

EECS 16B : Module 3 / Lecture 2

Announcements:

- 0.25 EC point for each lecture you attend for rest of the term.

links.eecs16b.org/lecture-ec

Last time:

- Minimum-Energy Control
- Recap of spectral theorem for symmetric matrices
- Singular Value Decomposition (SVD)

$$A = U \Sigma V^T$$

See Note 14

TODAY:

- SVD: $A = U \Sigma V^T$
 - "Full" SVD construction justification & algorithm
 - Examples
 - "Compact" SVD & "outer-product" SVD

RECAP

Let's now recall our study of symmetric matrix S :

- ① Symmetric matrix S can always be diagonalized.
- ② The diagonalizing basis/matrix V is made up of the eigenvectors of S that are orthonormal.
- ③ All the eigenvalues of S are real.

$$V^T S V = \Lambda$$

↑ orthonormal basis
 ↑ diagonal

$\lambda_1 \dots$	λ_r	$0 \dots 0$
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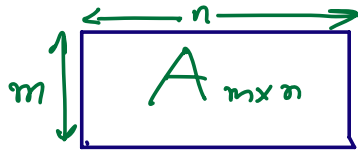
$$\Rightarrow S = V \Lambda V^T$$

$$S V = V \Lambda$$

$$S \left[\begin{array}{c|c} \begin{matrix} \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_r \end{matrix} & \begin{matrix} \vec{v}_{r+1} & \dots & \vec{v}_n \end{matrix} \end{array} \right] = \left[\begin{array}{c|c} \begin{matrix} \vec{v}_1 & \dots & \vec{v}_r \end{matrix} & \begin{matrix} \vec{v}_{r+1} & \dots & \vec{v}_n \end{matrix} \end{array} \right] \begin{bmatrix} \lambda_1 & & 0 \\ & \lambda_r & \\ 0 & & 0 \dots 0 \end{bmatrix}$$

correspond to non-zero e-vals
correspond to zero e-vals

$$\left. \begin{array}{l} S \vec{v}_{r+1} = 0 \\ S \vec{v}_{r+2} = 0 \\ \vdots \\ S \vec{v}_n = 0 \end{array} \right\} \Rightarrow \vec{v}_{r+1}, \vec{v}_{r+2}, \dots, \vec{v}_n \text{ form an orthonormal basis for } \underbrace{\text{Null-space}(S)}_{N(S)}$$



Q) What is a "good" decomposition for a general (non-square) matrix A ?

- We love an orthonormal basis 😊
- We love diagonalization 😊
- But we cannot rely on special structures like ~~symmetry~~ or even ~~square~~ matrices

Let us see how to generalize the concept of EIGENVALUE and EIGENVECTOR for square matrices to a similar concept for rectangular matrices, while insisting that we have orthonormal bases.

Key insight: We need TWO orthonormal bases, one for the Column Space (A) & one for the Row-Space (A).

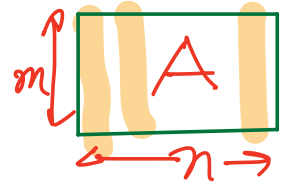
For square matrices

• $A \vec{v}_i = \lambda_i \vec{v}_i$;

(λ_i, \vec{v}_i) are an e-val/e-vector pair for A (e-vectors need not be \perp)

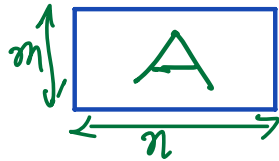
How about

$$A \vec{v}_i = \sigma_i \vec{u}_i$$



We now have 2 orthonormal bases:

- $\{\vec{u}_i\}$ for the col. space $(A) \in \mathbb{R}^m$ and
- $\{\vec{v}_i\}$ for the row space $(A) \in \mathbb{R}^n$



- Assume $m < n$
- Rank(A) = m

In matrix form:

$$A \begin{bmatrix} \vec{v}_1 & \dots & \vec{v}_m & \dots & \vec{v}_n \end{bmatrix} = \begin{bmatrix} \vec{u}_1 & \dots & \vec{u}_m \end{bmatrix} \begin{bmatrix} \sigma_1 & & & & \\ & \sigma_2 & & & \\ & & \dots & & \\ & & & \sigma_m & \\ & & & & 0 \end{bmatrix}$$

$A_{m \times n}$ $V_{n \times n}$ = $U_{m \times m}$ $\Sigma_{m \times n}$

$$A V = U \Sigma$$

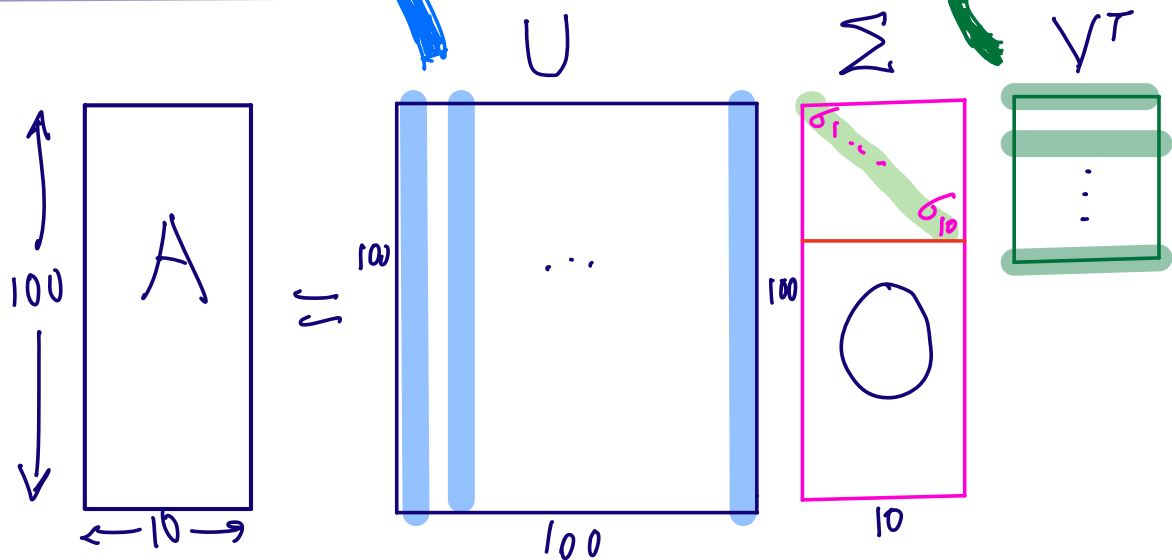
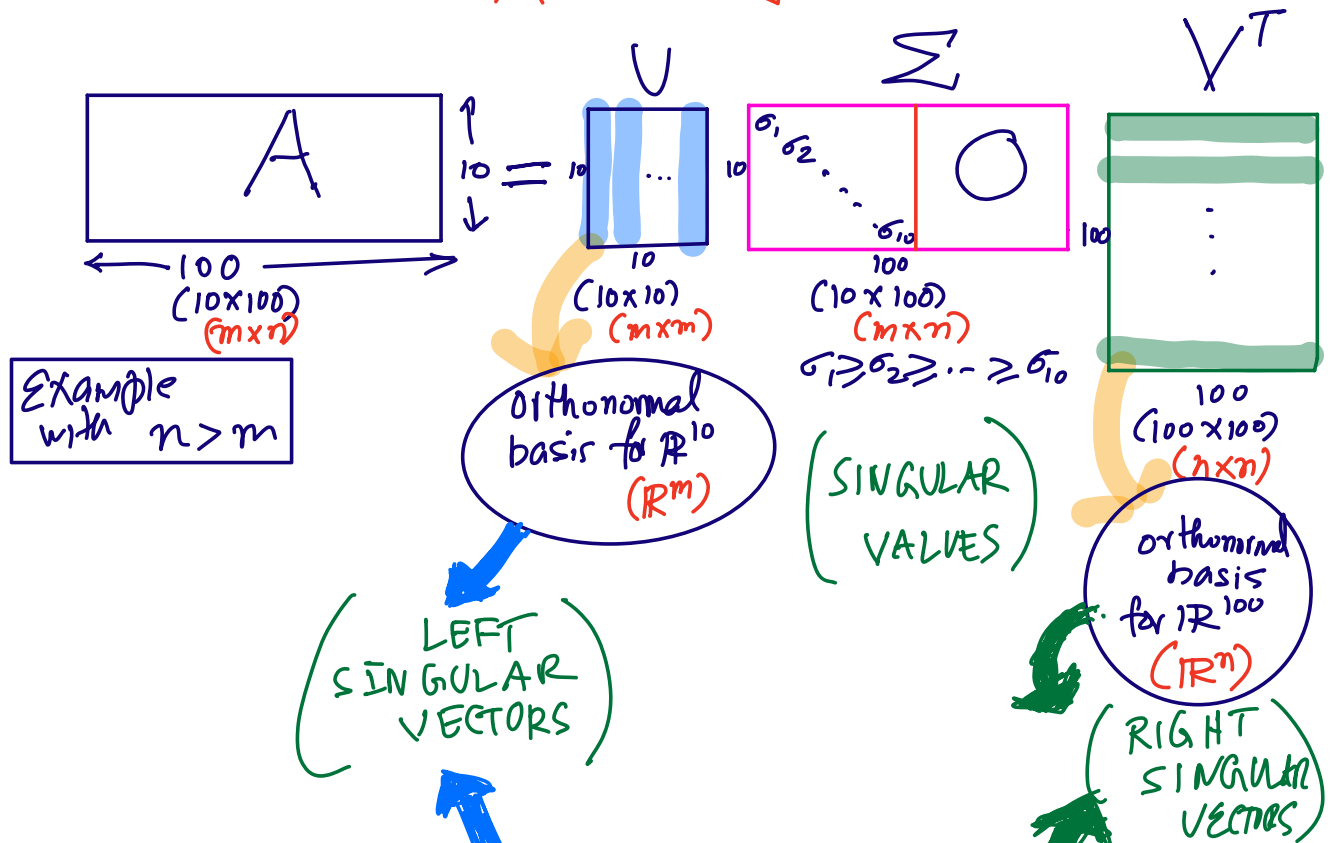
SINGULAR
VALUE
DECOMPOSITION
(SVD)

$$A = U \Sigma V^T$$

$$\text{rank}(A) = \min(m, n) = m$$

Singular Value Decomposition (SVD)

$$A = U \Sigma V^T$$



$$A V = U \Sigma$$

$$\Rightarrow \boxed{A = U \Sigma V^T}$$

"Full"-SVD
of A

left singular vectors →
Singular values along diagonal →
right singular vectors

Ex. (recap)

$$A = \begin{bmatrix} 4 & 4 \\ 3 & 3 \end{bmatrix} = \frac{1}{5} \begin{bmatrix} 4 & 3 \\ 3 & -4 \end{bmatrix} \begin{bmatrix} \sqrt{50} & \\ & 0 \end{bmatrix} \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$\vec{u}_1 = \begin{bmatrix} 4/5 \\ 3/5 \end{bmatrix}$, $\vec{u}_2 = \begin{bmatrix} 3/5 \\ -4/5 \end{bmatrix}$

U Σ V^T

Two orthonormal bases,

$$U = [\vec{u}_1 \ \vec{u}_2] \text{ for } \text{Col}(A) \in \mathbb{R}^2$$

and $V = [\vec{v}_1 \ \vec{v}_2]$ for $\text{Row}(A) \in \mathbb{R}^2$

NOTE: $A = U \Sigma V^T$ is different from
 $A = Q \Lambda Q^{-1}$ (eigendecomposition)
 even for square matrix A!
 why?

Consider $A^T A$

If we use SVD, $A = U \Sigma V^T$
 $m \times n$ $n \times n$ $n \times n$ $m \times n$

$$\text{then } A^T A = (U \Sigma V^T)^T U \Sigma V^T$$
$$= V \Sigma^T \underbrace{U^T U}_{I} \Sigma V^T$$

$$= V \Sigma^T \Sigma V^T = \boxed{V \Sigma \Sigma^T V^T}$$

$n \times n$ \downarrow square $(n \times n)$ $(n \times n)$

Similarly, $A A^T = U \Sigma \underbrace{V^T V}_{I} \Sigma^T U^T$

$$= \boxed{U \Sigma \Sigma^T U^T}$$

$m \times m$ $m \times m$ $m \times m$

Suggests that the key to understanding the SVD of $A = U \Sigma V^T$ is to study the square matrix $A^T A$!!!

Consider $C^T C$

Sorry, we will use C and A interchangeably!

Fact: $C^T C$ is symmetric

Proof: $(C^T C)^T = C^T C \quad \square$

Special property: eigenvalues of $S = C^T C$ are always real and non-negative.

Proof: $S \vec{v} = \lambda \vec{v}$ (Let (λ, \vec{v}) be an e-value/e-vector pair for S)

$C^T C \vec{v} = \lambda \vec{v}$ (We know that all e-values of $S = C^T C$ are real by the spectral theorem)

Left multiply by $\vec{v}^T \Rightarrow$

$$\vec{v}^T C^T C \vec{v} = \vec{v}^T \lambda \vec{v}$$

$$(C \vec{v})^T C \vec{v} = \lambda \vec{v}^T \vec{v}$$

$$\|C \vec{v}\|^2 = \lambda \|\vec{v}\|^2$$

$$\lambda = \frac{\|C \vec{v}\|^2}{\|\vec{v}\|^2} \geq 0$$

($C^T C$ is called a Positive Semi-Definite or PSD matrix) \square

$C^T C$ is a symmetric matrix having non-negative e-values. Order the e-values of $C^T C$ as:

$$\underbrace{\lambda_1 \geq \lambda_2 \geq \lambda_3 \geq \dots \geq \lambda_r}_{\text{positive eigenvalues}} > \underbrace{\lambda_{r+1} = \dots = \lambda_n = 0}_{\text{zero e-values}}$$

$$V = \left[\underbrace{\vec{v}_1 \ \vec{v}_2 \ \dots \ \vec{v}_r}_{\substack{\text{e-vector of} \\ C^T C \text{ corr. to} \\ \lambda_i > 0}} \quad \underbrace{\vec{v}_{r+1} \ \dots \ \vec{v}_n}_{\substack{\text{e-vector} \\ \text{of } C^T C \text{ corr.} \\ \text{to } \lambda_i = 0}} \right]$$

Fact: C and $C^T C$ have the same null space.

Pf: (16A) $N(A) = \{ \vec{x} : C\vec{x} = 0 \}$

- If $C\vec{x} = 0$, then $C^T C\vec{x} = 0$ (Pf: obvious)
- If $C^T C\vec{x} = 0$, then $C\vec{x} = 0$

Proof of ●

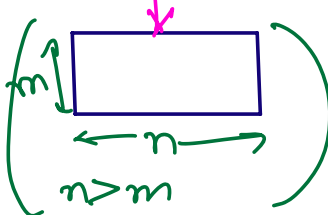
Left-multiply:
by \vec{x}^T

$$C^T C\vec{x} = 0$$

$$\vec{x}^T C^T C\vec{x} = 0$$

$$\|C\vec{x}\|^2 = 0 \Rightarrow C\vec{x} = 0 \quad \square$$

$$C V = \left[C \vec{v}_1 \dots C \vec{v}_m \mid \underbrace{C \vec{v}_{m+1} \dots C \vec{v}_n}_0 \right]$$


 (Assume full row rank m)

Null space of $C^T C$
 = Null space of C
 (dim. = $n - m$)

Fact: $\{C \vec{v}_1, C \vec{v}_2, \dots, C \vec{v}_m\}$ form an orthogonal (but not ON) basis set for \mathbb{R}^m .

Why is this reassuring? Then, we would have:

$$C_{m \times n} \left[\underbrace{V_{\text{col}} \mid V_{\text{null}}}_{n \times n} \right] = \left[\underbrace{U}_{m \times m} \mid \underbrace{\begin{bmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix} \mid 0}_{m \times n} \right]$$

and we would be done!

$$CV = [C\vec{v}_1 \dots C\vec{v}_m \mid C\vec{v}_{m+1} \dots C\vec{v}_n]$$

m
 n
 (assume full rank $r=m < n$)

FACT: $\{C\vec{v}_1, C\vec{v}_2, \dots, C\vec{v}_m\}$ form an orthogonal basis for \mathbb{R}^m

why? $\{C\vec{v}_1, C\vec{v}_2, \dots, C\vec{v}_m\} = \{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_m\}$

$$\begin{aligned}
 \langle C\vec{v}_i, C\vec{v}_j \rangle &= (C\vec{v}_i)^T C\vec{v}_j \\
 &= \vec{v}_i^T \underbrace{C^T C}_{\substack{S \\ \lambda_j \vec{v}_j}} \vec{v}_j \\
 &= \lambda_j \underbrace{\langle \vec{v}_i, \vec{v}_j \rangle}_0 = 0 \quad \text{if } i \neq j
 \end{aligned}$$

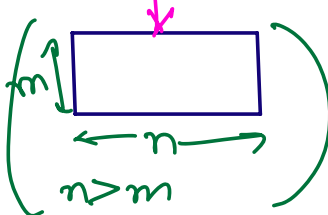
If we want orthonormality, we need to normalize $C\vec{v}_i$ to unit-length.

$$\langle C\vec{v}_i, C\vec{v}_i \rangle = \lambda_i \underbrace{\langle \vec{v}_i, \vec{v}_i \rangle}_1$$

$$\|C\vec{v}_i\|^2 = \lambda_i$$

$$\|C\vec{v}_i\| = \sqrt{\lambda_i} \quad \text{for } \lambda_i \neq 0$$

$$C V = \left[C \vec{v}_1 \dots C \vec{v}_m \mid \underbrace{C \vec{v}_{m+1} \dots C \vec{v}_n}_0 \right]$$


 (Assume full row rank m)

Null space of $C^T C$
 = Null space of C
 (dim. = $n - m$)

Fact: $\{C \vec{v}_1, C \vec{v}_2, \dots, C \vec{v}_m\}$ form an orthogonal basis for \mathbb{R}^m

Why? $\{C \vec{v}_1, C \vec{v}_2, \dots, C \vec{v}_m\} = \{\vec{u}_1, \vec{u}_2, \dots, \vec{u}_m\}$

$$\begin{aligned} \langle C \vec{v}_i, C \vec{v}_j \rangle &= (C \vec{v}_i)^T C \vec{v}_j \\ &= \vec{v}_i^T \underbrace{C^T C}_{\lambda_j \vec{v}_j} \vec{v}_j = \lambda_j \underbrace{\langle \vec{v}_i, \vec{v}_j \rangle}_{= 0 \text{ if } i \neq j} \end{aligned}$$

If we want an ON-set, we need to normalize $C \vec{v}_i$ to unit length:

$$\langle C \vec{v}_i, C \vec{v}_i \rangle = \lambda_i \langle \vec{v}_i, \vec{v}_i \rangle$$

$$\|C \vec{v}_i\|^2 = \lambda_i \Rightarrow \|C \vec{v}_i\| = \sqrt{\lambda_i}$$

singular value

Fact: $\left\{ \vec{u}_i = \frac{C \vec{v}_i}{\sqrt{\lambda_i}} \right\}_{i=1}^m$ forms an ON basis for \mathbb{R}^m corresponding to \vec{v}_i for which $\lambda_i > 0$.
 ($\vec{v}_{r_2+1}, \dots, \vec{v}_n$ corr. to $\lambda_i = 0$)

$$\begin{aligned}
 C V &= \begin{matrix} \begin{matrix} \leftarrow m \rightarrow \\ \leftarrow n \rightarrow \end{matrix} \\ \begin{matrix} \leftarrow m \rightarrow \\ \leftarrow n \rightarrow \end{matrix} \end{matrix} \begin{matrix} C_{m \times n} & V_{n \times n} \\ \left[\begin{array}{c|c} C \vec{v}_1 \dots C \vec{v}_m & C \vec{v}_{r_2+1} \dots C \vec{v}_n \\ \hline & 0 \end{array} \right] \end{matrix} \\
 &= \begin{matrix} \left[\begin{array}{c|c} \sqrt{\lambda_1} \vec{u}_1 \dots \sqrt{\lambda_m} \vec{u}_m & 0 \end{array} \right] \\ \leftarrow m \rightarrow & \leftarrow n \rightarrow \end{matrix} \\
 &= \begin{matrix} \left[\begin{array}{c|c} \vec{u}_1 \ \vec{u}_2 \ \dots \ \vec{u}_m & \\ \hline & 0 \end{array} \right] \\ \leftarrow m \rightarrow & \leftarrow n \rightarrow \end{matrix} \begin{matrix} \left[\begin{array}{c|c} \sqrt{\lambda_1} & \\ \sqrt{\lambda_2} & \\ \vdots & \\ \sqrt{\lambda_m} & \\ \hline & 0 \end{array} \right] \\ \leftarrow m \rightarrow & \leftarrow n \rightarrow \end{matrix} \\
 &\quad \text{singular values}
 \end{aligned}$$

$$\begin{aligned}
 &= U \sum_{m \times n} \\
 \Rightarrow C V &= U \Sigma \Rightarrow C = U \Sigma V^T
 \end{aligned}$$

SUMMARY:

$C_{10 \times 100} \times V_{100 \times 100} = U_{10 \times 10} \Sigma_{10 \times 100}$

$$C V = U \Sigma$$

$$\text{or } C = U \Sigma V^T$$

Ex.

$$A = \begin{bmatrix} 4 & 4 \\ 3 & 3 \end{bmatrix}$$

Note: We will use A
and C interchangeably!

$$\textcircled{1} A^T A = \begin{bmatrix} 4 & 3 \\ 4 & 3 \end{bmatrix} \begin{bmatrix} 4 & 4 \\ 3 & 3 \end{bmatrix} = \begin{bmatrix} 25 & 25 \\ 25 & 25 \end{bmatrix}$$

Eigenvalues of $A^T A$ are roots of $\det[A^T A - \lambda I] = 0$

$$\Rightarrow \begin{vmatrix} 25-\lambda & 25 \\ 25 & 25-\lambda \end{vmatrix} = 0 \Rightarrow (25-\lambda)^2 - 25^2 = 0 \\ \Rightarrow (50-\lambda)(0-\lambda) = 0 \\ \lambda = \underline{0, 50}$$

$$\lambda_1 = 50 ; \vec{v}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\lambda_2 = 0 ; \vec{v}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$A^T A = \underbrace{\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}}_V \underbrace{\begin{bmatrix} 50 & \\ & 0 \end{bmatrix}}_\Lambda \underbrace{\frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}}_{V^T}$$

$$\textcircled{2} \vec{u}_i = \frac{A \vec{v}_i}{\sqrt{\lambda_i}} \text{ for } \lambda_i \neq 0$$

$$\vec{u}_1 = \frac{\begin{bmatrix} 4 & 4 \\ 3 & 3 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}}{\sqrt{50}} = \frac{1}{10} \begin{bmatrix} 8 \\ 6 \end{bmatrix} = \begin{bmatrix} 4/5 \\ 3/5 \end{bmatrix}$$

$$\vec{u}_2 = ? \quad (\lambda_2 = 0)$$

Ans: Use Gram-Schmidt to "complete" ON basis!

$$\vec{u}_2 = \begin{bmatrix} 3/5 \\ -4/5 \end{bmatrix}$$

$$\Rightarrow U = \begin{bmatrix} 4/5 & 3/5 \\ 3/5 & -4/5 \end{bmatrix}$$

$$\textcircled{3} \quad \Sigma = \begin{bmatrix} \sqrt{50} & 0 \\ 0 & 0 \end{bmatrix} \quad A = \begin{bmatrix} 4/5 \\ 3/5 \end{bmatrix} \sqrt{50} \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$$

SVD for $A = \begin{bmatrix} 4 & 4 \\ 3 & 3 \end{bmatrix}$ is:

$$\underbrace{\begin{bmatrix} 4 & 4 \\ 3 & 3 \end{bmatrix}}_A = \underbrace{\begin{bmatrix} 4/5 & 3/5 \\ 3/5 & -4/5 \end{bmatrix}}_U \underbrace{\begin{bmatrix} \sqrt{50} & 0 \\ 0 & 0 \end{bmatrix}}_\Sigma \underbrace{\begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix}}_{V^T}$$

Two orthonormal bases,
 $U = [\vec{u}_1 \ \vec{u}_2]$ for $\text{Col}(A) \in \mathbb{R}^2$
 and $V = [\vec{v}_1 \ \vec{v}_2]$ for $\text{Row}(A) \in \mathbb{R}^2$

"Compact form" SVD.

Ex.:

$$A = \begin{bmatrix} 1 & 2 & 4 & 5 \\ 2 & 4 & 8 & 10 \end{bmatrix}_{2 \times 4}$$

Rank(A) = ?

$$A = \underbrace{\begin{bmatrix} \frac{1}{\sqrt{5}} & -\frac{2}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{bmatrix}}_{U_{2 \times 2}} \underbrace{\begin{bmatrix} \sqrt{230} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}}_{\Sigma_{2 \times 4}} \underbrace{\begin{bmatrix} \frac{1}{\sqrt{46}} & \sqrt{\frac{2}{23}} & 2\sqrt{\frac{2}{23}} & \frac{5}{\sqrt{46}} \\ -\frac{5}{\sqrt{26}} & 0 & 0 & \frac{1}{\sqrt{26}} \\ -\frac{2}{\sqrt{273}} & 0 & \sqrt{\frac{13}{21}} & \frac{-10}{\sqrt{273}} \\ -\frac{1}{\sqrt{483}} & \sqrt{\frac{2}{23}} & \frac{-4}{\sqrt{483}} & \frac{-5}{\sqrt{483}} \end{bmatrix}}_{V^T_{4 \times 2}}$$

$$= \underbrace{\begin{bmatrix} \frac{1}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} \end{bmatrix}}_{U_r(2 \times 1)} \underbrace{\begin{bmatrix} \sqrt{230} \end{bmatrix}}_{\Sigma_r(1 \times 1)} \underbrace{\begin{bmatrix} \frac{1}{\sqrt{46}} & \sqrt{\frac{2}{23}} & 2\sqrt{\frac{2}{23}} & \frac{5}{\sqrt{46}} \end{bmatrix}}_{V_r^T(1 \times 4)}$$

$$A \begin{bmatrix} \vec{v}_1 & \dots & \vec{v}_r \end{bmatrix} = \begin{bmatrix} \vec{u}_1 & \dots & \vec{u}_r \end{bmatrix} \begin{bmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_r \end{bmatrix}$$

$A_{(m \times n)}$ $V_r_{(n \times r)}$ $U_r_{(m \times r)}$ $\Sigma_r_{(r \times r)}$

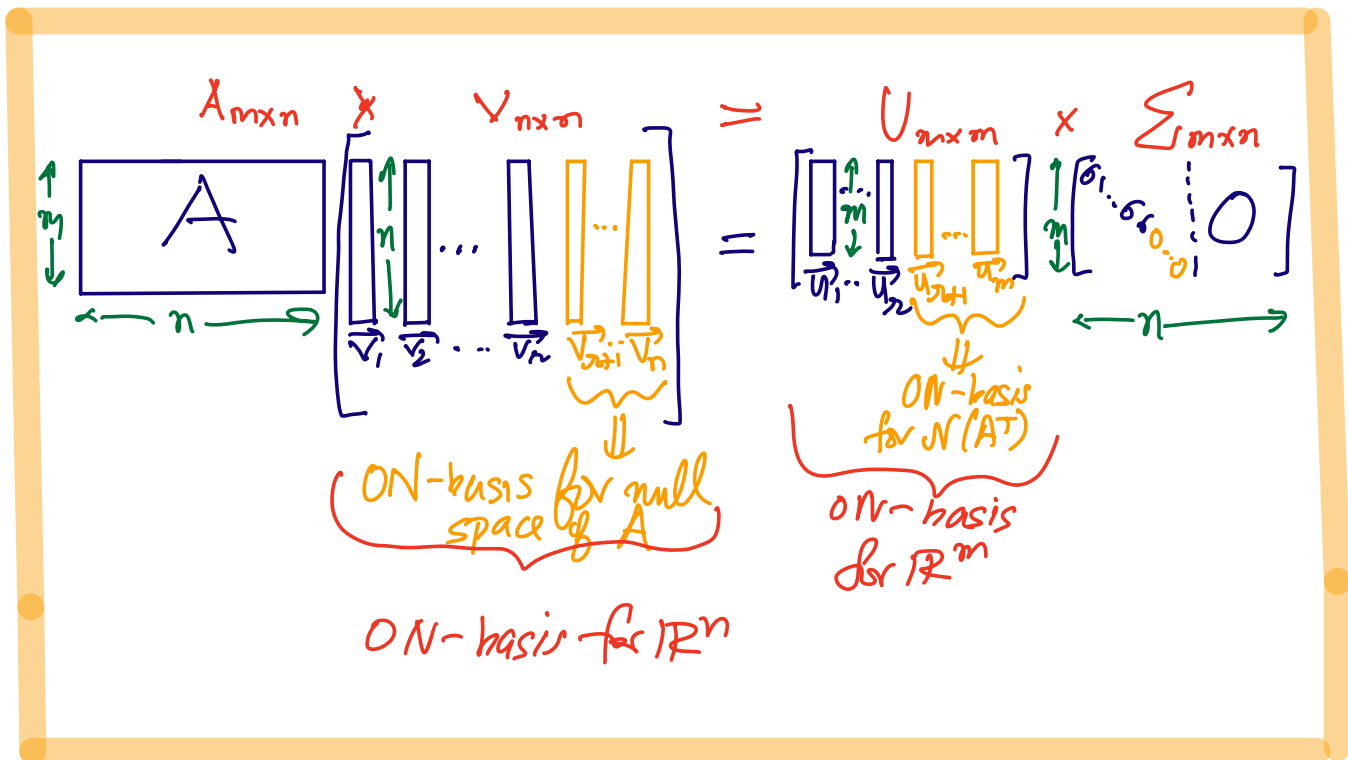
$$A V_r = U_r \Sigma_r$$

"Reduced"
or
"compact form"
SVD

$$A = U_r \Sigma_r V_r^T$$

$$r = \text{rank}(A) \leq \min(m, n)$$

Let's "expand" out V_r, U_r, Σ_r to "full" SVD:



Outer-Product Form

$$C \in \mathbb{R}^{m \times n}$$

$$\text{Rank}(C) = r$$

$$C = U \Sigma V^T$$

$$= \underbrace{\begin{bmatrix} | & | & \dots & | \\ \vec{u}_1 & \vec{u}_2 & \dots & \vec{u}_m \\ | & | & \dots & | \end{bmatrix}}_{m \times m} \underbrace{\begin{bmatrix} \sigma_1 & & & & & \\ & \sigma_2 & & & & \\ & & \dots & & & \\ & & & \sigma_r & & \\ & & & & & 0_{(m \times (n-r))} \end{bmatrix}}_{m \times n} \underbrace{\begin{bmatrix} \vec{v}_1^T \\ \vec{v}_2^T \\ \vdots \\ \vec{v}_n^T \end{bmatrix}}_{n \times n}$$

$$= \begin{matrix} \leftarrow r \rightarrow & \leftarrow (n-r) \rightarrow \\ \begin{bmatrix} | & | & \dots & | & | & | \\ \sigma_1 \vec{u}_1 & \sigma_2 \vec{u}_2 & \dots & \sigma_r \vec{u}_r & \vec{0} & \vec{0} \\ | & | & \dots & | & | & | \end{bmatrix} & \begin{bmatrix} \vec{v}_1^T \\ \vec{v}_2^T \\ \vdots \\ \vec{v}_n^T \end{bmatrix} \end{matrix}$$

r non-zero columns $(n-r)$ zero columns

$$= \left[\sigma_1 \vec{u}_1 \quad \sigma_2 \vec{u}_2 \quad \dots \quad \sigma_r \vec{u}_r \quad \vec{0} \quad \dots \quad \vec{0} \right]$$

$$\begin{bmatrix} \vec{v}_1^T \\ \vec{v}_2^T \\ \vdots \\ \vec{v}_n^T \end{bmatrix}$$

rank of matrix \leftarrow r

$$= \sum_{i=1}^r \underbrace{\sigma_i}_{(i)} \underbrace{\vec{u}_i}_{(m \times 1)} \underbrace{\vec{v}_i^T}_{(1 \times n)}$$

r : rank of matrix

: # of positive singular values

Outer-product form of SVD is the most efficient & compact for representation.

SUMMARY

Finding an SVD for $A \in \mathbb{R}^{m \times n}$ (with $\text{rank} = r$) from eigenvalues/eigenvectors of:

$$A^T A \in \mathbb{R}^{n \times n}$$

Eigenvalues of $A^T A$ are real and nonnegative. r of them are strictly positive; the remaining $n-r$ are zero.

Step 1: Find orthogonal matrix V diagonalizing $A^T A$:

$$V^T A^T A V = \begin{bmatrix} \lambda_1 & & & \\ & \ddots & & \\ & & \lambda_r & \\ & & & 0 & \dots & 0 \end{bmatrix}_{n-r}$$

$$\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_r > 0$$

Step 2: For each $i=1, \dots, r$ pick i th column \vec{v}_i of V (which is eigenvector for $A^T A$ for eigenvalue λ_i). Let

$$\sigma_i = \sqrt{\lambda_i}, \quad \vec{u}_i = \frac{1}{\sigma_i} A \vec{v}_i.$$

$$A A^T \in \mathbb{R}^{m \times m}$$

Eigenvalues: real, nonnegative eigenvalues, r of which are strictly positive, remaining $m-r$ are zero.

Step 1: Find orthogonal matrix $U \in \mathbb{R}^{m \times m}$ diagonalizing $A A^T$:

$$U^T A A^T U = \begin{bmatrix} \lambda_1 & & & \\ & \ddots & & \\ & & \lambda_r & \\ & & & 0 & \dots & 0 \end{bmatrix}_{m-r}$$

$$\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_r > 0$$

Step 2: For each $i=1, \dots, r$ pick i th column \vec{u}_i of U (which is eigenvector of $A A^T$ for eigenvalue λ_i). Let

$$\sigma_i = \sqrt{\lambda_i}, \quad \vec{v}_i = \frac{1}{\sigma_i} A^T \vec{u}_i.$$

Which procedure to use? Choose $A^T A$ or $A A^T$ based on which one leads simpler for finding eigenvalues/eigenvectors. If $m < n$, $A A^T$ ($m \times m$) is smaller than $A^T A$ ($n \times n$) and may be preferable.

Example

$$A = \begin{bmatrix} 4 & 4 \\ -3 & 3 \end{bmatrix} \quad A^T = \begin{bmatrix} 4 & -3 \\ 4 & 3 \end{bmatrix}$$

$$A^T A = \begin{bmatrix} 25 & 7 \\ 7 & 25 \end{bmatrix} \quad A A^T = \begin{bmatrix} 32 & 0 \\ 0 & 18 \end{bmatrix}$$

Example ~~_____~~ $A = \begin{bmatrix} 4 & 4 \\ -3 & 3 \end{bmatrix}$ $A^T = \begin{bmatrix} 4 & -3 \\ 4 & 3 \end{bmatrix}$

~~_____~~ $A^T A = \begin{bmatrix} 25 & 7 \\ 7 & 25 \end{bmatrix}$ $A A^T = \begin{bmatrix} 32 & 0 \\ 0 & 18 \end{bmatrix}$

Easier bc/ diagonal: choose $U = I$: $\vec{u}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ $\vec{u}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

$\lambda_1 = 32$, $\lambda_2 = 18 \Rightarrow \sigma_2 = \sqrt{\lambda_2} = 3\sqrt{2}$

↓

$\sigma_1 = \sqrt{\lambda_1} = 4\sqrt{2}$

$\vec{v}_2 = \frac{1}{\sigma_2} A^T \vec{u}_2 = \frac{1}{3\sqrt{2}} \begin{bmatrix} -3 \\ 3 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} -1 \\ 1 \end{bmatrix}$

$\vec{v}_1 = \frac{1}{\sigma_1} A^T \vec{u}_1 = \frac{1}{4\sqrt{2}} \begin{bmatrix} 4 \\ 4 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

Ex.

$$A = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \quad AA^T = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad U = I \text{ works for step 1}$$

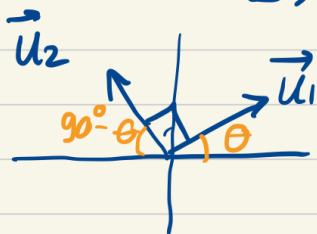
$$\lambda_1 = \lambda_2 = 1$$

$$\vec{u}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \vec{u}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\sigma_1 = \sigma_2 = 1$$

$$\vec{v}_1 = A^T \vec{u}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \vec{v}_2 = A^T \vec{u}_2 = \begin{bmatrix} 0 \\ -1 \end{bmatrix}$$

Since $AA^T = I$, any other orthonormal \vec{u}_1, \vec{u}_2 will work.



$$\vec{u}_1 = \begin{bmatrix} \cos \theta \\ \sin \theta \end{bmatrix} \quad \vec{u}_2 = \begin{bmatrix} -\sin \theta \\ \cos \theta \end{bmatrix}$$

$\vec{u}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \vec{u}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ above are a special case: $\theta = 0$

$$\vec{v}_1 = A^T \vec{u}_1 = \begin{bmatrix} \cos \theta \\ -\sin \theta \end{bmatrix} \quad \vec{v}_2 = A^T \vec{u}_2 = \begin{bmatrix} -\sin \theta \\ \cos \theta \end{bmatrix}. \quad \text{Conclusion:}$$

Repeated evalues of $A^T A$ or AA^T ($\lambda_1 = \lambda_2 = 1$ in this example) are another source of nonuniqueness in SVD.