## 1. System Identification by Means of Least Squares

(a) Consider the scalar discrete-time system

$$x[i+1] = ax[i] + bu[i] + w[i]$$
(1)

Where the scalar state at timestep *i* is x[i], the input applied at timestep *i* is u[i] and w[i] represents some (small) external disturbance that also participated at timestep *i* (which we cannot predict or control, it's a purely random disturbance).

Assume that you have measurements for the states x[i] from i = 0 to  $\ell$  and also measurements for the controls u[i] from i = 0 to  $\ell - 1$ . Further assume  $\ell \ge 2$ .

Show that we can set up a linear system as in eq. (2) to find constants *a* and *b*. How do we solve this system?

$$\underbrace{\begin{bmatrix} x[1]\\x[2]\\\vdots\\x[\ell]\end{bmatrix}}_{\vec{s}} \approx \underbrace{\begin{bmatrix} x[0] & u[0]\\x[1] & u[1]\\\vdots&\vdots\\x[\ell-1] & u[\ell-1]\end{bmatrix}}_{D} \underbrace{\begin{bmatrix} a\\b\end{bmatrix}}_{\vec{p}}$$
(2)

(b) What if there were now two distinct scalar inputs to a scalar system

$$x[i+1] = ax[i] + b_1 u_1[i] + b_2 u_2[i] + w[i]$$
(3)

and that we have measurements as before, but now also for both of the control inputs.

Set up a least-squares problem that you can solve to get an estimate of the unknown system parameters a,  $b_1$ ,  $b_2$ .

(c) What could go wrong in the previous case? For what kind of inputs would make least-squares fail to give you the parameters you want?

(d) Now consider the two dimensional state case with a single input.

$$\vec{x}[i+1] = \begin{bmatrix} x_1[i+1] \\ x_2[i+1] \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \vec{x}[i] + \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} u[i] + \vec{w}[i]$$
(4)

How can we treat this like two parallel problems to set this up using least-squares to get estimates for the unknown parameters  $a_{11}$ ,  $a_{12}$ ,  $a_{21}$ ,  $a_{22}$ ,  $b_1$ ,  $b_2$ ? Write the least squares solution in terms of your known matrices and vectors (including based on the labels you gave to various matrices/vectors in previous parts). *Hint: What work/computation can we reuse across the two problems*?

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