

The following note is useful for this discussion: [Note 18](#).

1. Linear Approximation

A common way to approximate a nonlinear function is to perform linearization near a point. In the case of a one-dimensional function $f(x)$, the linear approximation of $f(x)$ at a point x_* is given by

$$\hat{f}(x; x_*) = f(x_*) + f'(x_*) \cdot (x - x_*), \quad (1)$$

where $f'(x_*) := \frac{df}{dx}(x_*)$ is the derivative of $f(x)$ at $x = x_*$.

Keep in mind that wherever we see x_* , this denotes a *constant value* or operating point.

We can evaluate the accuracy of our approximation by calculating the approximation error, namely $|f(x) - \hat{f}(x; x_*)|$.

Suppose we have the single-variable function $f(x) = x^3 - 3x^2$. We can plot the function $f(x)$ as follows:

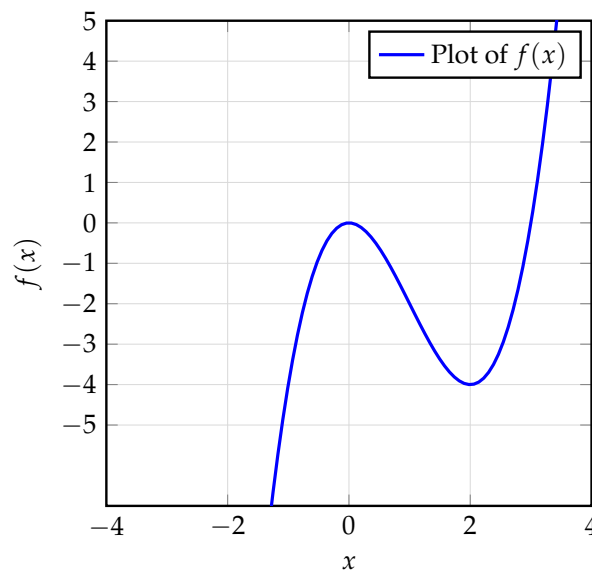


Figure 1: Plot of $f(x) = x^3 - 3x^2$

- (a) Write the linear approximation of the function around an arbitrary point x_* . **Solution:**

$$\hat{f}(x; x_*) = f(x_*) + f'(x_*) \cdot (x - x_*) \quad (2)$$

$$= f(x_*) + (3x_*^2 - 6x_*) \cdot (x - x_*) \quad (3)$$

- (b) Using the expression above, linearize the function around the point $x_* = 1.5$. Draw the linearization into the plot in fig. 1. Then evaluate the accuracy of the linear approximation at $x = 1.7$ and $x = 2.5$. Does the difference in accuracy make sense, based on the plot?

Solution:

$$\hat{f}(x; x_*) = f(1.5) + (3 \cdot 1.5^2 - 6 \cdot 1.5) \cdot (x - 1.5) \quad (4)$$

$$= -3.375 + (-2.25) \cdot (x - 1.5) \quad (5)$$

The plot is shown below:

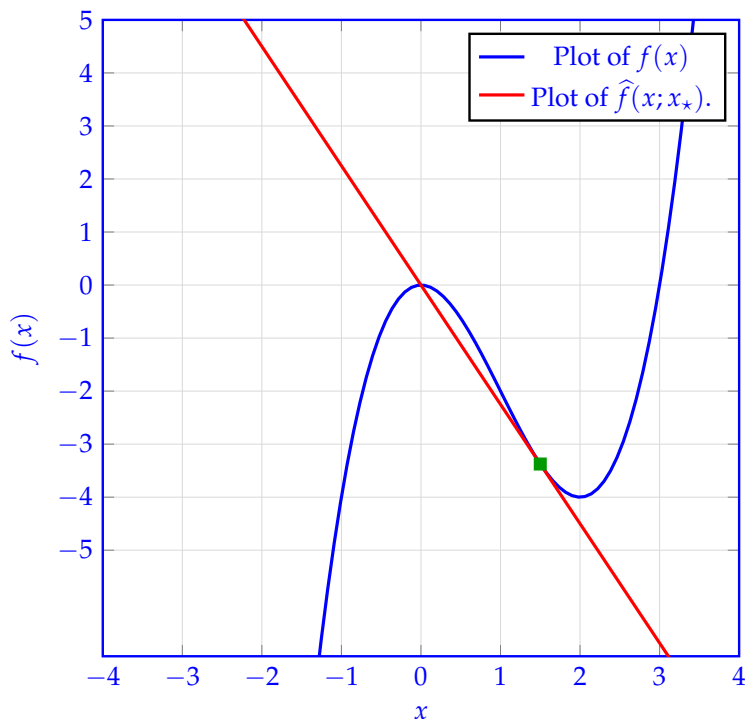


Figure 2: Plot of $\hat{f}(x; x_*)$ and $f(x)$

To evaluate the accuracy of $\hat{f}(x; x_*)$, we can compute $|\hat{f}(x; x_*) - f(x)|$. At $x = 1.7$:

$$\hat{f}(1.7; x_*) = -3.375 + (-2.25) \cdot (1.7 - 1.5) \quad (6)$$

$$= -3.375 - 0.45 \quad (7)$$

$$= -3.825 \quad (8)$$

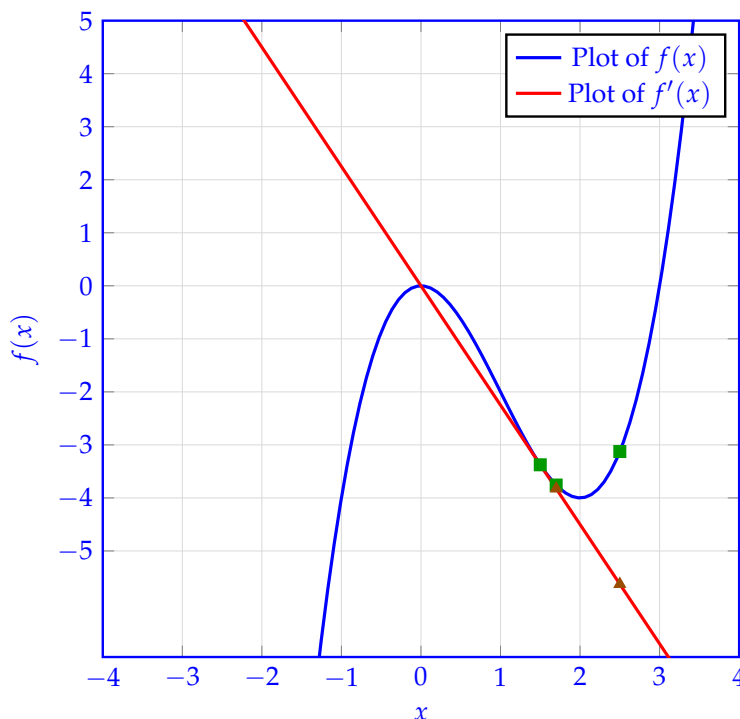
and $f(1.7) = 1.7^3 - 3 \cdot 1.7^2 = -3.757$. Hence, $|\hat{f}(1.7; x_*) - f(1.7)| = 0.068$. Now, at $x = 2.5$:

$$\hat{f}(2.5; x_*) = -3.375 + (-2.25) \cdot (2.5 - 1.5) \quad (9)$$

$$= -3.375 - 2.25 \quad (10)$$

$$= -5.625 \quad (11)$$

and $f(2.5) = 2.5^3 - 3 \cdot 2.5^2 = -3.125$. Hence, $|\hat{f}(2.5; x_*) - f(2.5)| = 2.5$. We see that the error at $x = 2.5$ is about 3 times higher than the error at $x = 1.7$. We can plot the points $x = 1.7$ and $x = 2.5$ on fig. 2 to explicitly see this difference in errors:



Now, we can extend this to higher dimensional functions. In the case of a two-dimensional function $f(x, y)$, the linear approximation of $f(x, y)$ at a point (x_*, y_*) is given by

$$\hat{f}(x, y; x_*, y_*) = f(x_*, y_*) + \frac{\partial f}{\partial x}(x_*, y_*) \cdot (x - x_*) + \frac{\partial f}{\partial y}(x_*, y_*) \cdot (y - y_*). \quad (12)$$

where $\frac{\partial f}{\partial x}(x_*, y_*)$ is the partial derivative of $f(x, y)$ with respect to x at the point (x_*, y_*) , and similarly for $\frac{\partial f}{\partial y}(x_*, y_*)$

- (c) Now, let's see how we can find partial derivatives. When we are given a function $f(x, y)$, we calculate the partial derivative of f with respect to x by fixing y and taking the derivative with respect to x . **Given the function $f(x, y) = x^2y$, find the partial derivatives $\frac{\partial f(x, y)}{\partial x}$ and $\frac{\partial f(x, y)}{\partial y}$.**

Solution: We have

$$\frac{\partial f(x, y)}{\partial x} = 2xy \quad (13)$$

$$\frac{\partial f(x, y)}{\partial y} = x^2. \quad (14)$$

- (d) **Write out the linear approximation of f near (x_*, y_*) .**

Solution: Based on the formula in eq. (12), we can write that:

$$\hat{f}(x, y; x_*, y_*) = f(x_*, y_*) + 2x_*y_* \cdot (x - x_*) + x_*^2 \cdot (y - y_*) \quad (15)$$

- (e) We want to see if the approximation arising from linearization of this function is reasonable for a point close to our point of evaluation. Suppose we want to evaluate the accuracy of our

approximation at some point $(x_* + \delta, y_* + \delta)$, where $x_* = 2$ and $y_* = 3$. **Find the accuracy of this approximation in terms of δ . What if $\delta = 0.01$?**

Solution: The true value of $f(2 + \delta, 3 + \delta)$ is

$$f(2 + \delta, 3 + \delta) = (2 + \delta)^2(3 + \delta) = (4 + 4\delta + \delta^2)(3 + \delta) = 12 + 16\delta + 7\delta^2 + \delta^3 \quad (16)$$

On the other hand, our approximation is

$$\hat{f}(2 + \delta, 3 + \delta; x_*, y_*) = f(2, 3) + 2 \cdot 2 \cdot 3 \cdot \delta + 2^2 \cdot \delta = 12 + 16\delta \quad (17)$$

So the approximation error is

$$\left| f(2 + \delta, 3 + \delta) - \hat{f}(2 + \delta, 3 + \delta; x_*, y_*) \right| = \left| 7\delta^2 + \delta^3 \right| \quad (18)$$

When δ is sufficiently small (i.e. close to 0), the δ^2 and δ^3 terms become very small, and hence our approximation is reasonable. For $\delta = 0.01$, the approximation error is $|7\delta^2 + \delta^3| = 0.000701$.

- (f) Suppose we have now a scalar-valued function $f(\vec{x}, \vec{y})$, which takes in vector-valued arguments $\vec{x} \in \mathbb{R}^n$, $\vec{y} \in \mathbb{R}^k$ and outputs a scalar $\in \mathbb{R}$. That is, $f(\vec{x}, \vec{y})$ is $\mathbb{R}^n \times \mathbb{R}^k \rightarrow \mathbb{R}$.

One way to linearize the function f is to do it for every single element in $\vec{x} = [x_1 \ x_2 \ \dots \ x_n]^\top$ and $\vec{y} = [y_1 \ y_2 \ \dots \ y_k]^\top$. Then, when we are looking at x_i or y_j , we fix everything else as constant. This would give us the linear approximation

$$f(\vec{x}, \vec{y}) \approx f(\vec{x}_*, \vec{y}_*) + \sum_{i=1}^n \frac{\partial f(\vec{x}, \vec{y})}{\partial x_i} \Big|_{(\vec{x}_*, \vec{y}_*)} (x_i - x_{i,*}) + \sum_{j=1}^k \frac{\partial f(\vec{x}, \vec{y})}{\partial y_j} \Big|_{(\vec{x}_*, \vec{y}_*)} (y_j - y_{j,*}). \quad (19)$$

In order to simplify this equation, we can define the following two vector quantities:

$$J_{\vec{x}}f = \begin{bmatrix} \frac{\partial f}{\partial x_1} & \dots & \frac{\partial f}{\partial x_n} \end{bmatrix} \quad (20)$$

$$J_{\vec{y}}f = \begin{bmatrix} \frac{\partial f}{\partial y_1} & \dots & \frac{\partial f}{\partial y_k} \end{bmatrix} \quad (21)$$

First, how can we “vectorize” eq. (19) using $J_{\vec{x}}f$ and $J_{\vec{y}}f$? Next, assume that $n = k$ and we define the function $f(\vec{x}, \vec{y}) = \vec{x}^\top \vec{y} = \sum_{i=1}^k x_i y_i$. Find $J_{\vec{x}}f$ and $J_{\vec{y}}f$ for this specific f .

(HINT: For vectorizing, think about replacing the summations as the multiplication of a row and column vector. What would these vectors be?)

Solution: To vectorize eq. (19), we can try to replace the summations with a dot product. That is, if we were to multiply the row vector $\left[\frac{\partial f}{\partial x_1} \Big|_{(\vec{x}_*, \vec{y}_*)} \ \dots \ \frac{\partial f}{\partial x_n} \Big|_{(\vec{x}_*, \vec{y}_*)} \right] = J_{\vec{x}}f \Big|_{(\vec{x}_*, \vec{y}_*)}$ with the

column vector $\begin{bmatrix} x_1 - x_{1,*} \\ \vdots \\ x_n - x_{n,*} \end{bmatrix} = \vec{x} - \vec{x}_*$, then we would get the same summation (and similarly for y_j). Writing this more compactly,

$$\hat{f}(\vec{x}, \vec{y}; \vec{x}_*, \vec{y}_*) = f(\vec{x}_*, \vec{y}_*) + J_{\vec{x}}f \Big|_{(\vec{x}_*, \vec{y}_*)} (\vec{x} - \vec{x}_*) + J_{\vec{y}}f \Big|_{(\vec{x}_*, \vec{y}_*)} (\vec{y} - \vec{y}_*) \quad (22)$$

Now, for the specific $f(\vec{x}, \vec{y})$ in this problem, we apply the definition (and write out the given function explicitly as $x_1y_1 + x_2y_2 + \dots + x_ky_k$) to obtain:

$$J_{\vec{x}}f = \begin{bmatrix} y_1 & y_2 & \cdots & y_k \end{bmatrix} = \vec{y}^\top \quad (23)$$

and

$$J_{\vec{y}}f = \begin{bmatrix} x_1 & x_2 & \cdots & x_k \end{bmatrix} = \vec{x}^\top \quad (24)$$

- (g) Following the above part, **find the linear approximation of $f(\vec{x}, \vec{y})$ near $\vec{x}_* = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ and $\vec{y}_* = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$.** Recall that $f(\vec{x}, \vec{y}) = \vec{x}^\top \vec{y} = \sum_{i=1}^k x_i y_i$.

Solution: From the solution in the previous part, we can write

$$\widehat{f}(\vec{x}, \vec{y}; \vec{x}_*, \vec{y}_*) = f(\vec{x}_*, \vec{y}_*) + J_{\vec{x}}f \Big|_{(\vec{x}_*, \vec{y}_*)} (\vec{x} - \vec{x}_*) + J_{\vec{y}}f \Big|_{(\vec{x}_*, \vec{y}_*)} (\vec{y} - \vec{y}_*) \quad (25)$$

$$= \vec{x}_*^\top \vec{y}_* + \vec{y}_*^\top (\vec{x} - \vec{x}_*) + \vec{x}_*^\top (\vec{y} - \vec{y}_*) \quad (26)$$

Putting in $\vec{x}_* = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ and $\vec{y}_* = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$,

$$\widehat{f}(\vec{x}, \vec{y}; \vec{x}_*, \vec{y}_*) = 3 + \begin{bmatrix} -1 \\ 2 \end{bmatrix}^\top \vec{x} - 3 + \begin{bmatrix} 1 \\ 2 \end{bmatrix}^\top \vec{y} - 3 \quad (27)$$

$$= \begin{bmatrix} -1 \\ 2 \end{bmatrix}^\top \vec{x} + \begin{bmatrix} 1 \\ 2 \end{bmatrix}^\top \vec{y} - 3 \quad (28)$$

These linearizations are important for us because we can do many easy computations using linear functions.

Contributors:

- Neelesh Ramachandran.
- Kuan-Yun Lee.