

$$\frac{d\vec{x}(t)}{dt} = A\vec{x}(t) + \vec{b}u(t)$$

$$\vec{z} = T\vec{x} \Leftrightarrow \underline{\underline{\vec{x} = T^{-1}\vec{z}}}$$

$$\frac{d}{dt} [T^{-1}\vec{z}(t)] = A T^{-1}\vec{z} + \vec{b}u(t)$$

$$T^{-1} \frac{d\vec{z}(t)}{dt} = A T^{-1}\vec{z} + \vec{b}u(t)$$

$$\frac{d}{dt} \vec{z}(t) = \underbrace{TAT^{-1}}_{\hat{A}} \vec{z} + \underbrace{T\vec{b}}_{\hat{b}} u(t)$$

orig. sys.:  $\rightarrow \vec{x}[t+1] = A\vec{x}[t] + \vec{b}u[t] \quad ; \quad y[t] = \vec{c}^T \vec{x}[t] + du[t]$  (1)

observer:  $\hat{x}[t+1] = A\hat{x}[t] + \vec{b}u[t] + \vec{l}(\vec{c}^T \hat{x}[t] - y[t] + du[t])$

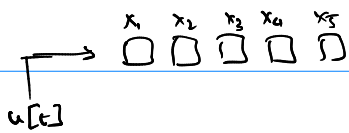
$$\hat{x}[t+1] = A\hat{x}[t] + \vec{b}u[t] + \vec{l}(\underbrace{\vec{c}^T \hat{x}[t]}_{+ du[t]} - \vec{c}^T \vec{x}[t] - du[t])$$

$$\rightarrow \hat{x}[t+1] = A\hat{x}[t] + \vec{b}u[t] + \vec{l}\vec{c}^T(\underbrace{\hat{x}[t] - \vec{x}[t]}_{\vec{e}[t]}) \quad (2)$$

$$(2) - (1) \quad \underbrace{\hat{x}[t+1] - \vec{x}[t+1]}_{\vec{e}[t+1]} = A(\underbrace{\hat{x}[t] - \vec{x}[t]}_{\vec{e}[t]}) + \vec{l}\vec{c}^T \vec{e}[t]$$

$$\Rightarrow \vec{e}[t+1] = A\vec{e}[t] + \vec{l}\vec{c}^T \vec{e}[t]$$

$$\Rightarrow \boxed{\vec{e}[t+1] = (A + \vec{l}\vec{c}^T)\vec{e}[t]}$$

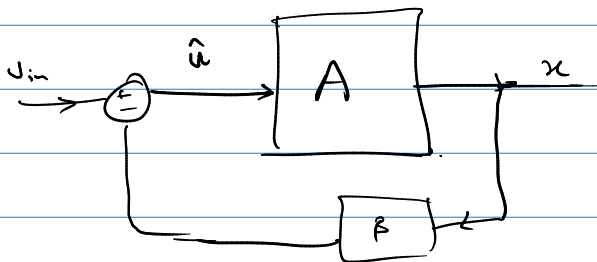


0-255

$$x_i \in [0, \dots, 255]$$

$$\vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_5 \end{bmatrix}$$

$$\begin{bmatrix} x_1[t+1] \\ x_2[t+1] \\ x_3[t+1] \\ x_4[t+1] \\ x_5[t+1] \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} x_1[t] \\ x_2[t] \\ x_3[t] \\ x_4[t] \\ x_5[t] \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} u[t]$$



$$\hat{u} = v_{in} - \beta x$$

$$x = A \hat{u}$$

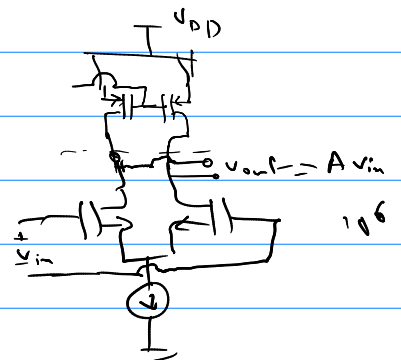
$$x = A(v_{in} - \beta x) \Rightarrow x(1 + \beta A) = A v_{in}$$

$$x = \frac{A}{1 + \beta A} v_{in} \approx \frac{A}{\beta A} v_{in} = \frac{v_{in}}{\beta}$$

$$\beta A \gg 1$$

$$A > 10^4$$

$A \sim$



10<sup>6</sup>

10<sup>-3</sup>