

EECS 16A  
August 6, 2020  
Lecture 6D  
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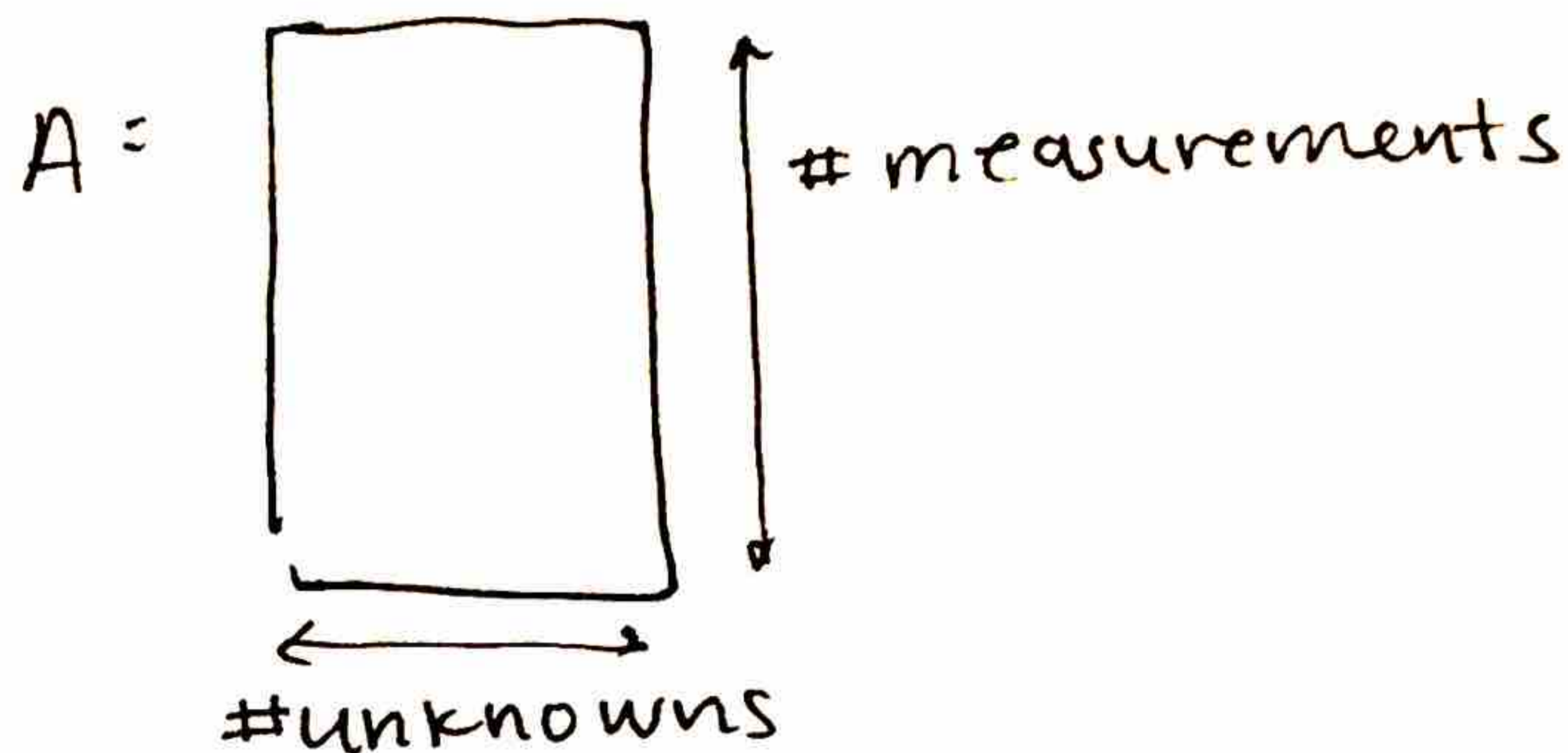
Today:

- Finish least squares  
↳ when does L.S. fail?
- Intro to OMP (orthogonal matching pursuit)

①

Yesterday: Least Squares

$A\vec{x} = \vec{b}$  has no solution  
because  $A$  is a "tall"



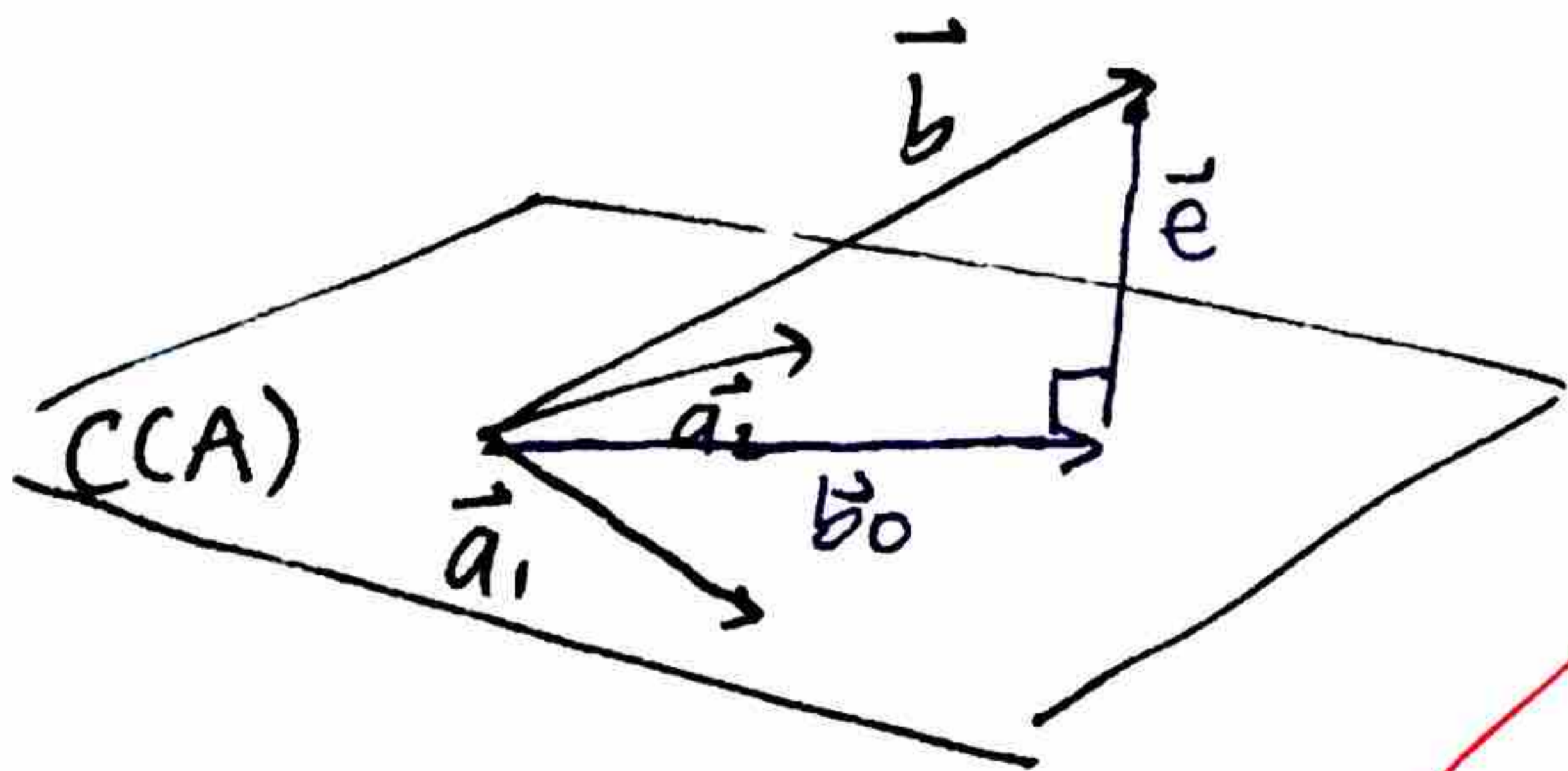
instead modify equation and solve

$$A\hat{x} = \vec{b}_0$$

↑  
best estimate of  $x$

①  $\vec{b}_0 \in C(A)$

②  $\|\vec{b}_0 - \vec{b}\|$  is minimized



$$\hat{x} = \boxed{(A^T A)^{-1}} A^T \vec{b}$$

$$\vec{b}_0 = A\hat{x} = A(A^T A)^{-1} A^T \vec{b}$$

$$\vec{e} = \vec{b} - \vec{b}_0$$

$\|\vec{e}\|^2$  ← metric of how close  $\vec{b}$  and  $\vec{b}_0$  are  
"How good a fit it is"

What if  $A^T A$  isn't invertible?

# When is $A^T A$ invertible?

Recall from mod. 1

$A^T A$  is invertible iff  $N(A^T A)$  is trivial  
" " is not invertible " " is non-trivial

**THM**  $N(A^T A) = N(A)$   
Nullspace of  $A^T A$  = Nullspace of  $A$

## What does this thm. tell us?

columns of  $A$  are lin. independent  $\Leftrightarrow N(A)$  is trivial  $\Leftrightarrow N(A^T A)$  is trivial  $\Leftrightarrow A^T A$  is invertible  $\Leftrightarrow$  L.S. works!

columns of  $A$  are dependent  $\leftarrow$   $\rightarrow$  L.S. does not work :)

## Before Proving.....

Transposes:

$A \in \mathbb{R}^{m \times n}$      $B \in \mathbb{R}^{n \times p}$

$C = AB$   
 $C^T = (AB)^T$   
 $C^T = B^T A^T$   
 $p \times m$      $p \times n$      $n \times m$

$C \in \mathbb{R}^{m \times p}$   
 $A^T B^T$  } can't even multiply  
 $\uparrow \quad \uparrow$   
 $n \times m \quad p \times n$

Try it:  $A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$   
 $B = \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix}$

Norms:

$\|\vec{x}\| = 0$  if and only if  $\vec{x} = \vec{0}$  ✓ property of norms

$$(\|\vec{x}\|)^2 = \left(\sqrt{x_1^2 + x_2^2 + \dots + x_n^2}\right)^2 = (0)^2$$

$$\underbrace{x_1^2}_{\text{w}} + \underbrace{x_2^2}_{\text{w}} + \dots + x_n^2 = 0$$

$$x_1^2 \geq 0 \quad x_2^2 \geq 0$$

↑ only sum to 0 if  $x_1^2 = 0, x_2^2 = 0, \dots$

↳  $x_1 = 0, x_2 = 0, \dots$

$$\vec{x} = \vec{0}$$

**THM**  $N(A^T A) = N(A)$

**proof** Need to prove 2 things

① if  $\vec{v} \in N(A)$  then  $\vec{v} \in N(A^T A)$

② if  $\vec{w} \in N(A^T A)$  then  $\vec{w} \in N(A)$

① Given:  $\vec{v} \in N(A)$   
 $A\vec{v} = \vec{0}$

$$A^T A \vec{v} = A^T \vec{0}$$

left multiplied by  $A^T$

$$A^T A \vec{v} = \vec{0}$$

Want to show:  $\vec{v} \in N(A^T A)$

✓ yay!

② Given:  $\vec{w} \in N(A^T A)$

④

$$A^T A \vec{w} = \vec{0}$$

$$\vec{w}^T A^T A \vec{w} = \vec{w}^T \vec{0} = 0 \quad \curvearrowright$$

$$\vec{w}^T A^T A \vec{w} = 0$$

$$(A\vec{w})^T (A\vec{w}) = 0$$

$$\|A\vec{w}\|^2 = 0^2 = 0$$

$$A\vec{w} = \vec{0} \iff \|A\vec{w}\| = 0$$

want to :  $\vec{w} \in N(A)$   
show

$$\|\vec{x}\|^2 = \vec{x}^T \vec{x}$$

Summary:

proved that we can look at the columns of  $A$  to determine if  $(A^T A)^{-1}$  exists

# Example when least squares fails

(5)

## Trilateration

3 beacons (A, B, C)

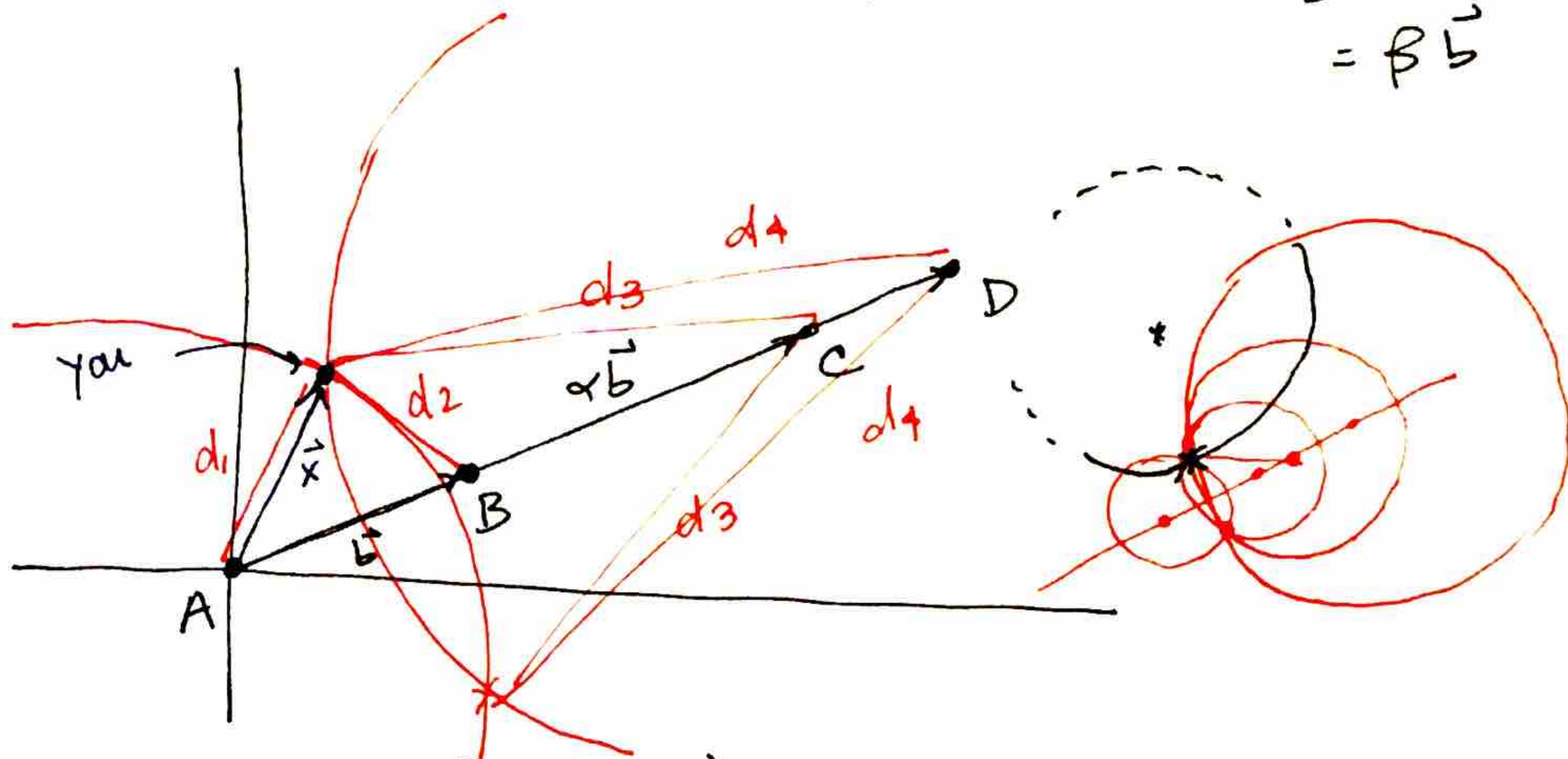
$$\vec{a} = \vec{0}$$

$$\vec{b} = \vec{b}$$

$$\vec{c} = \alpha \vec{b}$$

$$\vec{b} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$$

$$\vec{d} = \begin{bmatrix} \beta b_1 \\ \beta b_2 \end{bmatrix} = \beta \vec{b}$$



Solve for our position,  $\vec{x}$ :

$$\underbrace{2 \begin{bmatrix} \vec{b}^T - \vec{a}^T \\ \vec{c}^T - \vec{a}^T \end{bmatrix}}_A \vec{x} = \underbrace{\begin{bmatrix} d_1^2 - d_2^2 - \|\vec{a}\|^2 + \|\vec{b}\|^2 \\ d_1^2 - d_3^2 - \|\vec{a}\|^2 + \|\vec{c}\|^2 \end{bmatrix}}_b$$

$$A = \begin{bmatrix} 2\vec{b}^T \\ 2\alpha\vec{b}^T \end{bmatrix} = \begin{bmatrix} 2b_1 & 2b_2 \\ 2\alpha b_1 & 2\alpha b_2 \end{bmatrix}$$

dependent columns  $\parallel$

w/4 beacons:

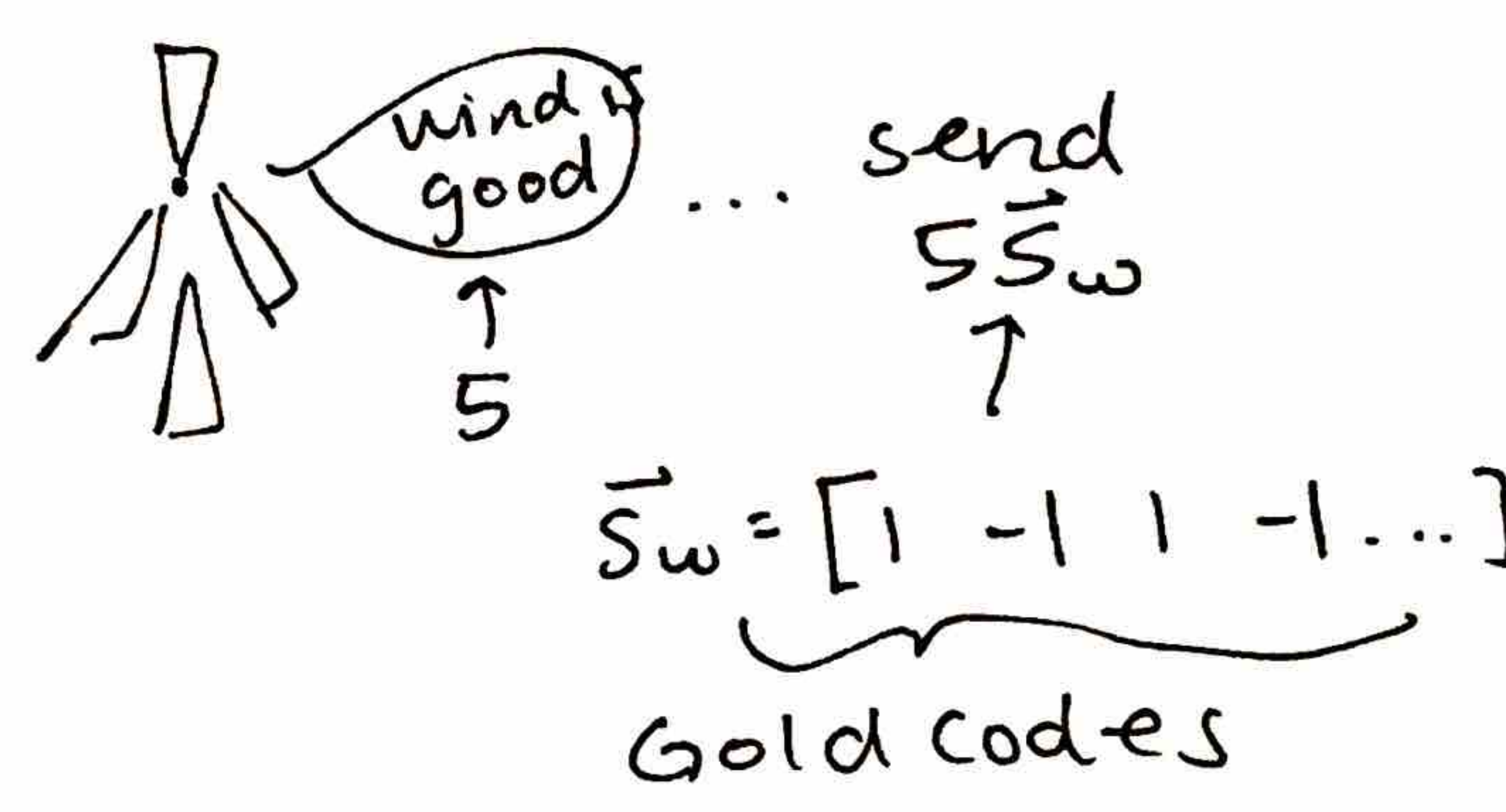
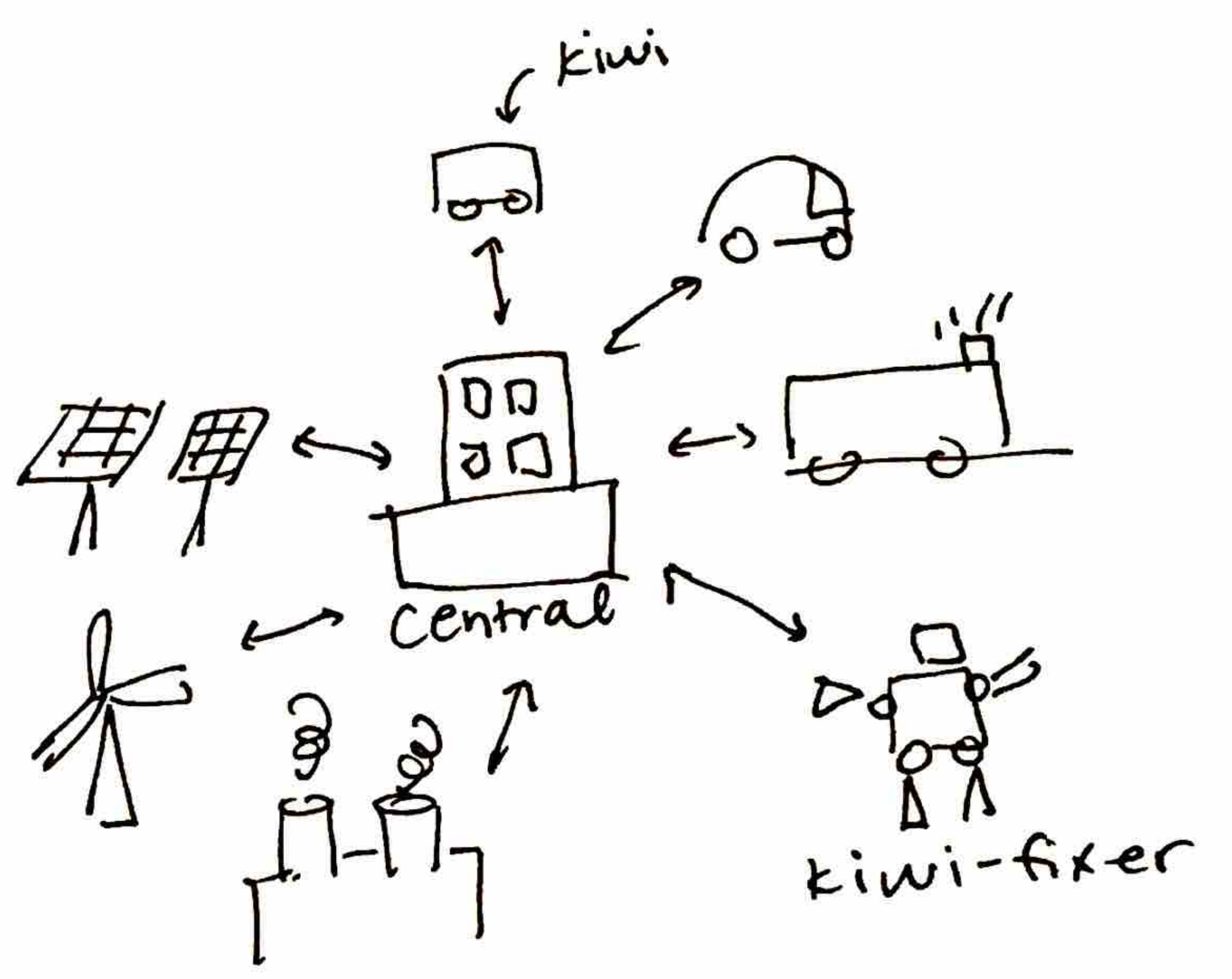
$$A = 2 \begin{bmatrix} \vec{b}^T - \vec{a}^T \\ \vec{c}^T - \vec{a}^T \\ \vec{d}^T - \vec{a}^T \end{bmatrix} = \begin{bmatrix} 2\vec{b}^T \\ 2\vec{c}^T \\ 2\vec{d}^T \end{bmatrix} = \begin{bmatrix} 2b_1 & 2b_2 \\ 2\alpha b_1 & 2\alpha b_2 \\ 2\beta b_1 & 2\beta b_2 \end{bmatrix}$$

# New TOpic : Orthogonal Matching Pursuit (OMP)

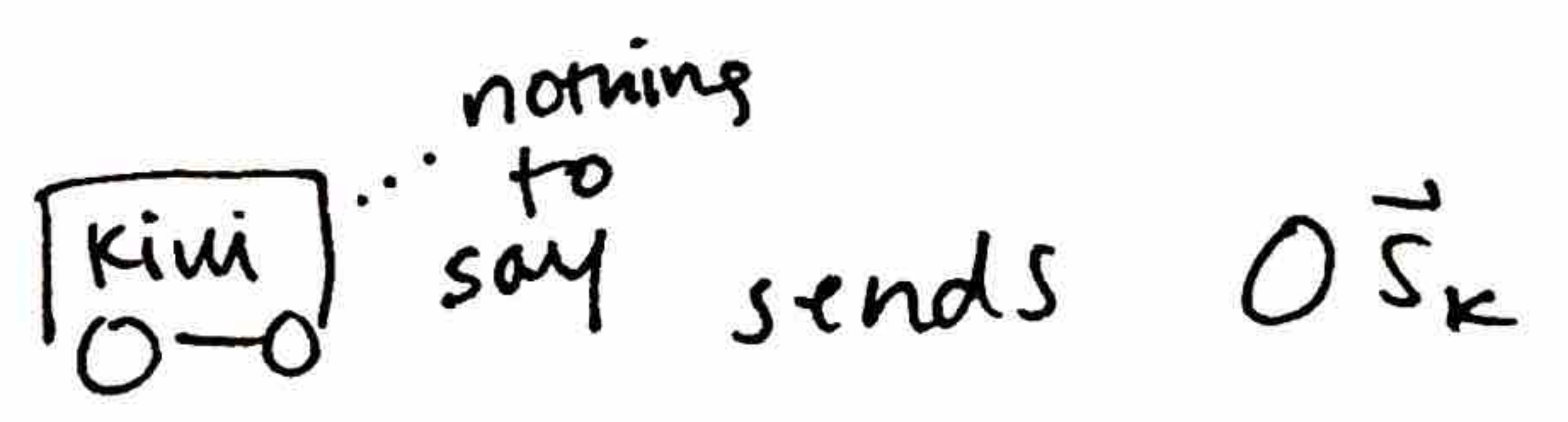
## Application: Smart City

- lots of devices say we have 10,000 devices

- Each device has a signature  $\vec{s}_i$  and if the device wants to send a message it sends  $\alpha \vec{s}_i$   
 message  $\uparrow$   $\alpha$   $\vec{s}_i$   $\uparrow$  signature



- Most devices don't have anything to say. They send  $0 \vec{s}_i$



- at central

$$\vec{r} = \alpha_1 \vec{s}_1 + \alpha_2 \vec{s}_2 + \dots + \alpha_{10,000} \vec{s}_{10,000}$$

$\uparrow$  received signal

want to know:

- which devices are transmitting
- what are they saying? (d?)

write as a matrix equation:

$$\underbrace{\begin{bmatrix} \vec{s}_1 & \vec{s}_2 & \dots & \vec{s}_{10,000} \\ | & | & & | \end{bmatrix}}_S \underbrace{\begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_{10,000} \end{bmatrix}}_{\vec{d}} = \begin{bmatrix} | \\ \vec{r} \\ | \end{bmatrix}$$

we'll use Gold codes for  $\vec{s}_i$ 's

Gold codes have length 1023  $\vec{s}_i \in \mathbb{R}^{1023}$   
 $\vec{r} \in \mathbb{R}^{1023}$

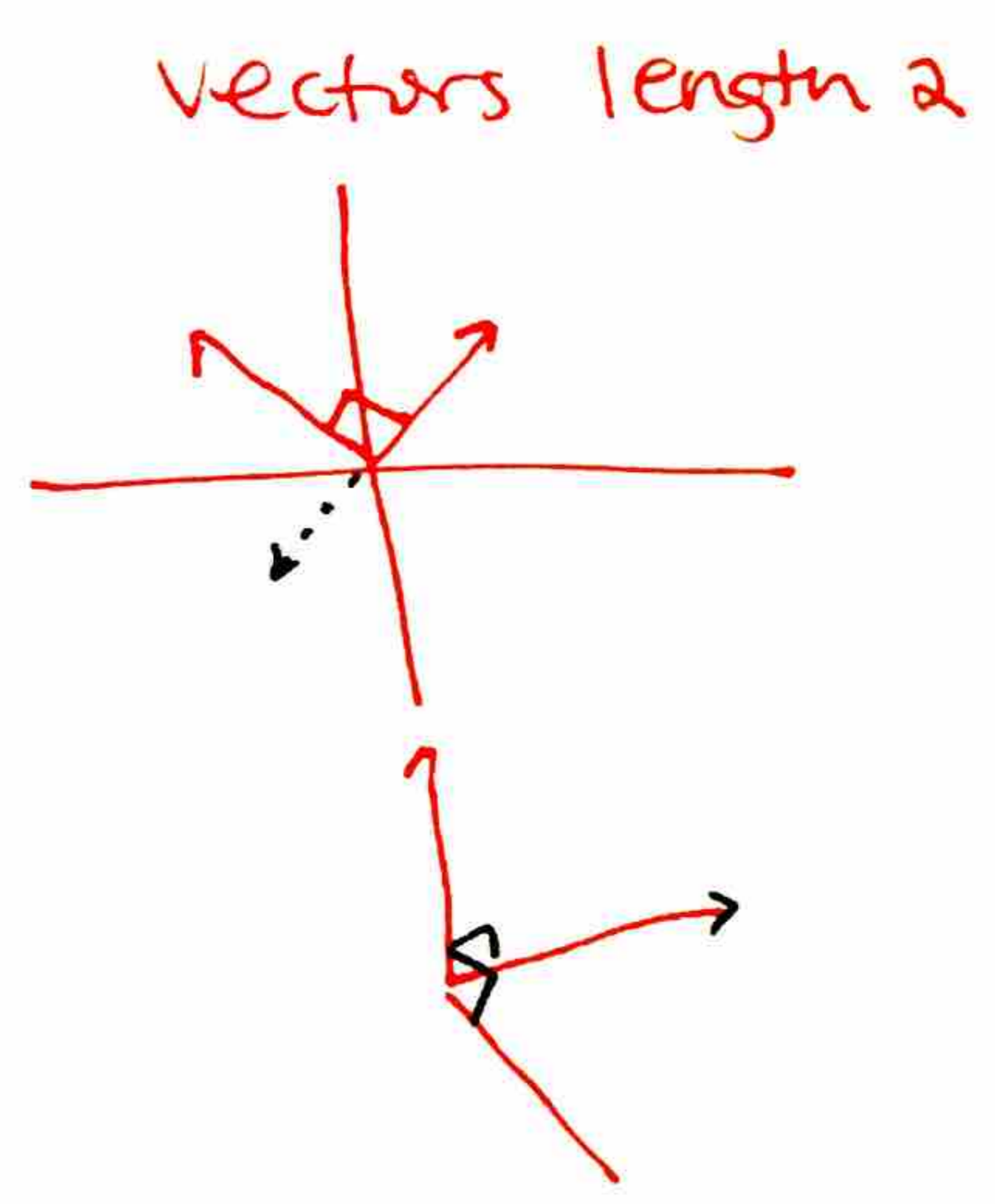
$$\begin{matrix} & \vec{S} & \vec{d} & = & \vec{r} \\ \uparrow & & \uparrow & & \uparrow \\ 1023 \times 10,000 & & 10,000 & & 1023 \end{matrix}$$

max 1023 orthogonal vectors

Idea: use addition structure (Information) in the problem

Gold codes are "nearly orthogonal" with each other

- $\vec{s}_1, \vec{s}_2 \}$  Gold codes
- $\langle \vec{s}_1, \vec{s}_2 \rangle$  is small
- $\langle \vec{s}_i, \vec{s}_i \rangle$  is large = 1023
- $\uparrow [1 \ -1 \ -1 \ \dots \ 1 \ -1]$
- $\langle \vec{s}_i, \vec{s}_i \rangle = \text{large, } 1023$
- $\langle \vec{s}_i, \vec{s}_{j \neq i} \rangle = \text{small}$



② most devices are silent most of the time

most  $\alpha_i = 0$

$\vec{\alpha}$  is mostly zero

" $\vec{\alpha}$  is a sparse vector"

$\vec{\alpha}$  is  $k$ -sparse if there are at most  $k$  non-zero elements