

Lecture notes by Dasol Yoon (02/03/2015)

## Imaging

### Examples of imaging:

- Get readings from the brain, then construct an image from the information
- Milk, Juice, and Empty bottles arranged in a 3x3 carton.

– Example carton:

(See Figure 1)

- If we shine light through the carton, we can try to figure out what types of bottles are in that row or column. A Milk bottle adds 3 units, a Juice bottle adds 2 units, and an Empty bottle adds 1 unit. So in our example carton, we would have 5 units total for the first row.

(See Figure 2)

- We have a closed carton, and we want to figure out what types of bottles are inside. A way that we can do this is by shining light on each row, column, and diagonal.

(See Figure 3)

- To solve this, we just combine these equations:

$$\text{rows: } \begin{cases} x_{1,1} + x_{1,2} + x_{1,3} = 5 \\ x_{2,1} + x_{2,2} + x_{2,3} = 6 \\ x_{3,1} + x_{3,2} + x_{3,3} = 4 \end{cases} \quad \text{columns: } \begin{cases} x_{1,1} + x_{2,1} + x_{3,1} = 6 \\ x_{1,2} + x_{2,2} + x_{3,2} = 3 \\ x_{1,3} + x_{2,3} + x_{3,3} = 6 \end{cases} \quad \text{diagonals: } \begin{cases} x_{1,1} + x_{2,2} + x_{3,3} = 5 \\ x_{1,3} + x_{2,2} + x_{3,1} = 5 \end{cases}$$

to get the result.

(See Figure 4)

We have a 9x9 matrix that we want to image. We can take the following steps:

- Shine light onto the image
- Collect reflected light
- Collect measurement that says whether the pixel is black or white

M	J	0
M	J	0
M	0	J

Figure 1: An example carton.

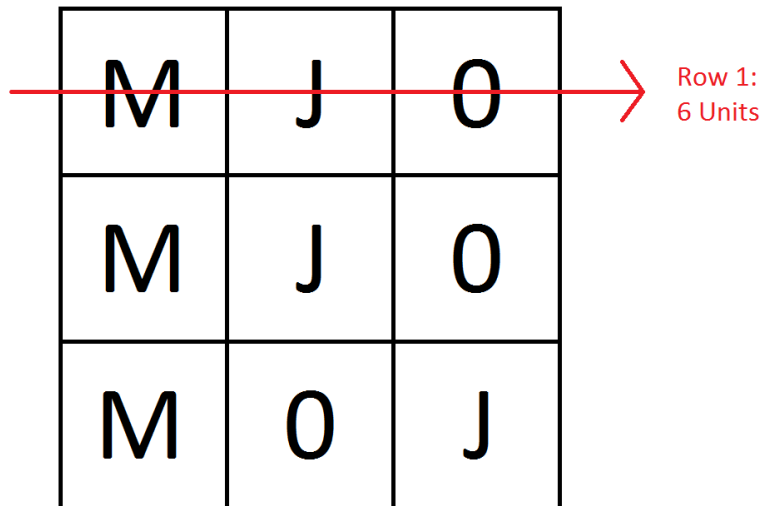


Figure 2: Shining a light through row 1 of the example carton.

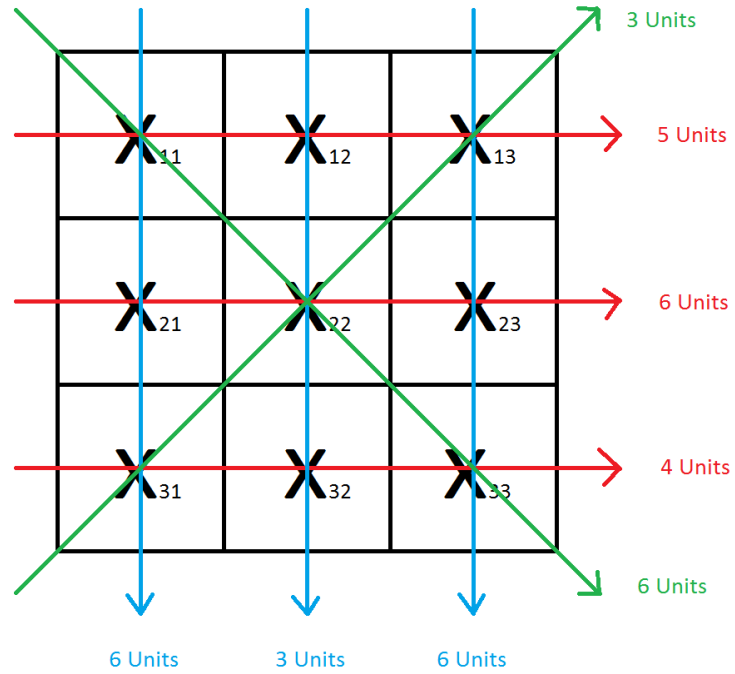


Figure 3: Shining lights through our mystery carton.

M	0	0
J	0	M
0	0	J

Figure 4: Our solved carton.

- Ideally, we would shine light on every pixel:

$$\begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \\ x_9 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \\ x_9 \end{pmatrix}$$

This is like the action of taking a picture and representing it with the matrix multiplication

- What if the photodetector had more constraints?

$$\begin{pmatrix} 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \\ x_9 \end{pmatrix} = \begin{pmatrix} x_1 + x_2 \\ x_2 + x_3 \\ x_3 + x_4 \\ x_4 + x_5 \\ x_5 + x_6 \\ x_6 + x_7 \\ x_7 + x_8 \\ x_8 + x_9 \\ x_9 \end{pmatrix}$$

We do not want to multiply by an 8x9 matrix because we could be losing information!

## Linear Equations

$$\begin{pmatrix} a_{1,1} & a_{1,2} & a_{1,3} \\ a_{2,1} & a_{2,2} & a_{2,3} \\ a_{3,1} & a_{3,2} & a_{3,3} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} \quad \text{We want to try to get an invertible matrix.}$$

$$a_{1,1}x_1 + a_{1,2}x_2 + a_{1,3}x_3 = b_1 \quad a_{2,1}x_1 + a_{2,2}x_2 + a_{2,3}x_3 = b_2 \quad a_{3,1}x_1 + a_{3,2}x_2 + a_{3,3}x_3 = b_3 \quad (1)$$

$$\begin{pmatrix} 0.5 & 0.5 & 0 & 0 \\ 0 & 0.5 & 0.5 & 0 \\ 0 & 0 & 0.5 & 0.5 \\ 0 & 0 & 0 & 0.5 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0.5 \\ 0.5 \\ 0.5 \\ 0.5 \end{pmatrix} \quad \text{This would produce an all - gray bar.}$$

$$\begin{pmatrix} 0.9 & 0.1 & 0 & 0 \\ 0 & 0.9 & 0.1 & 0 \\ 0 & 0 & 0.9 & 0.1 \\ 0 & 0 & 0 & 0.9 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0.1 \\ 0.9 \\ 0.1 \\ 0.9 \end{pmatrix} \quad \text{This would be closer to a gradient.}$$

# Vector Spaces

A **Basis** is the minimum number of representations of the vectors in a vector space.

A **vector space**  $(\mathbb{V}, \mathbb{F})$  is a set of vectors  $\mathbb{V}$ , a set of scalars  $\mathbb{F}$ , and two operators:

- Vector Addition

- Associative:  $\vec{u} + (\vec{v} + \vec{w}) = (\vec{u} + \vec{v}) + \vec{w}$
- Commutative:  $\vec{u} + \vec{v} = \vec{v} + \vec{u}$
- Additive Identity:  $\vec{0}$  such that  $\vec{v} + \vec{0} = \vec{v}$
- Additive Inverse:  $\vec{v}, \vec{w}$  such that  $\vec{v} + \vec{w} = \vec{0}$

- Scalar Multiplication

- Associative:  $\vec{u} \cdot (\vec{v} \cdot \vec{w}) = (\vec{u} \cdot \vec{v}) \cdot \vec{w}$
- Commutative:  $(\lambda \cdot \vec{u}) \cdot \vec{v} = \lambda \cdot (\vec{u} \cdot \vec{v})$
- Multiplicative Identity:  $1 \cdot \vec{v} = \vec{v}$
- Zero:  $\vec{0} \cdot \vec{v} = \vec{0}$

**Distributive Law:** Scalar multiplication will distribute across vector addition.