EECS 120 Signals & Systems Ramchandran

Homework 4 Due: Thursday, September 27, 2007, at 5pm Homework 4 GSI: Mark Johnson

(Submit your grades to ee120.gsi@gmail.com)

Reading OWN Chapter 3-4 (Fourier Representations.)

Practice Problems (Suggestions.) OWN 4.5, 4.11, 4.19

Problem 1 (Properties of the CTFS.)

OWN Problem 3.46, all parts (details below). For Part (a), start out by showing (in 3 lines at most!) that

$$c_k = \frac{1}{T} \int_T z(t) e^{-jk\omega_0 t} dt \tag{1}$$

$$= \sum_{n=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} a_n b_m \left(\frac{1}{T} \int_T e^{j(n+m-k)\omega_0 t} dt \right).$$
⁽²⁾

In this case, do not worry about shifting around infinite sums. Then, evaluate the integral to obtain

$$c_k = \sum_{n=-\infty}^{\infty} a_n b_{k-n}.$$
 (3)

Then, do Part (b), but only for Figure P3.46(a)

Finally, do Part (c).

Problem 2 (Properties of the CTFS.)

Recall that if a signal is periodic with period T, then it is also periodic with period mT, for any integer m.

Assume x(t) is a periodic signal with fundamental period T, whose Fourier series coefficients a_k are given by Equation 3.39 in OWN. Let b_k be the Fourier series coefficients that are found by considering x(t) to be periodic with period 2T. Prove that

$$b_k = \begin{cases} a_{k/2} & k \ even \\ 0 & k \ odd \end{cases}$$

Problem 3 (Properties of the DTFS.)

(a) OWN Problem 3.48, Part (a)

(b) OWN Problem 3.48, Part (e)

Problem 4 (Properties of the DTFS.)(a) OWN Problem 3.48, Part (f)

 $\left(b\right)$ OWN Problem 3.48, Part (h)

Problem 5 (FT.)

(a) OWN Problem 4.22, Part (e)

(b) OWN Problem 4.23, Parts (a) and (b)

Problem 6 (FT.)

(a) OWN Problem 4.29, only for the signal $x_a(t)$ and $x_c(t)$

(b) OWN Problem 4.41

Problem 7 (FT.)

OWN 4.36 (all parts)

Problem 8 (Frequency response of linear time-invariant systems.)

Let a system be specified by a differential equation. Then, its frequency response can be found easily, as you will establish in this homework problem.

(a) Suppose that the LTI system is specified by

$$\sum_{k=0}^{N} a_k \frac{d^k}{dt^k} y(t) = \sum_{m=0}^{M} b_m \frac{d^m}{dt^m} x(t).$$
(4)

Solve the differential equation for the input $x(t) = e^{j\omega t}$. As we have seen in class, if the input to a continuous-time LTI system is $x(t) = e^{j\omega t}$, then the output can be expressed as $y(t) = H(j\omega)e^{j\omega t}$. Plug this into the above differential equation to determine $H(j\omega)$. You will obtain an expression for $H(j\omega)$ in terms of the coefficients $a_k, k = 0, ..., N$ and $b_m, m = 0, ..., M$.

(b) For the system specified by the differential equation

$$2\frac{dy(t)}{dt} + 6y(t) = x(t),$$
 (5)

determine the frequency response $H(j\omega)$, and the corresponding impulse response h(t). Then, find the output when the input is $x(t) = \sin(t/4)$. *Hint:* Write $\sin(t/4)$ in terms of functions of the form $e^{j\omega_0 t}$, and recall from class that for such inputs, the output is imply given by $y(t) = H(j\omega_0)x(t)$.