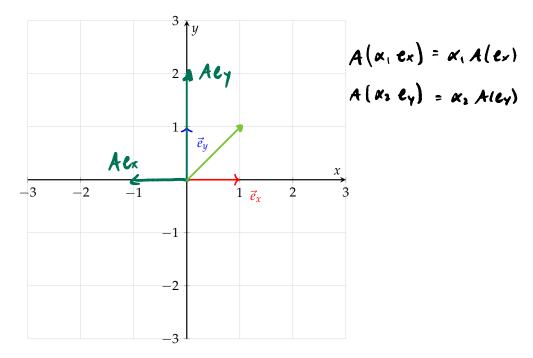
- 1. Geometric Interpretation of the SVD
 - (a) When we plot the transformation given by a specific matrix, we think about how the matrix transforms the standard basis vectors. In 2D, let $\vec{e}_x = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $\vec{e}_y = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$. The vectors \vec{e}_x and \vec{e}_y are shown below



Consider the following matrix

$$A = \begin{bmatrix} -1 & 0\\ 0 & 2 \end{bmatrix} \tag{1}$$

How would *A* transform \vec{e}_x and \vec{e}_y ? Plot the result.

$$A e_{x} = \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$A e_{y} = \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \end{bmatrix}$$

$$description : reflection$$

$$description : scaling by a factor
$$description : f(x, y) = f(x, y)$$$$

(b) Let's take a look at a special 2×2 matrix. \mathbf{u}_{1} \mathbf{u}_{2} $R = \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix} \cos \theta \begin{bmatrix} \sin \theta \\ \cos \theta \end{bmatrix} \qquad \begin{bmatrix} \mathbf{u}_{1} & \mathbf{u}_{2} & \mathbf{u}_{3} \\ \mathbf{u}_{1} & \mathbf{u}_{3} & \mathbf{u}_{3} \\ \mathbf{u}_{1} & \mathbf{u}_{3} & \mathbf{u}_{3} \end{bmatrix} \in \mathbb{R}^{3 \times 3}$ (2)

Show that this matrix is orthonormal. This matrix is called a rotation matrix and will rotate any vector counterclockwise by θ degrees.

Column are normalized culumn are mutually orthogonal F is square $u_1 \cdot u_2$ $\left\| \begin{bmatrix} \cos\theta \\ \sin\theta \end{bmatrix} \right\| = \sqrt{\cos^{10} + \sin^{10}} = 1$ $u_1^T u_2$ $\left[\cos\theta \\ \sin\theta \end{bmatrix} \begin{bmatrix} -\sin\theta \\ \cos\theta \end{bmatrix} = -\sin\theta \cos\theta + \sin\theta \cos\theta = 0$

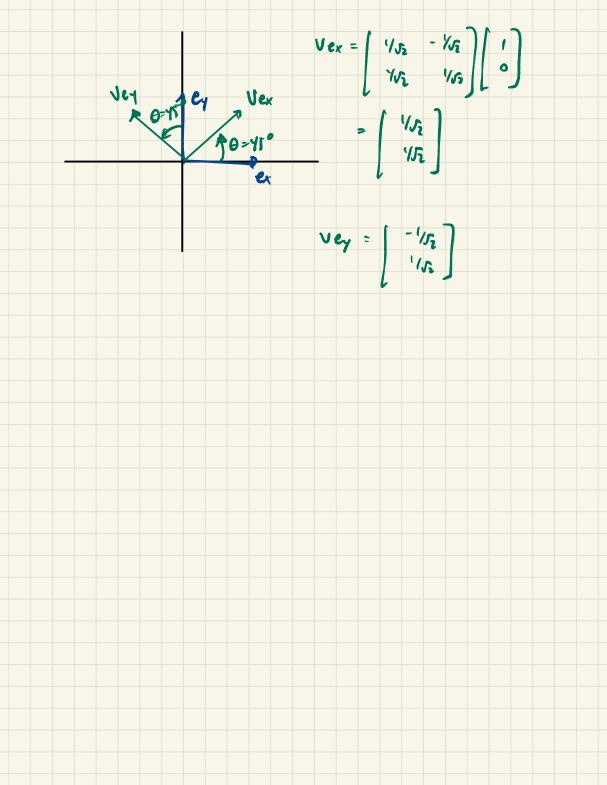
(c) Now let's consider how this transformation looks in the lens of the SVD. You are given the following matrix *A*:

$$A = \begin{bmatrix} -1 & -2\\ 2 & 1 \end{bmatrix}$$
(3)

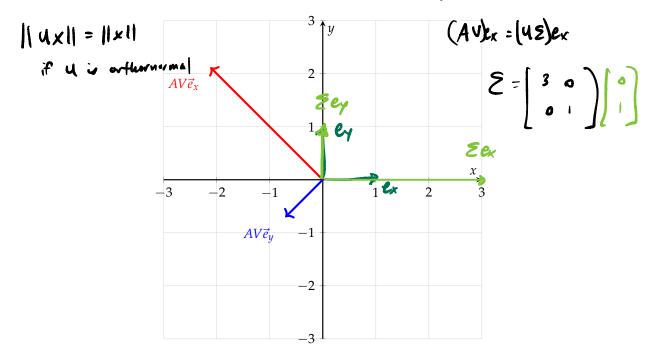
Recall that the SVD of this matrix is given by $A = U\Sigma V^{\top}$. Assume you are told that

$$V = \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$$
(4)

We will try to deduce U and Σ graphically, and the confirm our results numerically. Plot the transformation given by V by showing how it affects \vec{e}_x and \vec{e}_y via left multiplication. (*HINT: Try writing* V *as a rotation matrix with a specific* θ .)



(d) Suppose you are told that the transformation of AV on \vec{e}_x and \vec{e}_y looks like



Write this transformation AV in terms of U and Σ . Recall that the U matrix is an orthonormal matrix so it will correspond to any rotations or reflections, and the Σ matrix is a diagonal matrix and will perform any scaling operations. Based on this fact and the plot of the transformation above, write down a guess for what U and Σ might be.

 $A = U \leq v^{T}$ $A \vee = (U \leq v^{T}) \vee = U \leq T$ $V \vee orthonomed$ $A \vee e_{X} = U \leq e_{X}$ $A \vee e_{Y} = U \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ $= U \begin{bmatrix} 3 & 0 \\ 0 & \sigma_{2} \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ $U = \begin{bmatrix} u \otimes \theta & -si \otimes \theta \\ si \otimes \theta & c \otimes \theta \end{bmatrix} = \begin{bmatrix} -1/J_{2} & -1/J_{1} \\ 1/J_{2} & -1/J_{2} \end{bmatrix}$

(e) Based on the given V matrix, compute the SVD. Does your answer match your hypothesis from

the previous part?

(f) Using your answer for U and Σ from the previous part, plot the transformation of Σ on \vec{e}_x and \vec{e}_y . From here, plot the transformation of $U\Sigma$ on \vec{e}_x and \vec{e}_y . Does the final plot resemble the transformation shown by AV?

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