

Focal Points and Planes

(1)

opposite



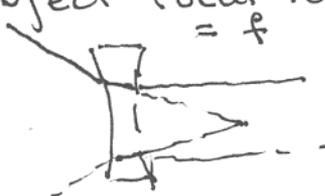
$s_o = f$ $s_i = \infty$

object focal length = f



$s_o = \infty$ $s_i = f$

image focal length = $f = F_i$



$s_o = \infty$

$s_i = f < 0$ image focal length

$R_1 < 0, R_2 > 0 \quad n > 1$

$f < 0$

Once again

$$\frac{1}{s_o} + \frac{1}{s_i} = \frac{1}{f} = (n-1) \left(\frac{1}{R_1} - \frac{1}{R_2} \right)$$

$s_o = f$ (negative number)

$s_i = \infty$

(Note: if $n < 1$ this becomes effectively a concave lens [what other consequences?])

Focal Plane



Focal Plane



Finite imagery - ray tracing - Use three rays to get image

real (rays forming image exist)



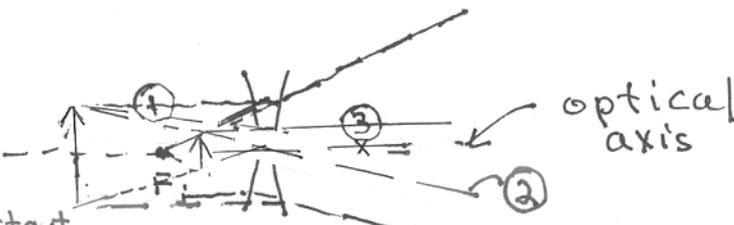
$$\begin{pmatrix} r_2 \\ r_2' \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ -\frac{1}{f} & 1 \end{pmatrix} \begin{pmatrix} r_1 \\ r_1' \end{pmatrix}$$

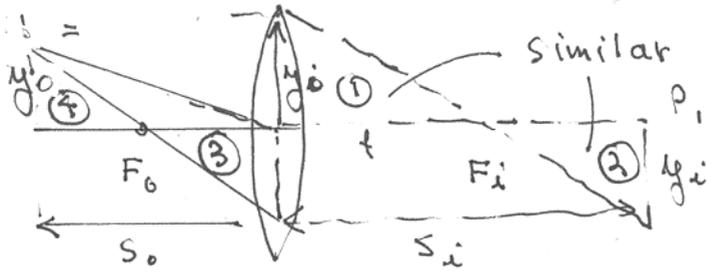
$r_1 = 0$

$r_2 = r_2$

$r_2' = r_1'$

virtual (rays forming image non-existent at image)





① $\frac{y_o}{f} = \frac{f}{s_i - f}$; ③ $\frac{|y_i|}{y_o} = \frac{f}{s_o - f}$

② $\frac{|y_i|}{y_o} = \frac{s_i}{s_o}$

③ + ④ $\frac{y_o}{y_i} = \frac{s_o}{s_i} = \frac{f}{s_i - f} = \frac{f}{x_i} = \frac{x_o}{f} \rightarrow x_o x_i = f^2$

Transverse Magnification

$M_T = \frac{y_i}{y_o} = -\frac{s_i}{s_o}$ (Hecht uses a - sign for an inverted image)

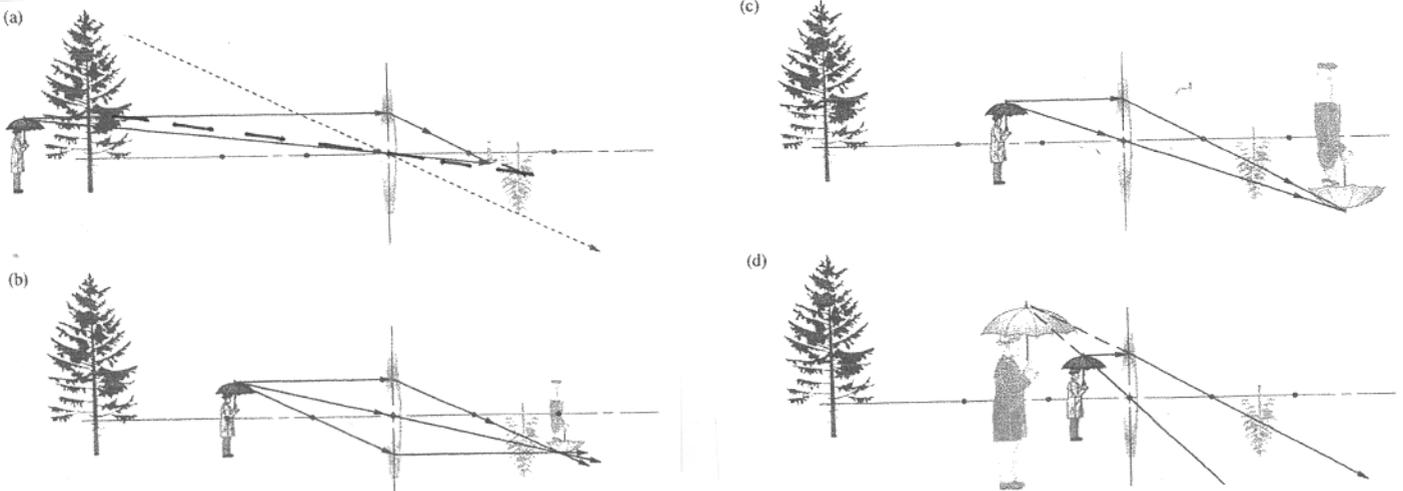
$= -\frac{f}{x_o} > 1$ if $x_o < f$

Longitudinal magnification

$M_L = \frac{dx_i}{dx_o}$

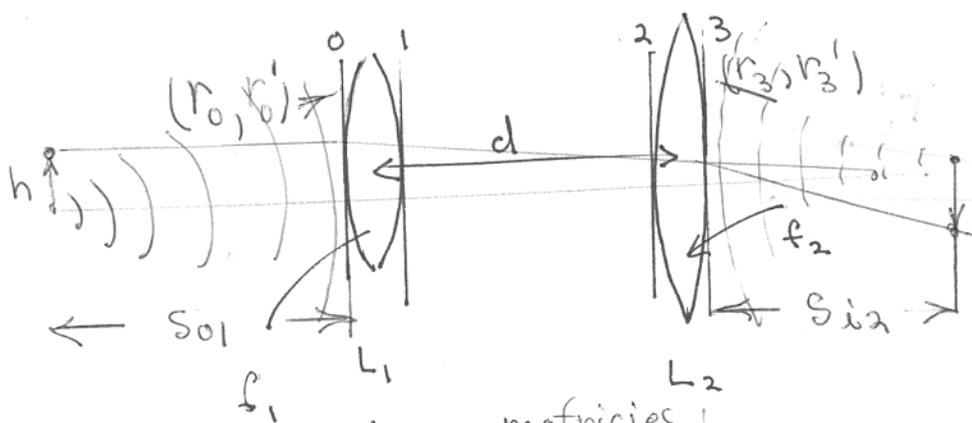
$= \frac{d(f^2/x_o)}{dx_o} = -\frac{f^2}{x_o^2} = -M_T^2$

Figure 5.24 The image-forming behavior of a thin positive lens.



Example of a Thin Lens Combination (page 107)

(3)



matrices

$$\begin{pmatrix} A & B \\ C & D \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ -\frac{1}{f_2} & 1 \end{pmatrix} \begin{pmatrix} 1 & d \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ -\frac{1}{f_1} & 1 \end{pmatrix}$$

$$\begin{pmatrix} r_3' \\ r_3 \end{pmatrix} = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \begin{pmatrix} r_0' \\ r_0 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & d \\ -\frac{1}{f_2} & -\frac{d}{f_2} + 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ -\frac{1}{f_1} & 1 \end{pmatrix} = \begin{pmatrix} 1 - \frac{d}{f_1} & d \\ -\frac{1}{f_2} - \frac{1}{f_1} \left(1 - \frac{d}{f_2}\right) & \left(1 - \frac{d}{f_2}\right) \end{pmatrix}$$

↑
det = 1

Various cases to be considered

From the ABCD matrix, we can write

$$\begin{aligned} R_{i2} &= \frac{\left(1 - \frac{d}{f_1}\right) R_{o1} + d}{\left(-\frac{1}{f_2} - \frac{1}{f_1} \left(1 - \frac{d}{f_2}\right)\right) R_{o1} + \left(1 - \frac{d}{f_2}\right)} \\ &= \frac{(f_1 d + (f_1 - d) R_{o1}) f_2}{(-f_1 - (f_2 - d) R_{o1} + f_1 f_2 - d f_1)} \end{aligned}$$

(Note that this is the negative of Eq (5.33)
(sign convention differences $R_{i2} = -S_{i2}$ and

$$R_{o1} = +S_{o1}$$

s_{o1} and s_{i2} are the object and image distances of the compound lens, respectively

Example - page 169 $f_1 = 30 \text{ cm}$ $d = 20 \text{ cm}$
 $f_2 = 50 \text{ cm}$

$$s_{i2} = 26.2 \text{ cm}$$

The image is real because $s_{i2} > 0$

Magnification

If $r'_0 = 0$ $r_0 = h_0$

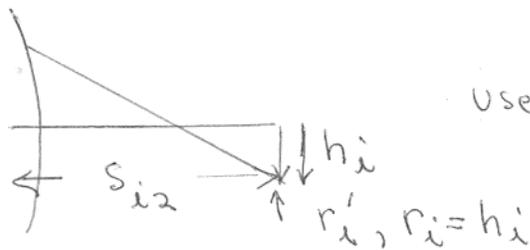
$$r'_3 = \left(1 - \frac{d}{f_1}\right) r'_0$$

Lens

$$r'_3 = \left(-\frac{1}{f_2} - \frac{1}{f_1} \left(1 - \frac{d}{f_2}\right)\right) h_0$$

free propagation

$$\begin{pmatrix} r_i \\ r'_i \end{pmatrix} = \begin{pmatrix} 1 & d \\ 0 & 1 \end{pmatrix} \begin{pmatrix} r_3 \\ r'_3 \end{pmatrix} \quad d = s_{i2}$$



Use

$$r_i = r_3 + s_{i2} r'_3$$

$$= \left(1 - \frac{d}{f_1}\right) h_0 + s_{i2} \left(-\frac{1}{f_2} - \frac{1}{f_1} \left(1 - \frac{d}{f_2}\right)\right) h_0$$

$$M_T = \frac{r_i}{h} = 1 - \frac{d}{f_1} + s_{i2} \left(-\frac{1}{f_2} - \frac{1}{f_1} \left(1 - \frac{d}{f_2}\right)\right)$$

$$= 1 - \frac{20}{30} + 26.2 \left(-\frac{1}{50} - \frac{1}{30} \left(1 - \frac{20}{50}\right)\right)$$

$$= 0.714 \quad (\text{as in the book page 168})$$

Note: To get the same analytical result solve for $\frac{1}{f_2}$ in the expression for s_{i2} (5.33) and eliminate it in the above

Note that as $d \rightarrow 0$ the ABCD reduce to an effective single lens with $\frac{1}{f} = \frac{1}{f_1} + \frac{1}{f_2}$

(Eq. 5.37 of text)