

Lecture 19: Small-Signal Analysis

• Announcements:

- HW#6 online and due Friday via Gradescope
- Those in the Wednesday lab section should finish their Lab#3 by going to the lab when the stations are free
- Per Piazza, Lab#3 is due on Friday at 8 p.m. for everyone
- Lab#4 this week
- Midterm 1 moved to Wednesday, Oct. 16, 4-5 p.m., in our regular room
- My Monday Office Hours are 5-6 p.m. today and thereafter

• Lecture Topics:

↳ Small Signal Analysis

- Linearizing Non-Linear Elements
- DC and Small-Signal AC Components
- Taylor Series Approximation

• Last Time:

- Going through biasing for discrete MOS transistors
- Now, continue with this ...

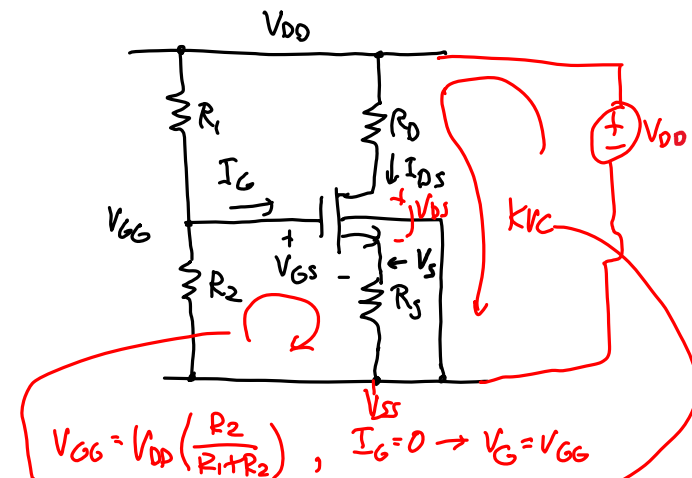
For practical amplification requirements: compromise:

- ① $V_{BB} \approx \frac{1}{3} V_{CC}$
- ② $V_{CE} \approx \frac{1}{3} V_{CC}$
- ③ $V_{R_E} = I_E R_E \approx \frac{1}{3} V_{CC}$
- ④ $0.1 I_E < I_{BIAS} < I_E$

} Good starting pt.
 ... but not rules!
 ↓
 must adjust for a given design

MOS Biasing

⇒ can use a similar biasing strategy for discrete MOS ckt's



$V_{GG} = V_{DD} \left(\frac{R_2}{R_1 + R_2} \right), I_G = 0 \rightarrow V_G = V_{GG}$

KVL: $V_{GG} = V_{GS} + I_{DS} R_S \quad (2)$

KVC: $V_{DD} = I_{DS} R_D + V_{DS} + I_{DS} R_S + V_S \quad (1)$

To find the DC operating point: (by hand)

① Assume saturation:

$$I_{D5} = \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_{GS} - V_t)^2 (1 + \lambda V_{DS})$$

$$\omega V_t = f(V_{SB}) = V_{t0} + \gamma (\sqrt{2\phi_f - V_{SB}} - \sqrt{2\phi_f})$$

$$\Rightarrow \text{using (2): } V_{GG} = V_{GS} + \frac{1}{2} \mu_n C_{ox} \frac{W}{L} (V_{GS} - V_t)^2 R_S \quad (3)$$

② Solve for V_{GS} assuming $V_t = V_{t0}$.

③ $V_S = V_{GG} - V_{GS} \rightarrow V_{SB} = V_S - V_{SS} \rightarrow$ find $V_t(V_{SB}) = V_t'$

④ Plug $V_t' = V_t(V_{SB})$ into (3) \rightarrow Get V_{GG}'

⑤ Back to ③ \rightarrow iterate to convergence

⋮

⑥ Check operating pt. \rightarrow saturated?

if yes \rightarrow done

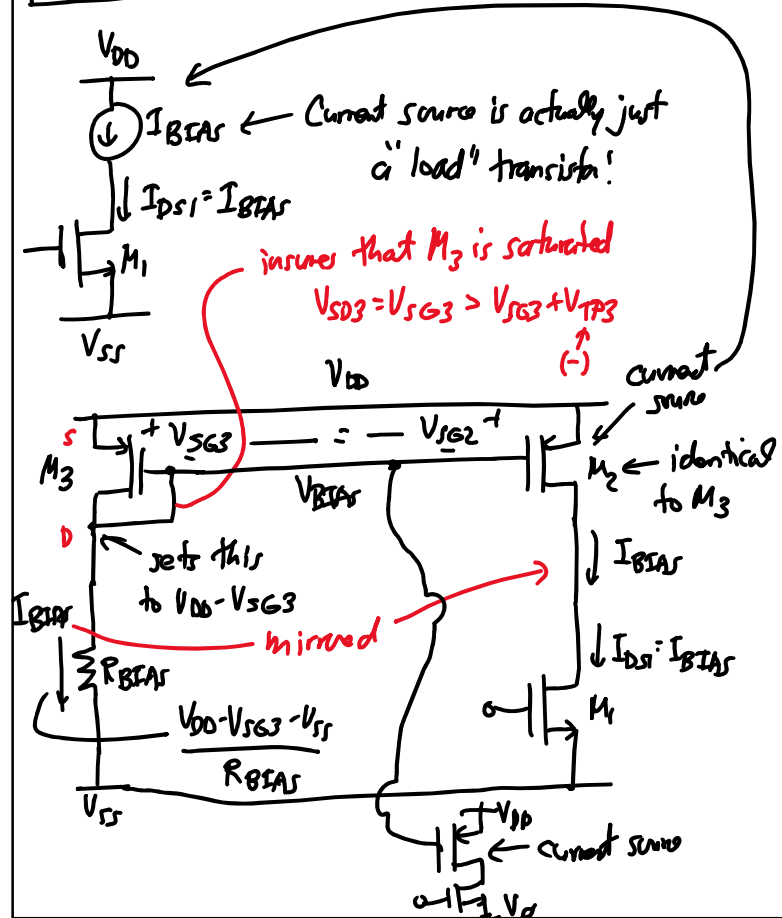
if no \rightarrow assume linear & start over

\Rightarrow tedious, but effective for discrete (i.e., off-chip) MOS ckt.

\Rightarrow on-chip, we generally use current mirrors...

- For discrete (off-chip) circuits, avoid resistors
 - \Leftarrow Discrete resistors are more expensive than discrete transistors
- For integrated (on-chip) circuits, avoid resistors
 - \Leftarrow Resistors take up much more space than transistors, and space is money
 - \Leftarrow Use lots of transistors and few if any resistors

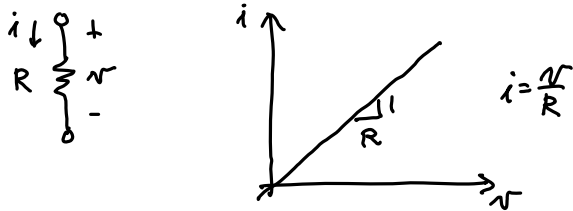
Current Mirror \leftarrow for on-chip



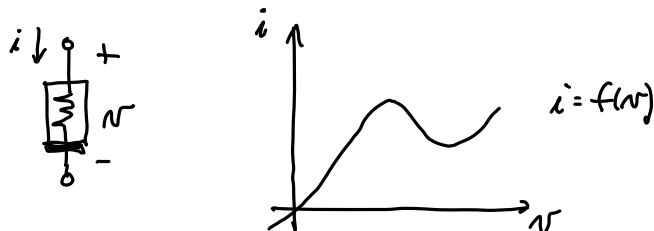
Small-Signal Analysis

- A method to solve nonlinear problems by linearizing them around a specific coordinate

Linear Resistor



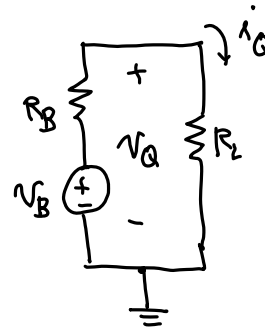
Non-linear Resistor



- As we've seen, transistors are nonlinear devices
- We've already experienced difficulty solving for DC operating points for nonlinear transistors
- So solving circuits with more complex inputs, e.g., sinusoids or sums of them, will become even more difficult
- Need some way to simplify these problems → Small-Signal Analysis
- Take a two-terminal nonlinear resistor circuit as an example:

Example. Two-Terminal Non-Linear Ckt.

⇒ First, look at a linear ckt:



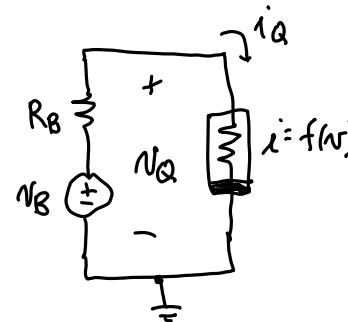
$$v_Q = v_B - i_Q R_B$$

$$v_Q = i_Q R_L$$

Solve two simultaneous linear equations:

$$v_Q = \left(\frac{R_L}{R_L + R_B} \right) v_B$$

⇒ With non-linear ckt., things become more difficult:



$$v_Q = v_B - i_Q R_B$$

$$i_Q = f(v_Q)$$

Must solve two simultaneous equations

$$v_Q = v_B - f(v_Q) R_B$$

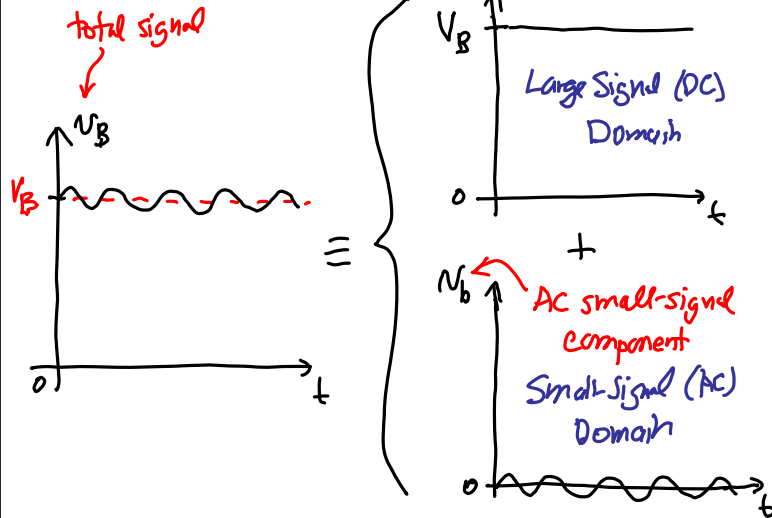
Not easy to solve!

Generally, can't get into closed form.

(e.g., $i = f(v) = 2v^2 + v^3 \rightarrow v_Q = v_B - (2v_Q^2 + v_Q^3) R_B$)

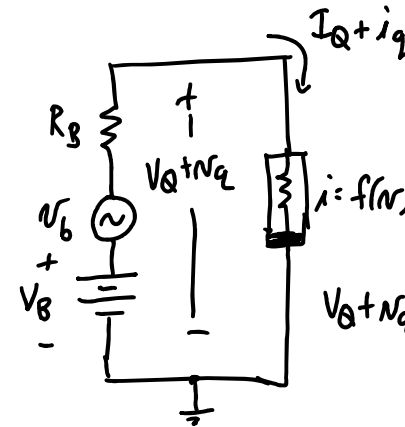
- Need a convenient method to solve this nonlinear circuit, i.e., need some way to linearize it
- Such linearization is possible for analog circuits when the signals can break down into DC and small-signal AC components

Signal Nomenclature



$v_B \cong V_B + n_b$
 Total Signal: lower case variable, upper case subscript, or upper case variable, lower case subscript. v_b
 DC Component: upper case variable, upper case subscript
 AC Small-Signal: lower case variable, lower case subscript

Using this notation:



$$v_Q + n_Q = V_B + n_b - f[v_Q + n_Q] R_B$$

For this: Use Taylor series approx. for $f(v)$ around the bias pt. $v = V_Q$.

Review Taylor Series:

function $f(x)$ can be approximated for points near $x=a$ by:

$$f(x) = f(a) + f'(a)(x-a) + \frac{f''(a)}{2!}(x-a)^2 + \dots + \frac{f^{(n)}(a)}{n!}(x-a)^n + \dots$$

1st derivative: $\frac{df}{dv} \Big|_{v=a}$
 $\approx f(a) + f'(a)(x-a)$
 linear! easy to solve!
 small signal
 total signal
 bias pt.

$$v_Q + n_Q = V_B + n_b - f[V_Q] R_B - f'[V_Q] n_Q R_B$$

$$V_Q + N_Q = V_B + N_b - I_Q R_B - \frac{R_B}{R_{s.s.}} N_Q$$

Evaluate nonlinear fcn
 $I_Q = f(V_Q)$

$$R_{s.s.} = \frac{1}{\frac{df}{dv} |_{V_Q}} \triangleq \text{small-signal resistance}$$

⇒ can split this into two equations → two ckt.

DC Components: $V_Q = V_B - I_Q R_B$

↑ must deal w a nonlinear calculation ... but only one!
 want: (V_Q, I_Q)
 operating pt.

Small-Signal AC Components: $N_Q = N_b - \frac{R_B}{R_{s.s.}} N_Q \leftarrow \text{linear!}$

Small-signal ckt.

$$R_{s.s.} = \frac{1}{\frac{df}{dv} |_{V_Q}}$$

⇒ all linear analysis! → Good!