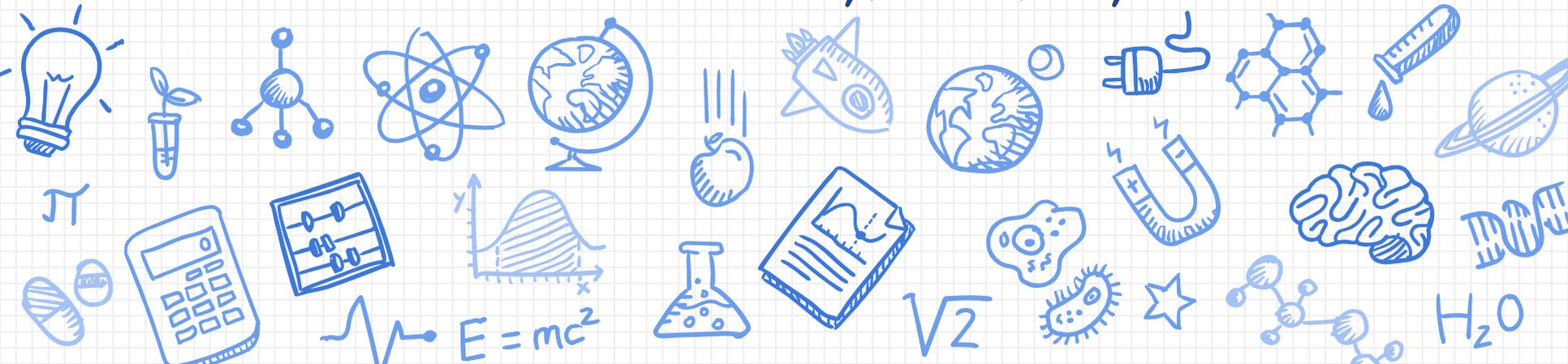


EE16A Lab: Locationing

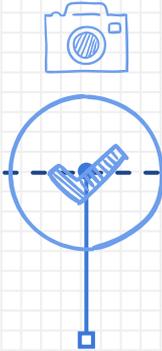
Wed 8-11

GSI: Angela

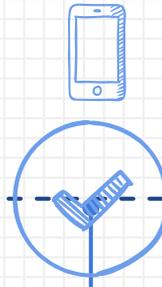
Lab Assistants: Gary, Loren, Seiya



Semester Outline



Imaging
Module



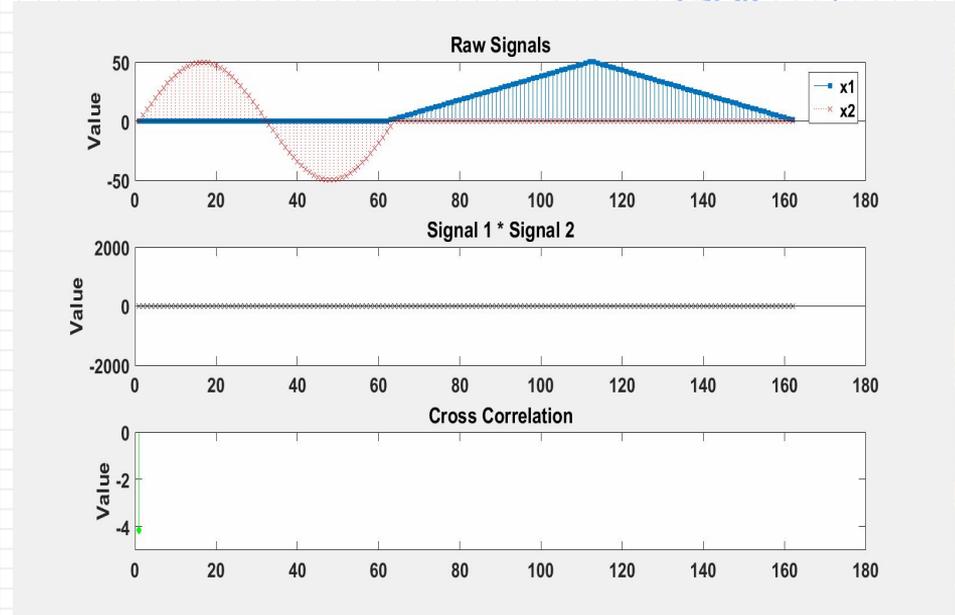
Touchscreen
Module



Locating
Module

Last lab

- ✗ Cross Correlation
 - ✗ Similarity between signals
 - ✗ Separate signals
 - ✗ Find index where signal arrived
- ✗ Signal arrival time to distance
 - ✗ How can we do this?



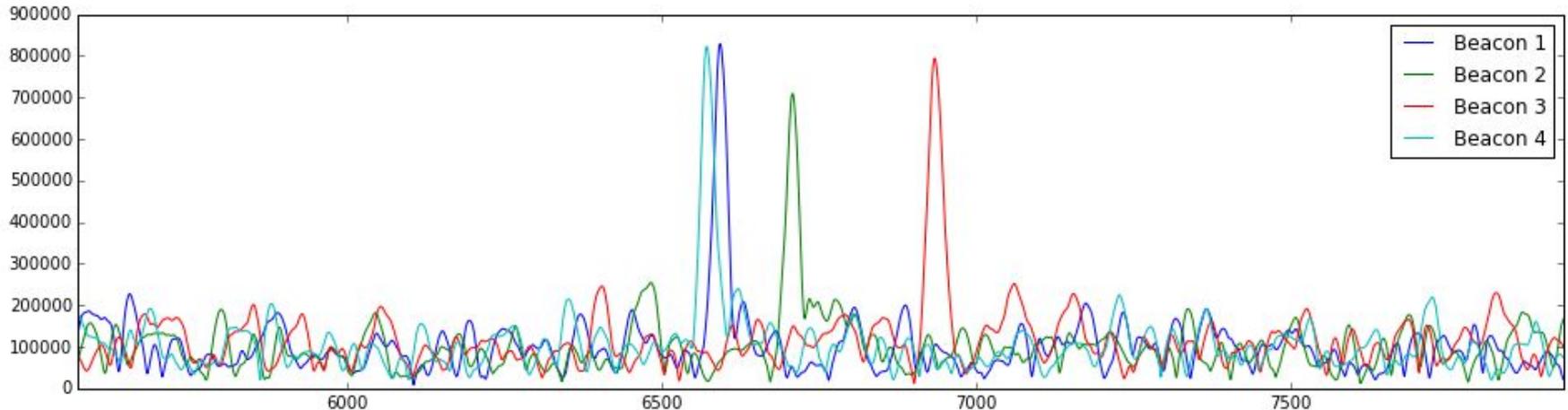


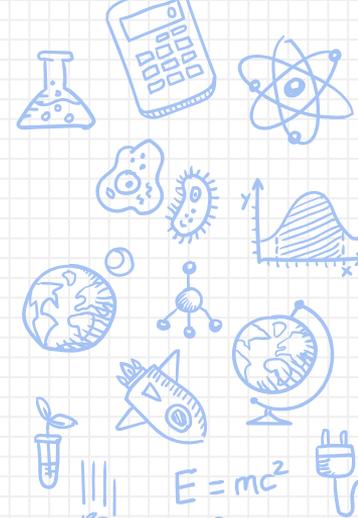
Separating Beacons

def separate_signal(raw_signal):

 input: raw signal from microphone

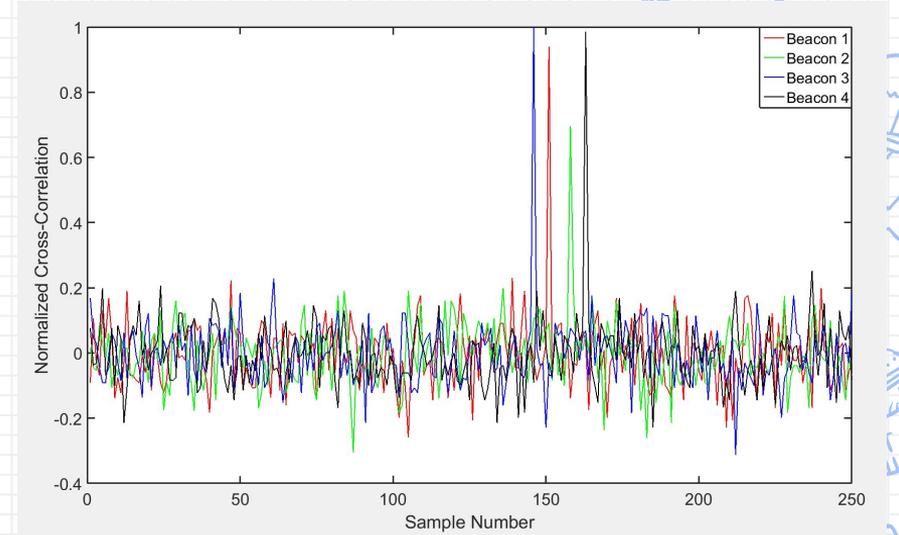
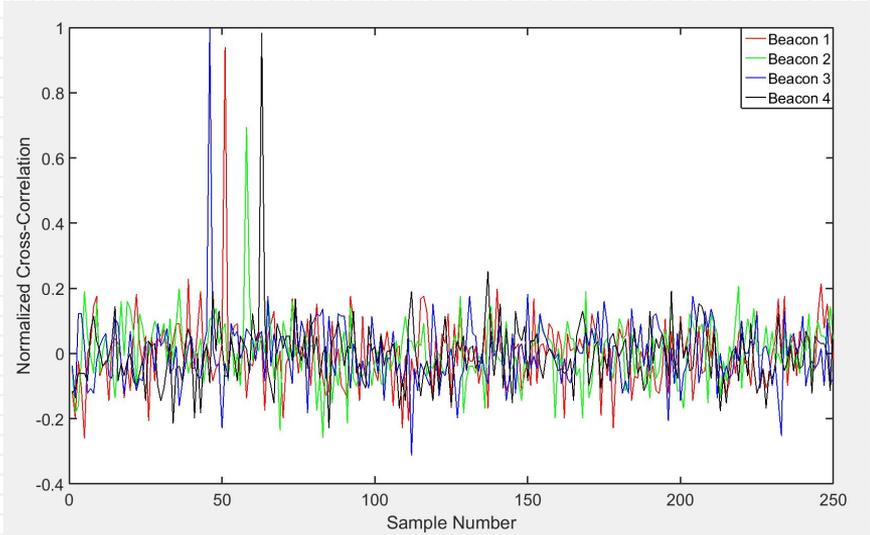
 output: list of cross-correlations of raw signal with each beacon signal

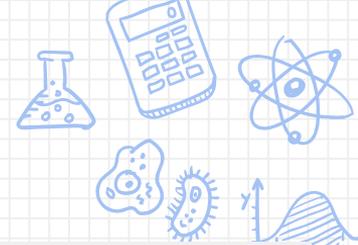




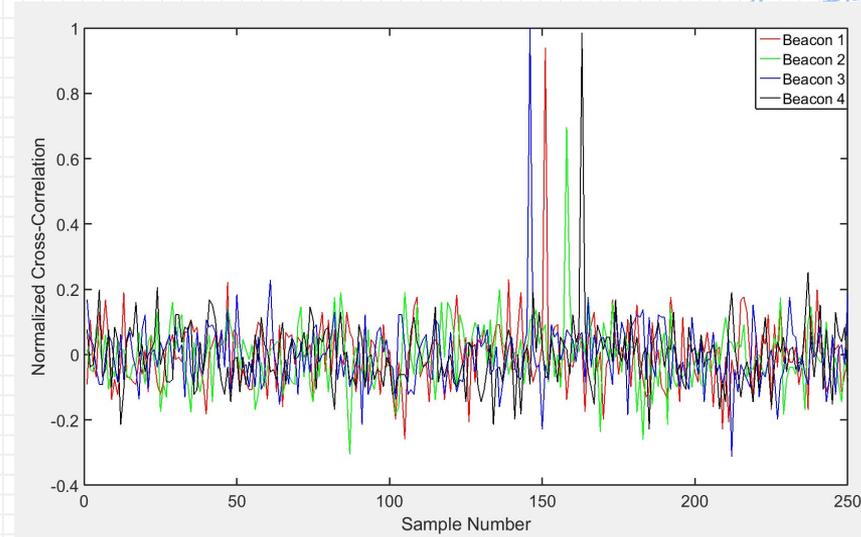
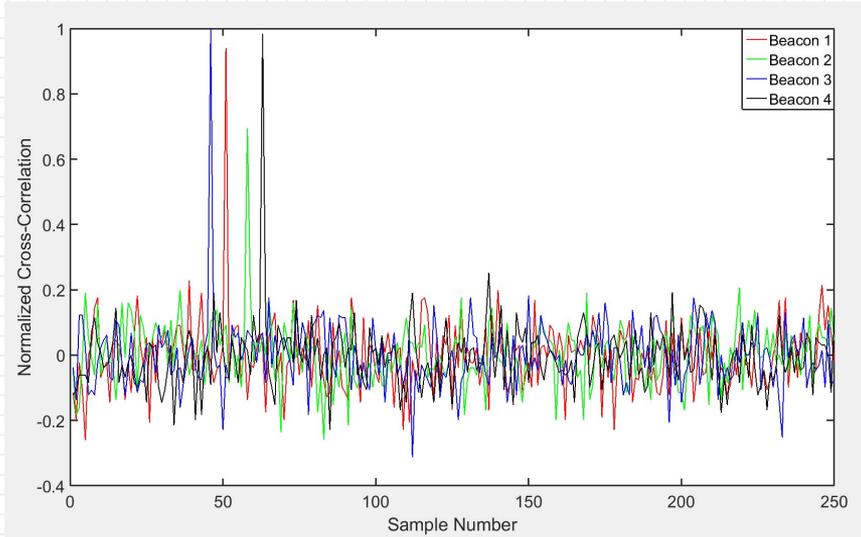
Issue With Locating System

- ✘ Beacons signal every 230ms
- ✘ Don't know when the signals were actually sent
- ✘ Cannot use beginning of recording as a reference



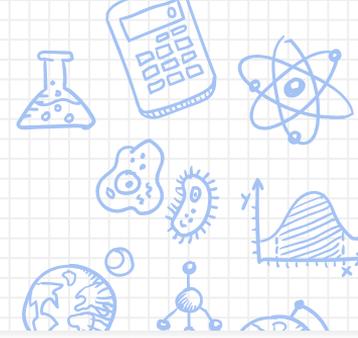


Task 2a: Computing Distances



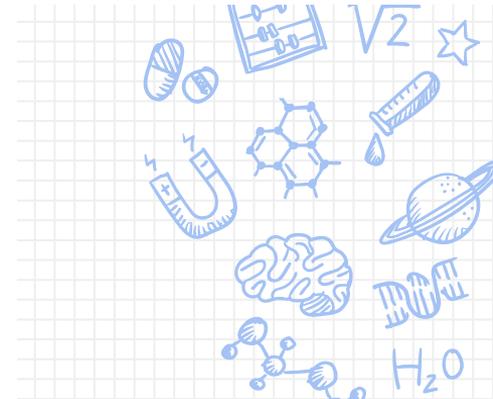
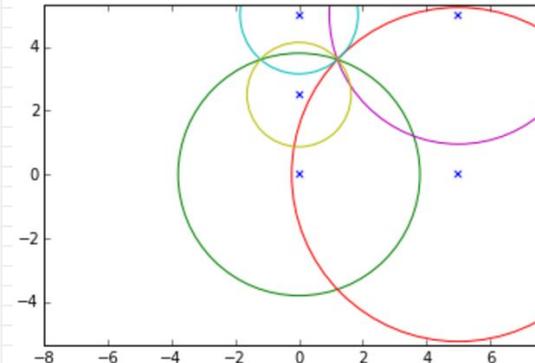
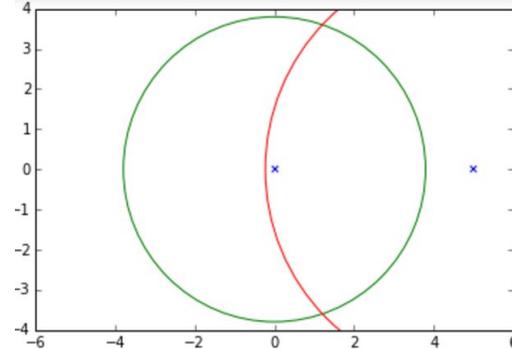
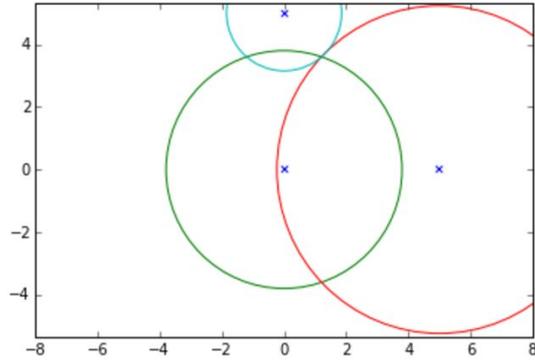
- ✘ Use a particular beacon as a reference
- ✘ Find offsets of other beacons with respect to reference beacon
- ✘ Turn these offsets into time difference of arrival (TDOA) then distances





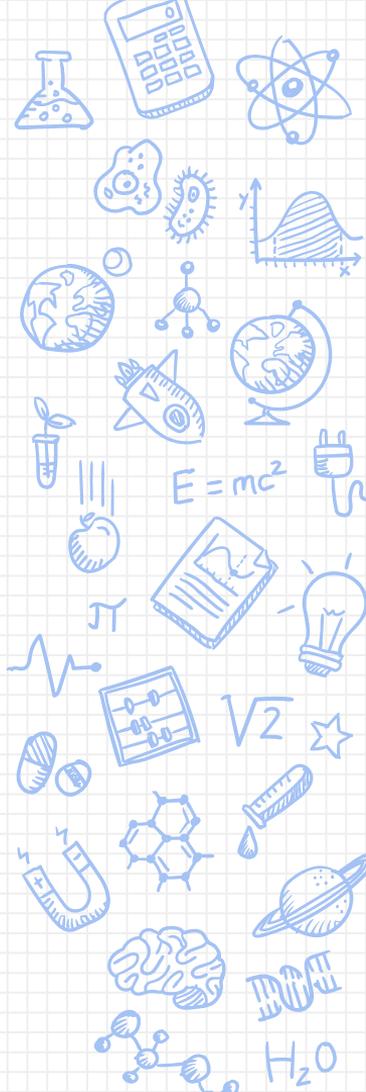
Number of Beacons

- ✘ What is the difference among using 2, 3 and 5 beacons?
- ✘ Any benefit to using more?
- ✘ What do the circles represent?
- ✘ What do their intersections represent?



Notes:

- ✗ If we knew distance / time of flight for beacon 0, finding location is easy
- ✗ Today this value will be given to you for testing purposes
- ✗ In the real system, we still won't know this
 - ✗ Turns out we don't need to -- next week!



Notes

- ✘ Plug the microphone in before starting your iPython notebook to avoid having to restart the kernel later on.

Question Form:

<http://tinyurl.com/lab114-form>

Question Queue:

<http://tinyurl.com/lab114-queue>

Questionnaire:

<http://tinyurl.com/foodiscool>

