

EECS120 - Fall 2003

Homework No. 3

Due: In the 120 Box or in lecture by the beginning of lecture on 9/18/2003

Collaboration permitted and solutions to be written up by groups up to 3.

Be clear and precise in your answers

Questions can be asked in `ucb.class.ee120` or in office hours

Problem 3.1 *Book Problems from Lee and Varaiya, chapter 10.*

Problems: 2,3,5

Problem 3.2 *Linear Algebra Review*

- a. *What is the determinant of aI where I is the $n \times n$ identity matrix? What is the trace?*
- b. *What are the eigenvalues and eigenvectors of the following matrices:*

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 \\ 0 & 5 & 6 \\ 0 & 8 & 9 \end{bmatrix}, \begin{bmatrix} 1 & 3 & 2 \\ 2 & 1 & 3 \\ 3 & 2 & 1 \end{bmatrix}$$

- c. *Consider vectors in three-dimensional space. Let H be a system that takes an incoming vector, projects it into the plane that is perpendicular to the direction $[111]^T$, and proceeds to rotate the resulting vector 90 degrees around the Z axis. Is H linear? Invertible? Representable as a matrix? (If so, what is the matrix representation?)*
- d. *Let the $n \times n$ real matrix M be such that it has n distinct eigenvalues λ_i . Show that there exists a coordinate system in which the operation of M can be represented by a diagonal matrix.*

Problem 3.3 *Finite domains without wrap-around*

Consider signals on the set $\{0, 1, 2, \dots, n-1\}$. Suppose that we interpret delay/shift to mean that if a signal is shifted by $+i$, then the first i values will be set to zero, while the first $n-i$ values will become the last $n-i$ values. Similarly, if a signal is shifted by $-i$, then the last i values will be set to zero while the last $n-i$ values will become the first $n-i$ values.

- a. *Prove that if L is an LTI system, then L is just a scalar gain.*
- b. *(Bonus) Characterize the entire class of time-invariant systems.*

Problem 3.4 *Finite domains with wrap-around*

Consider the domain Z_n (the integers mod $n > 0$). Here we interpret delay to mean that $[D_\tau x](t) = x(t - \tau \bmod n)$.

Consider $n = 3$.

- a. Show that the set of real-valued signals on this domain is representable by vectors in 3-dimensional space using the standard basis vectors.
- b. Show that all linear systems that map real-valued signals on this domain to real-valued signals on this domain are representable by real 3×3 matrices.
- c. What is the class of matrices that correspond to LTI systems?
- d. Show that there exists a complex coordinate system in which every LTI system is representable by a diagonal matrix.
- e. Represent D_1 and D_2 in both the coordinate system of (c) and (d).
- f. Show explicitly that the coordinate system of part (d) is orthogonal. (i.e. the basis vectors are all orthogonal to each other using the regular Euclidean inner product on complex spaces.)
- g. Do all complex diagonal matrices in the coordinate system of (d) correspond to real LTI systems? If not, which subset of the complex diagonal matrices correspond to real LTI systems?
- h. Give an LTI system that removes the DC offset of a signal, but otherwise leaves it unchanged. Express it both in terms of the impulse response and the “frequency response.”
- i. Repeat parts d,e,f,g,h for $n = 5, 6$

Problem 3.5 Suppose that $x(t)$ is a discrete-time signal that is periodic with period T (positive integer). If $y = Lx$ where L is an LTI system, is y guaranteed to be a periodic signal? Why or why not?