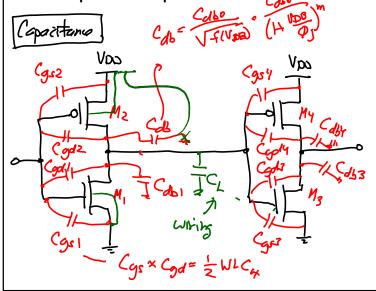
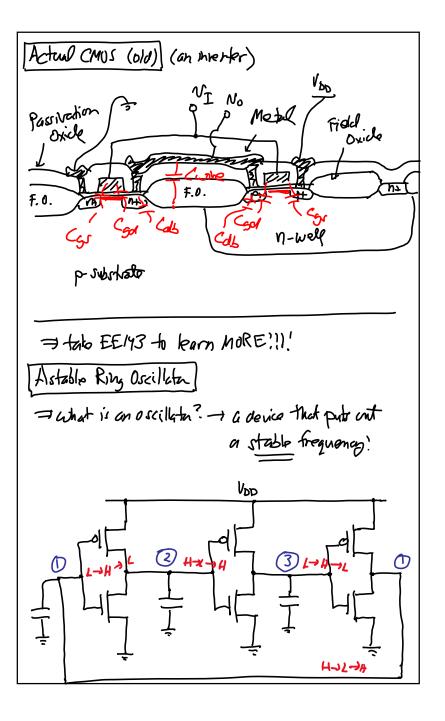


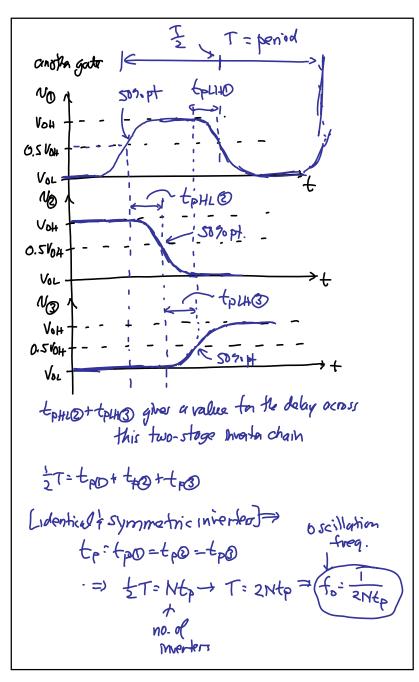
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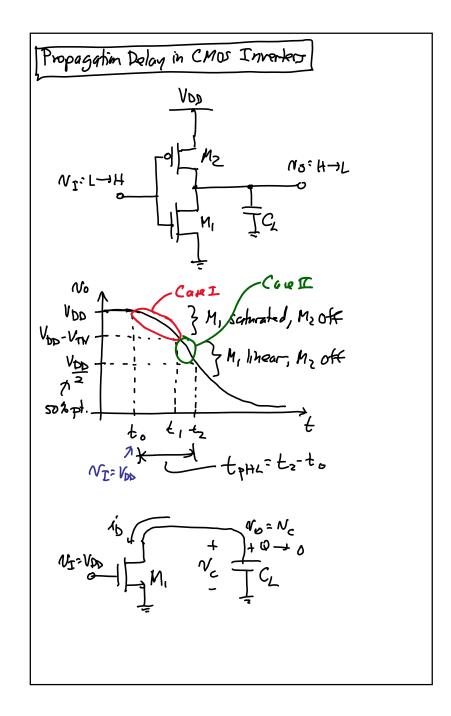


- Propagation delay is the delay experienced by a signal passing through a gate as measured between the 50% transition points between input and output waveforms
- In general, a gate displays different response times for rising and falling input waveforms
- Thus, define:
 - ♥ t_{pLH}: response time of a gate making a low→high output transition
 - ♥ t_{pHL}: response time of a gate making a high→low output transistion
- Propogation delay then defined as the average of t_{pLH} and t_{pHL}
- What causes switching delay?
 - ♥ Finite current transistor current drive (i.e., finite on resistance R_{on}
 - Soutput node capacitance









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> Car: No = Nob- Uny -> M, saturdad, M2 off $\frac{Cover \Sigma}{A_{D}(sof)} = \frac{K_{h}}{2} \left(V_{Gs} - U_{TN} \right)^{2} = -C_{L} \frac{Ch_{L}}{Ch}$ $dt = \frac{-2C_L d_{NC}}{K_N (N_{CS} - U_{TN})^2} = \frac{-2C_L d_{NC}}{K_N (N_{DS} - U_{TN})^2}$ [NGS: NOH = VOD: NT] $\int_{t_0}^{t_1} dt = \int_{V_{AL}}^{V_{BD}-V_{TN}} \frac{2C_L dV_L}{K_N (V_{DD}-V_{TN})^2}$ $(t_{1}, t_{0}) = -\frac{2C_{L}}{K_{w}(V_{D}, -V_{TN})} (V_{DD} - V_{TN} - V_{D})$ $(+,-+) = \frac{2C_L}{K_N (U_{DD} - U_{TN})} \frac{V_{TN}}{V_{DD} - V_{TN}} = \left(2C_L R_{on} \frac{V_{TN}}{V_{DD} - V_{TN}} = (++)\right)$ effective "on resistance" of the Xsistin ID Ron ICL

$$C_{\underline{OW}2}: N_{b} < V_{bb} - V_{TV} \rightarrow M_{i} (iheqr-
\dot{\lambda}_{D}(lh) = -C_{L}\frac{dV_{c}}{dt}
K_{W}(als - V_{TV} - \frac{V_{DL}}{a})N_{bT} = -C_{c}\frac{dV_{c}}{dt}
[N_{br}=N_{c}, N_{GS}: V_{bb}] \Rightarrow [K_{W}(V_{00} - V_{TV} - \frac{N_{c}}{a})N_{c} = -C_{c}\frac{dN_{c}}{dt}] \times 2
\int_{t_{i}}^{t_{2}} \frac{K_{W}}{2C_{L}}dt = -\int_{V_{i}}^{V_{2}} \frac{dN_{c}}{[2(V_{b0} - V_{TV}) - N_{c}]N_{c}}
[\int \frac{dx}{(b\cdot x)x} = \frac{1}{a} l_{m}(\frac{x}{a-x})]
[\int V_{2} = \frac{V_{Db}}{2}, V_{i} = V_{0b} - V_{TW}]
\frac{K_{N}}{2C_{L}}(t_{2} - t_{i}) = -\frac{i}{2(V_{bD} - V_{TW})} l_{m}[\frac{V_{DD}}{2(V_{00} - V_{TW}) - N_{c}}]V_{bb} - V_{TW}$$

$$: algebra$$

$$= -\frac{i}{2(V_{bD} - V_{TW})} l_{m}[\frac{V_{DD}}{4V_{Db}} - 4V_{TW} - V_{bb}]$$

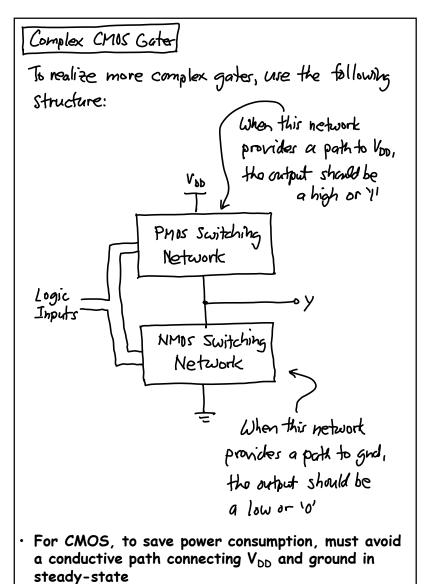
$$(-t_{2} - t_{i}) = \frac{C_{L}}{k_{V}(V_{bb} - V_{TW})} l_{m}[\frac{4(V_{DD} - V_{TW}) - V_{DD}}{V_{bb}}]$$

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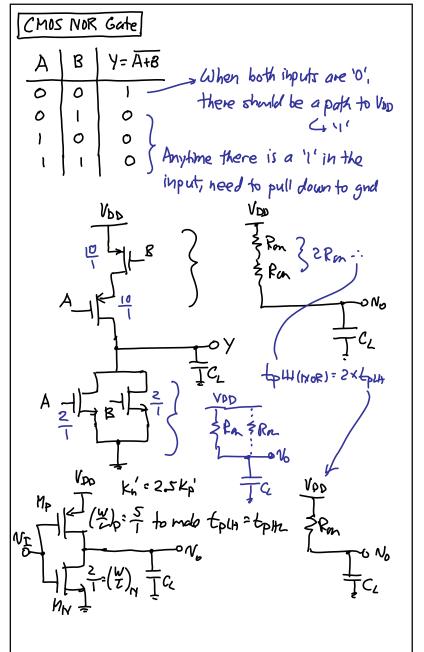
 $(t_2 - t_1)$; $\frac{C_c}{K_N(v_{DD} - v_{TN})} p_n \left(\frac{4(v_{DD} - v_{TN})}{v_{DD}} - 1 \right)$ $(t_2-t_1) = R_{G_1}C_1 l_n \left[\frac{4(v_{00}-v_{10})}{v_{00}} - 1\right]$ $t_{pHL} = (t_2 - t_1) + (t_1 - t_0) = (t_2 - t_0)$ $= \left(R_{on}C_L \int b_n \left(\frac{4(V_{ND} - V_{TN})}{V_{0D}} - 1\right) + \frac{2V_{TN}}{V_{0D} - V_{TN}} \int = t_{pHL}$ where $R_{on} = \frac{1}{K_N(V_{0D} - V_{TN})}$ $t_{pHL} = R_{on}C_L \times f(V_{DD}, V_{TN})$

$$\frac{t_{\text{PLH}}}{\rightarrow} \text{ connect } \mathcal{C}_{L} \text{ to } \mathcal{V}_{\text{DD}} \rightarrow \text{PMas } \text{cm. NMas off}$$

$$\frac{V_{\text{D}}}{V_{\text{D}}} + \frac{V_{\text{D}}}{V_{\text{D}}} + \frac{V_{\text{D}}}{V_{\text{C}}} + \frac{V_{\text{D}}}{V_{\text{C}}} + \frac{V_{\text{D}}}{V_{\text{C}}} + \frac{V_{\text{D}}}{V_{\text{C}}} + \frac{V_{\text{D}}}{V_{\text{D}}} + \frac{V_{\text{D}}}$$

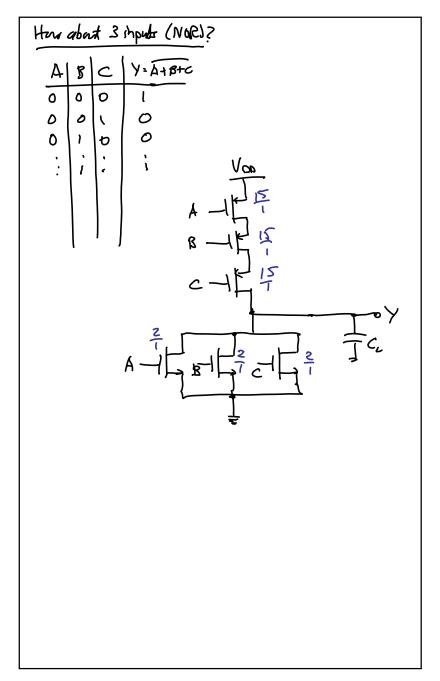


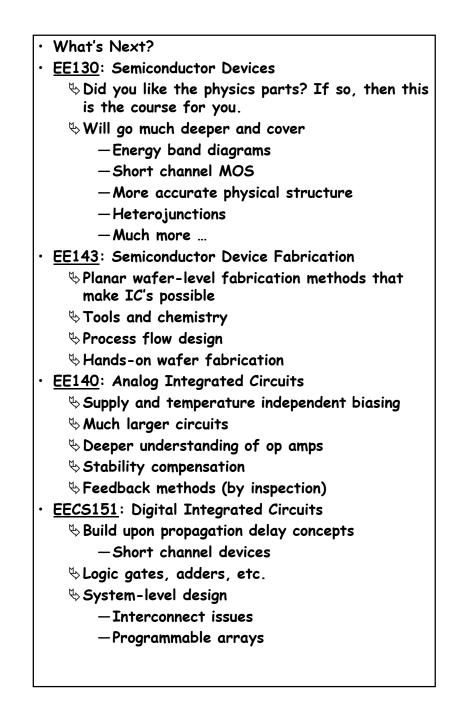
- Otherwise, too much current will flow and dissipate power
- Should also minimize this path during transitions



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- What's Next? (cont.)
- **<u>EE147</u>**: Microelectromechanical Systems (MEMS)
 - ♥ I'm biased, but ... this is the coolest stuff, period!
 - $\boldsymbol{\boldsymbol{\boldsymbol{\forall}}}$ Mechanics and Materials
 - Methods for fabricating tiny mechanics
 - Mechanical circuit design
 - Sou'll learn that all of your EE math skills and circuit techniques can just as easily be applied to mechanical devices and systems
 - $\textcircled{} \mathsf{h} \mathsf{Applications}$ to sensing and RF