

61B Lecture #21: Tree Searching

Binary Search Trees

Property:

contain *keys*, and possibly other data.
left subtree of node have *smaller keys*.
right subtree of node have *larger keys*.
contains any complete transitive, anti-symmetric ordering on

the set of $x < y$ and $y < x$ true.
 $y < z$ imply $x < z$.
usually, won't allow duplicate keys this semester).
in a binary database, node label would be (*word, definition*):
key.
In this class, we'll just use the standard Java convention
compareTo.

Inserting

```
/** Insert L in T, replacing existing
 * value if present, and returning
 * new tree. */
static BST insert(BST T, Key L) {
    if (T == null)
        return new BST(L);
    if (L.compareTo(T.label()) == 0)
        T.setLabel(L);
    else if (L.compareTo(T.label()) < 0)
        T.setLeft(insert(T.left(), L));
    else
        T.setRight(insert(T.right(), L));
    return T;
}
```

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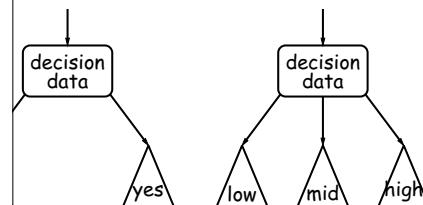
keys are set (to themselves, unless initially null).
Time complexity is proportional to height.

Public Service Announcement

There will be a grad school panel hosted by the AWE and Thursday, October 12, 5-7PM in 540AB Cory. There will be advice to women regarding how to get into grad school and research experience required."

Divide and Conquer

More computation is devoted to finding things in response
forms of query.
Time for response can be expensive, especially when data
is large for primary memory.
We need to have criteria for *dividing* data to be searched into
smaller pieces.
Time complexity for $\lg N$ algorithms: at $1\mu\text{sec}$ per comparison, could
search 10^6 items in 1 sec.
A general framework for the representation:



Finding

for 50 and 49:

```
/** Node in T containing L, or null if none */
static BST find(BST T, Key L) {
    if (T == null)
        return T;
    if (L.compareTo(T.label()) == 0)
        return T;
    else if (L.compareTo(T.label()) < 0)
        return find(T.left(), L);
    else
        return find(T.right(), L);
}
```

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Time complexity is proportional to height of tree.

Deletion Algorithm

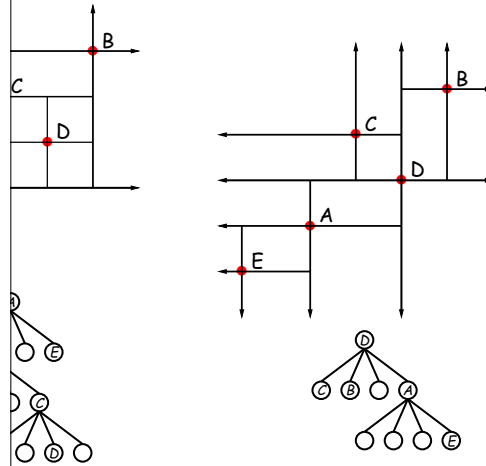
```

/** Remove L from T, returning new tree. */
static BST remove(BST T, Key L) {
    if (T == null)
        return null;
    if (L.compareTo(T.label()) == 0) {
        if (T.left() == null)
            return T.right();
        else if (T.right() == null)
            return T.left();
        else {
            Key smallest = minVal(T.right()); // ??
            T.setRight(remove(T.right(), smallest));
            T.setLabel(smallest);
        }
    }
    else if (L.compareTo(T.label()) < 0)
        T.setLeft(remove(T.left(), L));
    else
        T.setRight(remove(T.right(), L));
    return T;
}

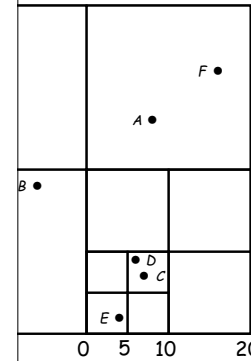
```

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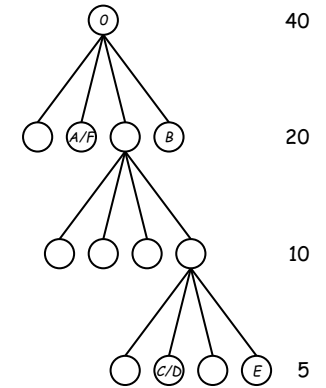
Classical Quadtree: Example



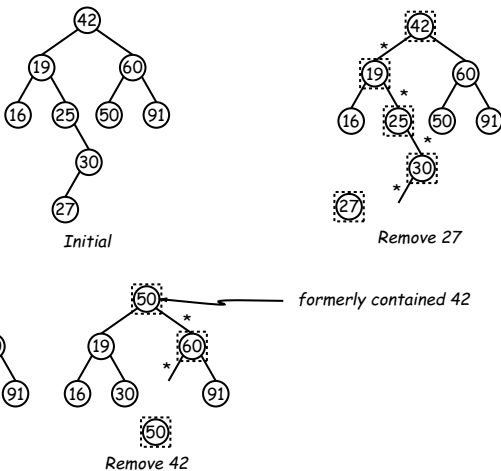
Example of PR Quadtree



2 points per leaf)



Deletion



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More Than Two Choices: Quadtrees

ex information about 2D locations so that items can be position.

o so using standard data-structuring trick: *Divide and*

(2D) space into four *quadrants*, and store items in the quadrant. Repeat this recursively with each quadrant s more than one item.

nition: a quadtree is either

t some position (x, y) , called the root, plus trees, each containing only items that are northwest, southwest, and southeast of (x, y) .

at if you are looking for point (x', y') and the root is not are looking for, you can narrow down which of the four the root to look in by comparing coordinates (x, y) with

Point-region (PR) Quadtrees

QuadTree to track moving objects, it may be useful to *delete* items from a tree: when an object moves, the it goes in may change.

do with the classical data structure above, so we'll de-

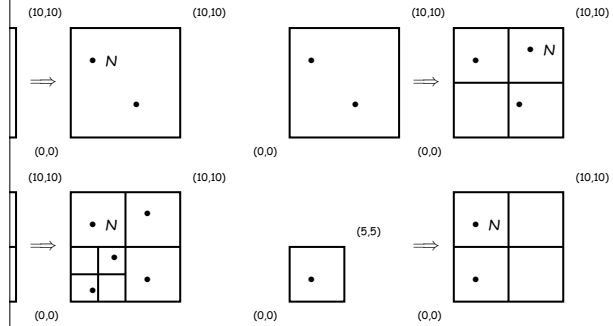
consists of a bounding rectangle, B and either

o a small number of items that lie in that rectangle, or trees whose bounding rectangles are the four quadrants f equal size).

y empty quadtree can have an arbitrary bounding rect- can wait for the first point to be inserted.

Insertion into PR Quadrees

For inserting a new point N , assuming maximum occupancy showing initial state \Rightarrow final state.



Navigating PR Quadrees

Item at (x, y) in quadtree T ,

is outside the bounding rectangle of T , or T is empty, (x, y) is not in T .

else, if T contains a small set of items, then (x, y) is in T among these items.

else, T consists of four quadtrees. Recursively look for (x, y) in each (however, step #1 above will cause all but one of the bounding boxes to reject the point immediately).

else, procedure works when looking for all items within some rectangle.

if R does not intersect the bounding rectangle of T , or T is empty, then there are no items in R .

else, if T contains a set of items, return those that are in R .

else, T consists of four quadtrees. Recursively look for R in each one of them.