

Agenda:

tinyurl.com/sp23-oliver-resources

- Welcome back!
- Grade Requests due Friday 4/7
- Status Check Released
- Recap:
 - Orthonormality
 - Gram Schmidt
- Today: More Orthonormality

★ Taken directly from Dis9B notes

Orthonormality {
 1) orthogonal
 2) normal

1) Given $\vec{x}, \vec{y} \in \mathbb{R}^n$:

$$\vec{x} \text{ and } \vec{y} \text{ are orthogonal} \Leftrightarrow \langle \vec{x}, \vec{y} \rangle = \vec{y}^\top \vec{x} = 0$$

Set of vectors $S = \{\vec{s}_1, \dots, \vec{s}_m\}$ if

$$\langle \vec{s}_i, \vec{s}_j \rangle = 0 \text{ for all } \vec{s}_i \neq \vec{s}_j$$

2) Normalized vectors: unit norm, $\|\vec{x}\| = 1$

Orthonormal sets of vectors (S)

(1) All vectors unit norm

(2) All vectors orthogonal to each other

Mathematically:

$$\langle \vec{x}, \vec{y} \rangle = \begin{cases} 1 & \text{if } \vec{x} = \vec{y} \\ 0 & \text{if } \vec{x} \neq \vec{y} \end{cases} \quad \text{for all } \vec{x}, \vec{y} \in S$$

(1) Square $Q \in \mathbb{R}^{n \times n}$ (column & rows are orthonormal sets)

- "orthonormal matrix"

$$Q^\top Q = I_n, \quad Q Q^\top = I_n, \quad Q^\top = Q^{-1}$$

(2) Tall $Q \in \mathbb{R}^{m \times n}$ ($m \geq n$) (columns are orthonormal set)

- "orthonormal columns"

$$Q^\top Q = I_n$$

(3) Wide $Q \in \mathbb{R}^{m \times n}$ ($m \leq n$) (rows are orthonormal set)

- "orthonormal rows"

$$Q Q^\top = I_m$$

Gram Schmidt Review (Dis 9B)

Goal: Given set of vectors $S = \{\vec{s}_1, \vec{s}_2, \dots, \vec{s}_m\}$, find an orthonormal set of vectors

$$Q = \{\vec{q}_1, \vec{q}_2, \dots, \vec{q}_m\} \text{ s.t. } \text{Span}\{\vec{Q}\} = \text{Span}\{\vec{S}\}$$

$$\vec{q}_1 = \frac{\vec{s}_1}{\|\vec{s}_1\|} \quad (\text{just normalize})$$

$$\vec{q}_2 = \frac{\vec{s}_2 - \langle \vec{s}_2, \vec{q}_1 \rangle \vec{q}_1}{\|\vec{s}_2 - \langle \vec{s}_2, \vec{q}_1 \rangle \vec{q}_1\|} \quad \text{where } \vec{z}_2 = \vec{s}_2 - \langle \vec{s}_2, \vec{q}_1 \rangle \vec{q}_1$$

$$\vec{q}_3 = \frac{\vec{s}_3 - \langle \vec{s}_3, \vec{q}_1 \rangle \vec{q}_1 - \langle \vec{s}_3, \vec{q}_2 \rangle \vec{q}_2}{\|\vec{s}_3 - \langle \vec{s}_3, \vec{q}_1 \rangle \vec{q}_1 - \langle \vec{s}_3, \vec{q}_2 \rangle \vec{q}_2\|} \quad \text{where } \vec{z}_3 = \vec{s}_3 - \langle \vec{s}_3, \vec{q}_1 \rangle \vec{q}_1 - \langle \vec{s}_3, \vec{q}_2 \rangle \vec{q}_2$$

$$\vec{q}_4 = \frac{\vec{s}_4 - \langle \vec{s}_4, \vec{q}_1 \rangle \vec{q}_1 - \langle \vec{s}_4, \vec{q}_2 \rangle \vec{q}_2 - \langle \vec{s}_4, \vec{q}_3 \rangle \vec{q}_3}{\|\vec{s}_4 - \langle \vec{s}_4, \vec{q}_1 \rangle \vec{q}_1 - \langle \vec{s}_4, \vec{q}_2 \rangle \vec{q}_2 - \langle \vec{s}_4, \vec{q}_3 \rangle \vec{q}_3\|} \quad \text{where } \vec{z}_4 = \vec{s}_4 - \langle \vec{s}_4, \vec{q}_1 \rangle \vec{q}_1 - \langle \vec{s}_4, \vec{q}_2 \rangle \vec{q}_2 - \langle \vec{s}_4, \vec{q}_3 \rangle \vec{q}_3$$

⋮

Subtract projections of \vec{s}_i onto all previous vectors in set

$$\vec{q}_i = \frac{\vec{s}_i - \sum_{j=1}^{i-1} \langle \vec{s}_i, \vec{q}_j \rangle \vec{q}_j}{\|\vec{s}_i - \sum_{j=1}^{i-1} \langle \vec{s}_i, \vec{q}_j \rangle \vec{q}_j\|} \quad \text{where } \vec{z}_i = \vec{s}_i - \sum_{j=1}^{i-1} \langle \vec{s}_i, \vec{q}_j \rangle \vec{q}_j$$

Recall: \vec{z}_i represents component of \vec{s}_i that is orthogonal to all previous vectors in set

"Basis Extension" via Gram-Schmidt (Algorithm 24 in Note 11)

Problem: Starting w/ some set of vectors S which span a subspace of \mathbb{R}^n , we want to find an orthonormal basis for \mathbb{R}^n that contains the basis vectors of the original S

Idea: append some basis of \mathbb{R}^n to S & run GS on all vectors

⇒ Use standard basis vectors! *

Ex: Suppose you want to extend an orthonormal basis of \mathbb{R}^3 from $S = \left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$

→ First notice than $\text{Span}\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\} \neq \mathbb{R}^3$

→ To extend basis, add standard basis of \mathbb{R}^3 & run GS

$$\text{GS}\left(\underbrace{\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}}_{\text{appended standard basis vectors}}\right) \Rightarrow \text{basis for } \mathbb{R}^3$$