“Paper” Battery Developed by Researchers at Rensselaer
“Last time…”

- Magnetic Disks continue rapid advance: 60%/yr capacity, 40%/yr bandwidth, slow on seek, rotation improvements, MB/$ improving 100%/yr?
  - Designs to fit high volume form factor
  - PMR a fundamental new technology
    - breaks through barrier

- RAID
  - Higher performance with more disk arms per $
  - Adds option for small # of extra disks
  - Can nest RAID levels
  - Today RAID is > tens-billion dollar industry, 80% nonPC disks sold in RAIDs, started at Cal
1. RAID 1 (mirror) and 5 (rotated parity) help with performance **and** availability

2. RAID 1 has higher cost than RAID 5

3. Small writes on RAID 5 are slower than on RAID 1
Peer Instruction Answer

1. **All** RAID (0-5) helps with performance, only RAID0 doesn’t help availability. TRUE

2. Surely! Must buy 2x disks rather than 1.25x (from diagram, in practice even even less) TRUE

3. RAID5 (2R,2W) vs. RAID1 (2W). Latency worse, throughput (ll writes) better. TRUE

1. RAID 1 (mirror) and 5 (rotated parity) help with performance **and** availability

2. RAID 1 has higher cost than RAID 5

3. Small writes on RAID 5 are slower than on RAID 1
Why Performance? Faster is better!

• **Purchasing Perspective**: given a collection of machines (or upgrade options), which has the
  - best performance?
  - least cost?
  - best performance / cost?

• **Computer Designer Perspective**: faced with design options, which has the
  - best performance improvement?
  - least cost?
  - best performance / cost?

• All require basis for comparison and metric for evaluation!

• **Solid metrics lead to solid progress!**
### Two Notions of “Performance”

<table>
<thead>
<tr>
<th>Plane</th>
<th>DC to Paris</th>
<th>Top Speed</th>
<th>Passengers</th>
<th>Throughput (pmph)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Boeing 747</td>
<td>6.5 hours</td>
<td>610 mph</td>
<td>470</td>
<td>286,700</td>
</tr>
<tr>
<td>BAD/Sud Concorde</td>
<td>3 hours</td>
<td>1350 mph</td>
<td>132</td>
<td>178,200</td>
</tr>
</tbody>
</table>

• Which has higher performance?
• Interested in time to deliver 100 passengers?
• Interested in delivering as many passengers per day as possible?

• In a computer, time for one task called **Response Time or Execution Time**
• In a computer, tasks per unit time called **Throughput or Bandwidth**
Definitions

• Performance is in units of things per sec
  • bigger is better

• If we are primarily concerned with response time
  • performance(x) = \frac{1}{\text{execution_time}(x)}

"F(ast) is n times faster than S(low)" means…

\[
\frac{\text{performance}(F)}{\text{execution_time}(S)} = n = \frac{\text{performance}(S)}{\text{execution_time}(F)}
\]
Example of Response Time v. Throughput

• Time of Concorde vs. Boeing 747?
  • Concord is 6.5 hours / 3 hours = 2.2 times faster

• Throughput of Boeing vs. Concorde?
  • Boeing 747: 286,700 pmph / 178,200 pmph = 1.6 times faster

• Boeing is 1.6 times ("60%") faster in terms of throughput

• Concord is 2.2 times ("120%") faster in terms of flying time (response time)

We will focus primarily on response time.
Words, Words, Words…

- Will (try to) stick to “n times faster”; its less confusing than “m % faster”

- As faster means both decreased execution time and increased performance, to reduce confusion we will (and you should) use “improve execution time” or “improve performance”
What is Time?

• Straightforward definition of time:
  • Total time to complete a task, including disk accesses, memory accesses, I/O activities, operating system overhead, ...
  • “real time”, “response time” or “elapsed time”

• Alternative: just time processor (CPU) is working only on your program (since multiple processes running at same time)
  • “CPU execution time” or “CPU time”
  • Often divided into system CPU time (in OS) and user CPU time (in user program)
How to Measure Time?

• Real Time ⇒ Actual time elapsed

• CPU Time: Computers constructed using a clock that runs at a constant rate and determines when events take place in the hardware
  • These discrete time intervals called clock cycles (or informally clocks or cycles)
  • Length of clock period: clock cycle time (e.g., 2 nanoseconds or 2 ns) and clock rate (e.g., 500 megahertz, or 500 MHz), which is the inverse of the clock period; use these!
Measuring Time using Clock Cycles (1/2)

- **CPU execution time for a program**
  \[ \text{CPU execution time} = \text{Clock Cycles for a program} \times \text{Clock Period} \]

- or

  \[ \text{CPU execution time} = \frac{\text{Clock Cycles for a program}}{\text{Clock Rate}} \]
Measuring Time using Clock Cycles (2/2)

• One way to define clock cycles:

**Clock Cycles for program**

\[ \text{Clock Cycles for program} = \text{Instructions for a program (called “Instruction Count”)} \times \text{Average Clock cycles Per Instruction (abbreviated “CPI”) } \]

• CPI one way to compare two machines with same instruction set, since Instruction Count would be the same
Performance Calculation (1/2)

• CPU execution time for program
  \[= \text{Clock Cycles for program} \times \text{Clock Cycle Time}\]

• Substituting for clock cycles:
  \[\text{CPU execution time for program} = (\text{Instruction Count} \times \text{CPI}) \times \text{Clock Cycle Time}\]
  \[= \text{Instruction Count} \times \text{CPI} \times \text{Clock Cycle Time}\]
### Performance Calculation (2/2)

CPU time = \( \frac{\text{Instructions}}{\text{Program}} \times \frac{\text{Cycles}}{\text{Instruction}} \times \frac{\text{Seconds}}{\text{Cycle}} \)

- Product of all 3 terms: if missing a term, can’t predict time, the real measure of performance
How Calculate the 3 Components?

- **Clock Cycle Time**: in specification of computer (Clock Rate in advertisements)

- **Instruction Count**:
  - Count instructions in loop of small program
  - Use simulator to count instructions
  - Hardware counter in spec. register
    - (Pentium II,III,4)

- **CPI**:
  - Calculate: \( \frac{\text{Execution Time}}{\text{Clock cycle time}} \times \frac{1}{\text{Instruction Count}} \)

- Hardware counter in special register (PII,III,4)
Calculating CPI Another Way

• First calculate CPI for each individual instruction (add, sub, and, etc.)

• Next calculate frequency of each individual instruction

• Finally multiply these two for each instruction and add them up to get final CPI (the weighted sum)
### Example (RISC processor)

<table>
<thead>
<tr>
<th>Op</th>
<th>Freq(_i)</th>
<th>CPI(_i)</th>
<th>Prod</th>
<th>(% Time)</th>
</tr>
</thead>
<tbody>
<tr>
<td>ALU</td>
<td>50%</td>
<td>1</td>
<td>.5</td>
<td>(23%)</td>
</tr>
<tr>
<td>Load</td>
<td>20%</td>
<td>5</td>
<td>1.0</td>
<td>(45%)</td>
</tr>
<tr>
<td>Store</td>
<td>10%</td>
<td>3</td>
<td>.3</td>
<td>(14%)</td>
</tr>
<tr>
<td>Branch</td>
<td>20%</td>
<td>2</td>
<td>.4</td>
<td>(18%)</td>
</tr>
</tbody>
</table>

\[
\text{Instruction Mix} = 2.2 \\
\text{(Where time spent)}
\]

- What if Branch instructions twice as fast?
What Programs Measure for Comparison?

• Ideally run typical programs with typical input before purchase, or before even build machine
  • Called a “workload”; For example:
    • Engineer uses compiler, spreadsheet
    • Author uses word processor, drawing program, compression software

• In some situations its hard to do
  • Don’t have access to machine to “benchmark” before purchase
  • Don’t know workload in future
Benchmarks

• Obviously, apparent speed of processor depends on code used to test it

• Need industry standards so that different processors can be fairly compared

• Companies exist that create these benchmarks: “typical” code used to evaluate systems

• Need to be changed every ~5 years since designers could (and do!) target for these standard benchmarks
Example Standardized Benchmarks (1/2)

• Standard Performance Evaluation Corporation (SPEC) SPEC CPU2006
  • CINT2006 12 integer (perl, bzip, gcc, go, ...)
  • CFP2006 17 floating-point (povray, bwaves, ...)
  • All relative to base machine (which gets 100)
    Sun Ultra Enterprise 2 w/296 MHz UltraSPARC II
  • They measure
    ▪ System speed (SPECint2006)
    ▪ System throughput (SPECint_rate2006)

• www.spec.org/osg/cpu2006/
Example Standardized Benchmarks (2/2)

- **SPEC**
  - Benchmarks distributed in source code
  - Members of consortium select workload
    - 30+ companies, 40+ universities, research labs
  - Compiler, machine designers target benchmarks, so try to change every 5 years

- **SPEC CPU2006:**

<table>
<thead>
<tr>
<th>Benchmark</th>
<th>Language</th>
<th>Category</th>
</tr>
</thead>
<tbody>
<tr>
<td>perlbench</td>
<td>C</td>
<td>Perl Programming language</td>
</tr>
<tr>
<td>bzip2</td>
<td>C</td>
<td>Compression</td>
</tr>
<tr>
<td>gcc</td>
<td>C</td>
<td>C Programming Language Compiler</td>
</tr>
<tr>
<td>mcf</td>
<td>C</td>
<td>Combinatorial Optimization</td>
</tr>
<tr>
<td>gobmk</td>
<td>C</td>
<td>Artificial Intelligence : Go</td>
</tr>
<tr>
<td>hmer</td>
<td>C</td>
<td>Search Gene Sequence</td>
</tr>
<tr>
<td>sjeng</td>
<td>C</td>
<td>Artificial Intelligence : Chess</td>
</tr>
<tr>
<td>libquantum</td>
<td>C</td>
<td>Simulates quantum computer</td>
</tr>
<tr>
<td>h264ref</td>
<td>C</td>
<td>H.264 Video compression</td>
</tr>
<tr>
<td>omnetpp</td>
<td>C++</td>
<td>Discrete Event Simulation</td>
</tr>
<tr>
<td>astar</td>
<td>C++</td>
<td>Path-finding Algorithms</td>
</tr>
<tr>
<td>xalancbmk</td>
<td>C++</td>
<td>XML Processing</td>
</tr>
<tr>
<td>bwaves</td>
<td>Fortran</td>
<td>Fluid Dynamics</td>
</tr>
<tr>
<td>gamedess</td>
<td>Fortran</td>
<td>Quantum Chemistry</td>
</tr>
<tr>
<td>milc</td>
<td>C</td>
<td>Physics / Quantum Chromodynamics</td>
</tr>
<tr>
<td>zeusmp</td>
<td>Fortran</td>
<td>Physics / CFD</td>
</tr>
<tr>
<td>gromacs</td>
<td>C,Fortran</td>
<td>Biochemistry / Molecular Dynamics</td>
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<td>C,Fortran</td>
<td>Physics / General Relativity</td>
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<td>leslie3d</td>
<td>Fortran</td>
<td>Fluid Dynamics</td>
</tr>
<tr>
<td>namd</td>
<td>C++</td>
<td>Biology / Molecular Dynamics</td>
</tr>
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<td>deal11</td>
<td>C++</td>
<td>Finite Element Analysis</td>
</tr>
<tr>
<td>soplex</td>
<td>C++</td>
<td>Linear Programming, Optimization</td>
</tr>
<tr>
<td>povray</td>
<td>C++</td>
<td>Image Ray-tracing</td>
</tr>
<tr>
<td>calculix</td>
<td>C,Fortran</td>
<td>Structural Mechanics</td>
</tr>
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<td>GemsFDTD</td>
<td>Fortran</td>
<td>Computational Electromagnetics</td>
</tr>
<tr>
<td>tonto</td>
<td>Fortran</td>
<td>Quantum Chemistry</td>
</tr>
<tr>
<td>lbm</td>
<td>C</td>
<td>Fluid Dynamics</td>
</tr>
<tr>
<td>wrf</td>
<td>C,Fortran</td>
<td>Weather</td>
</tr>
<tr>
<td>sphinx3</td>
<td>C</td>
<td>Speech recognition</td>
</tr>
</tbody>
</table>
Another Benchmark

- PCs: Ziff-Davis Benchmark Suite
  - "Business Winstone is a system-level, application-based benchmark that measures a PC's overall performance when running today's top-selling Windows-based 32-bit applications... it doesn't mimic what these packages do; it runs real applications through a series of scripted activities and uses the time a PC takes to complete those activities to produce its performance scores.
  - Also tests for CDs, Content-creation, Audio, 3D graphics, battery life

http://www.etestinglabs.com/benchmarks/
Performance Evaluation: An Aside Demo

If we’re talking about performance, let’s discuss the ways shady salespeople have fooled consumers (so you don’t get taken!)

5. Never let the user touch it
4. Only run the demo through a script
3. Run it on a stock machine in which “no expense was spared”
2. Preprocess all available data
1. Play a movie
A. Rarely does a company selling a product give unbiased performance data.

B. The Sieve of Eratosthenes and Quicksort were early effective benchmarks.

C. A program runs in 100 sec. on a machine, `mult` accounts for 80 sec. of that. If we want to make the program run 6 times faster, we need to up the speed of `mults` by AT LEAST 6.
Peer Instruction Answers

A. Rarely does a company selling a product give **unbiased** performance data.

B. The Sieve of Eratosthenes, Puzzle and Quicksort were early effective benchmarks.

C. A program runs in 100 sec. on a machine, `mult` accounts for 80 sec. of that. If we want to make the program run 6 times faster, we need to up the speed of `mults` by **AT LEAST 6**.

A. **TRUE.** It is rare to find a company that gives Metrics that do not favor its product.

B. Early benchmarks? Yes. **Effective? No.** Too simple!

C. 6 times faster = 16 sec. `mults` must take -4 sec! i.e., impossible!
“And in conclusion…”

\[
\text{CPU time} = \frac{\text{Instructions}}{\text{Program}} \times \frac{\text{Cycles}}{\text{Instruction}} \times \frac{\text{Seconds}}{\text{Cycle}}
\]

- Latency v. Throughput
- **Performance doesn’t depend on any single factor:** need Instruction Count, Clocks Per Instruction (CPI) and Clock Rate to get valid estimations
- **User Time:** time user waits for program to execute: depends heavily on how OS switches between tasks
- **CPU Time:** time spent executing a single program: depends solely on design of processor (datapath, pipelining effectiveness, caches, etc.)
- **Benchmarks**
  - Attempt to predict perf, Updated every few years
  - Measure everything from simulation of desktop graphics programs to battery life
- **Megahertz Myth**
  - MHz ≠ performance, it’s just one factor
Administrivia

• HW8 due tonight at 11:59pm (no slip)

• Put in regrade requests now for any assignment past HW2

• Final: Thursday 7-10pm @ 10 Evans
  • NO backpacks, cells, calculators, pagers, PDAs
  • 2 writing implements (we’ll provide write-in exam booklets) – pencils ok!
  • Two pages of notes (both sides) 8.5”x11” paper
  • One green sheet

• Scott is holding extra OH today 4-6 in 329 Soda

• Course Survey last lecture, 2pts for doing it
Big Problems Show Need for Parallel

• Simulation: the Third Pillar of Science
  • Traditionally perform experiments or build systems
  • Limitations to standard approach:
    ▪ Too difficult – build large wind tunnels
    ▪ Too expensive – build disposable jet
    ▪ Too slow – wait for climate or galactic evolution
    ▪ Too dangerous – weapons, drug design

• Computational Science:
  ▪ Simulate the phenomenon on computers
  ▪ Based on physical laws and efficient numerical methods

• Search engines needs to build an index for the entire Internet

• Pixar needs to render movies

• Desire to go green and use less power

• Intel, Microsoft, Apple, Dell, etc. would like to sell you a new computer next year
What Can We Do?

• Wait for our machines to get faster?
  • Moore’s law tells us things are getting better; why not stall for the moment?

• Moore on last legs!
  • Many believe so … thus push for multi-core (Friday)!

Let’s Put Many CPUs Together!

- **Distributed computing (SW parallelism)**
  - Many separate computers (each with independent CPU, RAM, HD, NIC) that communicate through a network
  - Grids (home computers across Internet) and Clusters (all in one room)
  - Can be “commodity” clusters, 100K+ nodes
  - About being able to solve “big” problems, not “small” problems faster

- **Multiprocessing (HW parallelism)**
  - Multiple processors “all in one box” that often communicate through shared memory
  - Includes multicore (many new CPUs)
Performance Requirements

• Performance terminology
  • the FLOP: FLoating point OPeration
  • Computing power in FLOPS (FLOP per Second)

• Example: Global Climate Modeling
  • Divide the world into a grid (e.g. 10 km spacing)
  • Solve fluid dynamics equations for each point & minute
    ▪ Requires about 100 Flops per grid point per minute
  • Weather Prediction (7 days in 24 hours):
    ▪ 56 Gflops
  • Climate Prediction (50 years in 30 days):
    ▪ 4.8 Tflops

• Perspective
  • Pentium 4 3GHz Desktop Processor
    ▪ ~6-12 Gflops
    ▪ Climate Prediction would take ~50-100 years


www.epm.ornl.gov/chammp/chammp.html
Recent History of Parallel Computing

- Parallel Computing as a field exploded in popularity in the mid-1990s
- This resulted in an “arms race” between universities, research labs, and governments to have the fastest supercomputer in the world
  - LINPACK (solving dense system of linear equations) is benchmark

Source: top500.org
Current Champions (June 2007)

BlueGene/L – eServer Blue Gene Solution
IBM DOE / NNSA / LLNL
Livermore, CA, United States
65,536 dual-processors, 280.6 Tflops/s
0.7 GHz PowerPC 440, IBM

Jaguar – Cray XT3 & XT4
NCLF / Oak Ridge National Lab
Oak Ridge, TN, United States
11,706 Processors, 119 Tflops/s
2.6 GHz dual-core Opteron, Cray Inc.

Red Storm – Sandia / Cray Red Storm
NNSA / Sandia National Laboratories
Albuquerque, NM, United States
26,544 Processors, 101.4 Tflops/s
2.4 GHz dual-core Opteron, Cray Inc.
The Future of Parallelism

“Parallelism is the biggest challenge since high level programming languages. It’s the biggest thing in 50 years because industry is betting its future that parallel programming will be useful.”

– David Patterson
Distributed Computing Themes

• Let’s network many disparate machines into one compute cluster

• These could all be the same (easier) or very different machines (harder)

• Common themes
  • “Dispatcher” gives jobs & collects results
  • “Workers” (get, process, return) until done

• Examples
  • SETI@Home, BOINC, Render farms
  • Google clusters running MapReduce
Distributed Computing Challenges

• Communication is fundamental difficulty
  • Distributing data, updating shared resource, communicating results
  • Machines have separate memories, so no usual inter-process communication – need network
  • Introduces inefficiencies: overhead, waiting, etc.

• Need to parallelize algorithms
  • Must look at problems from parallel standpoint
  • Tightly coupled problems require frequent communication (more of the slow part!)
  • We want to decouple the problem
    ▪ Increase data locality
    ▪ Balance the workload
# Things to Worry About: Parallelizing Code

- Applications can almost **never** be completely parallelized; some serial code remains.

\[ \text{Speedup}(P) = \frac{\text{Time}(1)}{\text{Time}(P)} \leq \frac{1}{s + \left(\frac{1-s}{P}\right)} \], and as \( P \to \infty \)

\[ \leq \frac{1}{s} \]

- Even if the parallel portion of your application speeds up perfectly, your performance may be limited by the sequential portion.
But… What About Overhead?

• Amdahl’s law ignores overhead
  • E.g. from communication, synchronization

• Amdahl’s is useful for bounding a program’s speedup, but cannot predict speedup
Peer Instruction of Assumptions

1. Writing & managing SETI@Home is relatively straightforward; just hand out & gather data

2. Most parallel programs that, when run on N (N big) identical supercomputer processors will yield close to N x performance increase

3. The majority of the world’s computing power lives in supercomputer centers
Peer Instruction Answer

1. The heterogeneity of the machines, handling machines that fail, falsify data. FALSE

2. The combination of Amdahl’s law, overhead, and load balancing take its toll. FALSE

3. Have you considered how many PCs + game devices exist? Not even close. FALSE

1. Writing & managing SETI@Home is relatively straightforward; just hand out & gather data

2. Most parallel programs that, when run on N (N big) identical supercomputer processors will yield close to N x performance increase

3. The majority of the world’s computing power lives in supercomputer centers
Summary

• Parallelism is necessary
  • It looks like the future of computing…
  • It is unlikely that serial computing will ever catch up with parallel computing

• Software parallelism
  • Grids and clusters, networked computers
  • Two common ways to program:
    ▪ Message Passing Interface (lower level)
    ▪ MapReduce (higher level, more constrained)

• Parallelism is often difficult
  • Speedup is limited by serial portion of code and communication overhead
A New Hope: Google’s MapReduce

• Remember CS61A?

\[
\begin{align*}
(\text{reduce} & + (\text{map} \ \text{square} \ ' (1 \ 2 \ 3))) \Rightarrow \\
(\text{reduce} & + ' (1 \ 4 \ 9)) \Rightarrow \\
14
\end{align*}
\]

• We told you “the beauty of pure functional programming is that it’s easily parallelizable”
  • Do you see how you could parallelize this?
  • What if the `reduce` function argument were associative, would that help?

• Imagine 10,000 machines ready to help you compute anything you could cast as a MapReduce problem!
  • This is the abstraction Google is famous for authoring (but their `reduce` not the same as the CS61A’s or MPI’s `reduce`)
    ▪ Builds a reverse-lookup table
  • It hides LOTs of difficulty of writing parallel code!
  • The system takes care of load balancing, dead machines, etc.
MapReduce Programming Model

Input & Output: each a set of key/value pairs

Programmer specifies two functions:

**map** \((in\_key, in\_value) \rightarrow \text{list}(out\_key, intermediate\_value)\)
- Processes input key/value pair
- Produces set of intermediate pairs

**reduce** \((out\_key, \text{list}(intermediate\_value)) \rightarrow \text{list}(out\_value)\)
- Combines all intermediate values for a particular key
- Produces a set of merged output values (usu just one)

[link](code.google.com/edu/parallel/mapreduce-tutorial.html)
MapReduce Code Example

```java
map(String input_key,
    String input_value):
    // input_key : document name
    // input_value: document contents
    for each word w in input_value:
        EmitIntermediate(w, "1");

reduce(String output_key,
        Iterator intermediate_values):
    // output_key : a word
    // output_values: a list of counts
    int result = 0;
    for each v in intermediate_values:
        result += ParseInt(v);
    Emit(AsString(result));
```

- “Mapper” nodes are responsible for the `map` function
- “Reducer” nodes are responsible for the `reduce` function
- Data on a distributed file system (DFS)
MapReduce Example Diagram

Input:

<table>
<thead>
<tr>
<th>file_1</th>
<th>file_2</th>
<th>file_3</th>
<th>file_4</th>
<th>file_5</th>
<th>file_6</th>
<th>file_7</th>
</tr>
</thead>
<tbody>
<tr>
<td>ah ah er</td>
<td>ah</td>
<td>if or</td>
<td>or uh</td>
<td>or</td>
<td>ah if</td>
<td></td>
</tr>
</tbody>
</table>

map(String input_key, String input_value):
  // input_key: doc name
  // input_value: doc contents
  for each word w in input_value:
    EmitIntermediate(w, "1");

Intermediate:

<table>
<thead>
<tr>
<th>k1:v</th>
<th>k1:v</th>
<th>k2:v</th>
<th>k1:v</th>
<th>k3:v</th>
<th>k4:v</th>
<th>k4:v</th>
<th>k5:v</th>
<th>k1:v</th>
<th>k3:v</th>
</tr>
</thead>
<tbody>
<tr>
<td>ah:1</td>
<td>ah:1</td>
<td>er:1</td>
<td>ah:1</td>
<td>if:1</td>
<td>or:1</td>
<td>or:1</td>
<td>uh:1</td>
<td>or:1</td>
<td>ah:1</td>
</tr>
</tbody>
</table>

Group by Key:

| ah:1,1,1,1 | er:1 | if:1,1 or:1,1,1 | uh:1 |

Grouped:

<table>
<thead>
<tr>
<th>k1:v,v,v,v</th>
<th>k2:v</th>
<th>k3:v,v</th>
<th>k4:v,v,v</th>
<th>k5:v</th>
</tr>
</thead>
</table>

reduce(String output_key, Iterator intermediate_values):
  // output_key: a word
  // output_values: a list of counts
  int result = 0;
  for each v in intermediate_values:
    result += ParseInt(v);
  Emit(AsString(result));

Output:

<table>
<thead>
<tr>
<th>4</th>
<th>1</th>
<th>2</th>
<th>3</th>
<th>1</th>
</tr>
</thead>
<tbody>
<tr>
<td>(ah)</td>
<td>(er)</td>
<td>(if)</td>
<td>(or)</td>
<td>(uh)</td>
</tr>
</tbody>
</table>
MapReduce Advantages/Disadvantages

- Now it’s easy to program for many CPUs
  - Communication management effectively gone
    - I/O scheduling done for us
  - Fault tolerance, monitoring
    - Machine failures, suddenly-slow machines, other issues are handled
  - Can be much easier to design and program!

- But… it further restricts solvable problems
  - Might be hard to express some problems in a MapReduce framework
  - Data parallelism is key
    - Need to be able to break up a problem by data chunks
  - MapReduce is closed-source – Hadoop!