{r^2}{2} \right) \Big|_0^1 \theta \Big|_0^{2\pi} = \pi$$

$$p(r, \theta) dr d\theta = \frac{1}{\pi} r dr d\theta \Rightarrow p(r, \theta) = \frac{r}{\pi}$$

$$p(r, \theta) = p(r)p(\theta)$$

$$p(\theta) = \frac{1}{2\pi}$$

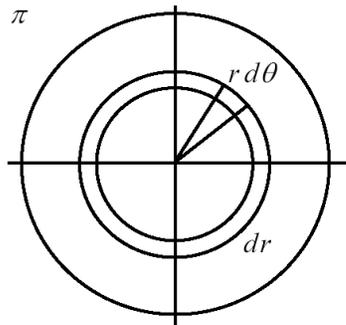
$$\theta = 2\pi U_1$$

$$P(\theta) = \frac{1}{2\pi} \theta$$

$$p(r) = 2r$$

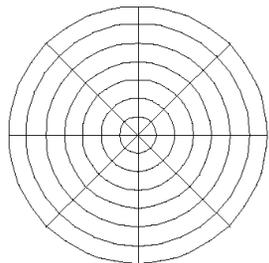
$$r = \sqrt{U_2}$$

$$P(r) = r^2$$



## Sampling a Circle

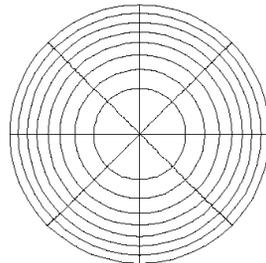
**WRONG**  $\neq$  Equi-Areal



$$\theta = 2\pi U_1$$

$$r = U_2$$

**RIGHT** = Equi-Areal



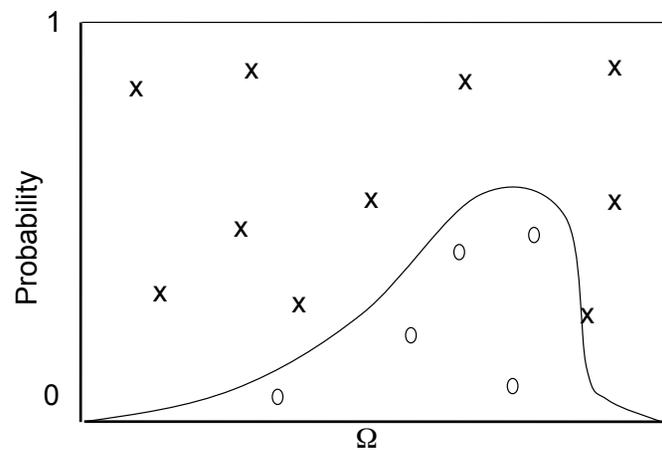
$$\theta = 2\pi U_1$$

$$r = \sqrt{U_2}$$

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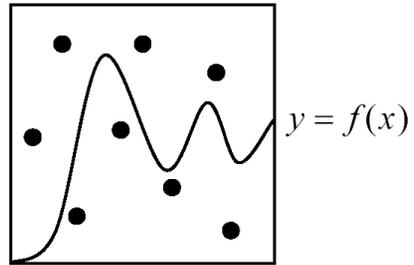
## Rejection Sampling



## Rejection Methods

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$$I = \int_0^1 f(x) dx$$
$$= \iint_{y < f(x)} dx dy$$



### Algorithm

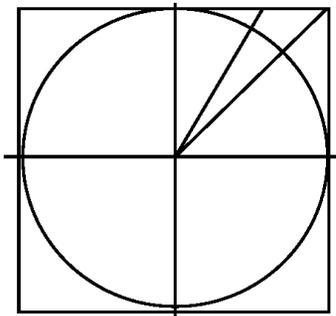
Pick  $U_1$  and  $U_2$

Accept  $U_1$  if  $U_2 < f(U_1)$

**Wasteful? Efficiency = Area / Area of rectangle**

## Sampling a Circle: Rejection

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```
do {  
  X=1-2*U1  
  Y=1-2*U2  
while( X2+ Y2 >1 )
```

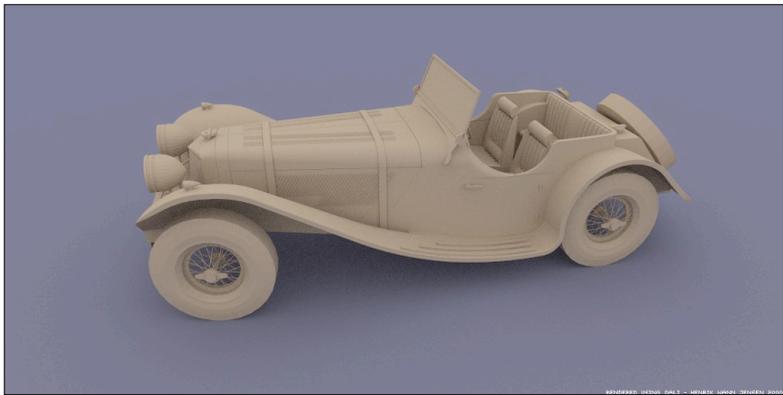
**May be used to pick random 2D directions**

**Circle techniques may also be applied to the sphere**

## Outline

- Motivation
- Overview, 1D integration
- Basic probability and sampling
- *Monte Carlo estimation of integrals*

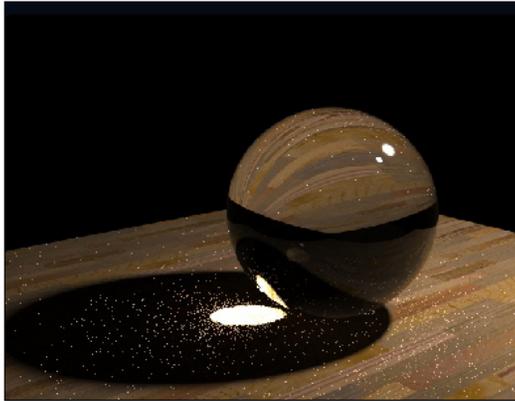
## Monte Carlo Path Tracing



Big diffuse light source, 20 minutes

Motivation for rendering in graphics: Covered in detail in next lecture

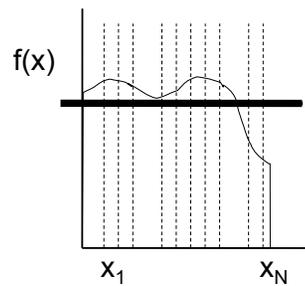
## Monte Carlo Path Tracing



1000 paths/pixel

Jensen

## Estimating the average



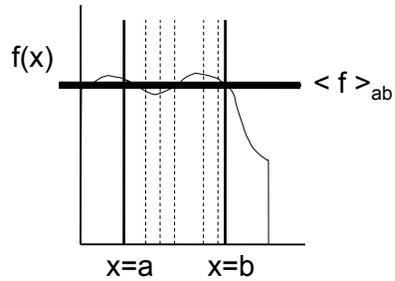
Monte Carlo methods (random choose samples)

$E(f(x))$  Advantages:

- Robust for discontinuities
- Converges reasonably for large dimensions
- Can handle complex geometry, integrals
- Relatively simple to implement, reason about

Slide courtesy of Peter Shirley

## Other Domains



Slide courtesy of  
Peter Shirley

## More formally

**Definite integral**  $I(f) \equiv \int_0^1 f(x) dx$

**Expectation of  $f$**   $E[f] \equiv \int_0^1 f(x) p(x) dx$

**Random variables**  $X_i \sim p(x)$   
 $Y_i = f(X_i)$

**Estimator**  $F_N = \frac{1}{N} \sum_{i=1}^N Y_i$

## Unbiased Estimator

$$E[F_N] = I(f)$$

$$\begin{aligned} E[F_N] &= E\left[\frac{1}{N} \sum_{i=1}^N Y_i\right] \\ &= \frac{1}{N} \sum_{i=1}^N E[Y_i] = \frac{1}{N} \sum_{i=1}^N E[f(X_i)] \\ &= \frac{1}{N} \sum_{i=1}^N \int_0^1 f(x) p(x) dx \\ &= \frac{1}{N} \sum_{i=1}^N \int_0^1 f(x) dx \\ &= \int_0^1 f(x) dx \end{aligned}$$

### Properties

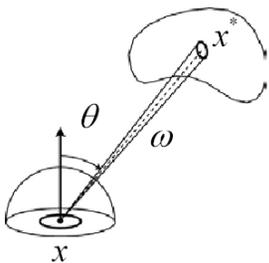
$$E\left[\sum_i Y_i\right] = \sum_i E[Y_i]$$

$$E[aY] = aE[Y]$$

Assume uniform probability distribution for now

## Direct Lighting - Directional Sampling

$$E(x) = \int_{\Omega} L(x, \omega) \cos \theta d\omega$$



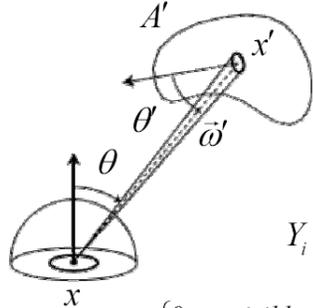
Ray intersection  $x^*(x, \omega)$

Sample  $\omega$  uniformly by  $\Omega$

$$Y_i = L(x^*(x, \omega_i), -\omega_i) \cos \theta 2\pi$$

## Direct Lighting - Area Sampling

$$E(x) = \int_{\Omega} L_i(x, \omega) \cos \theta d\omega = \int_{A'} L_o(x', \omega') V(x, x') \frac{\cos \theta \cos \theta'}{|x - x'|^2} dA'$$



**Ray direction**  $\omega' = x - x'$

**Sample  $x'$  uniformly by  $A'$**

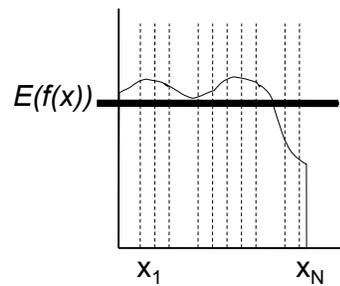
$$Y_i = L_o(x'_i, \omega'_i) V(x, x'_i) \frac{\cos \theta \cos \theta'_i}{|x - x'_i|^2} A$$

$$V(x, x') = \begin{cases} 0 & \text{-visible} \\ 1 & \text{visible} \end{cases}$$

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## Variance



## Variance

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### Definition

$$\begin{aligned}V[Y] &\equiv E[(Y - E[Y])^2] \\ &= E[Y^2 - 2YE[Y] + E[Y]^2] \\ &= E[Y^2] - E[Y]^2\end{aligned}$$

### Properties

$$V[\sum_i Y_i] = \sum_i V[Y_i]$$

$$V[aY] = a^2 V[Y]$$

### Variance decreases with sample size

$$V\left[\frac{1}{N} \sum_{i=1}^N Y_i\right] = \frac{1}{N^2} \sum_{i=1}^N V[Y_i] = \frac{1}{N} V[Y]$$

CS348B Lecture 6

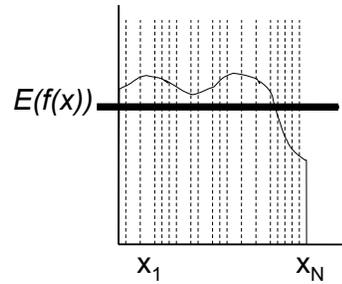
Pat Hanrahan, Spring 2004

## Variance for Dice Example?

- Work out on board (variance for single dice roll)

Exercise for students at home.

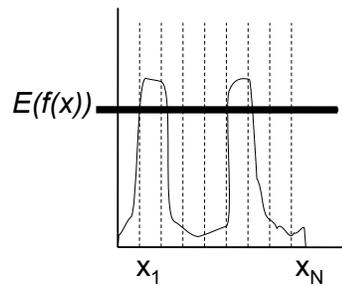
## Variance



Variance decreases as  $1/N$   
Error decreases as  $1/\sqrt{N}$

## Variance

- Problem: variance decreases with  $1/N$ 
  - Increasing # samples removes noise slowly



## Variance Reduction

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### Efficiency measure

$$\text{Efficiency} \propto \frac{1}{\text{Variance} \bullet \text{Cost}}$$

### Techniques

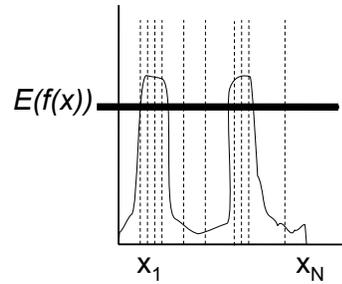
- Importance sampling
- Sampling patterns: stratified, ...

## Variance Reduction Techniques

- Importance sampling
- Stratified sampling

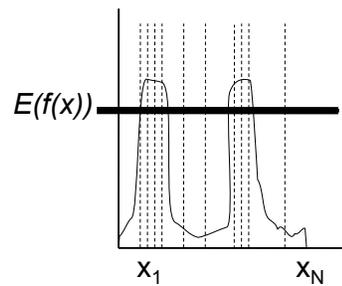
## Importance Sampling

Put more samples where  $f(x)$  is bigger



## Importance Sampling

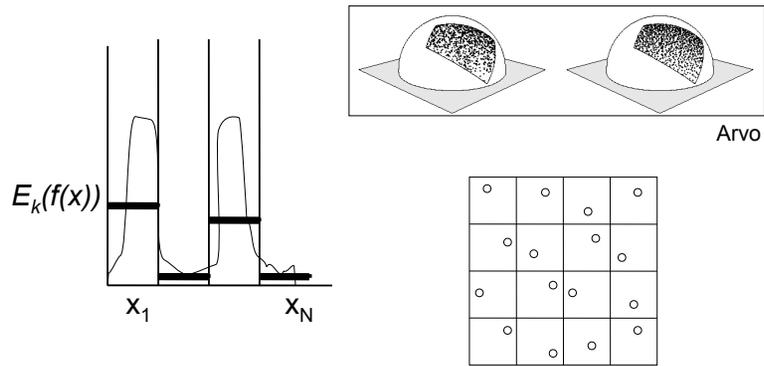
- This is still unbiased



for all  $N$

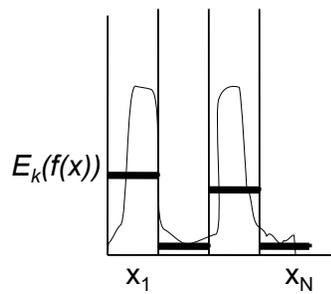
## Stratified Sampling

- Estimate subdomains separately



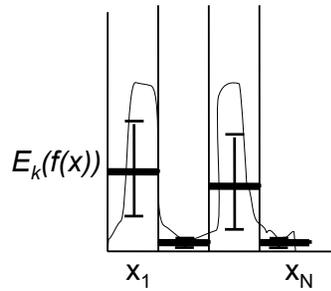
## Stratified Sampling

- This is still unbiased



## Stratified Sampling

- Less overall variance if less variance in subdomains



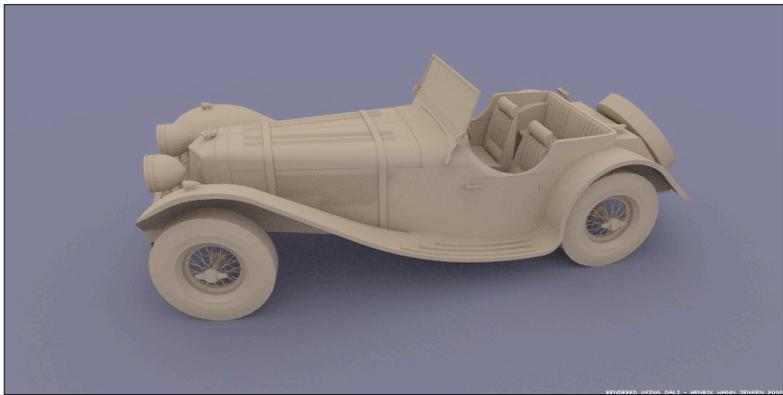
## More Information

- Veach PhD thesis chapter (linked to from website)
- Course Notes (links from website)
  - *Mathematical Models for Computer Graphics*, Stanford, Fall 1997
  - *State of the Art in Monte Carlo Methods for Realistic Image Synthesis*, Course 29, SIGGRAPH 2001

## Motivation

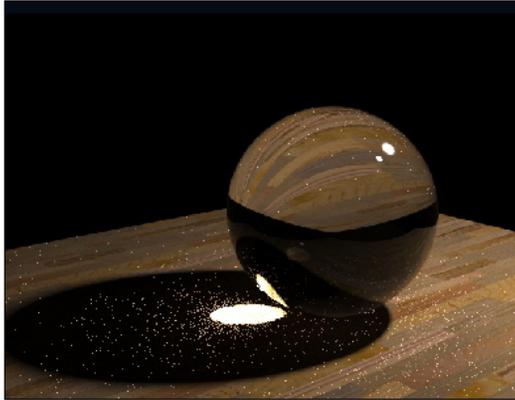
- General solution to rendering and global illumination
- Suitable for a variety of general scenes
- Based on Monte Carlo methods
- Enumerate all paths of light transport

## Monte Carlo Path Tracing



Big diffuse light source, 20 minutes

## Monte Carlo Path Tracing



1000 paths/pixel

Jensen

## Monte Carlo Path Tracing

### Advantages

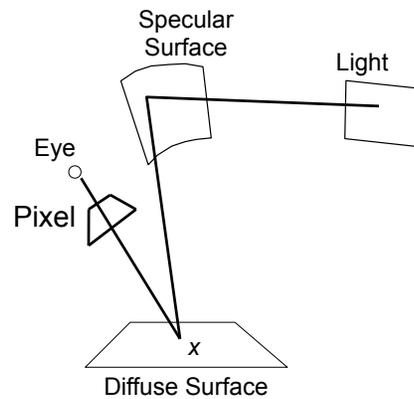
- Any type of geometry (procedural, curved, ...)
- Any type of BRDF (specular, glossy, diffuse, ...)
- Samples all types of paths (L(SD)\*E)
- Accuracy controlled at pixel level
- Low memory consumption
- Unbiased - error appears as noise in final image

### Disadvantages (standard Monte Carlo problems)

- Slow convergence (square root of number of samples)
- Noise in final image

## Monte Carlo Path Tracing

Integrate radiance for each pixel by sampling paths randomly



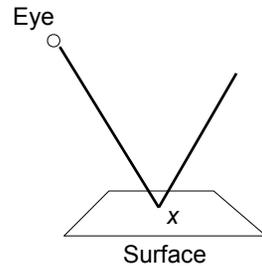
## Simple Monte Carlo Path Tracer

- *Step 1: Choose a ray  $(u, v, \theta, \phi)$  [per pixel]; assign weight = 1*
- *Step 2: Trace ray to find intersection with nearest surface*
- *Step 3: Randomly choose between emitted and reflected light*
  - *Step 3a: If emitted,*  
*return weight' \*  $L_e$*
  - *Step 3b: If reflected,*  
*weight'' \*= reflectance*  
*Generate ray in random direction*  
*Go to step 2*

## Sampling Techniques

Problem: how do we generate random points/directions during path tracing and reduce variance?

- Importance sampling (e.g. by BRDF)
- Stratified sampling



## Outline

- Motivation and Basic Idea
- *Implementation of simple path tracer*
- Variance Reduction: Importance sampling
- Other variance reduction methods
- Specific 2D sampling techniques

## Simplest Monte Carlo Path Tracer

For each pixel, cast  $n$  samples and average over paths

- Choose a ray with  $p$ =camera,  $d=(\theta,\phi)$  within pixel
- Pixel color  $+= (1/n) * \text{TracePath}(p, d)$

$\text{TracePath}(p, d)$  returns (r,g,b) [and calls itself recursively]:

- Trace ray  $(p, d)$  to find nearest intersection  $p'$
- Select with probability (say) 50%:
  - Emitted:  
return  $2 * (L_{e_{\text{red}}}, L_{e_{\text{green}}}, L_{e_{\text{blue}}}) // 2 = 1/(50\%)$
  - Reflected:  
generate ray in random direction  $d'$   
return  $2 * f_{i,d \rightarrow d'} * (n \cdot d') * \text{TracePath}(p', d')$

## Simplest Monte Carlo Path Tracer

For each pixel, cast  $n$  samples and average

- Choose a ray with  $p$ =camera,  $d=(\theta,\phi)$  within pixel
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return  $2 * (L_{e_{\text{red}}}, L_{e_{\text{green}}}, L_{e_{\text{blue}}}) // 2 = 1/(50\%)$
    - Reflected:  
generate ray in random direction  $d'$   
return  $2 * f_{i,d \rightarrow d'} * (n \cdot d') * \text{TracePath}(p', d')$
- Weight = 1/probability  
Remember: unbiased  
requires having  $f(x) / p(x)$

# Simplest Monte Carlo Path Tracer

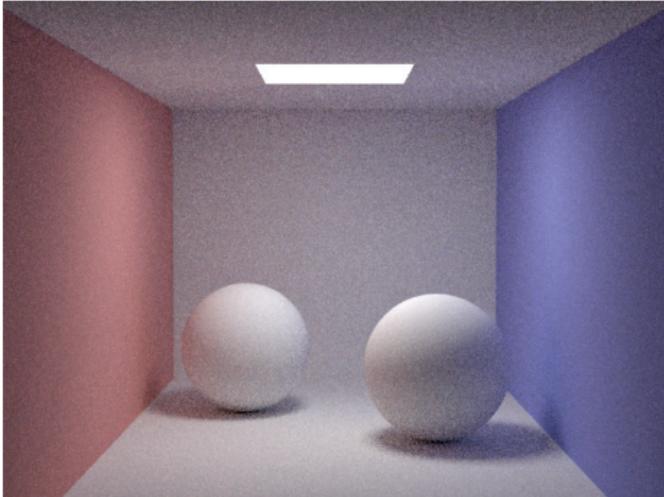
For each pixel, cast  $n$  samples and average

- Choose a ray with  $p$ =camera,  $d=(\theta,\phi)$  within pixel
- Pixel color  $+= (1/n) * \text{TracePath}(p, d)$

$\text{TracePath}(p, d)$  returns (r,g,b) [and calls itself recursively]:

- Trace ray  $(p, d)$  to find nearest intersection  $p'$
- Select with probability (say) 50%:
  - Emitted:  
 $\text{return } 2 * (L_{\text{red}}, L_{\text{green}}, L_{\text{blue}}) // 2 = 1/(50\%)$
  - Reflected:  $\text{generate ray in random direction } d'$  ← Path terminated when Emission evaluated  
 $\text{return } 2 * f_r(d \rightarrow d') * (n-d') * \text{TracePath}(p', d')$

## Path Tracing



## Arnold Renderer (M. Fajardo)

- Works well diffuse surfaces, hemispherical light



## From CS 283(294) last year



Daniel Ritchie and Lita Cho

## Advantages and Drawbacks

- Advantage: general scenes, reflectance, so on
  - By contrast, standard recursive ray tracing only mirrors
- This algorithm is *unbiased*, but horribly inefficient
  - Sample “emitted” 50% of the time, even if emitted=0
  - Reflect rays in random directions, even if mirror
  - If light source is small, rarely hit it
- Goal: improve efficiency without introducing bias
  - Variance reduction using many of the methods discussed for Monte Carlo integration last week
  - Subject of much interest in graphics in 90s till today

## Outline

- Motivation and Basic Idea
- Implementation of simple path tracer
- *Variance Reduction: Importance sampling*
- Other variance reduction methods
- Specific 2D sampling techniques

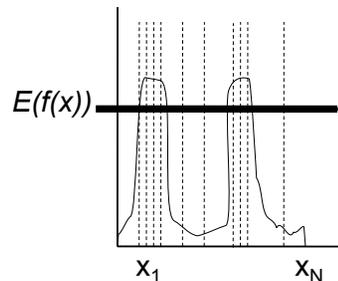
## Importance Sampling

- Pick paths based on energy or expected contribution
  - More samples for high-energy paths
  - Don't pick low-energy paths
- At “macro” level, use to select between reflected vs emitted, or in casting more rays toward light sources
- At “micro” level, importance sample the BRDF to pick ray directions
- Tons of papers in 90s on tricks to reduce variance in Monte Carlo rendering

## Importance Sampling

Can pick paths however we want, but contribution weighted by  $1/\text{probability}$

- Already seen this division of  $1/\text{prob}$  in weights to emission, reflectance



## Simplest Monte Carlo Path Tracer

For each pixel, cast  $n$  samples and average

- Choose a ray with  $p$ =camera,  $d=(\theta,\phi)$  within pixel
- Pixel color  $+= (1/n) * \text{TracePath}(p, d)$

$\text{TracePath}(p, d)$  returns (r,g,b) [and calls itself recursively]:

- Trace ray  $(p, d)$  to find nearest intersection  $p'$
- Select with probability (say) 50%:
  - Emitted:  
return  $2 * (L_{e_{\text{red}}}, L_{e_{\text{green}}}, L_{e_{\text{blue}}}) // 2 = 1/(50\%)$
  - Reflected:  
generate ray in random direction  $d'$   
return  $2 * f_r(d \rightarrow d') * (n \cdot d') * \text{TracePath}(p', d')$

## Importance sample Emit vs Reflect

$\text{TracePath}(p, d)$  returns (r,g,b) [and calls itself recursively]:

- Trace ray  $(p, d)$  to find nearest intersection  $p'$
- If  $L_e = (0,0,0)$  then  $p_{\text{emit}} = 0$  else  $p_{\text{emit}} = 0.9$  (say)
- If  $\text{random}() < p_{\text{emit}}$  then:
  - Emitted:  
return  $(1/p_{\text{emit}}) * (L_{e_{\text{red}}}, L_{e_{\text{green}}}, L_{e_{\text{blue}}})$
  - Else Reflected:  
generate ray in random direction  $d'$   
return  $(1/(1-p_{\text{emit}})) * f_r(d \rightarrow d') * (n \cdot d') * \text{TracePath}(p', d')$

## Importance sample Emit vs Reflect

TracePath( $p, d$ ) returns (r,g,b) [and calls itself recursively]:

- Trace ray ( $p, d$ ) to find nearest intersection  $p'$
  - If  $L_e = (0,0,0)$  then  $p_{\text{emit}} = 0$  else  $p_{\text{emit}} = 0.9$  (say)
  - If  $\text{random}() < p_{\text{emit}}$  then:
    - Emitted:  
return  $(1/p_{\text{emit}}) * (L_{e_{\text{red}}}, L_{e_{\text{green}}}, L_{e_{\text{blue}}})$
    - Else Reflected:  
generate ray in random direction  $d'$   
return  $(1/(1-p_{\text{emit}})) * f_r(d \rightarrow d') * (n \cdot d') * \text{TracePath}(p', d')$
- Can never be 1 unless Reflectance is 0

## Outline

- Motivation and Basic Idea
- Implementation of simple path tracer
- Variance Reduction: Importance sampling
- *Other variance reduction methods*
- Specific 2D sampling techniques

## More variance reduction

- Discussed “macro” importance sampling
  - Emitted vs reflected
- How about “micro” importance sampling
  - *Shoot rays towards light sources in scene*
  - Distribute rays according to BRDF

## One Variation for Reflected Ray

- Pick a light source
- Trace a ray towards that light
- Trace a ray anywhere except for that light
  - Rejection sampling
- Divide by probabilities
  - $1/(\text{solid angle of light})$  for ray to light source
  - $(1 - \text{the above})$  for non-light ray
  - Extra factor of 2 because shooting 2 rays

## Russian Roulette

---

Terminate photon with probability  $p$

Adjust weight of the result by  $1/(1-p)$

$$E(X) = p \cdot 0 + (1-p) \frac{E(X)}{1-p} = E(X)$$

Intuition:

Reflecting from a surface with  $R=.5$

100 incoming photons with power 2 W

1. Reflect 100 photons with power 1 W
2. Reflect 50 photons with power 2 W

## Path Tracing: Include Direct Lighting

---

Step 1. Choose a camera ray  $r$  given the

$(x, y, u, v, t)$  sample

weight = 1;

$L = 0$

Step 2. Find ray-surface intersection

Step 3.

$L += \text{weight} * L_r(\text{light sources})$

weight \*= reflectance( $r$ )

Choose new ray  $r' \sim \text{BRDF pdf}(r)$

Go to Step 2.

## Monte Carlo Extensions

### Unbiased

- Bidirectional path tracing
- Metropolis light transport

### Biased, but consistent

- Noise filtering
- Adaptive sampling
- Irradiance caching

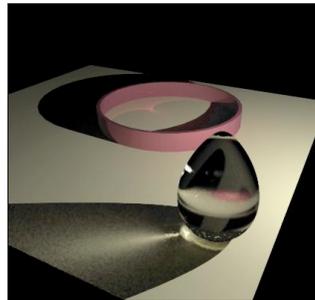
## Monte Carlo Extensions

### Unbiased

- Bidirectional path tracing
- Metropolis light transport

### Biased, but consistent

- Noise filtering
- Adaptive sampling
- Irradiance caching



RenderPark

## Monte Carlo Extensions

### Unbiased

- Bidirectional path tracing
- Metropolis light transport

### Biased, but consistent

- Noise filtering
- Adaptive sampling
- Irradiance caching



Heinrich

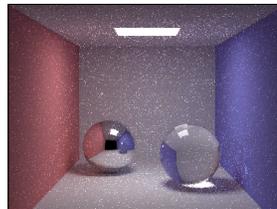
## Monte Carlo Extensions

### Unbiased

- Bidirectional path tracing
- Metropolis light transport

### Biased, but consistent

- Noise filtering
- Adaptive sampling
- Irradiance caching



Unfiltered



Filtered

Jensen

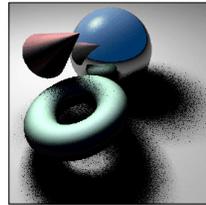
## Monte Carlo Extensions

### Unbiased

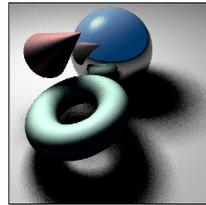
- Bidirectional path tracing
- Metropolis light transport

### Biased, but consistent

- Noise filtering
- Adaptive sampling
- Irradiance caching



Fixed



Adaptive Ohbuchi

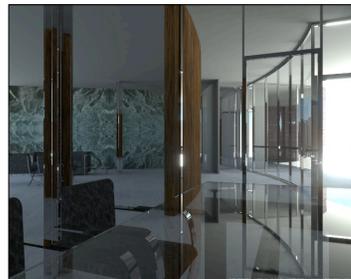
## Monte Carlo Extensions

### Unbiased

- Bidirectional path tracing
- Metropolis light transport

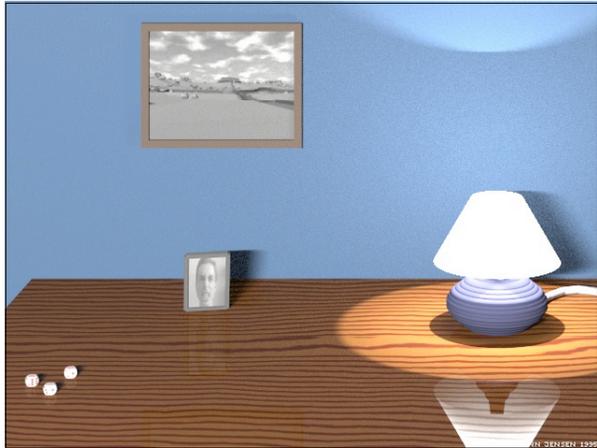
### Biased, but consistent

- Noise filtering
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Jensen

## Monte Carlo Path Tracing Image



2000 samples per pixel, 30 computers, 30 hours

Jensen

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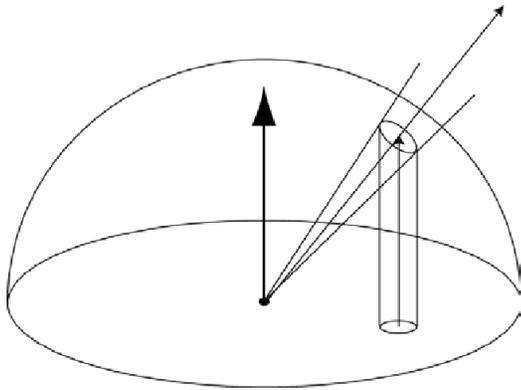
## 2D Sampling: Motivation

- Final step in sending reflected ray: sample 2D domain
- According to projected solid angle
- Or BRDF
- Or area on light source
- Or sampling of a triangle on geometry
- Etc.

## Sampling Projected Solid Angle

---

Generate cosine weighted distribution



## Sampling Upper Hemisphere

- Uniform directional sampling: how to generate random ray on a hemisphere?
- Option #1: rejection sampling
  - Generate random numbers  $(x,y,z)$ , with  $x,y,z$  in  $-1..1$
  - If  $x^2+y^2+z^2 > 1$ , reject
  - Normalize  $(x,y,z)$
  - If pointing into surface ( $\text{ray dot } n < 0$ ), flip

## Sampling Upper Hemisphere

- Option #2: inversion method
  - In polar coords, density must be proportional to  $\sin \theta$  (remember  $d(\text{solid angle}) = \sin \theta d\theta d\phi$ )
  - Integrate, invert  $\rightarrow \cos^{-1}$
- So, recipe is
  - Generate  $\phi$  in  $0..2\pi$
  - Generate  $z$  in  $0..1$
  - Let  $\theta = \cos^{-1} z$
  - $(x,y,z) = (\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta)$

## BRDF Importance Sampling

- Better than uniform sampling: importance sampling
- Because you divide by probability, ideally probability  $\propto f_r \cdot \cos \theta_i$

## BRDF Importance Sampling

- For cosine-weighted Lambertian:
  - Density =  $\cos \theta \sin \theta$
  - Integrate, invert  $\rightarrow \cos^{-1}(\text{sqrt})$
- So, recipe is:
  - Generate  $\phi$  in  $0..2\pi$
  - Generate  $z$  in  $0..1$
  - Let  $\theta = \cos^{-1}(\text{sqrt}(z))$

## BRDF Importance Sampling

- Phong BRDF:  $f_r \propto \cos^n \alpha$  where  $\alpha$  is angle between outgoing ray and ideal mirror direction
- Constant scale =  $k_s(n+2)/(2\pi)$
- Can't sample this times  $\cos \theta_i$ 
  - Can only sample BRDF itself, then multiply by  $\cos \theta_i$
  - That's OK – still better than random sampling

## BRDF Importance Sampling

- Recipe for sampling specular term:
  - Generate  $z$  in  $0..1$
  - Let  $\alpha = \cos^{-1}(z^{1/(n+1)})$
  - Generate  $\phi_\alpha$  in  $0..2\pi$
- This gives direction w.r.t. ideal mirror direction
- Convert to  $(x,y,z)$ , then rotate such that  $z$  points along mirror dir.

## Summary

- Monte Carlo methods robust and simple (at least until nitty gritty details) for global illumination
- Must handle many variance reduction methods in practice
- Importance sampling, Bidirectional path tracing, Russian roulette etc.
- Rich field with many papers, systems researched over last 10 years