

# LINEAR TIME-INVARIANT (LTI) SYSTEMS (CONTD.)

1. INTRODUCTION ✓
2. RECAP OF LINEARITY ✓
3. TIME INVARIANCE ✓
4. EXAMPLES ✓
5. LTI SYSTEMS: IMPULSE RESPONSE CHARACTERIZATION (CAUSALITY) - DISCRETE ✓
6. ILLUSTRATION OF DISCRETE CONVOLUTION (INCL. WITH PICTURES) ✓
7. VERY SIMILAR RESULT FOR C.T. ✓

→ EXAMPLE:  $x[t+1] = a x[t] + b u[t]$ ,  $y[t] = c x[t] + d u[t]$

→ I.C.  $x[0] = 0$

→ IMPULSE INPUT  $\delta[t] = \begin{cases} 1, & t=0 \\ 0, & \text{otherwise} \end{cases}$

$$y[0] = c x[0] + d u[0] = d u[0] = d \delta[0] = d$$

$$x[1] = a x[0] + b u[0] = b \quad ; \quad y[1] = c b + d u[1] = c b$$

$$x[2] = a x[1] + b u[1] = a b \quad ; \quad y[2] = c a b$$

$$x[3] = a x[2] + b u[2] = a^2 b \quad ; \quad y[3] = c a^2 b$$

$$\vdots$$
$$x[t] = a^{t-1} b$$

$$; \quad y[t] = c a^{t-1} b$$

→  $y[t] = \sum_{i=0}^t u[i] h[t-i]$

(assuming 1) causal & 2)  $u[t] = 0$  for  $t < 0$

→ if  $u[i] = \delta[i]$

→  $y[t] = \underset{1}{u[0]} h[t] = h[t] \checkmark$

→ FOR THIS SYSTEM:

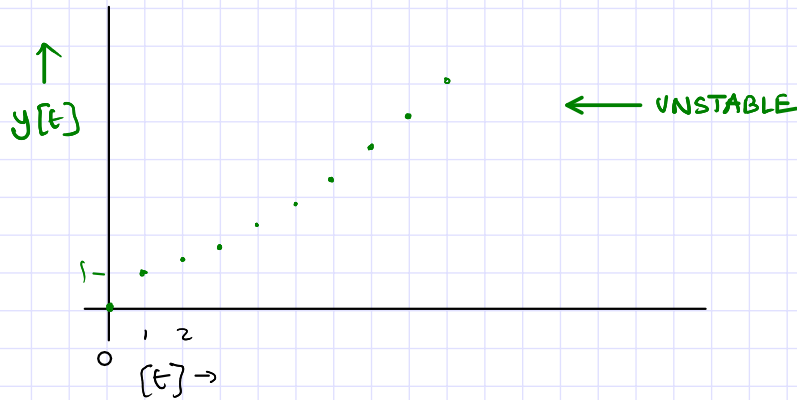
$$h[t] = \begin{cases} d, & \text{if } t=0 \\ c a^{t-1} b, & \text{for } t > 0 \end{cases}$$

→ COMPOUND INTEREST EXAMPLE

→  $S[t+1] = (1+r/12) S[t] + u[t], \quad y[t] = S[t]$

→  $a = (1+r/12), \quad b = 1, \quad c = 1, \quad d = 0$

→  $h[t] = \begin{cases} 0, & t = 0 \\ (1+r/12)^{t-1}, & t > 0 \end{cases}$



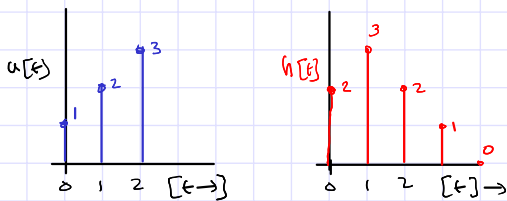
→ GIVEN ONLY  $h[t]$  for some LTI system

→ CAN YOU DETERMINE IF THE SYSTEM IS BIBO STABLE?

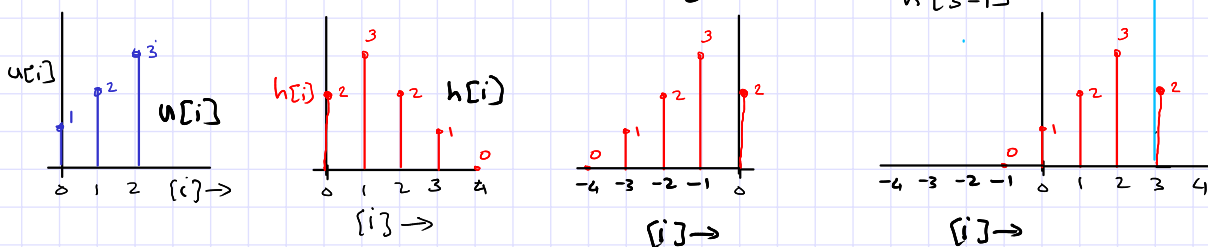
↑ FIGURE OUT FOR YOURSELF

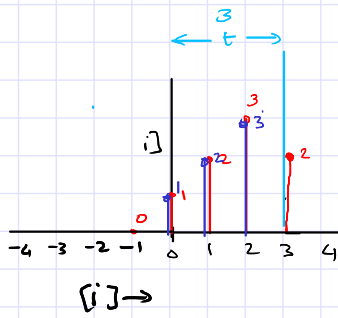
6. CONVOLUTION, ILLUSTRATED GRAPHICALLY

$y[t] = u[t] \otimes h[t] = \sum_{i=0}^t u[i] h[t-i]$  (assuming 1) causal, 2)  $u[t] = 0 \quad \forall t < 0$ )



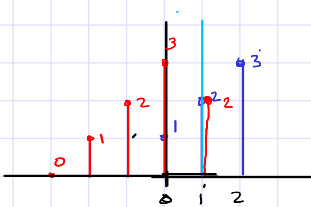
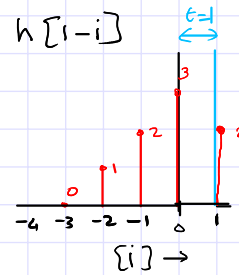
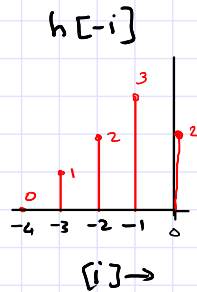
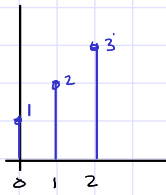
t=3:  $y[3] = \sum_{i=0}^3 u[i] h[3-i]$





$$y[3] = 1 + 4 + 9 = 14$$

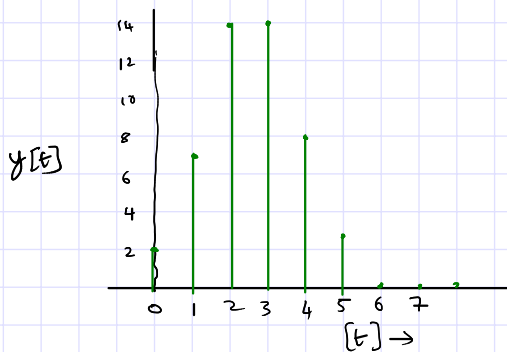
$$y[n] = \sum_{i=0}^n u[i] h[n-i]$$



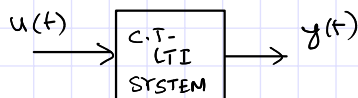
$$y[2] = 3 + 4 = 7$$

$$y[0] = 2 ; y[1] = 7 ; y[2] = 14 ; y[3] = 14 ; y[4] = 8 ; y[5] = 3$$

$y[6]$  and above = 0



→ OUTLINE OF FLOW FOR C.T. SYSTEMS



→ DIRAC  $\delta$  function:  $\delta(t) = \begin{cases} \infty, & t=0 \\ 0, & \text{everywhere else} \end{cases}$

$$\int_{-\epsilon}^{\epsilon} \delta(z) dz = 1 \text{ for any } \epsilon > 0$$

→ Apply  $\delta(t)$  as input to the system

→ Record  $y(t)$  ← this is the impulse response  $h(t)$

→ Given any  $u(t)$ , if  $u(t) \mapsto y(t)$ , then:

$$\rightarrow y(t) = \int_{-\infty}^{\infty} u(\tau) h(t-\tau) d\tau = u(t) \otimes h(t)$$

↑ CONTINUOUS TIME CONVOLUTION

→ Causality for C.T. systems:

→ LTI. C.T. system is causal iff  $h(t) = 0 \quad \forall t < 0$

$$\rightarrow y(t) = \int_{-\infty}^t u(\tau) h(t-\tau) d\tau$$

---











