
CS 294-73
Software Engineering for
Scientific Computing

Lecture 7: STL Containers

Function and Operator Overloading

- We are using $+$, $*$, $-$, $/$. . . with many different types of arguments, different meanings in different contexts.
 - Familiar in all programming languages: $a*b$ is understood for a, b integers, floats, ...
- C++ takes this to the limit consistent with static strong typing.
 - Operators: binary infix ($x, *, \dots$) , prefix / postfix ($++, --$) , operator precedence is tied to the operator, but otherwise we can define them anyway we want.
 - Function names can also be overloaded
 - Uniquely determined by types of arguments, return values, classes.
- One more level of overloading can be obtained by using namespaces.

Examples of Overloading

- `ostream& operator<<(ostream&, const T&)`
`cout << t << ... ;`
- `void RectMDArray<T,N>::operator*=(const T&);`
`void RectMDArray<T,N>::operator*=(const RectMDArray<T,N>);`
- `const T& RectMDArray<T,N>::operator()(const Point&, int) const;`
`T& RectMDArray<T,N>::operator()(const Point&, int);`
- Member function names. In fact, you *want* to use the same member function names for analogous functionality across multiple classes (see later with iterators).

Standard Template Library containers.

Predefined classes: aggregates that are templated on the type being held.

Example of a namespace. The names of these classes are `std::className`.

We use the command

```
using namespace std;
```

in global scope to tell compiler to look for functions of the form `std::className`. Some authorities view this as bad form.

<http://www.cplusplus.com/>

NB: C++11 standard.

Various choices in container templates

Container templates in the STL

- C arrays as first-class objects (`array`),
 - dynamic arrays (`vector`),
 - queues (`queue`),
 - stacks (`stack`),
 - heaps (`priority_queue`),
 - linked lists (`list`),
 - trees (`set`),
 - associative arrays (`map`)
- They are distinguished by the kinds of access they provide and the complexity of their operations.
 - To use these, you need to include the appropriate header file, e.g.
`#include <array>`

Array<T,N>, pair<T1,T2>

- Why not `int foo[3]`, rather than `Array<int, 3> foo` ?
 - `array<int, 3>` is a type – objects of this type can be returned, assigned, etc.
 - `array<int,3> tupleFunction(...)` // perfectly ok.
 - `int foo[3] tupleFunction(...)` // doesn't make sense.
- `pair`: lots of circumstances where you need to hand around pairs of objects of different classes.
 - `pair<T1,T2> pr = make_pair(t1,t2);`
 - `pr.first`
 - `pr.second`

vector<T>

```
vector<int> foo;
for (int k = 0; k < 10; k++)
    {
        foo.push_back(k);
    }
for (auto it=foo.begin(); it != foo.end(); ++it)
    {
        cout << *it << endl;
    }
```

vector<T>

Several new things:

- Classes declared inside of classes. What things can be declared inside of a class A ?
 - Functions `void A::bar(...)`
 - Data `a.m_foo` (one per object); `A::s_bar` (static, one per class).
 - Classes: `A::Aprime;`
- `vector<T>::iterator` is a class member of `vector<T>` .
Abstracts the idea of location in a linearly-ordered set.
 - `it = vec.begin();` Calls a member function of `vector<T>` that returns an object of class `vector<T>::iterator`, initialized to initial location in `vec` .
 - `it.end() == true` if you have reached the end of `vec`.
 - `++it`, `--it` increments, decrements the location by one.
 - `*it` returns a reference to the contents at the current location in `vec`.
 - You could have gotten the same functionality by an ordinary loop and indexing, but only for `vector`, not for the other containers.

vector<T>

- auto
 - `(vector<T>::iterator it = vec.begin()); ...` is a lot of keystrokes.
 - `auto <varname> = ...;` can be used instead of a type declaration if the type can be inferred unambiguously from the right-hand side at compile time. In this case, `vector<T>::begin()` has not been overloaded, i.e. there is only one member function with that name and no arguments, and its return type is `vector<T>::iterator`.
 - `auto` can be used for many other things than this. For readability and self-documentation, it is probably best not to overuse it (Compilers can find meaningful interpretations of what may be typographical errors).

Adding, deleting, accessing elements of vector

```
unsigned int size();
```

```
push_back(const T&);
```

```
pop_back(const T&);
```

```
T& back();
```

```
T& front();
```

```
operator[ ](int);
```

```
Vector<T>::iterator begin()
```

- Looks like a 1D array: can index any element by an integer less than `size()`.
- Can add, delete elements at the end of an array.
- Fast access: data stored in contiguous locations in memory (just as if you had used `new`. In fact, you can access the underlying contiguous storage as an ordinary 1D array.

Back to vector<T>

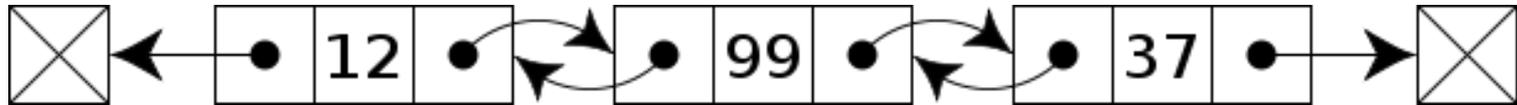
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    }
```

How do remove an element from a vector ?

- Can do this at the end easily, but in general
 - find the element you wish to remove
 - make a whole new vector 1 smaller than the original
 - copy all but the excluded object to the new vector
- But we have already been doing something almost as awful with the `push_back` function of vector
 - grow vector length by one
 - copy all elements to the new vector with `length+=1`
 - copy the new element on the end
 - (in reality vector is doing a version of doubling it's size when it runs out of room and keeps track of it's "real" size and it's `size()`)
- Vectors are good at:
 - Accessing individual elements by their position index (constant time).
 - Iterating over the elements in any order (linear time).
 - Add and remove elements from its end (constant amortized time).

list<T>

- `std::list` provides the following features
 - Efficient insertion and removal of elements anywhere in the container (constant time).
 - Efficient moving elements and block of elements within the container or even between different containers (constant time).
 - Iterating over the elements in forward or reverse order (linear time).



- What list is not good at is random access.
 - ie. if you wanted to access the 35th entry in a list, you need to walk down the linked list to the 35th entry and return it.

list<T>

```
unsigned int size();  
  
push_back(const T&);  
  
pop_back(const T&);  
  
T& front();  
  
T& back();  
  
insert(list<T>::iterator ,const T&);  
  
erase(list<T>::iterator );  
  
list<T>::iterator begin();
```

But no indexing operator ! However, insertion / deletion is cheap once you find the location you want to insert or delete at.

Why list instead of vector ?

- erase, insert, splice, merge are $O(1)$ complexity
- remove, unique are $O(\text{linear})$ complexity.

```
void removeBoundary(std::list<Node>& a_nodes, std::list<Node>&
    a_boundary)
{
    std::list<Node>::iterator it;
    for(it=a_nodes.begin(); it!=a_nodes.end(); ++it)
    {
        if(!it->isInterior())
        {
            a_boundary.splice(a_boundary.start(), a_nodes, it);
        }
    }
}
```

Executes in linear time, and Node is never copied.

<map> : an associative container

- Stores elements formed by the combination of a *key value* and a *mapped value*.
- You index into a map with the key, you get back out the value.
 - You could consider vector a simple map where the key is an unsigned integer, and the value is the template class, but that imposes the constraint that they keys are the continuous interval $[0, \text{size}-1]$
 - but what if your keys don't have this nice simple property ?
- map take two template arguments, one for the key, and one for the value
- The key class needs to implement the operator<
 - **Strict Weak Ordering**
 - if $a < b$ and $b < c$, then $a < c$
 - if $a < b$ then $!(b < a)$
 - if $!(a < b)$ and $!(b < a)$ then $a == b$

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Map<Key,T>

```
unsigned int size();

insert(pair<Key,T>);
insert(list<T>::iterator ,const T&);

erase(list<T>::iterator );
erase(const Key K&);

T& front();
T& back();

list<T>::iterator begin();
operator[](const Key K&);
```

A simple dictionary object

```
#include <map>
#include <string>
#include <iostream>
using namespace std;
void fillDictionary(map<string,string>& a_dictionary, const string& filename);
int main(int argc, char* argv[])
{
    map<string, string> dictionary;
    string key;
    fillDictionary(dictionary, argv[1]);
    while(true)
    {
        cout<<"query :";
        cin>>key;
        if(key.size()==0) return 0;
        map<string,string>::iterator val = dictionary.find(key);
        if(val==dictionary.end())
            cout<<"\n did not find that word in the dictionary "<<endl;
        else
            cout<<"\n"<<val->second<<endl;
    }
}
```

parse a simple input file

```
void fillDictionary(map<string,string>& a_dictionary, const string&
    filename)
{
    ifstream f(filename.c_str()); string key, value; char buffer[2048];
    bool next=true; char token[] = ":";
    while(f.getline(buffer,2048, token[0]))
        {
            if(next)
                {
                    key = string(buffer); next = !next;
                }
            else
                {
                    value = string(buffer); a_dictionary[key]=value; next=!next;
                }
        }
}
```

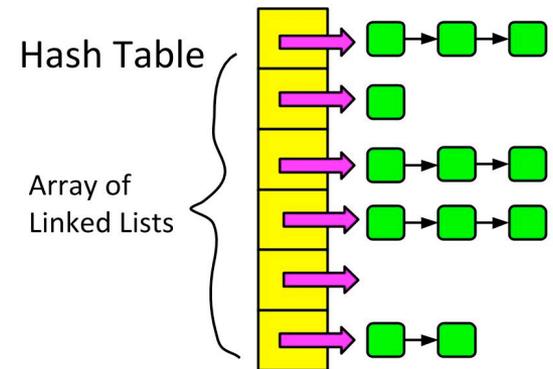
Access with operator[]
keys are unique
if not found, makes new entry



std::unordered_map

- Same Interface as std::map, but this is a *hash table*
- Optimized for fast lookup
 - std::map is $O(\log N)$ insertion and lookup, std::unordered_map is $O(\log N)$ insertion and $O(1)$ lookup
 - The constant is non-trivial
- Implementation generally uses more memory to speed up lookup (one or two levels of binning)
- Relies on the concept of *hashing*
 - Turn Key type into a `size_t` integer.

```
std::size_t h = std::hash<Bob>(myBob);
```
 - A good hash has few if any collisions
 - A good container hash even density
- Encryption hashing has different goals
 - Nearby Key types should hash to very different integers
 - you use more bits to have lots of room and reduce the probability of collision
- Not a good choice if your access pattern is visiting every member



Hierarchical use of RectMDArray

```
/// Boolean-valued RectMDArray. Defines which Boxes are  
members of the domain.
```

```
RectMDArray<bool> m_bitmap;
```

```
/// Vector of Points each of which is associated with a  
data in the region defined by a Point: a refined patch of  
grid, a collection of particles.
```

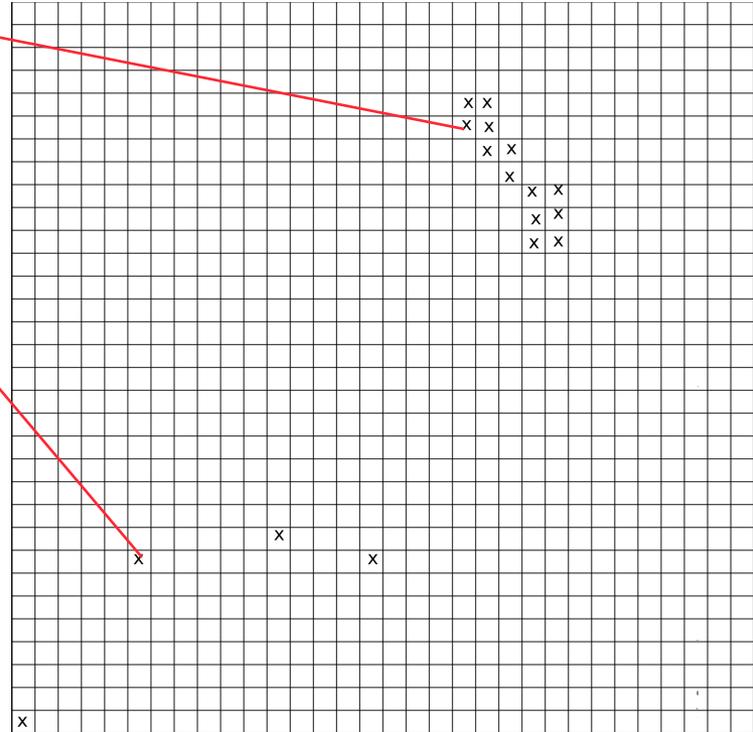
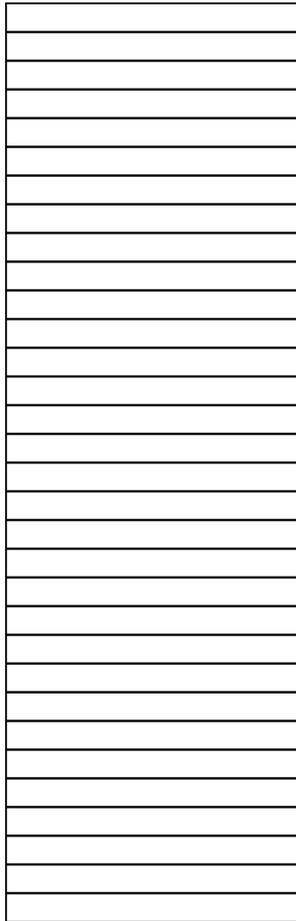
```
vector<T> m_stuff;
```

```
/// Maps Points to an index into m_stuff.
```

```
map<Point, int > m_getPatches;
```

Hierarchical use of RectMDArray

```
map<Point,int> m_getContents;  
int k = m_getContents[pt];
```



```
RectMDArray<bool> m_bitmap;
```

```
vector<list<Particle > > m_particles;  
vector<RectMDArray<T,N> > m_refGrids;
```