

Purposes of Sorting

ports searching
h standard example
s other kinds of search:
: two equal items in this set?
: two items in this set that both have the same value for X?
my nearest neighbors?
rious unexpected algorithms, such as convex hull (small-polygon enclosing set of points).

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Classifications

Arrays keep all data in primary memory.
Batching process large amounts of data in batches, keeping it in secondary storage (in the old days, tapes).
Key-based sorting assumes only thing we know about keys is
Key uses more information about key structure.
Insertion works by repeatedly inserting items at their positions in the sorted sequence being constructed.
Selection works by repeatedly selecting the next larger item in order and adding it to one end of the sorted sequence.

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Types of Reference Types in the Java Library

reference types, C, that have a *natural order* (that is, that implement `Comparable`), we have four analogous methods: `sort`, `threeArgumentSort`, and two `parallelSort`

```
all elements of ARR stably into non-descending order. */
; extends Comparable<? super C>> sort(C[] arr) {...}
```

reference types, R, we have four more:

```
all elements of ARR stably into non-descending order
according to the ordering defined by COMP. */
> void sort(R[] arr, Comparator<? super R> comp) {...}
```

fancy generic arguments?

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algorithms: why?
sort.

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Some Definitions

Algorithm (or *sort*) *permutes* (re-arranges) a sequence of items into order, according to some *total order*.

\preceq, \succeq , is:

$x \preceq y$ or $y \preceq x$ for all x, y .

$x \preceq x$;

Transitive: $x \preceq y$ and $y \preceq x$ iff $x = y$.

Transitive: $x \preceq y$ and $y \preceq z$ implies $x \preceq z$.

Some orderings may treat unequal items as equivalent:

There can be two dictionary definitions for the same word. It is not only by the word being defined (ignoring the definition) that sorting could put either entry first.

Stable sorting does not change the relative order of equivalent elements compared to the input) is called *stable*.

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Types of Primitive Types in the Java Library

Array provides static methods to sort arrays in the class `Arrays`.

For primitive type P other than boolean, there are

```
all elements of ARR into non-descending order. */
void sort(P[] arr) { ... }
```

```
elements FIRST .. END-1 of ARR into non-descending order. */
void sort(P[] arr, int first, int end) { ... }
```

```
all elements of ARR into non-descending order,
possibly using multiprocessing for speed. */
void parallelSort(P[] arr) { ... }
```

```
elements FIRST .. END-1 of ARR into non-descending order,
possibly using multiprocessing for speed. */
void parallelSort(P[] arr, int first, int end) {...}
```

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Sorting Lists in the Java Library

java.util.Collections contains two methods similar to methods for arrays of reference types:

```
    all elements of LST stably into non-descending
    order according to the ordering defined by COMP. */
    @SuppressWarnings("unchecked")
    public <C> void sort(List<C> lst) {...}
```

```
    all elements of LST stably into non-descending
    order according to the ordering defined by COMP. */
    public void sort(List<R> lst, Comparator<R> comp) {...}
```

It is also an instance method in the List<R> interface itself:

```
    all elements of LST stably into non-descending
    order according to the ordering defined by COMP. */
    void sort(Comparator<R> comp) {...}
```

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Sorting by Insertion

With an empty sequence of outputs.

Each item from input, *inserting* into output sequence at right

is good for small sets of data.

For a linked list, time for find + insert of one item is at least $\Omega(k)$ where k is # of outputs so far.

Overall a $\Theta(N^2)$ algorithm (worst case as usual).

More?

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Shell's sort

Like insertion sort by first sorting *distant* elements:

Subsequences of elements $2^k - 1$ apart:

Pass #0, $2^k - 1, 2(2^k - 1), 3(2^k - 1), \dots$, then

Pass #1, $1 + 2^k - 1, 1 + 2(2^k - 1), 1 + 3(2^k - 1), \dots$, then

Pass #2, $2 + 2^k - 1, 2 + 2(2^k - 1), 2 + 3(2^k - 1), \dots$, then

Pass # $2^k - 2$, $2(2^k - 1) - 1, 3(2^k - 1) - 1, \dots$,

Each time an item moves, can reduce #inversions by as much as

Subsequences of elements $2^{k-1} - 1$ apart:

Pass #0, $2^{k-1} - 1, 2(2^{k-1} - 1), 3(2^{k-1} - 1), \dots$, then

Pass #1, $1 + 2^{k-1} - 1, 1 + 2(2^{k-1} - 1), 1 + 3(2^{k-1} - 1), \dots$,

Like insertion sort ($2^0 = 1$ apart), but with most inversions

reduced by $\approx N^2/4$ (take CS170 for why!).

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Sorting Arrays of Reference Types in the Java Library

For arrays of reference types, C, that have a *natural order* (that is, that implement Comparable), we have four analogous methods: natural sort, three-argument sort, and two parallelSort

```
    all elements of ARR stably into non-descending
    order according to the ordering defined by COMP. */
    @SuppressWarnings("unchecked")
    public <C> void sort(C[] arr) {...}
```

For arrays of reference types, R, we have four more:

```
    all elements of ARR stably into non-descending order
    according to the ordering defined by COMP. */
    public void sort(R[] arr, Comparator<R> comp) {...}
```

Can you pass fancy generic arguments?

Can you allow types that have compareTo methods that apply to other general types.

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Examples

```
    public static void main(String[] args) {
        List<String> list = new ArrayList<>();
        list.add("101");
        list.add("10");
        list.add("100");
        list.sort();
        System.out.println(list);
    }
    // or ...
    Collections.sort(list);
    // reverse order (Java 8):
    Collections.reverseOrder(list);
    list.sort(Collections.reverseOrder());
    // String x, String y -> { return y.compareTo(x); }
```

```
    Collections.reverseOrder()); // or
    Collections.reverseOrder()); // for X a List
```

..., X[100] in array or List X (rest unchanged):

..., 101, 10, 100;

..., L[100] in list L (rest unchanged):

```
    Collections.reverseOrder());
    Collections.reverseOrder());
```

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Inversions

Number of comparisons if already sorted.

Typical implementation for arrays:

```
    for (int i = 0; i < A.length; i++) {
        for (int j = i + 1; j < A.length; j++) {
            if (A[i] > A[j]) {
                swap(A, i, j);
            }
        }
    }
```

Executes for each $j \approx$ how far x must move.

Within K of proper places, then takes $O(KN)$ operations. For any amount of *nearly sorted* data.

Measure of unsortedness: # of *inversions*: pairs that are out of order when sorted, $N(N-1)/2$ when reversed.

Each swap of (2) decreases inversions by 1.

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Sorting by Selection: Heapsort

selecting smallest (or largest) element.

operate on a simple list or vector.

as already seen it in action: use heap.

N algorithm (N remove-first operations).

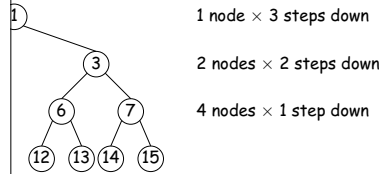
As we move items from end of heap, we can use that area to result:

original:	19	0	-1	7	23	2	42
heapified:	42	23	19	7	0	2	-1
	23	7	19	-1	0	2	42
Heap part	19	7	2	-1	0	23	42
Sorted part	7	0	2	-1	19	23	42
	2	0	-1	7	19	23	42
	0	-1	2	7	19	23	42
	-1	0	2	7	19	23	42
	-1	0	2	7	19	23	42

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Cost of Creating Heap



Worst-case cost for a heap with $h + 1$ levels is

$$h + 2^1 \cdot (h - 1) + \dots + 2^{h-1} \cdot 1$$

$$+ 2^1 + \dots + 2^{h-1} + (2^0 + 2^1 + \dots + 2^{h-2}) + \dots + (2^0 - 1) + (2^{h-1} - 1) + \dots + (2^1 - 1)$$

$$= 1 - h$$

$$\Theta(N)$$

The rest of heapsort still takes $\Theta(N \lg N)$, this does not asymptotic cost.

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Example of Shell's Sort

#I	#C
11	0
11	1
42	11
4	31
0	50

Asymptotic comparisons used to sort subsequences by insertion sort.

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Sorting By Selection: Initial Heapifying

Before creating heaps, we created them by insertion in any heap.

When an array of unheaped data to start with, there is a procedure (assume heap indexed from 0):

```

heapify(int[] arr) {
    l = arr.length;
    for (int k = N / 2; k >= 0; k --) {
        for (int p = k, c = 0; 2*p + 1 < N; p = c) {
            reheapify downward from p;
        }
    }
}
    
```

During the p loop, only the element at p might be out of order with respect to its descendants, so reheapifying downward from the subtree rooted at p to proper heap ordering.

The procedure for re-inserting an element after the top of the heap is removed, repeated $N/2$ times.

Instead of being $\Theta(N \lg N)$, it's just $\Theta(N)$.

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