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 EECS 16A    Designing Information Devices and Systems I    Discussion 12A  
 Fall 2019
 

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**1. Reference****Inner products:**

The inner product is for two vectors  $\vec{x}$  and  $\vec{y}$  defined as:

$$\langle \vec{x}, \vec{y} \rangle = \vec{x}^T \vec{y}$$

The inner product satisfies the following properties:

(a) **Symmetry:**  $\langle \vec{x}, \vec{y} \rangle = \langle \vec{y}, \vec{x} \rangle$ .

**(b) Linearity:**

i.  $\langle \vec{x}, \vec{y} + \vec{z} \rangle = \langle \vec{x}, \vec{y} \rangle + \langle \vec{x}, \vec{z} \rangle$ .

ii.  $\langle c\vec{x}, \vec{y} \rangle = c\langle \vec{x}, \vec{y} \rangle$ .

(c) **Norm:**  $\langle \vec{x}, \vec{x} \rangle = \|\vec{x}\|^2$ .

(d) If  $\langle \vec{x}, \vec{x} \rangle = 0$ , then  $\vec{x} = \mathbf{0}$ .

**Cauchy-Schwartz inequality:**

Recall that

$$\langle \vec{v}, \vec{w} \rangle = \|\vec{v}\| \cdot \|\vec{w}\| \cos \theta,$$

where  $\theta$  is the angle between the two vectors  $\vec{v}$  and  $\vec{w}$ . This leads to the Cauchy-Schwarz inequality, which states that for two vectors  $\vec{v}, \vec{w} \in \mathbb{R}^n$ :

$$\langle \vec{v}, \vec{w} \rangle \leq \|\vec{v}\| \cdot \|\vec{w}\|.$$

**Cross-correlation:**

The cross-correlation between two signals  $r[n]$  and  $s[n]$  is defined as follows:

$$\text{corr}_r(s)[k] = \sum_{i=-\infty}^{\infty} r[i]s[i-k].$$

**2. A review of Inner Products**

Find the inner product of the following three pairs of vectors.

(a)

$$\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

**Answer:** Recall that the inner product of two vectors  $\vec{x}$  and  $\vec{y}$  is  $\vec{x}^T \vec{y}$ , thus:

$$\begin{bmatrix} 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} = 1 + 3 = 4$$

(b)

$$\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

**Answer:** When working with real numbers, the inner product is commutative, thus the answer is the same as part a), 4

(c)

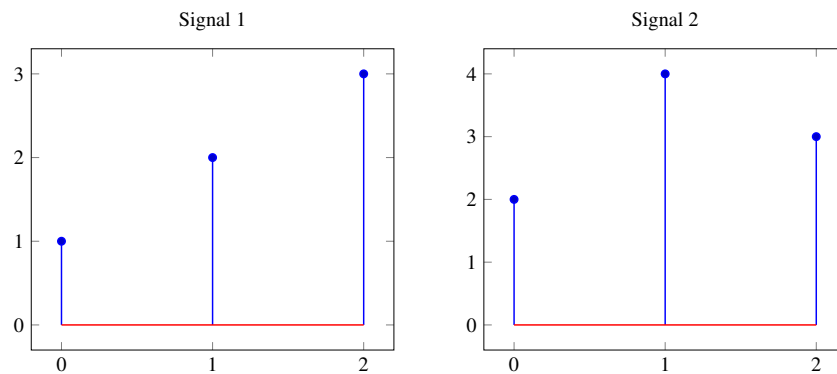
$$\begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} -3 \\ 2 \\ 1 \end{bmatrix}$$

**Answer:**

$$\begin{bmatrix} 1 & 0 & 3 \end{bmatrix} \begin{bmatrix} -3 \\ 2 \\ 1 \end{bmatrix} = -3 + 3 = 0$$

### 3. Correlation

We are given the following two signals,  $s_1[n]$  and  $s_2[n]$  respectively.



Find the cross correlations,  $\text{corr}_{s_1}(s_2)$  and  $\text{corr}_{s_2}(s_1)$  for signals  $s_1[n]$  and  $s_2[n]$ . Recall

$$\text{corr}_x(y)[k] = \sum_{i=-\infty}^{\infty} x[i]y[i-k].$$

	$\text{corr}_{\vec{s}_1}(\vec{s}_2)[k]$						
$\vec{s}_1$	0	0	1	2	3	0	0
$\vec{s}_2[n+2]$							
$\langle \vec{s}_1, \vec{s}_2[n+2] \rangle$		+	+	+	+	+	+
							=

	$\text{corr}_{\vec{s}_2}(\vec{s}_1)[k]$						
$\vec{s}_1$	0	0	1	2	3	0	0
$\vec{s}_2[n+1]$							
$\langle \vec{s}_1, \vec{s}_2[n+1] \rangle$		+	+	+	+	+	+
							=

$\vec{s}_1$	0	0	1	2	3	0	0	
$\vec{s}_2[n]$								
$\langle \vec{s}_1, \vec{s}_2[n] \rangle$	+	+	+	+	+	+	+	=

$\vec{s}_1$	0	0	1	2	3	0	0	
$\vec{s}_2[n-1]$								
$\langle \vec{s}_1, \vec{s}_2[n-1] \rangle$	+	+	+	+	+	+	+	=

$\vec{s}_1$	0	0	1	2	3	0	0	
$\vec{s}_2[n-2]$								
$\langle \vec{s}_1, \vec{s}_2[n-2] \rangle$	+	+	+	+	+	+	+	=

$\vec{s}_2$	0	0	$\text{corr}_{\vec{s}_2}(\vec{s}_1)[k]$		3	0	0	
$\vec{s}_1[n+2]$								
$\langle \vec{s}_2, \vec{s}_1[n+2] \rangle$	+	+	+	+	+	+	+	=

$\vec{s}_2$	0	0	2	4	3	0	0	
$\vec{s}_1[n+1]$								
$\langle \vec{s}_2, \vec{s}_1[n+1] \rangle$	+	+	+	+	+	+	+	=

$\vec{s}_2$	0	0	2	4	3	0	0	
$\vec{s}_1[n]$								
$\langle \vec{s}_2, \vec{s}_1[n] \rangle$	+	+	+	+	+	+	+	=

$\vec{s}_2$	0	0	2	4	3	0	0	
$\vec{s}_1[n-1]$								
$\langle \vec{s}_2, \vec{s}_1[n-1] \rangle$	+	+	+	+	+	+	+	=

$\vec{s}_2$	0	0	2	4	3	0	0	
$\vec{s}_1[n-2]$								
$\langle \vec{s}_2, \vec{s}_1[n-2] \rangle$	+	+	+	+	+	+	+	=

**Answer:** The linear cross-correlation is calculated by shifting the second signal both forward and backward until there is no overlap between the signals. When there is no overlap, the cross-correlation goes to zero. Both of these cross-correlations should have only zeros outside the range:  $-2 \leq n \leq 2$ .

$$\text{corr}_{\vec{s}_1}(\vec{s}_2)[k]$$

$\vec{s}_1$	0	0	1	2	3	0	0							
$\vec{s}_2[n+2]$	2	4	3	0	0	0	0							
$\langle \vec{s}_1, \vec{s}_2[n+2] \rangle$	0	+	0	+	3	+	0	+	0	+	0	+	0	= 3

$\vec{s}_1$	0	0	1	2	3	0	0							
$\vec{s}_2[n+1]$	0	2	4	3	0	0	0							
$\langle \vec{s}_1, \vec{s}_2[n+1] \rangle$	0	+	0	+	4	+	6	+	0	+	0	+	0	= 10

$\vec{s}_1$	0	0	1	2	3	0	0							
$\vec{s}_2[n]$	0	0	2	4	3	0	0							
$\langle \vec{s}_1, \vec{s}_2[n] \rangle$	0	+	0	+	2	+	8	+	9	+	0	+	0	= 19

$\vec{s}_1$	0	0	1	2	3	0	0							
$\vec{s}_2[n-1]$	0	0	0	2	4	3	0							
$\langle \vec{s}_1, \vec{s}_2[n-1] \rangle$	0	+	0	+	0	+	4	+	12	+	0	+	0	= 16

$\vec{s}_1$	0	0	1	2	3	0	0							
$\vec{s}_2[n-2]$	0	0	0	0	2	4	3							
$\langle \vec{s}_1, \vec{s}_2[n-2] \rangle$	0	+	0	+	0	+	0	+	6	+	0	+	0	= 6

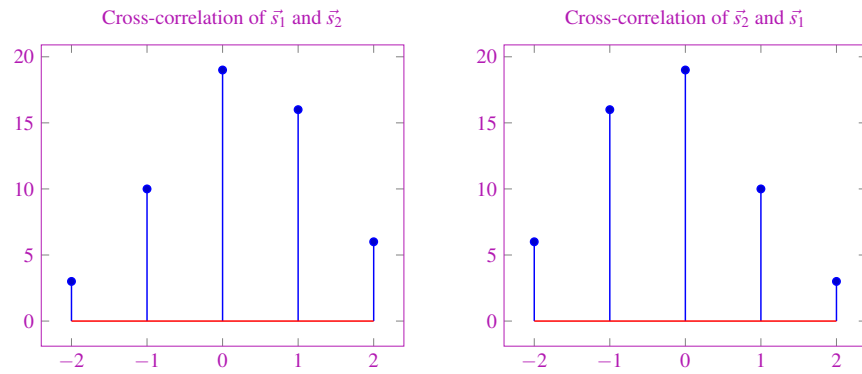
					$\text{corr}_{\vec{s}_2}(\vec{s}_1)[k]$									
$\vec{s}_2[n]$	0	0	2	4	3	0	0							
$\vec{s}_1[n+2]$	1	2	3	0	0	0	0							
$\langle \vec{s}_2, \vec{s}_1[n+2] \rangle$	0	+	0	+	6	+	0	+	0	+	0	+	0	= 6

$\vec{s}_2[n]$	0	0	2	4	3	0	0							
$\vec{s}_1[n+1]$	0	1	2	3	0	0	0							
$\langle \vec{s}_2, \vec{s}_1[n+1] \rangle$	0	+	0	+	4	+	12	+	0	+	0	+	0	= 16

$\vec{s}_2[n]$	0	0	2	4	3	0	0							
$\vec{s}_1[n]$	0	0	1	2	3	0	0							
$\langle \vec{s}_2, \vec{s}_1[n] \rangle$	0	+	0	+	2	+	8	+	9	+	0	+	0	= 19

$\vec{s}_2[n]$	0	0	2	4	3	0	0							
$\vec{s}_2[n-1]$	0	0	0	1	2	3	0							
$\langle \vec{s}_2, \vec{s}_1[n-1] \rangle$	0	+	0	+	0	+	4	+	6	+	0	+	0	= 10

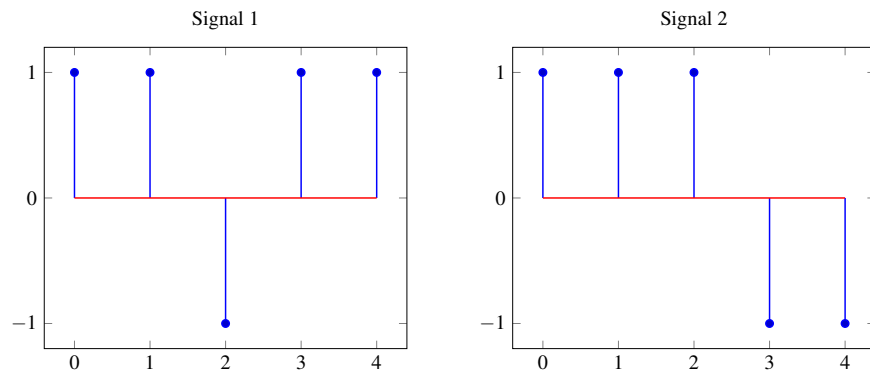
$\vec{s}_2[n]$	0	0	2	4	3	0	0							
$\vec{s}_2[n-2]$	0	0	0	0	1	2	3							
$\langle \vec{s}_2, \vec{s}_1[n-2] \rangle$	0	+	0	+	0	+	0	+	3	+	0	+	0	= 3



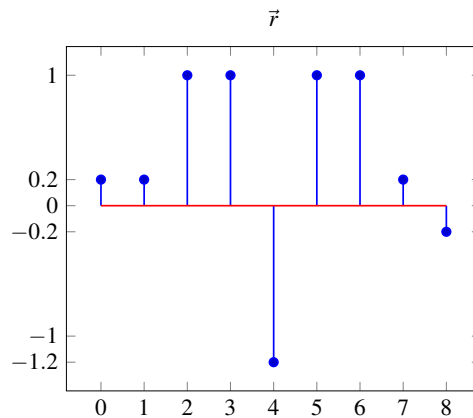
Notice that  $\text{corr}_{\vec{s}_1}(\vec{s}_2)[k] = \text{corr}_{\vec{s}_2}(\vec{s}_1)[-k]$ , i.e. changing the order of the signals reverses the cross-correlation sequence.

#### 4. Identifying satellites and their delays

We are given the following two signals,  $\vec{s}_1$  and  $\vec{s}_2$  respectively, that are signatures for two satellites.



(a) Your cellphone antenna receives the following signal  $r[n]$ . You know that there may be some noise present in  $r[n]$  in addition to the transmission from the satellite.



Which satellites are transmitting? What is the delay between the satellite and your cellphone? Use cross-correlation to justify your answer.

**Answer:** We calculate both  $\text{corr}_r(\vec{s}_1)[k]$  and  $\text{corr}_r(\vec{s}_2)[k]$ :

$$\text{corr}_r(\vec{s}_1)[-4] = (0.2)(1) = 0.2$$

$$\text{corr}_r(\vec{s}_1)[-3] = (0.2)(1) + (0.2)(1) = 0.4$$

$$\text{corr}_r(\vec{s}_1)[-2] = (1)(1) + (0.2)(1) + (0.2)(-1) = 1$$

$$\text{corr}_r(\vec{s}_1)[-1] = (1)(1) + (1)(1) + (0.2)(-1) + (0.2)(1) = 2$$

$$\text{corr}_r(\vec{s}_1)[0] = (-1.2)(1) + (1)(1) + (1)(-1) + (0.2)(1) + (0.2)(1) = -0.8$$

$$\text{corr}_r(\vec{s}_1)[1] = (1)(1) + (-1.2)(1) + (1)(-1) + (1)(1) + (0.2)(1) = 0$$

$$\text{corr}_r(\vec{s}_1)[2] = (1)(1) + (1)(1) + (-1.2)(-1) + (1)(1) + (1)(1) = \mathbf{5.2}$$

$$\text{corr}_r(\vec{s}_1)[3] = (0.2)(1) + (1)(1) + (1)(-1) + (-1.2)(1) + (1)(1) = 0$$

$$\text{corr}_r(\vec{s}_1)[4] = (-0.2)(1) + (0.2)(1) + (1)(-1) + (1)(1) + (-1.2)(1) = -1.2$$

$$\text{corr}_r(\vec{s}_1)[5] = (-0.2)(1) + (0.2)(-1) + (1)(1) + (1)(1) = 1.6$$

$$\text{corr}_r(\vec{s}_1)[6] = (-0.2)(-1) + (0.2)(1) + (1)(1) = 1.4$$

$$\text{corr}_r(\vec{s}_1)[7] = (-0.2)(1) + (0.2)(1) = 0$$

$$\text{corr}_r(\vec{s}_1)[8] = (-0.2)(1) = -0.2$$

$$\text{corr}_r(\vec{s}_2)[-4] = (0.2)(-1) = -0.2$$

$$\text{corr}_r(\vec{s}_2)[-3] = (0.2)(-1) + (0.2)(-1) = -0.4$$

$$\text{corr}_r(\vec{s}_2)[-2] = (1)(-1) + (0.2)(-1) + (0.2)(1) = -1$$

$$\text{corr}_r(\vec{s}_2)[-1] = (1)(-1) + (1)(-1) + (0.2)(1) + (0.2)(1) = -1.6$$

$$\text{corr}_r(\vec{s}_2)[0] = (-1.2)(-1) + (1)(-1) + (1)(1) + (0.2)(1) + (0.2)(1) = 1.6$$

$$\text{corr}_r(\vec{s}_2)[1] = (1)(-1) + (-1.2)(-1) + (1)(1) + (1)(1) + (0.2)(1) = 2.4$$

$$\text{corr}_r(\vec{s}_2)[2] = (1)(-1) + (1)(-1) + (-1.2)(1) + (1)(1) + (1)(1) = -1.2$$

$$\text{corr}_r(\vec{s}_2)[3] = (0.2)(-1) + (1)(-1) + (1)(1) + (-1.2)(1) + (1)(1) = -0.4$$

$$\text{corr}_r(\vec{s}_2)[4] = (-0.2)(-1) + (0.2)(-1) + (1)(1) + (1)(1) + (-1.2)(1) = 0.8$$

$$\text{corr}_r(\vec{s}_2)[5] = (-0.2)(-1) + (0.2)(1) + (1)(1) + (1)(1) = 2.4$$

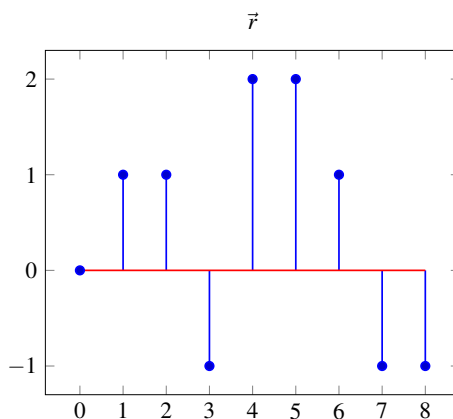
$$\text{corr}_r(\vec{s}_2)[6] = (-0.2)(1) + (0.2)(1) + (1)(1) = 1$$

$$\text{corr}_r(\vec{s}_2)[7] = (-0.2)(1) + (0.2)(1) = 0$$

$$\text{corr}_r(\vec{s}_2)[8] = (-0.2)(1) = -0.2$$

The maximum correlation value is 5.2 at  $k = 2$ . Since we have a plus-minus 1 signal of length 5, this high correlation likely comes from the satellite 1 transmission.

- (b) Now your cellphone receives a new signal  $r[n]$  as below. What the satellites that are transmitting and what is the delay between each satellite and your cellphone?



**Answer:** We want to find shifts  $k_1$  and  $k_2$  such that:  $\vec{r}[n] = \vec{s}_1[n - k_1] + \vec{s}_2[n - k_2]$ .

We calculate both  $\text{corr}_{\vec{r}}(\vec{s}_1)[k]$  and  $\text{corr}_{\vec{r}}(\vec{s}_2)[k]$  for different shifts  $k$ . The index where the maximum correlation value is achieved will tell us the shift indices (delays).

$$\text{corr}_{\vec{r}}(\vec{s}_1)[-3] = (1)(1) = 1$$

$$\text{corr}_{\vec{r}}(\vec{s}_1)[-2] = (1)(1) + (1)(1) = 2$$

$$\text{corr}_{\vec{r}}(\vec{s}_1)[-1] = (-1)(1) + (1)(1) + (1)(-1) = -1$$

$$\text{corr}_{\vec{r}}(\vec{s}_1)[0] = (2)(1) + (-1)(1) + (1)(-1) + (1)(1) = 1$$

$$\text{corr}_{\vec{r}}(\vec{s}_1)[1] = (2)(1) + (2)(1) + (-1)(-1) + (1)(1) + (1)(1) = 7$$

$$\text{corr}_{\vec{r}}(\vec{s}_1)[2] = (1)(1) + (2)(1) + (2)(-1) + (-1)(1) + (1)(1) = 1$$

$$\text{corr}_{\vec{r}}(\vec{s}_1)[3] = (-1)(1) + (1)(1) + (2)(-1) + (2)(1) + (-1)(1) = -1$$

$$\text{corr}_{\vec{r}}(\vec{s}_1)[4] = (-1)(1) + (-1)(1) + (1)(-1) + (2)(1) + (2)(1) = 1$$

$$\text{corr}_{\vec{r}}(\vec{s}_1)[5] = (-1)(1) + (-1)(-1) + (1)(1) + (2)(1) = 3$$

$$\text{corr}_{\vec{r}}(\vec{s}_1)[6] = (-1)(-1) + (-1)(1) + (1)(1) = 1$$

$$\text{corr}_{\vec{r}}(\vec{s}_1)[7] = (-1)(1) + (-1)(1) = -2$$

$$\text{corr}_{\vec{r}}(\vec{s}_1)[8] = (-1)(1) = -1$$

$$\begin{aligned}
\text{corr}_{\vec{r}}(\vec{s}_2)[-3] &= (1)(-1) = -1 \\
\text{corr}_{\vec{r}}(\vec{s}_2)[-2] &= (1)(-1) + (1)(-1) = -2 \\
\text{corr}_{\vec{r}}(\vec{s}_2)[-1] &= (-1)(-1) + (1)(-1) + (1)(1) = 1 \\
\text{corr}_{\vec{r}}(\vec{s}_2)[0] &= (2)(-1) + (-1)(-1) + (1)(1) + (1)(1) = 1 \\
\text{corr}_{\vec{r}}(\vec{s}_2)[1] &= (2)(-1) + (2)(-1) + (-1)(1) + (1)(1) + (1)(1) = -3 \\
\text{corr}_{\vec{r}}(\vec{s}_2)[2] &= (1)(-1) + (2)(-1) + (2)(1) + (-1)(1) + (1)(1) = -1 \\
\text{corr}_{\vec{r}}(\vec{s}_2)[3] &= (-1)(-1) + (1)(-1) + (2)(1) + (2)(1) + (-1)(1) = 3 \\
\text{corr}_{\vec{r}}(\vec{s}_2)[4] &= (-1)(-1) + (-1)(-1) + (1)(1) + (2)(1) + (2)(1) = \mathbf{7} \\
\text{corr}_{\vec{r}}(\vec{s}_2)[5] &= (-1)(-1) + (-1)(1) + (1)(1) + (2)(1) = 3 \\
\text{corr}_{\vec{r}}(\vec{s}_2)[6] &= (-1)(1) + (-1)(1) + (1)(1) = -1 \\
\text{corr}_{\vec{r}}(\vec{s}_2)[7] &= (-1)(1) + (-1)(1) = -2 \\
\text{corr}_{\vec{r}}(\vec{s}_2)[8] &= (-1)(1) = -1
\end{aligned}$$

The maximum correlation between signals  $\vec{r}$  and  $\vec{s}_1$  was achieved at  $k_1 = 1$ , and the maximum correlation between signals  $\vec{r}$  and  $\vec{s}_2$  was achieved at  $k_2 = 4$ .