

2. Finding The Bright Cave

Nara the one-handed druid and Kody the one-handed ranger find themselves in dire straits. Before them is a cliff with four cave entrances arranged in a square: two upper caves and two lower caves. Each entrance emits a certain amount of light, and the two wish to find exactly the amount of light coming from each cave. Here's the catch: after contracting a particularly potent strain of ghoul fever, our intrepid heroes are only able to see the total intensity of light before them (so their eyes operate like a single-pixel camera). Kody and Nara are capable adventurers, but they don't know any linear algebra – and they need your help.

Kody proposes an imaging strategy where he uses his hand to completely block the light from two caves at a time. He is able to take measurements using the following four masks (black means the light is blocked from that cave):

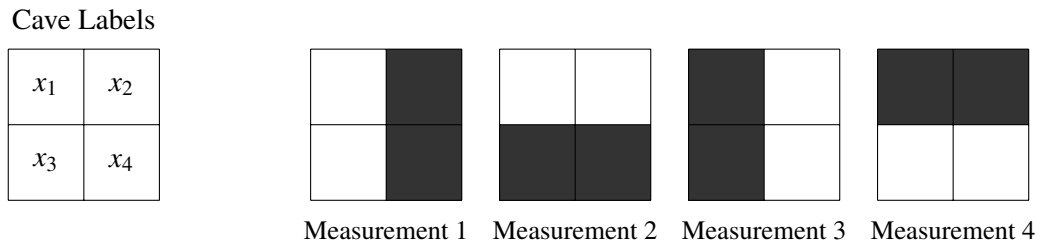


Figure 1: Four image masks.

- Let \vec{x} be the four-element vector that represents the magnitude of light emanating from the four cave entrances. Write a matrix \mathbf{K} that performs the masking process in Figure 1 on the vector \vec{x} , such that $\mathbf{K}\vec{x}$ is the result of the four measurements.
- Does Kody's set of masks give us a unique solution for all four caves' light intensities? Why or why not?
- Nara, in her infinite wisdom, places her one hand diagonally across the entrances, covering two of the cave entrances. However, her hand is not wide enough, letting in 50% of the light from the caves covered and 100% of the light from the caves not covered. The following diagram shows the percentage of light let through from each cave:

50%	100%
100%	50%

Does this additional measurement give them enough information to solve the problem? Why or why not?

3. (Optional Practice) Gaussian Elimination

Gaussian Elimination is a systematic procedure that a computer could follow for solving a large system of linear equations simultaneously. The augmented matrix is in the form:

$$\left[\begin{array}{cccc|c} a_{11} & a_{12} & \cdots & a_{1n} & b_1 \\ a_{21} & a_{22} & \cdots & a_{2n} & b_2 \\ \vdots & & & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} & b_m \end{array} \right] \quad (1)$$

Gaussian Elimination Algorithm for augmented matrix (1):

Step 1: For $i = 1, 2, \dots, m$

- (i) If necessary, swap row i with the row below it, so that the leading entry in row i is as far left as possible.
- (ii) Rescale row i so that its leading entry is equal to 1.
- (iii) For rows $j = i + 1, \dots, m$, add to row j a scalar multiple of row i , so that the leading entry of row i has all zeros below it.

Step 2: For $i = m, m - 1, \dots, 1$

- (i) Add to each row $j = 1, 2, \dots, i - 1$ a scalar multiple of row i so that the leading entry of row i has all zeros above it.

For the following systems, use Gaussian Elimination to solve the problem. Does a solution exist? Is it unique? If there are an infinite number of solutions, give the solution in the parametric form.

- (a) Let the three variables be x_1, x_2, x_3 . Solve the following augmented matrix form using Gaussian Elimination.

$$\left[\begin{array}{ccc|c} 3 & -1 & 2 & 1 \\ 0 & 0 & 2 & 1 \end{array} \right]$$

- (b) True or False: A system of equations with more equations than unknowns will always have either infinite solutions or no solutions.

(c)

$$\begin{bmatrix} 2 & 0 & 4 \\ 0 & 1 & 2 \\ 1 & 2 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 6 \\ -3 \\ 3 \end{bmatrix}$$

(d)

$$\begin{bmatrix} 1 & 4 & 2 \\ 1 & 2 & 8 \\ 1 & 3 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ 3 \end{bmatrix}$$

(e)

$$\begin{bmatrix} 2 & 2 & 3 \\ 0 & 1 & 1 \\ 2 & 0 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 7 \\ 3 \\ 1 \end{bmatrix}$$