

Advanced Computer Graphics (Fall 2009)

CS 294, Rendering Lecture 10
Precomputation-Based Real-Time Rendering
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Motivation

- Previously: seen IBR. Use measured data (real photographs) and interpolate for realistic real-time
- Why not apply to real-time rendering?
 - Precompute (offline) some information (images) of interest
 - Must assume something about scene is constant to do so
 - Thereafter real-time rendering. Often accelerate hardware
- Easier and harder than conventional IBR
 - Easier because synthetic scenes give info re geometry, reflectance (but CG rendering often longer than nature)
 - Harder because of more complex effects (lighting from all directions for instance, not just changing view)
- Representations and Signal-Processing crucial

My General Philosophy

- This general line of work is a large data management and signal-processing problem
- Precompute high-dimensional complex data
- Store efficiently (find right mathematical represent.)
- Render in real-time
 - Worry about systems issues like caching
 - Good signal-processing: use only small amount of data but guarantee high fidelity
- Many insights into structure of lighting, BRDFs, ...
 - Not just blind interpolation and IBR, signal processing

Precomputation-Based Relighting

- Analyze precomputed images of scene



Precomputation-Based Relighting

- Analyze precomputed images of scene



Assumptions

- Static geometry
- Precomputation
- Real-Time Rendering (relight all-frequency effects)
 - Exploit linearity of light transport for this
 - Later, change viewpoint as well



Why is This Hard?

- Plain graphics hardware supports only simple (point) lights, BRDFs (Phong) without any shadows
- Shadow maps can handle point lights (hard shadows)
- Environment maps complex lighting, BRDFs but no shadows
- IBR can often do changing view, fixed lighting
- How to do complex shadows in complex lighting?
- With dynamically changing illumination and view?

Relighting as a Matrix-Vector Multiply

$$\begin{bmatrix} P_1 \\ P_2 \\ P_3 \\ \vdots \\ P_N \end{bmatrix} \begin{img alt="A 3D rendered scene of a plant on a white surface." data-bbox="633 157 728 231"/>$$

$$= \begin{bmatrix} T_{11} & T_{12} & \dots & T_{1M} \\ T_{21} & T_{22} & \dots & T_{2M} \\ T_{31} & T_{32} & \dots & T_{3M} \\ \vdots & \vdots & \ddots & \vdots \\ T_{N1} & T_{N2} & \dots & T_{NM} \end{bmatrix} \begin{bmatrix} L_1 \\ L_2 \\ \vdots \\ L_M \end{bmatrix} \begin{img alt="A cross-shaped grid of cubemap images representing input lighting." data-bbox="783 251 865 302"/>$$

Relighting as a Matrix-Vector Multiply

$$\begin{bmatrix} P_1 \\ P_2 \\ P_3 \\ \vdots \\ P_N \end{bmatrix} \begin{img alt="A 3D rendered scene of a plant on a white surface, overlaid with a grid." data-bbox="208 433 306 507"/>$$

Output Image (Pixel Vector)

$$= \begin{bmatrix} T_{11} & T_{12} & \dots & T_{1M} \\ T_{21} & T_{22} & \dots & T_{2M} \\ T_{31} & T_{32} & \dots & T_{3M} \\ \vdots & \vdots & \ddots & \vdots \\ T_{N1} & T_{N2} & \dots & T_{NM} \end{bmatrix} \begin{bmatrix} L_1 \\ L_2 \\ \vdots \\ L_M \end{bmatrix} \begin{img alt="A cross-shaped grid of cubemap images representing input lighting." data-bbox="358 521 441 578"/>$$

Precomputed Transport Matrix (Cubemap Vector)

Matrix Columns (Images)

$$\begin{bmatrix} T_{11} & T_{12} & \dots & T_{1M} \\ T_{21} & T_{22} & \dots & T_{2M} \\ T_{31} & T_{32} & \dots & T_{3M} \\ \vdots & \vdots & \ddots & \vdots \\ T_{N1} & T_{N2} & \dots & T_{NM} \end{bmatrix} \begin{img alt="A 3D rendered scene of a plant on a white surface." data-bbox="743 464 856 554"/>$$

Precompute: Ray-Trace Image Cols

$$\begin{bmatrix} T_{11} & T_{12} & \dots & T_{1M} \\ T_{21} & T_{22} & \dots & T_{2M} \\ T_{31} & T_{32} & \dots & T_{3M} \\ \vdots & \vdots & \ddots & \vdots \\ T_{N1} & T_{N2} & \dots & T_{NM} \end{bmatrix} \begin{img alt="A 3D rendered scene of a dark object on a white surface." data-bbox="321 741 434 831"/>$$

Precompute 2: Rasterize Matrix Rows

$$\begin{bmatrix} T_{11} & T_{12} & \dots & T_{1M} \\ T_{21} & T_{22} & \dots & T_{2M} \\ T_{31} & T_{32} & \dots & T_{3M} \\ \vdots & \vdots & \ddots & \vdots \\ T_{N1} & T_{N2} & \dots & T_{NM} \end{bmatrix} \begin{img alt="A cross-shaped grid of cubemap images representing input lighting." data-bbox="748 758 843 818"/>$$

Problem Definition

Matrix is Enormous

- 512 x 512 pixel images
- 6 x 64 x 64 cubemap environments

Full matrix-vector multiplication is intractable

- On the order of 10^{10} operations *per frame*

How to relight quickly?

Outline

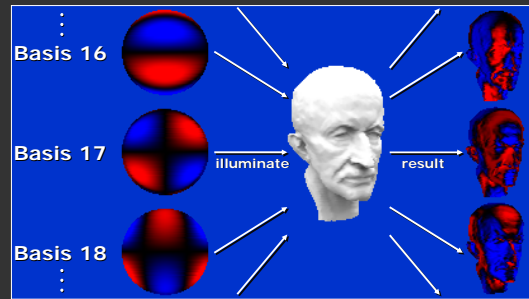
- Motivation and Background
- *Compression methods*
 - *Low frequency linear spherical harmonic approximation*
 - Factorization and PCA
 - Local factorization and clustered PCA
 - Non-linear wavelet approximation
- Changing view as well as lighting
 - Clustered PCA
 - Factored BRDFs
 - Triple Product Integrals

Precomputed Radiance Transfer

- Better light integration and transport
 - dynamic, area lights
 - self-shadowing
 - interreflections
- For diffuse and glossy surfaces
- At real-time rates
- Sloan et al. 02



Precomputation: Spherical Harmonics



Diffuse Transfer Results

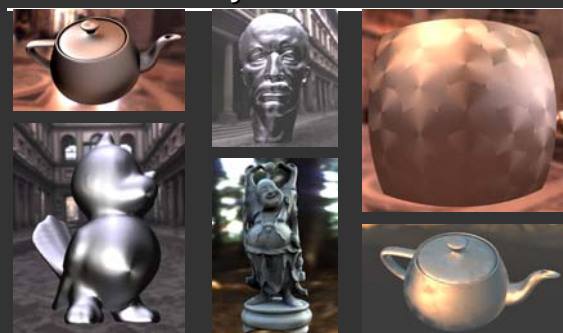


No Shadows/Inter

Shadows

Shadows+Inter

Arbitrary BRDF Results



Anisotropic BRDFs

Other BRDFs

Spatially Varying

Relighting as a Matrix-Vector Multiply

$$\begin{bmatrix} P_1 \\ P_2 \\ P_3 \\ \vdots \\ P_N \end{bmatrix} \begin{img alt="A photograph of a vase with green plants." data-bbox="208 157 308 231"/>$$

$$= \begin{bmatrix} T_{11} & T_{12} & \dots & T_{1M} \\ T_{21} & T_{22} & \dots & T_{2M} \\ T_{31} & T_{32} & \dots & T_{3M} \\ \vdots & \vdots & \ddots & \vdots \\ T_{N1} & T_{N2} & \dots & T_{NM} \end{bmatrix} \begin{bmatrix} L_1 \\ L_2 \\ \vdots \\ L_M \end{bmatrix} \begin{img alt="A cross-shaped arrangement of small images showing different lighting conditions on the vase." data-bbox="358 251 441 301"/>$$

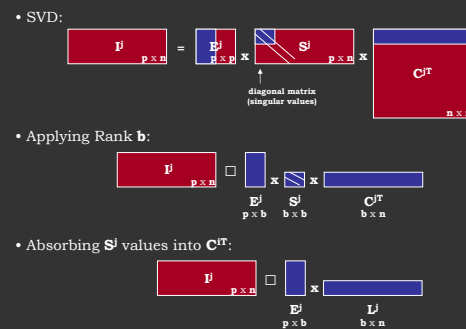
Idea of Compression

- The vector is projected onto low-frequency components (say 25). Size greatly reduced.
- Hence, only 25 matrix columns
- But each pixel still treated separately (still have 300000 matrix rows for 512 x 512 image)
- Actually, for each pixel, dot product of matrix row (25 elems) and lighting vector (25 elems) in hardware
- Good technique (becoming common in games) but useful only for broad low-frequency lighting

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PCA or SVD factorization



Idea of Compression

- Represent matrix (rather than light vector) compactly
- Can be (and is) combined with low frequency vector
- Useful in broad contexts.
 - BRDF factorization for real-time rendering (reduce 4D BRDF to 2D texture maps) McCool et al. 01 etc
 - Surface Light field factorization for real-time rendering (4D to 2D maps) Chen et al. 02, Nishino et al. 01
 - Factorization of Orientation Light field for complex lighting and BRDFs (4D to 2D) Latta et al. 02
- **Not too useful for general precomput. relighting**
 - Transport matrix not low-dimensional!!

Local or Clustered PCA

- Exploit local coherence (in say 16x16 pixel blocks)
 - Idea: light transport is locally low-dimensional. Why?
 - Even though globally complex
 - See Mahajan et al. 07 for theoretical analysis
- Original idea: Each triangle separately
 - Example: Surface Light Fields 3D subspace works well
 - Vague analysis of size of triangles
 - Instead of triangle, 16x16 image blocks [Nayar et al. 04]
- Clustered PCA [Sloan et al. 2003]
 - Combines two widely used compression techniques: Vector Quantization or VQ and Principal Component Analysis
 - For complex geometry, no need for parameterization / topology

Demo (block PCA relighting)

Practical Case
Human Face

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Sparse Matrix-Vector Multiplication

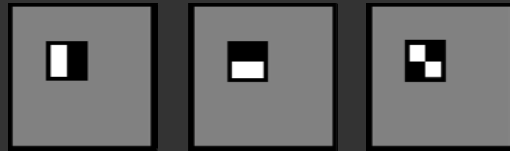
Choose data representations with mostly zeroes

Vector: Use *non-linear wavelet approximation* on lighting

Matrix: Wavelet-encode transport rows

$$\begin{bmatrix} T_{11} & T_{12} & \dots & T_{1M} \\ T_{21} & T_{22} & \dots & T_{2M} \\ T_{31} & T_{32} & \dots & T_{3M} \\ \vdots & \vdots & \ddots & \vdots \\ T_{N1} & T_{N2} & \dots & T_{NM} \end{bmatrix} \begin{bmatrix} L_1 \\ L_2 \\ \vdots \\ L_M \end{bmatrix}$$


Haar Wavelet Basis



Non-linear Wavelet Approximation

Wavelets provide dual space / frequency locality

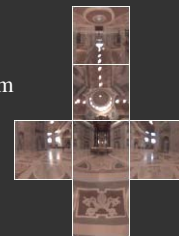
- Large wavelets capture low frequency area lighting
- Small wavelets capture high frequency compact features

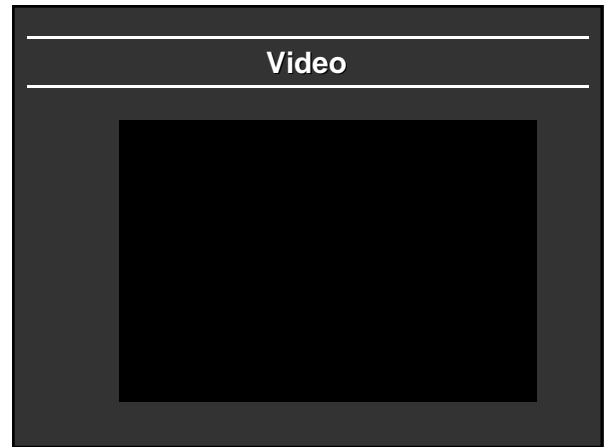
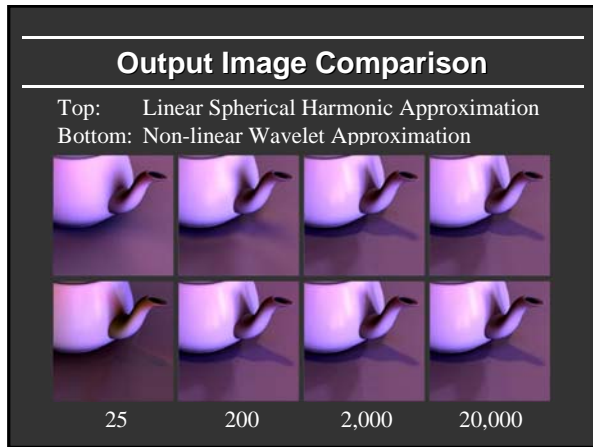
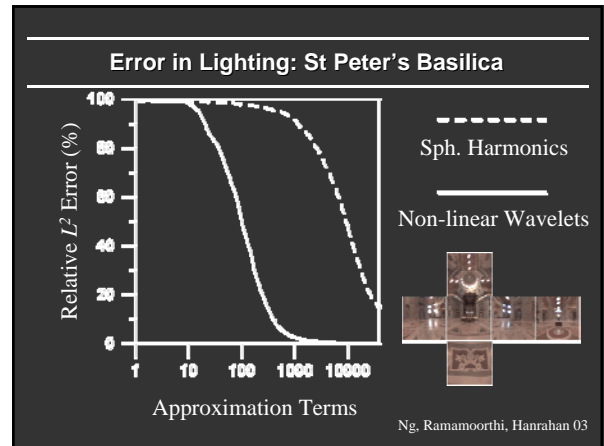
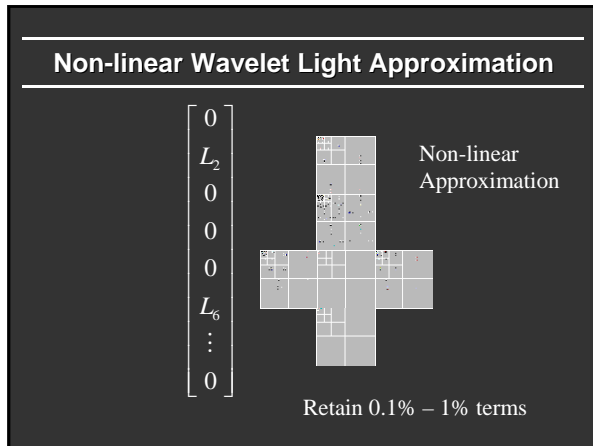
Non-linear Approximation

- Use a **dynamic** set of approximating functions (*depends on each frame's lighting*)
- By contrast, linear approx. uses **fixed** set of basis functions (like 25 lowest frequency spherical harmonics)
- We choose 10's - 100's from a basis of 24,576 wavelets

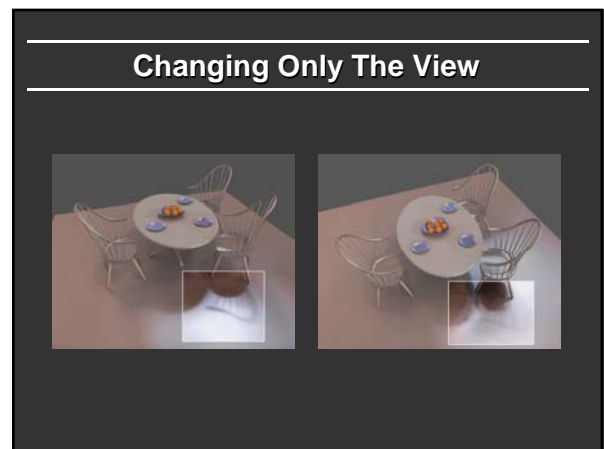
Non-linear Wavelet Light Approximation

Wavelet Transform





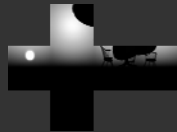
- ### Outline
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Problem Characterization

6D Precomputation Space

- Distant Lighting (2D)
- View (2D)
- Rigid Geometry (2D)



With ~ 100 samples per dimension
 $\sim 10^{12}$ samples total!! : Intractable computation, rendering

Clustered PCA

- Use low-frequency light and view variation (Order 4 spherical harmonic = 25 for both; total = $25*25=625$)
- 625 element vector for each vertex
- Apply CPCA directly (Sloan et al. 2003)
- Does not easily scale to high frequencies
 - Really cubic complexity (number of vertices, illumination directions or harmonics, and view directions or harmonics)
- Practical real-time method on GPU

Factored BRDFs

- Sloan et al. 04, Wang et al. 04: All-frequency effects
- Combines lots of things: BRDF factorization, CPCA, nonlinear approx. with wavelets
- Idea: Factor BRDF to depend on incident, outgoing
 - Incident part handled with view-independent relighting
 - Then linearly combine based on outgoing factor
- Effectively, break problem into a few subproblems that can be solved view-independently and added up
 - Can apply nonlinear wavelet approx. to each subproblem
 - And CPCA to the matrices for further compression

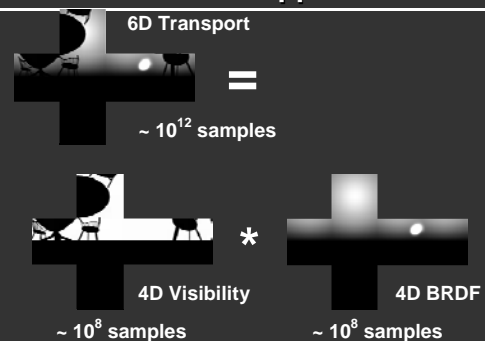
Factored BRDFs: Critique

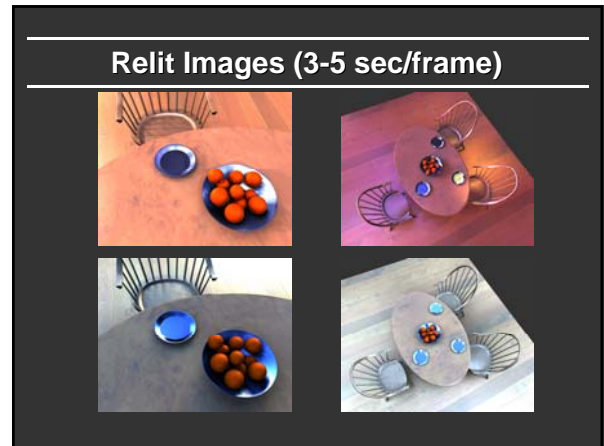
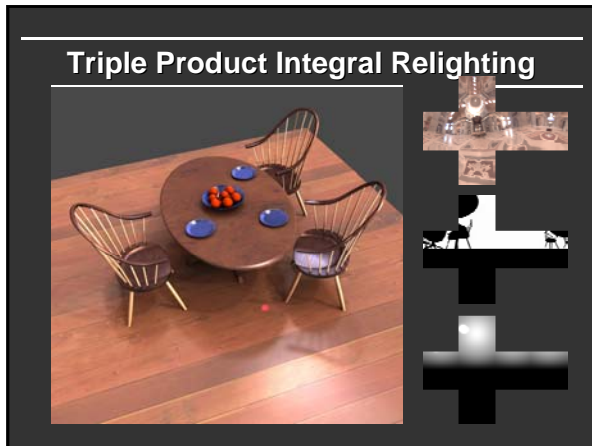
- Simple, reasonably practical method
- Problem: Non-optimal factorization, few terms
 - Can only handle less glossy materials
 - Accuracy not properly investigated
- Very nice synthesis of many existing ideas
- Comparison to triple product integrals
 - Not as deep or cool, but simpler and real-time
 - Limits BRDF fidelity, glossiness much more
 - In a sense, they are different types of factorizations

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 - *Triple Product Integrals*

Factorization Approach





Triple Product Integrals

$$\begin{aligned}
 B &= \int_{S^2} L(\omega) V(\omega) \tilde{\rho}(\omega) d\omega \\
 &= \int_{S^2} \left(\sum_i L_i \Psi_i(\omega) \right) \left(\sum_j V_j \Psi_j(\omega) \right) \left(\sum_k \tilde{\rho}_k \Psi_k(\omega) \right) d\omega \\
 &= \sum_i \sum_j \sum_k L_i V_j \tilde{\rho}_k \int_{S^2} \Psi_i(\omega) \Psi_j(\omega) \Psi_k(\omega) d\omega \\
 &= \sum_i \sum_j \sum_k L_i V_j \tilde{\rho}_k C_{ijk}
 \end{aligned}$$

Basis Requirements

$$B = \sum_i \sum_j \sum_k L_i V_j \tilde{\rho}_k C_{ijk}$$

1. Need few non-zero "tripling" coefficients

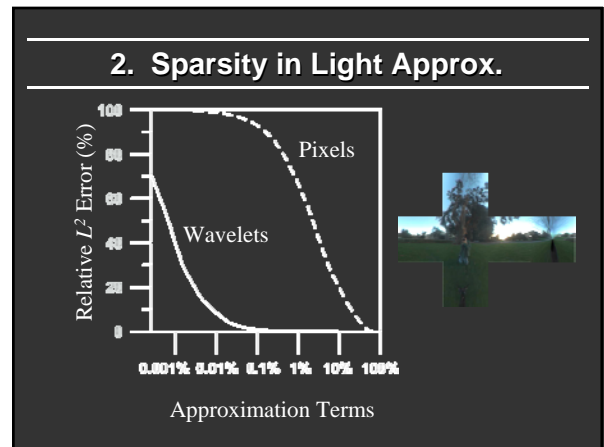
$$C_{ijk} = \int_{S^2} \Psi_i(\omega) \Psi_j(\omega) \Psi_k(\omega) d\omega$$

2. Need sparse basis coefficients
 $L_i, V_j, \tilde{\rho}_k$

1. Number Non-Zero Tripling Coeffs

$$C_{ijk} = \int_{S^2} \Psi_i(\omega) \Psi_j(\omega) \Psi_k(\omega) d\omega$$

Basis Choice	Number Non-Zero C_{ijk}
General (e.g. PCA)	$O(N^3)$
Pixels	$O(N)$
Fourier Series	$O(N^2)$
Sph. Harmonics	$O(N^{5/2})$
Haar Wavelets	$O(N \log N)$



Summary of Wavelet Results

- Derive direct $O(N \log N)$ triple product algorithm
- Dynamic programming can eliminate $\log N$ term
- Final complexity linear in number of retained basis coefficients

Broader Computational Relevance

- Clebsch-Gordan triple product series for spherical harmonics in quantum mechanics (but not focused on computation)
- Essentially no previous work graphics, applied math
- Same machinery applies to basic operation: multiplication
 - Signal multiplication for audio, image compositing,....
 - Compressed signals/videos (e.g. wavelets JPEG 2000)



Summary

- Really a big data compression and signal-processing problem
- Apply many standard methods
 - PCA, wavelet, spherical harmonic, factor compression
- And invent new ones
 - VQPCA, wavelet triple products
- Guided by and gives insights into properties of illumination, reflectance, visibility
 - How many terms enough? How much sparsity?

Subsequent Work

- My survey linked from website (lecture only covers 2002-2004)
- Varied lighting/view. What about dynamic scenes, BRDFs
 - Much recent work [Zhou et al. 05, Ben-Artzi et al. 06]. But still limited for dynamic scenes
- Must work on GPU to be practical
- Sampling on object geometry remains a challenge
- Near-Field Lighting has had some work, remains a challenge
- Applications to lighting design, direct to indirect transfer
- New basis functions and theory
- Newer methods do not require precompute, various GPU tricks
- So far, low-frequency spherical harmonics used in games, all-frequency techniques have had limited applicability