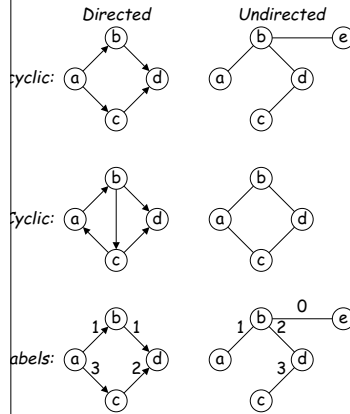


## Why Graphs?

Representing non-hierarchically related items

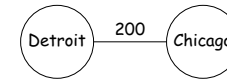
Examples: pipelines, roads, assignment problems  
 Modeling processes: flow charts, Markov models  
 Finding partial orderings: PERT charts, makefiles  
 Seen, in representing connected structures as used in

## Some Pictures

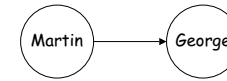
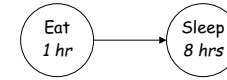


## Examples of Use

Modeling a road, with length.



Modeling a task to be completed before; Node label = time to complete.



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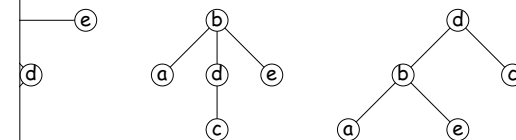
Topics: Graph Structures: *DSIJ*, Chapter 12

## Some Terminology

A graph consists of  
 nodes (aka *vertices*)  
 edges: pairs of nodes.  
 Nodes with an edge between them are *adjacent*.  
 In a graph on problem, nodes or edges may have *labels* (or *weights*)  
 Given a node set  $V = \{v_0, \dots\}$ , and edge set  $E$ .  
 If edges have an order (first, second), they are *directed edges*,  
 forming a *directed graph (digraph)*, otherwise an *undirected graph*.  
 A node is *incident* to their nodes.  
 A node *exits* one node and *enters* the next.  
 A path without repeated edges leading from a node back to itself (following arrows if directed).  
 A graph is *cyclic* if it has a cycle, else *acyclic*. Abbreviation: Directed Acyclic Graph—*DAG*.

## Trees are Graphs

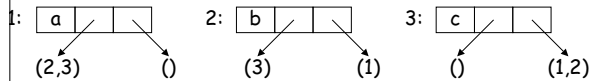
A graph is *connected* if there is a (possibly directed) path between every pair of nodes.  
 A node of the pair is *reachable* from the other.  
 A (rooted) tree iff connected, and every node but the root has one parent.  
 An acyclic, undirected graph is also called a *free tree*.  
 In a tree, you can pick the root; e.g., all the following are the same



## Representation

to number the nodes, and use the numbers in edges.

**Representation:** each node contains some kind of list (e.g., array) of its successors (and possibly predecessors).



collection of all edges. For graph above:

$\{(1, 2), (1, 3), (2, 3)\}$

**Matrix:** Represent connection with matrix entry:

	1	2	3
1	0	1	1
2	0	0	1
3	0	0	0

## Recursive Depth-First Traversal of a Graph

and combinatorial problems using the "bread-crumbs" in earlier lectures for a maze.

mark nodes as we traverse them and don't traverse previously visited nodes.

to talk about *preorder* and *postorder*, as for trees.

```

void postorderTraverse(Graph G, Node v)
{
    if (v is unmarked) {
        mark(v);
        for (Edge(v, w) ∈ G)
            traverse(G, w);
        visit v;
    }
}
    
```

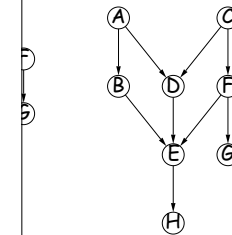
## Topological Sorting

In a DAG, find a linear order of nodes consistent with dependencies.

Order the nodes  $v_0, v_1, \dots$  such that  $v_k$  is never reachable from  $v_{k+1}$ .

Use DFS to find this. Also PERT charts.

Graph (two views)

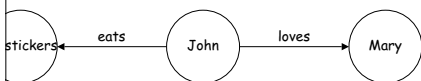


Possible Orderings

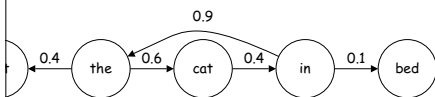
A	C	C
C	A	F
B	F	G
D	D	A
F	B	B
E	G	D
G	E	E
H	H	H

## More Examples

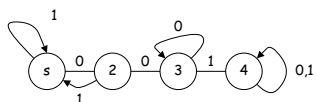
Relationship



State machine



State in state machine, label is triggering input. (Start state 4 means "there is a substring '001' somewhere in the string")

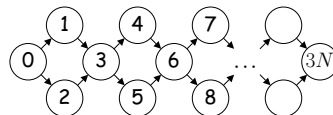


## Traversing a Graph

Time complexity depends on traversing all or some nodes.

Avoid recursion because of cycles.

In directed graphs, can get combinatorial explosions:



Start at the root and do recursive traversal down the two edges. Time complexity:  $\Theta(2^N)$  operations!

Try to visit each node constant # of times (e.g., once).

## Recursive Depth-First Traversal of a Graph (II)

If you're interested in traversing *all* nodes of a graph, not just a path, you need to be able to return to the start.

Repeat the procedure as long as there are unmarked nodes.

```

void postorderTraverse(Graph G) {
    for (all marks)
        for (v ∈ nodes of G)
            postorderTraverse(G, v);
}
    
```

```

void postorderTraverse(Graph G) {
    for (all marks)
        for (v ∈ nodes of G)
            postorderTraverse(G, v);
}
    
```

## General Graph Traversal Algorithm

```

OF_VERTICES fringe;
INITIAL_COLLECTION;
while (!fringe.isEmpty()) {
    fringe.REMOVE_HIGHEST_PRIORITY_ITEM();
}
DFS(v) {
    for each edge(v,w) {
        DFS_PROCESSING(w);
        add w to fringe;
    }
}

```

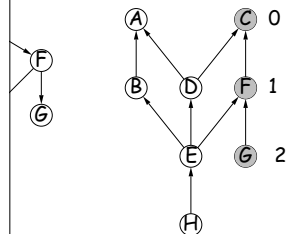
ADJUSTMENT\_OF\_VERTICES, INITIAL\_COLLECTION, etc. with expressions, or methods to different graph algorithms.

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## Sorting and Depth First Search

Suppose we *reverse the links* on our graph.  
 Recursive DFS on the reverse graph, starting from node G, will find all nodes that must come *before* H.  
 When DFS reaches a node in the reversed graph and there are no unvisited successors, we know that it is safe to put that node first.  
 A *postorder* traversal of the *reversed* graph visits nodes in an order where all predecessors have been visited.

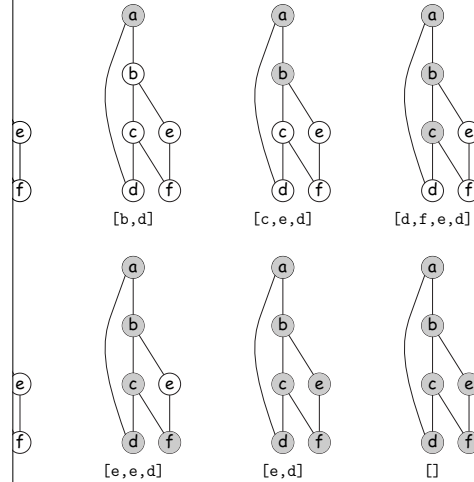


Numbers show post-order traversal order starting from G: everything that must come before G.

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## Depth-First Traversal Illustrated



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## Example: Depth-First Traversal

Visit every node reachable from  $v$  once, visiting nodes further from  $v$  first.

DFS is a specialization of general algorithm

```

DFS(v) {
    while (!fringe.isEmpty()) {
        w = fringe.pop();
        DFS(w);
    }
}

```

```

DFS(v) {
    if (!visited(w)) {
        DFS(w);
    }
}

```

```

DFS(v) {
    if (!visited(w)) {
        DFS(w);
        mark(w);
    }
}

```

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## Shortest Paths: Dijkstra's Algorithm

Find shortest paths in a graph (directed or undirected) with non-negative edge weights, starting from a given source node,  $s$ , to a target node,  $t$ .

The path with the smallest sum of weights along path is shortest.  
 Always keep estimated distance from  $s$ .  
 Always pick the next node in shortest path from  $s$ .

```

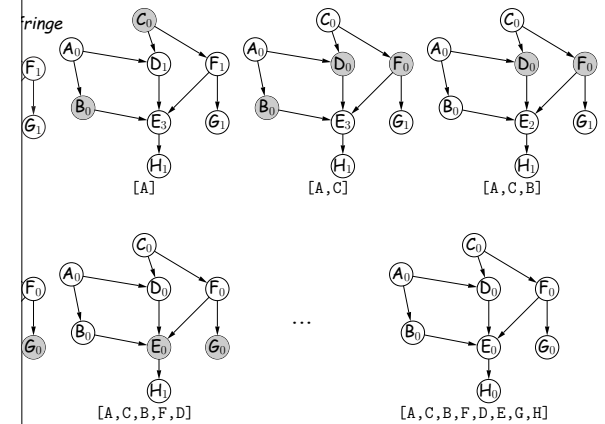
Dijkstra's Algorithm
Vertex> fringe;
for each v { v.dist() = ∞; v.back() = null; }
Priority queue ordered by smallest .dist();
while (!fringe.isEmpty()) {
    v = fringe.removeFirst();
    for each edge(v,w) {
        if (v.dist() + weight(v,w) < w.dist()) {
            w.dist() = v.dist() + weight(v,w); w.back() = v; }
    }
}

```

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## Topological Sort in Action



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### Example

