

# EE100Su08 Lecture #11 (July 21<sup>st</sup> 2008)

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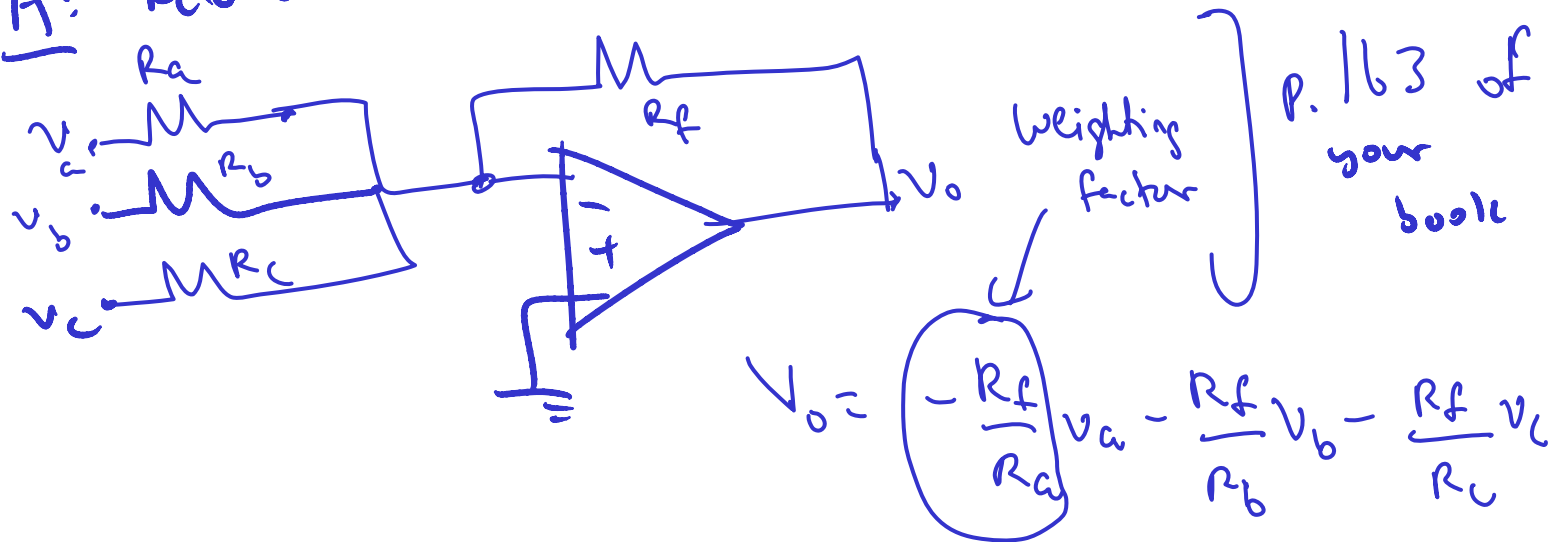
- Bureaucratic Stuff
  - Lecture videos should be up by tonight
  - HW #2: Pick up from office hours today, will leave them in lab.  
REGRADE DEADLINE: Monday, July 28<sup>th</sup> 2008, 5:00 pm PST, Bart's office hours.
  - HW #1: Pick up from lab.
  - Midterm #1: Pick up from me in OH  
REGRADE DEADLINE: Wednesday, July 23<sup>rd</sup> 2008, 5:00 pm PST. Midterm: drop off in hw box with a note attached on the first page explaining your request.
- OUTLINE
  - QUESTIONS?
  - Op-amp MultiSim example
  - Introduction and Motivation
  - Arithmetic with Complex Numbers (Appendix B in your book)
  - Phasors as notation for Sinusoids
  - Complex impedances
  - Circuit analysis using complex impedances
  - Derivative/Integration as multiplication/division
  - Phasor Relationship for Circuit Elements
  - Frequency Response and Bode plots
- Reading
  - Chapter 9 from your book (skip 9.10, 9.11 (duh)), Appendix E\* (skip second-order resonance bode plots)
  - Chapter 1 from your reader (skip second-order resonance bode plots)

# Op-amps: Conclusion

- Questions?

Ex 5-2 → What do you mean by a "weighting factor"?

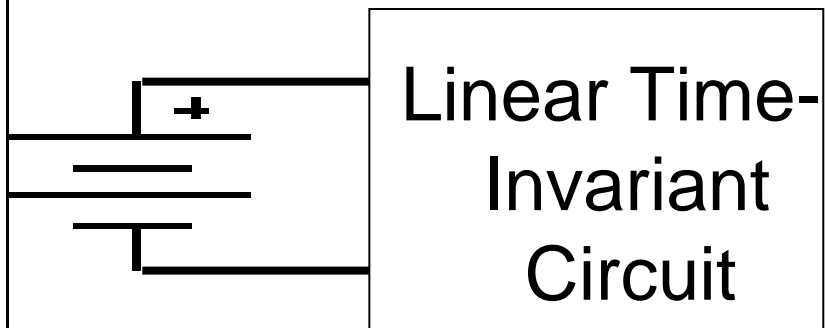
A: Related to the summing amplifiers!



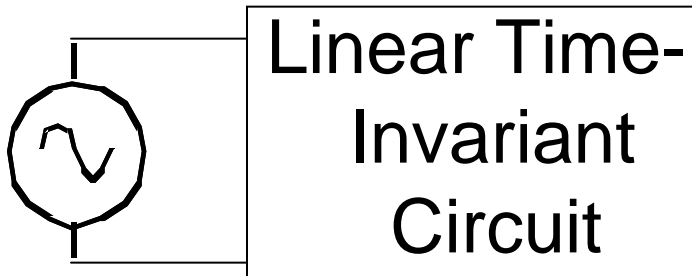
- MultiSim Example

# Types of Circuit Excitation

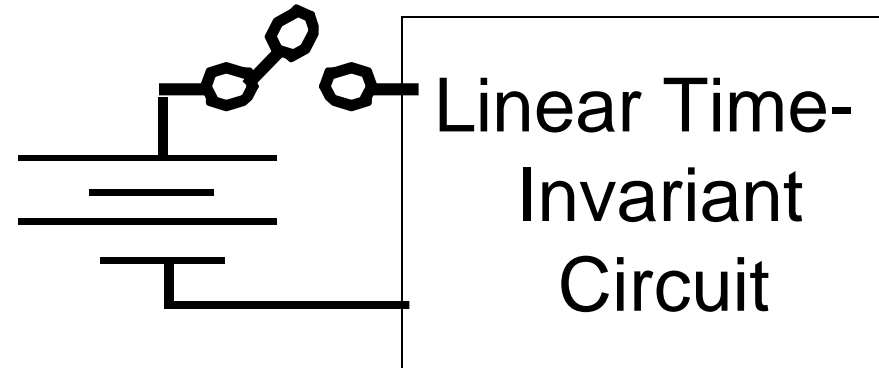
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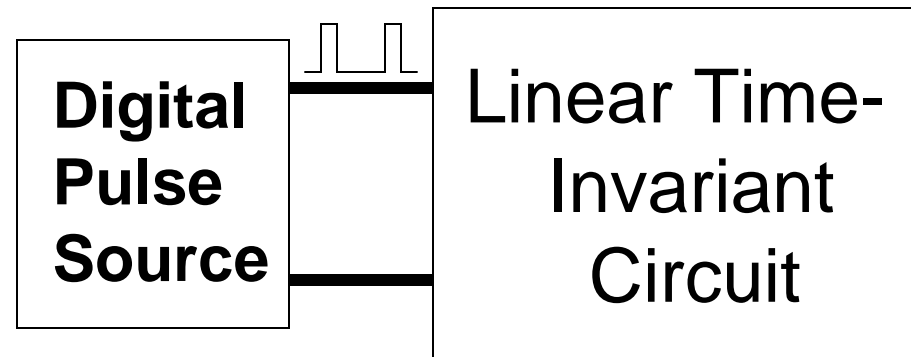
**Steady-State Excitation  
(DC Steady-State)**



**Sinusoidal (Single-Frequency) Excitation  
→ AC Steady-State**



**OR**



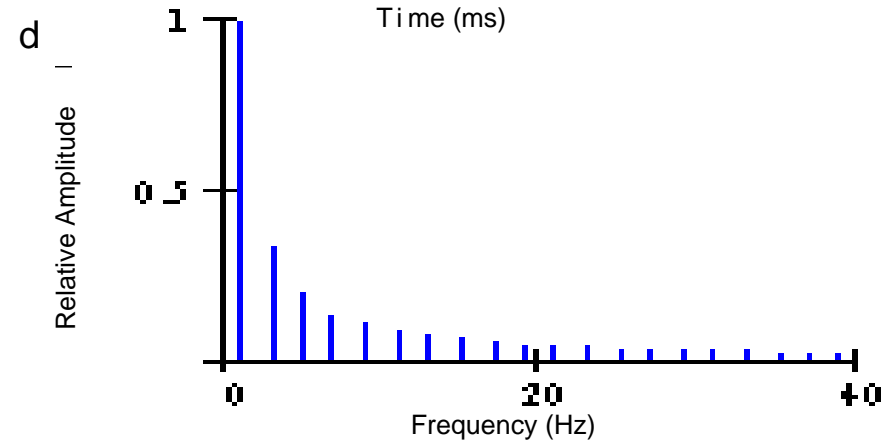
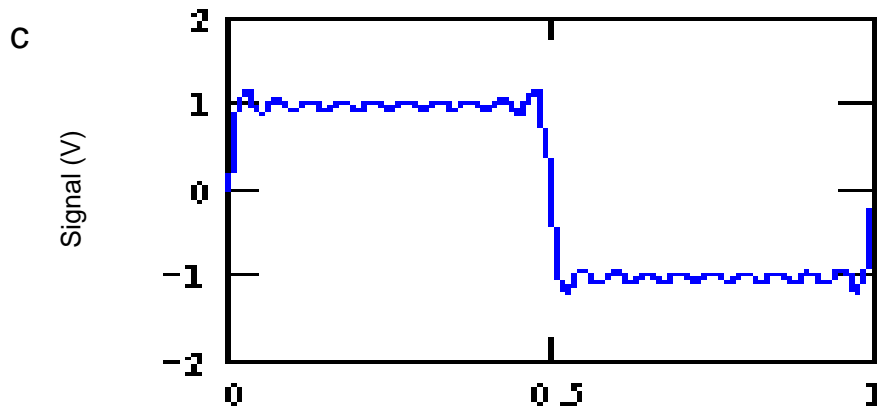
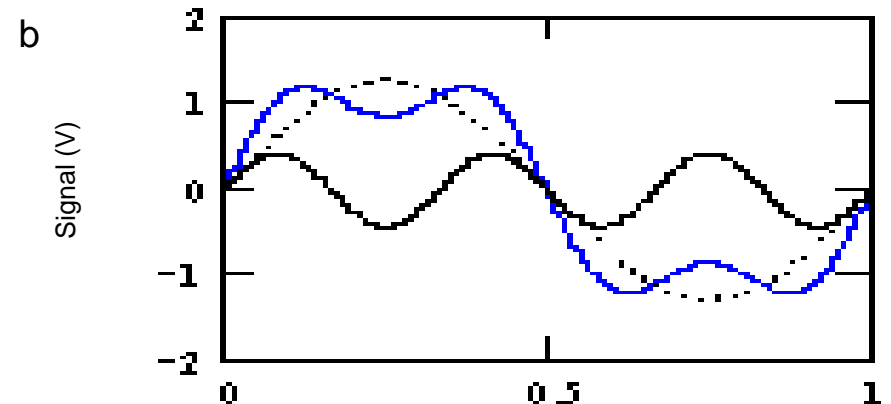
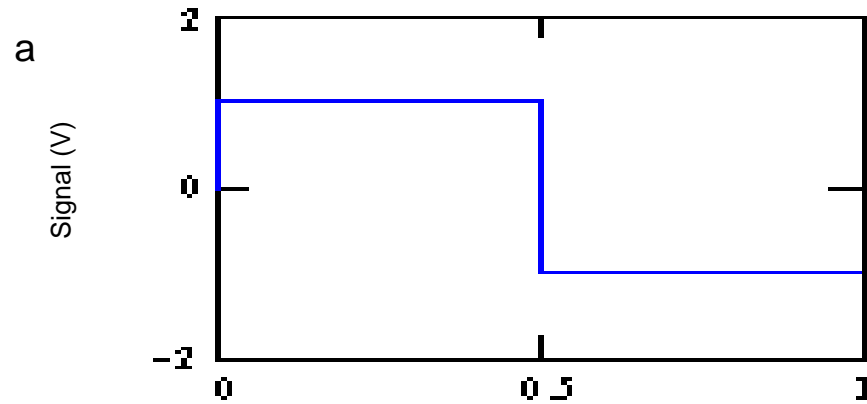
**Transient Excitation**

## Why is Single-Frequency Excitation Important?

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- Some circuits are driven by a single-frequency sinusoidal source.
- Some circuits are driven by sinusoidal sources whose frequency changes slowly over time.
- You can express any periodic electrical signal as a sum of single-frequency sinusoids – so you can analyze the response of the (linear, time-invariant) circuit to each individual frequency component and then sum the responses to get the total response.
- This is known as Fourier Transform and is tremendously important to all kinds of engineering disciplines!

# Representing a Square Wave as a Sum of Sinusoids



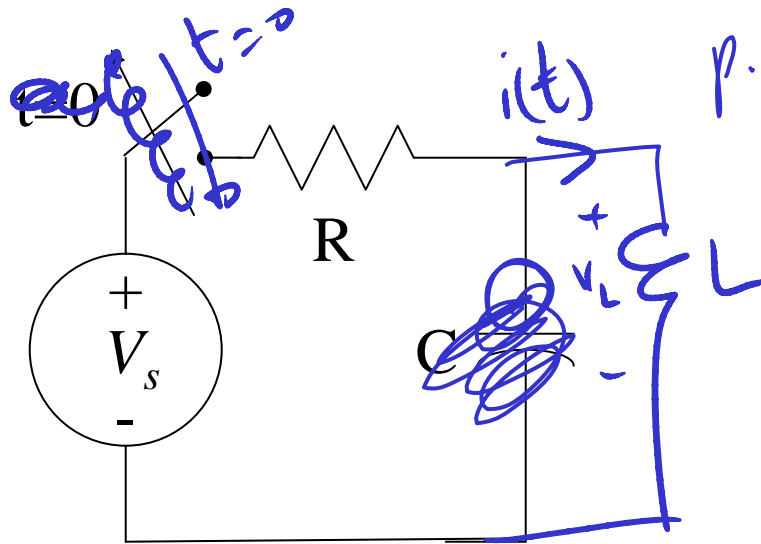
(a) Square wave with 1-second period. (b) Fundamental component (dotted) with 1-second period, third-harmonic (solid black) with 1/3-second period, and their sum (blue). (c) Sum of first ten components. (d) Spectrum with 20 terms.

# Steady-State Sinusoidal Analysis

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- Also known as AC **steady-state**
- Any steady state voltage or current in a linear circuit with a sinusoidal source is a sinusoid.
  - This is a consequence of the nature of particular solutions for sinusoidal forcing functions.
- All AC steady state voltages and currents have the same frequency as the source.
- In order to find a steady state voltage or current, all we need to know is its magnitude and its phase relative to the source
  - We already know its frequency.
- Usually, an AC steady state voltage or current is given by the **particular solution** to a differential equation.

# Example: 1<sup>st</sup> order RC Circuit with sinusoidal excitation



p. 335-337

"sinusoid"

Subst.  $v_s(t) = V_m \cos(\omega t + \phi)$   
 [Find expression for determining  $i(t)$ ?]  
 $(t \geq 0)$

KVL:  $iR + v_L = v_s$

$$\Rightarrow iR + L \frac{di}{dt} = v_s(t)$$

Solution: 
$$i(t) = \underbrace{\frac{-V_m}{\sqrt{R^2 + \omega^2 L^2}} \cos(\phi - \theta) e^{-(R/L)t}}_{\text{transient}} + \underbrace{\frac{V_m}{\sqrt{R^2 + \omega^2 L^2}} \cos(\omega t + \phi - \theta)}_{\text{steady-state}}$$

# Sinusoidal Sources Create Too Much Algebra

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$$x_p(t) + \tau \frac{dx_p(t)}{dt} = F_A \sin(\omega t) + F_B \cos(\omega t)$$

Guess a solution

Two terms to be general

$$x_p(t) = A \sin(\omega t) + B \cos(\omega t)$$

$$(A \sin(\omega t) + B \cos(\omega t)) + \tau \frac{d(A \sin(\omega t) + B \cos(\omega t))}{dt} = F_A \sin(\omega t) + F_B \cos(\omega t)$$

$$(A - \tau B - F_A) \sin(\omega t) + (B + \tau A - F_B) \cos(\omega t) = 0$$

Equation holds for all time  
and time variations are  
independent and thus each  
time variation coefficient is  
individually zero

$$(A - \tau B - F_A) = 0$$

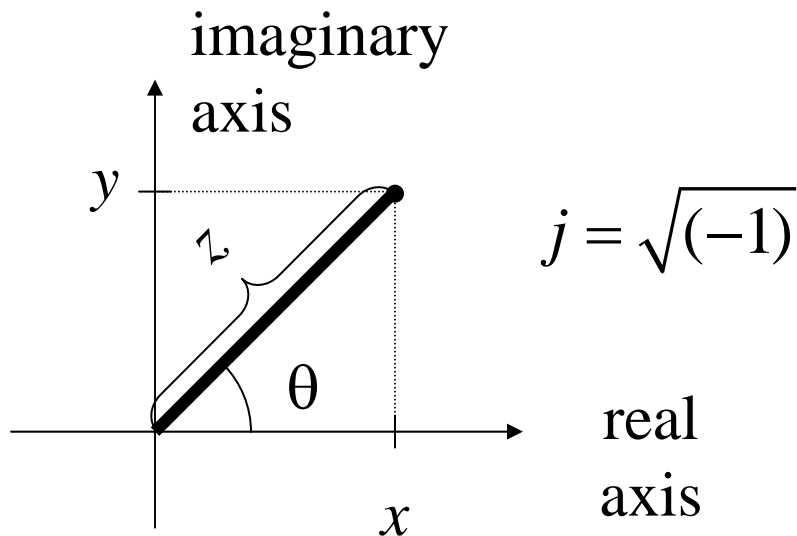
$$(B + \tau A - F_B) = 0$$

$$A = \frac{F_A + \tau F_B}{\tau^2 + 1} \quad B = -\frac{\tau F_A - F_B}{\tau^2 + 1}$$

**Phasors (vectors that rotate in the complex plane) are a clever alternative.**



# Complex Numbers (1)



- $x$  is the real part
- $y$  is the imaginary part
- $z$  is the magnitude
- $\theta$  is the phase

$$x = z \cos \theta \quad y = z \sin \theta$$

$$z = \sqrt{x^2 + y^2} \quad \theta = \tan^{-1} \frac{y}{x}$$

$$\mathbf{Z} = z(\cos \theta + j \sin \theta)$$

$$1 = 1e^{j0} = 1\angle 0^\circ$$

$$j = 1e^{j\frac{\pi}{2}} = 1\angle 90^\circ$$

- Rectangular Coordinates

$$\mathbf{Z} = x + jy$$

- Polar Coordinates:

$$\mathbf{Z} = z \angle \theta$$

- Exponential Form:

$$\mathbf{Z} = |\mathbf{Z}| e^{j\theta} = z e^{j\theta}$$

## Complex Numbers (2)

### Euler's Identities

Bart's fav. ident's

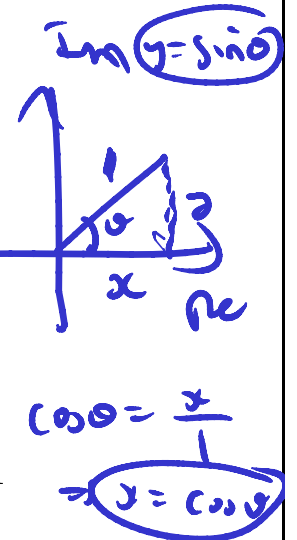
$$\underline{e^{j\pi} + 1 = 0}$$

$$\cos \theta = \frac{e^{j\theta} + e^{-j\theta}}{2}$$

$$\sin \theta = \frac{e^{j\theta} - e^{-j\theta}}{2j}$$

$$e^{j\theta} = \cos \theta + j \sin \theta$$

$$|e^{j\theta}| = \sqrt{\cos^2 \theta + \sin^2 \theta} = 1$$



### Exponential Form of a complex number

$$\mathbf{Z} = |\mathbf{Z}| e^{j\theta} = z e^{j\theta} = z \angle \theta$$

# Arithmetic With Complex Numbers

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- To compute phasor voltages and currents, we need to be able to perform computation with complex numbers.
  - Addition
  - Subtraction
  - Multiplication
  - Division
- Later use multiplication by  $j\omega$  to replace:
  - Differentiation
  - Integration

# Addition

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- Addition is most easily performed in rectangular coordinates:

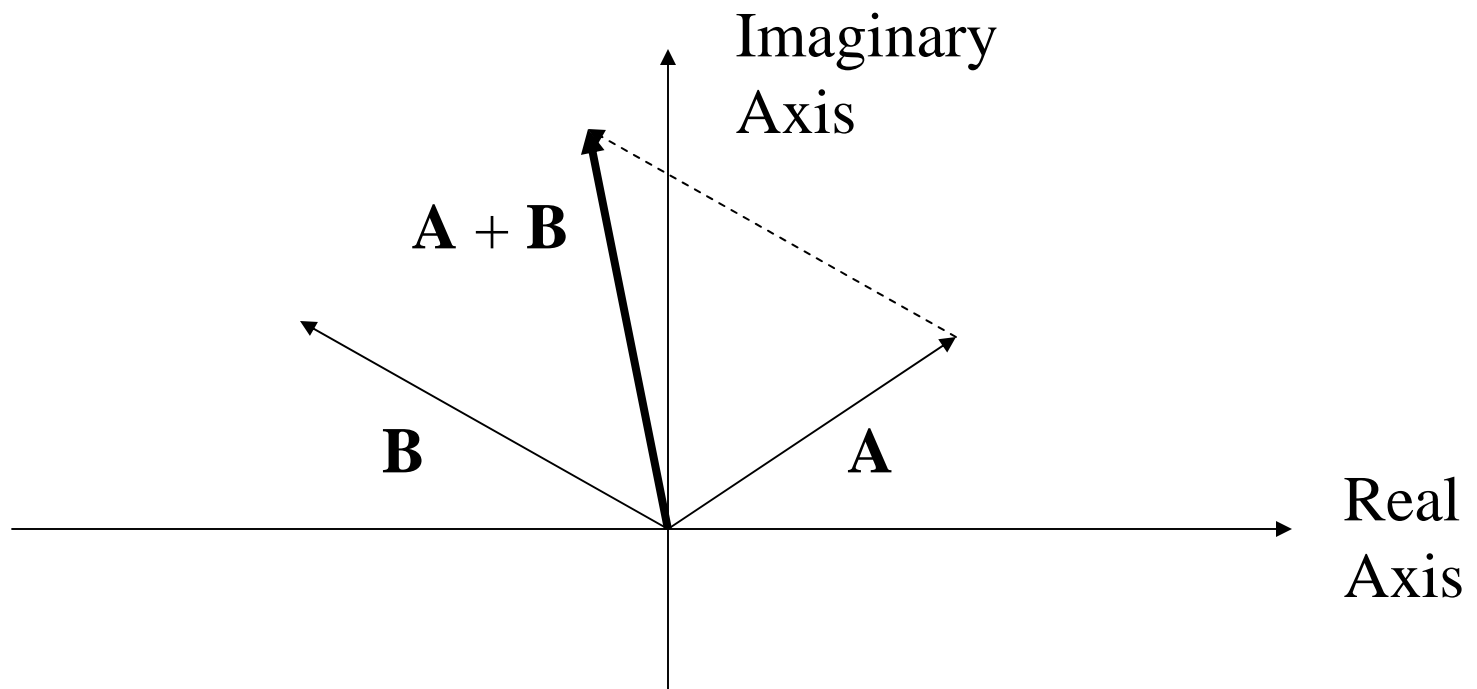
$$\mathbf{A} = x + jy$$

$$\mathbf{B} = z + jw$$

$$\mathbf{A} + \mathbf{B} = (x + z) + j(y + w)$$

# Addition

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# Subtraction

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- Subtraction is most easily performed in rectangular coordinates:

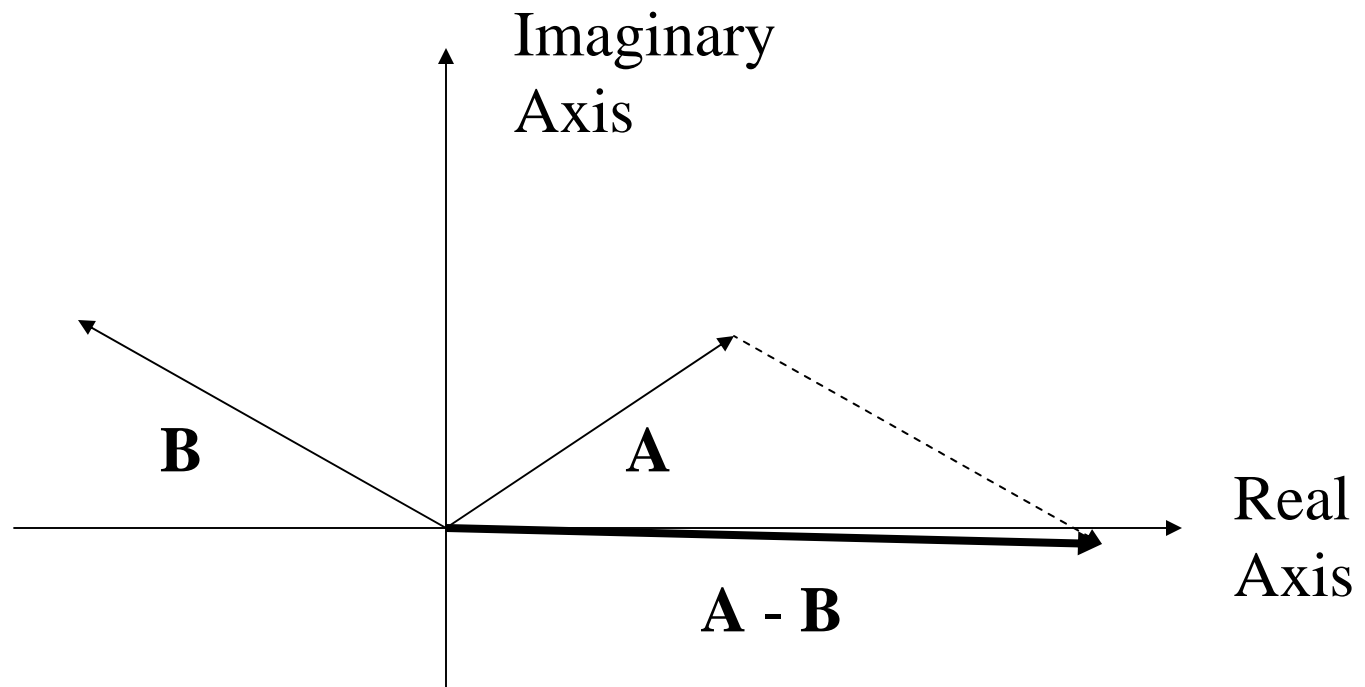
$$\mathbf{A} = x + jy$$

$$\mathbf{B} = z + jw$$

$$\mathbf{A} - \mathbf{B} = (x - z) + j(y - w)$$

# Subtraction

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# Multiplication

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- Multiplication is most easily performed in polar coordinates:

$$\mathbf{A} = A_M \angle \theta$$

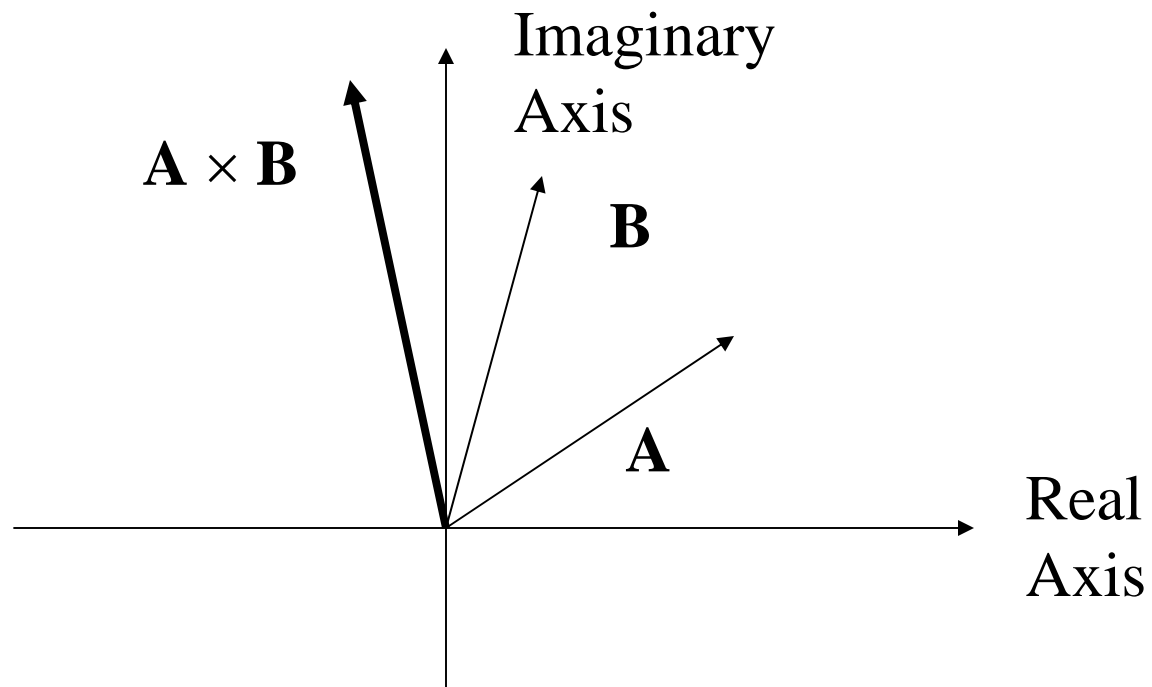
$$\mathbf{B} = B_M \angle \phi$$

$$\mathbf{A} \times \mathbf{B} = (A_M \times B_M) \angle (\theta + \phi)$$



# Multiplication

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# Division

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- Division is most easily performed in polar coordinates:

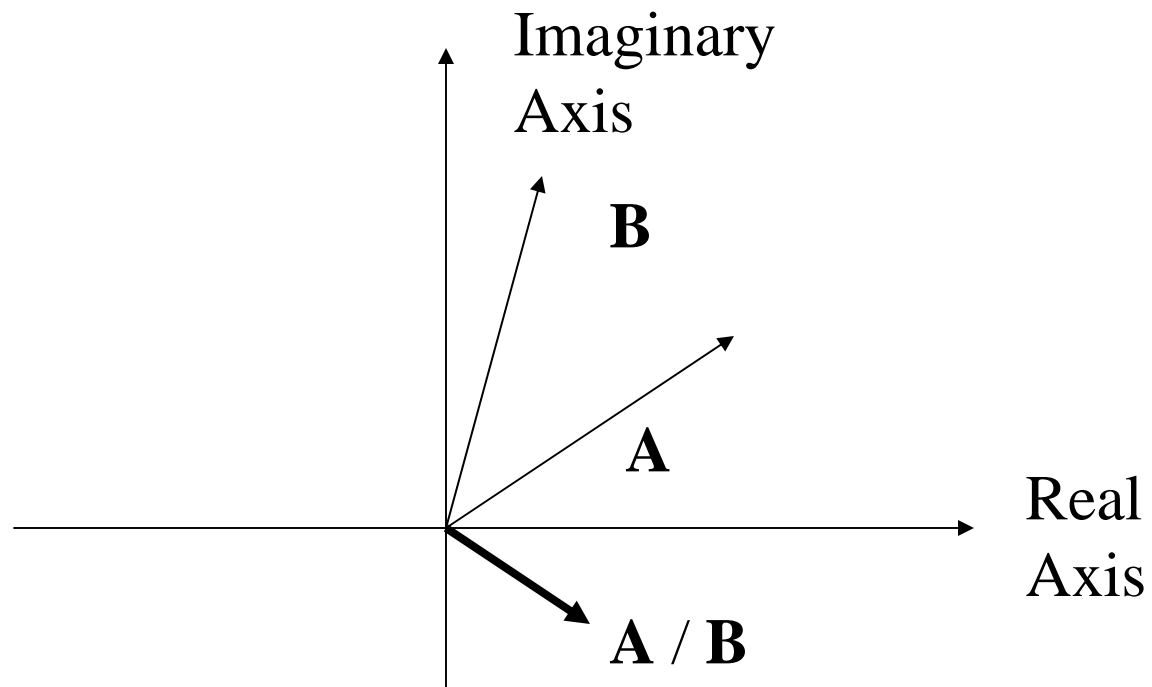
$$\mathbf{A} = A_M \angle \theta$$

$$\mathbf{B} = B_M \angle \phi$$

$$\mathbf{A} / \mathbf{B} = (A_M / B_M) \angle (\theta - \phi)$$

# Division

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# Arithmetic Operations of Complex Numbers

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- Add and Subtract: it is easiest to do this in rectangular format
  - Add/subtract the real and imaginary parts separately
- Multiply and Divide: it is easiest to do this in exponential/polar format
  - Multiply (**divide**) the magnitudes
  - Add (**subtract**) the phases

$$\mathbf{Z}_1 = z_1 e^{j\theta_1} = z_1 \angle \theta_1 = z_1 \cos \theta_1 + jz_1 \sin \theta_1$$

$$\mathbf{Z}_2 = z_2 e^{j\theta_2} = z_2 \angle \theta_2 = z_2 \cos \theta_2 + jz_2 \sin \theta_2$$

$$\mathbf{Z}_1 + \mathbf{Z}_2 = (z_1 \cos \theta_1 + z_2 \cos \theta_2) + j(z_1 \sin \theta_1 + z_2 \sin \theta_2)$$

$$\mathbf{Z}_1 - \mathbf{Z}_2 = (z_1 \cos \theta_1 - z_2 \cos \theta_2) + j(z_1 \sin \theta_1 - z_2 \sin \theta_2)$$

$$\mathbf{Z}_1 \times \mathbf{Z}_2 = (z_1 \times z_2) e^{j(\theta_1 + \theta_2)} = (z_1 \times z_2) \angle (\theta_1 + \theta_2)$$

$$\mathbf{Z}_1 / \mathbf{Z}_2 = (z_1 / z_2) e^{j(\theta_1 - \theta_2)} = (z_1 / z_2) \angle (\theta_1 - \theta_2)$$

# Phasors

- Assuming a source voltage is a sinusoid time-varying function

$$v(t) = V \cos(\omega t + \theta)$$

*Handwritten:*  $V \operatorname{Re}[e^{j(\omega t + \theta)}]$   
 $= V \operatorname{Re}\{\cos(\omega t + \theta) + j \sin(\omega t + \theta)\}$

- We can write:

$$v(t) = V \cos(\omega t + \theta) = V \operatorname{Re}[e^{j(\omega t + \theta)}] = \operatorname{Re}[V e^{j(\omega t + \theta)}]$$

Define Phasor as  $V e^{j\theta} = V \angle \theta$

*Handwritten:* Do NOT put a "time" anywhere in a phasor!

- Similarly, if the function is  $v(t) = V \sin(\omega t + \theta)$

$$v(t) = V \sin(\omega t + \theta) = V \cos(\omega t + \theta - \frac{\pi}{2}) = \operatorname{Re}\left[V e^{j(\omega t + \theta - \frac{\pi}{2})}\right]$$

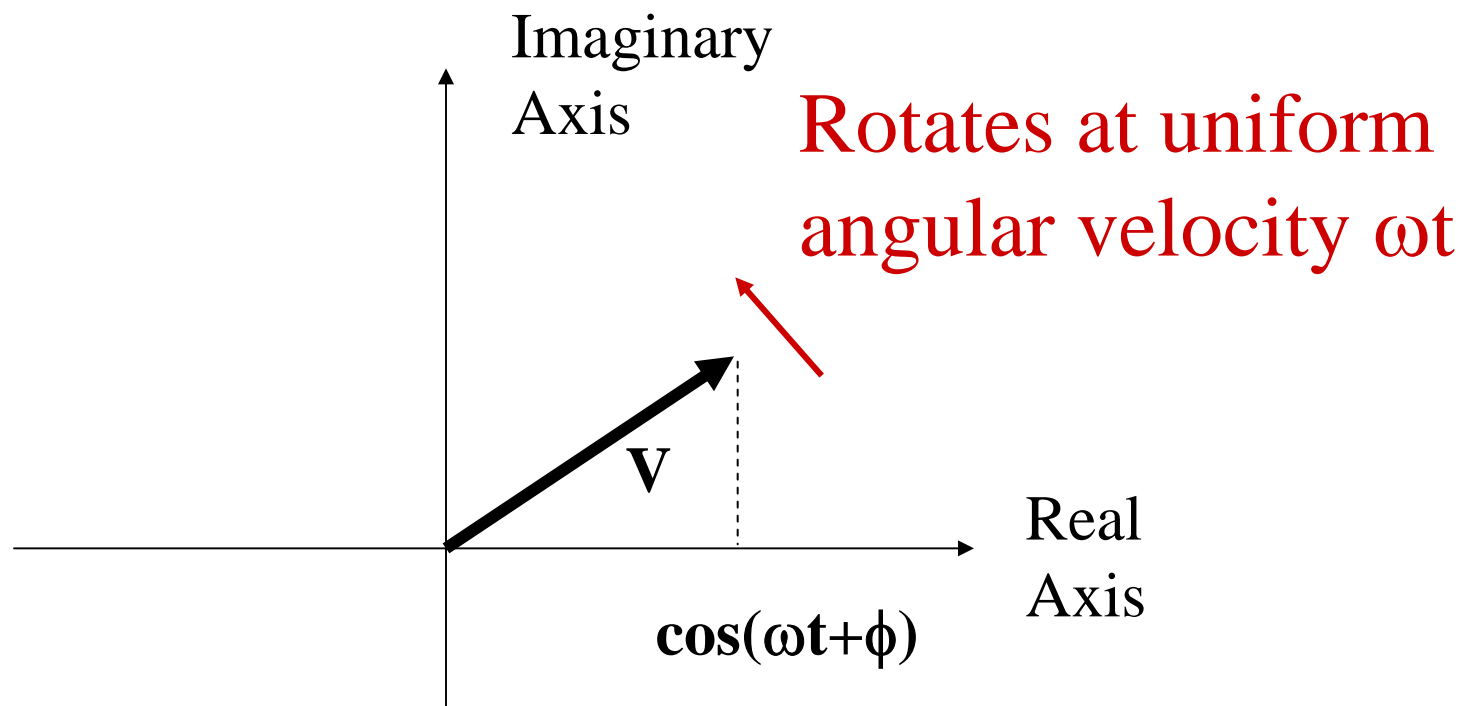
Phasor =  $V \angle \left(\theta - \frac{\pi}{2}\right)$

*Handwritten:*  $V \operatorname{Re}[e^{j(\omega t + \theta)}] = V \operatorname{Re}[e^{j\omega t} \cdot e^{j\theta}]$   
 $= \operatorname{Re}[V e^{j\theta} \cdot e^{j\omega t}]$

# Phasor: Rotating Complex Vector

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$$v(t) = V \cos(\omega t + \phi) = \operatorname{Re}\{V e^{j\phi} e^{j\omega t}\} = \operatorname{Re}(V e^{j\omega t})$$



**The head start angle is  $\phi$ .**

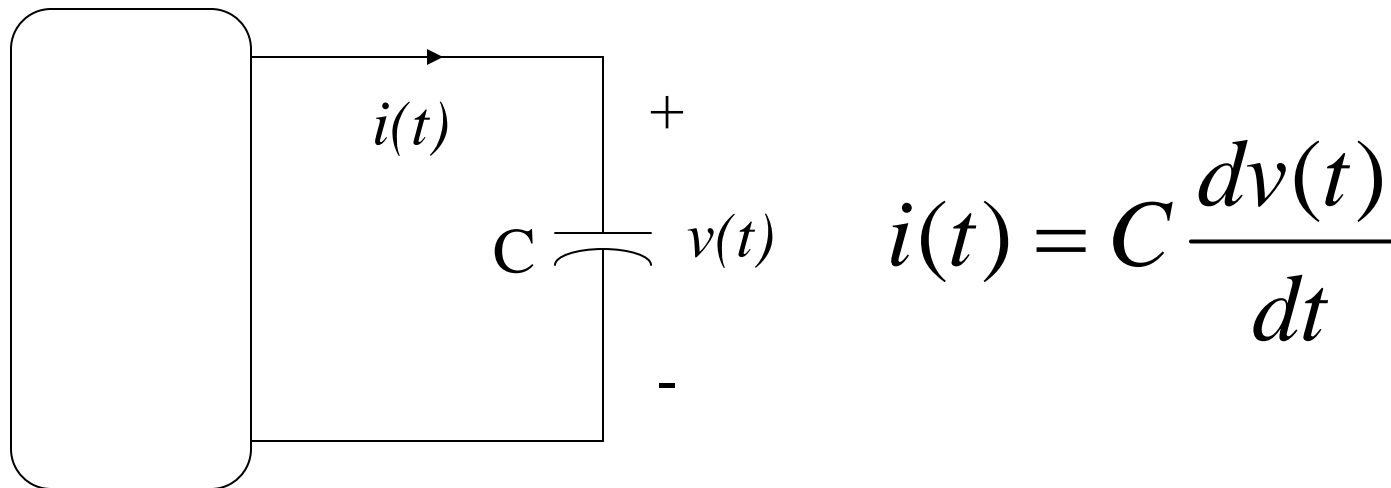
# Complex Exponentials

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- We represent a real-valued sinusoid as the **real part of a complex exponential after multiplying by  $e^{j\omega t}$** .
- Complex exponentials
  - provide the link between time functions and phasors.
  - Allow derivatives and integrals to be replaced by multiplying or dividing by  $j\omega$
  - make solving for AC steady state simple algebra with complex numbers.
- Phasors allow us to express current-voltage relationships for inductors and capacitors much like we express the current-voltage relationship for a resistor.

# I-V Relationship for a Capacitor

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Suppose that  $v(t)$  is a sinusoid:

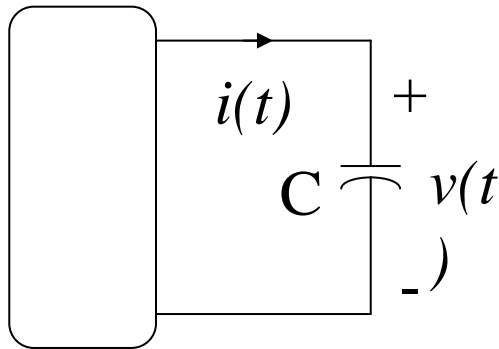
$$v(t) = \text{Re}\{V e^{j(\omega t + \theta)}\}$$

Find  $i(t)$ .

$$= \text{Re}\left[ V \cdot \cos(\omega t + \theta) + j V \sin(\omega t + \theta) \right]$$
$$= V \cdot \cos(\omega t + \theta)$$



# Capacitor Impedance (1)



$$i(t) = C \frac{dv(t)}{dt}$$

Handwritten notes:

$$v(t) = V \cos(\omega t + \theta)$$

$$i = C \frac{d}{dt} [V \cos(\omega t + \theta)]$$

$$= -C V \sin(\omega t + \theta) \cdot \omega$$

$$v(t) = V \cos(\omega t + \theta) = \frac{V}{2} [e^{j(\omega t + \theta)} + e^{-j(\omega t + \theta)}]$$

$$i(t) = C \frac{dv(t)}{dt} = \frac{CV}{2} \frac{d}{dt} [e^{j(\omega t + \theta)} + e^{-j(\omega t + \theta)}] = \frac{CV}{2} j\omega [e^{j(\omega t + \theta)} - e^{-j(\omega t + \theta)}]$$

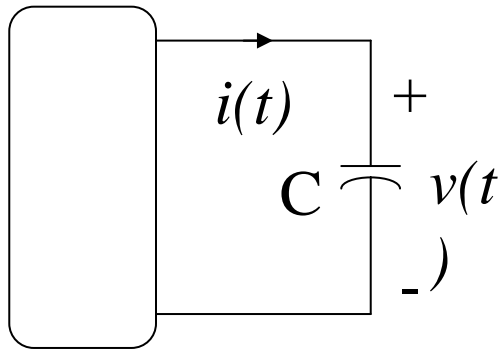
$$= \frac{-\omega CV}{2j} [e^{j(\omega t + \theta)} - e^{-j(\omega t + \theta)}] = -\omega CV \sin(\omega t + \theta) = \omega CV \cos(\omega t + \theta + \frac{\pi}{2})$$

$$Z_c = \frac{V}{I} = \frac{V \angle \theta}{I \angle (\theta + \frac{\pi}{2})} = \frac{V}{\omega CV} \angle (\theta - \theta - \frac{\pi}{2}) = \frac{1}{\omega C} \angle (-\frac{\pi}{2}) = -j \frac{1}{\omega C} = \frac{1}{j\omega C}$$

Handwritten notes for impedance:

$$\text{Impedance} \rightarrow Z_c = \frac{V \angle \theta}{I} = \frac{V \angle \theta}{\omega CV \angle (\theta + \pi/2)}$$

# Capacitor Impedance (2)



$$i(t) = C \frac{dv(t)}{dt}$$

Phasor definition

$$v(t) = V \cos(\omega t + \theta) = \text{Re} \left[ V e^{j(\omega t + \theta)} \right] \Rightarrow \mathbf{V} = V \angle \theta$$

$$i(t) = C \frac{dv(t)}{dt} = \text{Re} \left[ C V \frac{d e^{j(\omega t + \theta)}}{dt} \right] = \text{Re} \left[ j\omega C V e^{j(\omega t + \theta)} \right] \Rightarrow \mathbf{I} = I \angle \theta$$

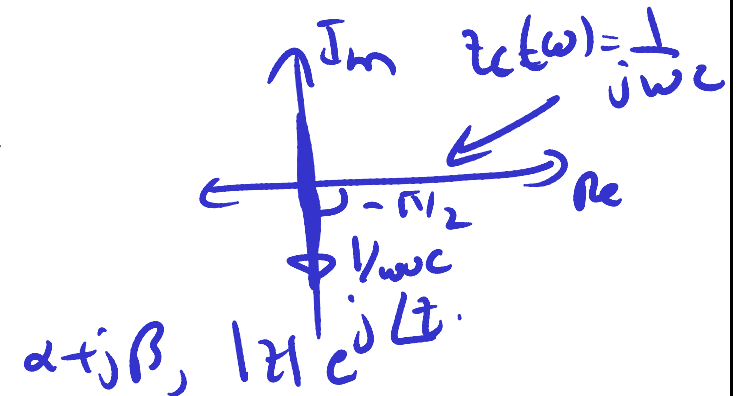
$$Z_c = \frac{\mathbf{V}}{\mathbf{I}} = \frac{V \angle \theta}{I \angle \theta} = \frac{V}{j\omega C V} \angle(\theta - \theta) = \frac{1}{j\omega C}$$

Points to note:

$$(1) Z_c(\omega) = \frac{1}{j\omega C} = -j \frac{1}{\omega C}$$

$|Z_c| = \frac{1}{\omega C}$   
 $\angle Z_c = -90^\circ$

Note:  $\omega = 2\pi f$



# Example

$\omega = 2\pi \cdot 60$  Watt outlet

$$v(t) = 120V \cos(377t + 30^\circ)$$

$$C = 2\mu F$$

- What is  $V$ ?
- What is  $I$ ?
- What is  $i(t)$ ?

$\frac{\pi}{6}$

$$\frac{120 \angle \frac{\pi}{6}}{\frac{1}{\omega C} \angle -\frac{\pi}{2}} = 120\omega C \angle \frac{\pi}{6} + \frac{\pi}{2} \Big|_{\omega=377}$$

$\bar{V} = 120 \angle \frac{\pi}{6}$	$\bar{I} \rightarrow i(t)$ $= \frac{\bar{V}}{Z_C} = \frac{120 \angle \frac{\pi}{6}}{\frac{1}{\omega C}}$	$i(t) = C \frac{dv}{dt}$ $= (2\mu F) \frac{d}{dt} (120V \cos(377t + \frac{\pi}{6}))$ $= -(2\mu F)(120V) \sin(377t + \frac{\pi}{6})$
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# Computing the Current

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Advantage of phasors!

[Capacitor:  $i = C \frac{dv}{dt}$   
 $\Rightarrow \bar{I} = \bar{V} / \frac{1}{j\omega C}$ ]

[Inductor: READ THE BOOK]

Note: The differentiation and integration operations become algebraic operations

$$\frac{d}{dt} \Rightarrow j\omega$$

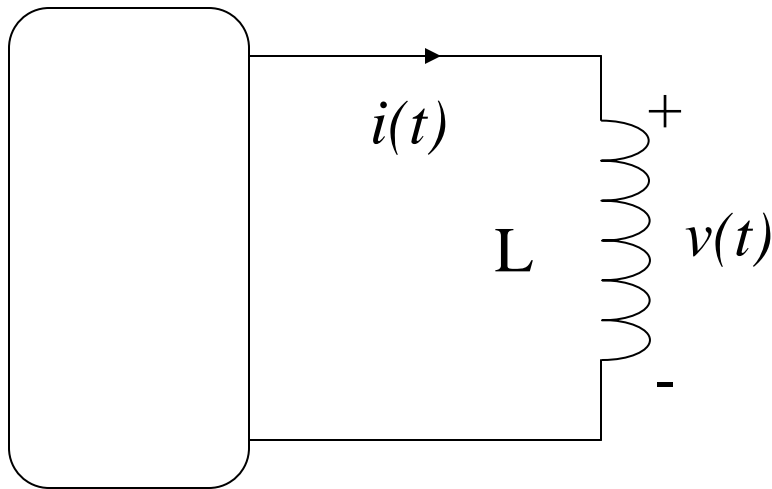
$$\int dt \Rightarrow \frac{1}{j\omega}$$

(Sections 9.1 - 9.4)

# Inductor Impedance

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[Section 9.4 in your book]



$$v(t) = L \frac{di(t)}{dt}$$

$$\mathbf{V} = j\omega L \mathbf{I}$$

## Example

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$$i(t) = 1\mu\text{A} \cos(2\pi \cdot 9.15 \cdot 10^7 t + 30^\circ)$$

$$L = 1\mu\text{H}$$

- What is **I**?
- What is **V**?
- What is  $v(t)$ ?

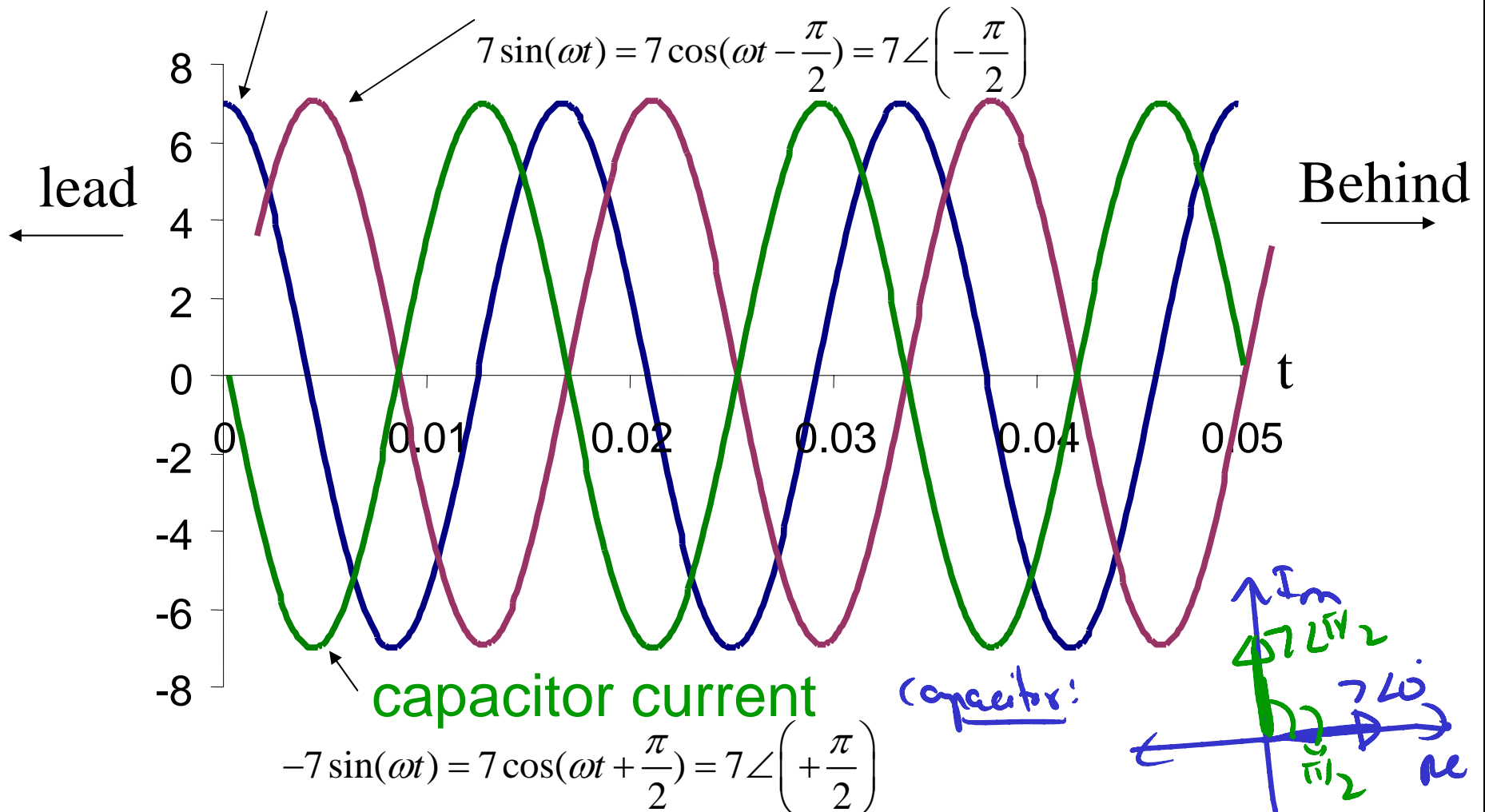
# Phase

## Voltage

$$7 \cos(\omega t) = 7 \angle 0^\circ$$

## inductor current

$$7 \sin(\omega t) = 7 \cos\left(\omega t - \frac{\pi}{2}\right) = 7 \angle \left(-\frac{\pi}{2}\right)$$



$$-7 \sin(\omega t) = 7 \cos\left(\omega t + \frac{\pi}{2}\right) = 7 \angle \left(+\frac{\pi}{2}\right)$$

# Phasor Diagrams

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- A phasor diagram is just a graph of several phasors on the complex plane (using real and imaginary axes).
- A phasor diagram helps to visualize the relationships between currents and voltages.
- Capacitor:  $I$  leads  $V$  by  $90^\circ$
- Inductor:  $V$  leads  $I$  by  $90^\circ$



# Impedance

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- AC steady-state analysis using phasors allows us to express the relationship between current and voltage using a formula that looks like Ohm's law:

$$\mathbf{V} = \mathbf{I} \mathbf{Z}$$

- $\mathbf{Z}$  is called **impedance**.

## Some Thoughts on Impedance

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- Impedance depends on the frequency  $\omega$ .
- Impedance is (often) a complex number.
- Impedance allows us to use the same solution techniques for AC steady state as we use for DC steady state.