

EECS 16A
July 2, 2020
Lecture 1D

Topics:
- Nullspace
- Columnspace

Announcements:

- 1) Friday OH happening today
- 2) Friday HW party moved to Monday

★ For an n -dimensional space, we need n basis vectors.

$$A \in \mathbb{R}^{m \times n}$$
$$\bar{x} \in \mathbb{R}^n$$
$$\bar{b} \in \mathbb{R}^m$$

For $A\bar{x} = \bar{b}$
Transformation
 $\mathbb{R}^n \rightarrow \mathbb{R}^m$

If, $\bar{x} = \begin{bmatrix} m \\ n \end{bmatrix} \in \mathbb{R}^2$ $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix} \in \mathbb{R}^{3 \times 2}$

$$\bar{b} = A\bar{x} = \begin{bmatrix} m \\ n \\ m+n \end{bmatrix} \in \mathbb{R}^3$$

← Dim = 2
Lecture 1C

Nullspace: All solutions for $A\bar{x} = 0$ is called the nullspace of A .

For $A \in \mathbb{R}^{m \times n}$, $N(A) = \{\bar{x} \in \mathbb{R}^n \mid A\bar{x} = 0\}$

Ex 1: Show that $N(A)$ is a subspace of \mathbb{R}^n , where $A \in \mathbb{R}^{m \times n}$

i) If $\bar{x}_1 \in N(A)$, $\bar{x}_2 \in N(A)$

$$A\bar{x}_1 = \bar{0} \quad (I) \qquad A\bar{x}_2 = \bar{0} \quad (II)$$

$$(I) + (II)$$

$$A\bar{x}_1 + A\bar{x}_2 = \bar{0}$$

$$\Rightarrow A(\bar{x}_1 + \bar{x}_2) = \bar{0}$$

So $(\bar{x}_1 + \bar{x}_2) \in N(A)$

ii) If $\bar{x} \in N(A)$

$$\Rightarrow A\bar{x} = \bar{0}$$

$$\Rightarrow \alpha A\bar{x} = \bar{0} \Rightarrow A(\alpha\bar{x}) = \bar{0}$$

$\Rightarrow \alpha\bar{x} \in N(A)$, α is a scalar

iii) $A\bar{0} = \bar{0}$, $\bar{0} \in N(A)$

$N(A)$ is a subspace of \mathbb{R}^n

* Can be also proven for column space

Columnspace / range: Span of columns of A .

If $A = \begin{bmatrix} \bar{a}_1 & \dots & \bar{a}_n \end{bmatrix} \in \mathbb{R}^{m \times n}$, columnspace

$$= C(A) = \text{Range}(A)$$

$$= \{A\bar{x} \mid \bar{x} \in \mathbb{R}^n\}$$

$$A\bar{x} = \begin{bmatrix} \bar{a}_1 & \dots & \bar{a}_n \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

$$= [\bar{a}_1 x_1 + \bar{a}_2 x_2 + \dots]$$

= linear comb of $\{\bar{a}_1, \dots, \bar{a}_n\}$

For all values of \bar{x}

$$A\bar{x} \rightarrow \text{span}\{\bar{a}_1, \dots, \bar{a}_n\}$$

$$A\bar{x} \rightarrow C(A) \in \mathbb{R}^m$$

Lecture
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Takeaway:

$$\left. \begin{array}{l} \text{If } \bar{x} \in N(A), A\bar{x} = \bar{0} \\ \text{If } \bar{x} \notin N(A), A\bar{x} \neq \bar{0} \end{array} \right\} A\bar{x} \rightarrow C(A)$$

Ex 2 $A = \begin{bmatrix} 1 & 2 & 3 & 5 \\ 2 & 4 & 4 & 6 \end{bmatrix}$

Find $N(A)$, $C(A)$ & their basis/dim.

Nullspace: $A\bar{x} = \bar{0}$

$$\begin{bmatrix} 1 & 2 & 3 & 5 & | & 0 \\ 2 & 4 & 4 & 6 & | & 0 \end{bmatrix} \quad \text{lin indep columns}$$

$R_2' \leftarrow R_2 - 2R_1 \rightarrow \begin{bmatrix} 1 & 2 & 3 & 5 & | & 0 \\ 0 & 0 & -2 & -4 & | & 0 \end{bmatrix}$

$R_2' \leftarrow R_2 / -2 \rightarrow \begin{bmatrix} 1 & 2 & 3 & 5 & | & 0 \\ 0 & 0 & 1 & 2 & | & 0 \end{bmatrix}$

$R_1' \leftarrow R_1 - 3R_2 \rightarrow \begin{bmatrix} 1 & 2 & 0 & -1 & | & 0 \\ 0 & 0 & 1 & 2 & | & 0 \end{bmatrix}$

Free variables: x_2, x_4

Basic variables: $x_1 = -2x_2 + x_4$

$$x_3 = -2x_4$$

$$N(A) = \begin{bmatrix} -2x_2 + x_4 \\ x_2 \\ -2x_4 \\ x_4 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \end{bmatrix}$$

$$= \text{span} \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \end{bmatrix} \right\}$$

$$\text{Basis for } N(A) = \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \end{bmatrix} \right\}$$

$$\begin{aligned} \dim(N(A)) &= \# \text{ basis vectors for } N(A) \\ &= \# \text{ free variables} \\ &= 2 \end{aligned}$$

$$C(A) = \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 4 \end{bmatrix}, \begin{bmatrix} 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 5 \\ 6 \end{bmatrix} \right\} \quad (\mathbb{R}^2)$$

$$= \text{span} \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ 4 \end{bmatrix} \right\} \quad (\text{still } \mathbb{R}^2)$$

$$\text{Basis for } C(A) = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ 4 \end{bmatrix} \right\}$$

→ columns producing leading entries of 1.

$$\begin{aligned} \text{GE: } \# \text{ Free variables} &= \dim(N(A)) \\ \# \text{ Basic variables} &= \dim(C(A)) \\ \hline \# \text{ Variables} &= n \\ &= \# \text{ columns} \end{aligned}$$

Rank-Nullity Theorem:
Rank = $\dim(C(A))$
Nullity = $\dim(N(A))$

If $A \in \mathbb{R}^{m \times n}$ is a linear
from $V \rightarrow W$, where $V \in \mathbb{R}^n$ & $W \in \mathbb{R}^m$
then
$$\begin{aligned} \dim(C(A)) + \dim(N(A)) \\ &= \text{Rank}(A) + \text{Nullity}(A) \\ &= n = \dim(V) \end{aligned}$$

Full rank matrix:

GE: All the columns having leading entries of 1 $\rightarrow A\bar{x} = b$
has unique solution

Ex 3 Jupyter demo \rightarrow website

$$\begin{array}{ccc} \text{LHS} & & \text{RHS} \\ \bar{x} & & A\bar{x} \\ N(A) \longrightarrow & \{0\} & \left. \begin{array}{l} \{0\} \\ \neq \{0\} \end{array} \right\} C(A) \\ \text{Not of } N(A) \longrightarrow & \neq \{0\} & \end{array}$$

Ex 1

Ex 2

Ex 3

$$\dim(N(A)) = 2 \quad \dim(C(A)) = 1 \quad \begin{array}{l} 2+1 \\ = 3 \end{array}$$

3x3 matrix: 3 rows \rightarrow all dependent
3 columns \rightarrow all dependent
Free var = 2 $\rightarrow \dim(N(A))$
Basic var = 1 $\rightarrow \dim(C(A))$

Ex 4 $A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ 1 & 2 \end{bmatrix}$

Find Rank & nullity.

Nullspace: $\left[\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 1 & 2 & 0 \end{array} \right]$

$\rightarrow \left[\begin{array}{cc|c} 1 & 1 & 0 \\ 1 & 2 & 0 \\ 0 & 1 & 0 \end{array} \right] \rightarrow \left[\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \end{array} \right]$

$\rightarrow \left[\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right]$

Free variables = 0 \rightarrow nullity
Basic variables = 2 \rightarrow rank

Significance of $N(A)$ & $C(A)$:

i) case 1: No solution

No \bar{x} exists that satisfies $A\bar{x} = \bar{b}$
All possible values of $A\bar{x} \rightarrow C(A)$
 $\bar{b} \notin C(A)$

ii) Case 2: Unique solution

Free variables = 0

$$\dim(N(A)) = 0$$

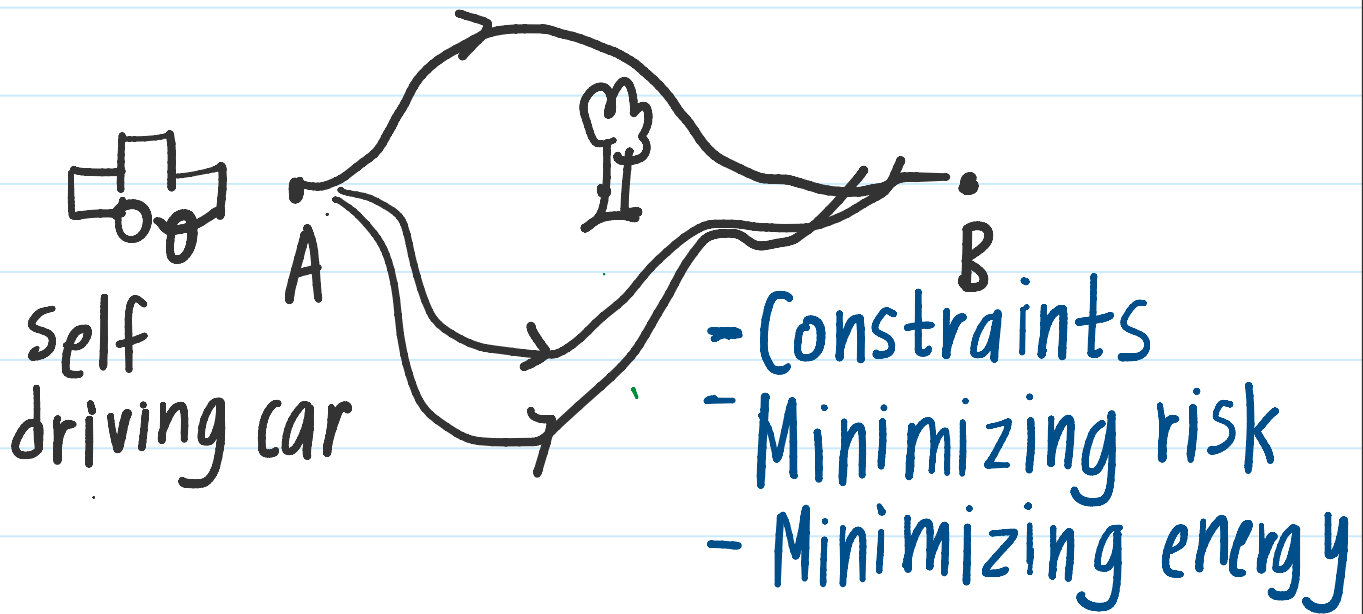
← trivial nullspace

iii) Case 3: Infinite solutions

free var > 0

$$\dim(N(A)) > 0$$

- * $C(A)$ can tell us if there is a solution to $A\bar{x} = \bar{b}$
- * $N(A)$ can characterize all existing solution.



Ex 5 If \bar{x}_0 is a solution to $A\bar{x} = \bar{b}$
and $\bar{v} \in N(A)$,
show that $\bar{x}_1 = \bar{x}_0 + \bar{v}$ should be
another solution to $A\bar{x} = \bar{b}$

$$\begin{aligned} \text{Given, } & A\bar{x}_0 = \bar{b} \quad (I) \\ & A\bar{v} = \bar{0} \quad (II) \\ (I) + (II) \Rightarrow & A(\bar{x}_0 + \bar{v}) = \bar{b} \end{aligned}$$

want to show $A\bar{x}_1 = \bar{b}$

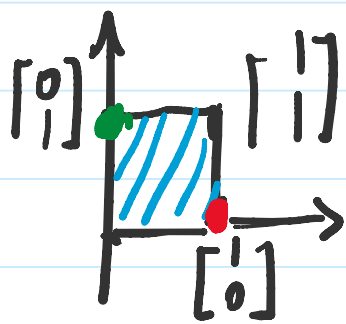
$\bar{x}_1 = \bar{x}_0 + \bar{v}$ is a solution

* If \bar{x}_0 is a solution to $A\bar{x} = \bar{b}$
and $\bar{x}_1 = \bar{x}_0 + \bar{v}$ is another soln
to $A\bar{x} = \bar{b} \Rightarrow \bar{v}$ must belong
in the nullspace of A .

Determinant: For $A \in \mathbb{R}^{n \times n}$, $\det(A)$ is the volume of n -dimensional parallelepiped spanned by columns of A .

→ $\det(A)$ represents the change of volume when transformed by A .

Example: $A \in \mathbb{R}^{2 \times 2}$ $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$



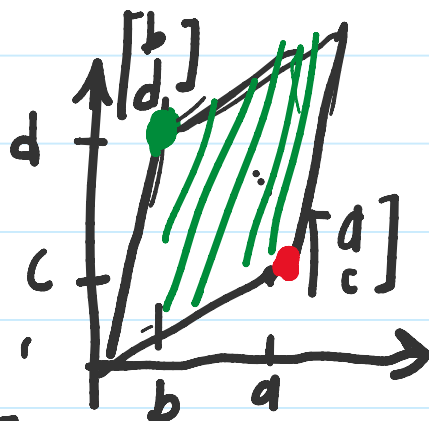
Input: \bar{x}

Volume = 1



$$A \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} a \\ c \end{bmatrix}$$

$$A \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} b \\ d \end{bmatrix}$$



Output: $A\bar{x}$

Volume = $ad - bc$

Change of volume = $\frac{ad - bc}{1} = ad - bc$

$$\det(A) = ad - bc$$

For $\mathbb{R}^{2 \times 2}$, volume $\neq 0$, only when the two col vectors are lin. indep

