# EECS 16B Designing Information Devices and Systems II Spring 2016 Anant Sahai and Michel Maharbiz Discussion 6B

# 1. Complex Algebra

We provide a review of complex algebra to prepare you for the introduction of the phasor domain technique.

- (a) A complex number can be written in the rectangular form: z = x + iy, where x and y are the real and imaginary parts of z, respectively. How to express the following values in polar forms,  $|z|e^{i\theta}$ , where |z| and  $\theta$  are the magnitude and phase, respectively: -1, i, -i,  $\sqrt{i}$ , and  $\sqrt{-i}$ .
- (b) **Euler's identity.** How to represent  $\sin \theta$  and  $\cos \theta$  using complex numbers?
- (c) Show that  $|z| = \sqrt{zz^*}$ , where  $z^*$  is the complex conjugate of z.

Now let's tackle a numerical problem. Given two complex numbers, V = 3 - i4, I = -(2 + i3).

- (d) Express V and I in polar form.
- (e) Find VI,  $VI^*$ , V/I, and  $\sqrt{I}$ .

We have provided you with a table of useful properties of complex numbers.

#### **Complex Number Representation**

# **Rectangular vs polar forms:** $z = x + iy = |z|e^{i\theta}$ (1)

S: z = x + iy = |z|e (1) Addition:  $z_1 + z_2 = (x_1 + x_2) + i(y_1 + y_2)$   $= \tan^{-1}(y/x)$ . We can also Multiplication:  $z_1 z_2 = |z_1||z_2|e^{i(\theta_1 + \theta_2)}$ 

(4)

(6) (7)

where 
$$|z| = \sqrt{zz^*} = \sqrt{x^2 + y^2}$$
,  $\theta = \tan^{-1}(y/x)$ . We can also write  $x = |z| \cos \theta$ ,  $y = |z| \sin \theta$ .

**Euler's identity:** 
$$e^{i\theta} = \cos\theta + i\sin\theta$$
 (2)

$$\sin\theta = \frac{e^{i\theta} - e^{-i\theta}}{2i}, \cos\theta = \frac{e^{i\theta} + e^{-i\theta}}{2}.$$
 (3)

**Complex conjugate:**  $z^* = x - iy = |z|e^{-i\theta}$ .

$$(z+w)^* = z^* + w^*, (z-w)^* = z^* - w^*$$
(5)

$$(zw)^* = z^*w^*, (z/w)^* = z^*/w^*$$

$$z^* = z \Leftrightarrow z$$
 is real

$$(z^{n})^{*} = (z^{*})^{n} \tag{8}$$

Let  $z_1 = x_1 + iy_1 = |z_1|e^{i\theta_1}$ ,  $z_2 = x_2 + iy_2 = |z_2|e^{i\theta_2}$ .

**Aultiplication:** 
$$z_1 z_2 = |z_1| |z_2| e^{i(\theta_1 + \theta_2)}$$

(Note that we adopt the easier representation between rectangular form and polar form.)

Division: 
$$\frac{z_1}{z_2} = \frac{|z_1|}{|z_2|} e^{i(\theta_1 - \theta_2)}$$
 (11)

**Power:** 
$$z_1^n = |z_1|^n e^{in\theta_1}$$
 (12)

$$z_1^{1/2} = \pm |z_1|^{1/2} e^{i\theta_1/2} \tag{13}$$

## **Useful Relations**

$$-1 = i^2 = e^{i\pi} = e^{-i\pi} \tag{14}$$

$$i = e^{i\pi/2} = \sqrt{-1}$$
 (15)

$$-i = -e^{i\pi/2} = e^{-i\pi/2} \tag{16}$$

$$\sqrt{i} = (e^{i\pi/2})^{1/2} = \pm e^{i\pi/4} = \frac{\pm(1+i)}{\sqrt{2}}$$
 (17)

$$-\sqrt{i} = (e^{-i\pi/2})^{1/2} = \pm e^{i\pi/4} = \frac{\pm(1-i)}{\sqrt{2}}$$
(18)

#### 2. Phasor analysis

Any sinusoidal time-varying function x(t), representing a voltage or a current, can be expressed in the form

$$x(t) = \Re \mathfrak{e}[X e^{i\omega t}], \tag{19}$$

(9)

(10)

where X is a time-independent function called the phasor counterpart of x(t). Thus, x(t) is defined in the time domain, while its counterpart X is defined in the phasor domain.

The phasor analysis method consists of five steps. Consider the RC circuit below.



The voltage source is given by

$$v_s = 12\sin(\omega t - \frac{\pi}{4}),\tag{20}$$

with  $\omega = 10^3$  rad/s,  $R = \sqrt{3} k\Omega$ , and  $C = 1 \mu F$ .

Our goal is to obtain a solution for i(t) with the sinusoidal voltage source  $v_s$ .

#### (a) Step 1: Adopt cosine references

All voltages and currents with known sinusoidal functions should be expressed in the standard cosine format. Convert  $v_s$  into a cosine and write down its phasor representation  $V_s$ .

# (b) Step 2: Transform circuits to phasor domain

The voltage source is represented by its phasor  $V_s$ . The current i(t) is related to its phasor counterpart I by

$$i(t) = \Re \mathfrak{e}[Ie^{i\omega t}]. \tag{21}$$

What are the phasor representations of *R* and *C*?

# (c) Step 3: Cast KCL and/or KVL equations in phasor domain

Use Kirchhoff's laws to write down a loop equation that relates all phasors in Step 2.

(d) Step 4: Solve for unknown variables

Solve the equation you derived in Step 3 for *I*. What is the polar form of  $I (Ae^{i\theta})$ , where *A* is a positive real number)?

# (e) Step 5: Transform solutions back to time domain

To return to time domain, we apply the fundamental relation between a sinusoidal function and its phasor counterpart. What is i(t)?

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