

Parallel-Plate Capacitive Nonlinearity

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- **Example:** clamped-clamped laterally driven beam with balanced electrodes
- **Nomenclature:**

V_a or v_A $v_a = |v_a| \cos \omega t$

V_a or $v_A = V_A + v_a$

Total Value AC or Signal Component (lower case variable; lower case subscript)

DC Component (upper case variable; upper case subscript)

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Voltage-Controllable Center Frequency

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- **Quadrature force voltage-controllable electrical stiffness:**

$$k_e = \frac{\epsilon_0 A_o}{d^3} V_P^2$$

Electrode Overlap Area

Gap

$$f_o = \frac{1}{2\pi} \sqrt{\frac{k_m - k_e}{m_r}}$$

Frequency [MHz]

DC-Bias [V_P]

1.1%

$A_o = 88 \mu\text{m}^2$
 $d = 1000 \text{\AA}$

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Microresonator Thermal Stability

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Fractional frequency change [ppm]

Temperature [°C]

AT-Cut Quartz Crystal at various angles

−1.7ppm/°C

35°05', 35°10', 35°15', 35°20', 35°25', 35°30'

Drive electrode, Anchor, Sense electrode, Resonant beam

Poly-Si resonator - 17ppm/°C

- Thermal stability of poly-Si micromechanical resonator is 10X worse than the worst case of AT-cut quartz crystal

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Geometric-Stress Compensation

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- Use a temperature dependent mechanical stiffness to null frequency shifts due to Young's modulus thermal dep.

Fractional Frequency Change [ppm]

Temperature [K]

−2.5ppm/°C

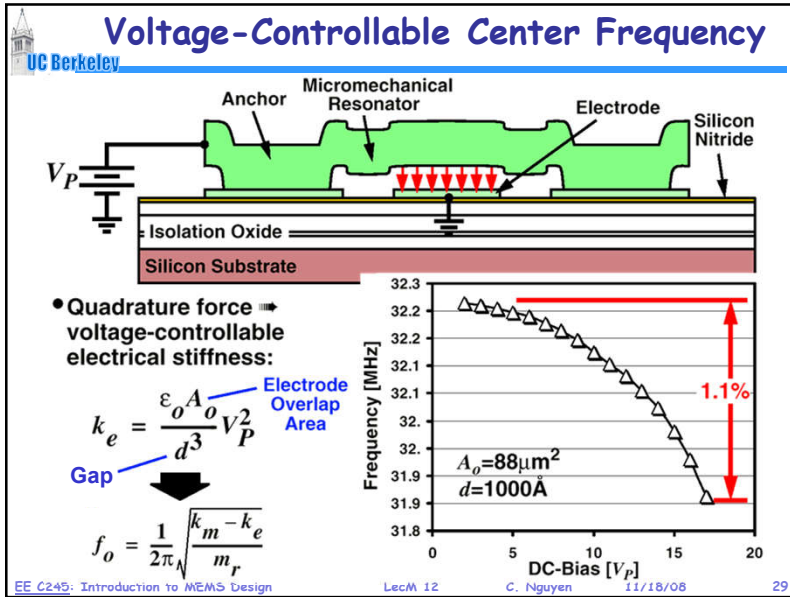
L_2/L_1 : 60/40, 50/40, 70/40, 40/40, 80/40, 30/40

- **Problems:**
 - stress relaxation
 - compromised design flexibility

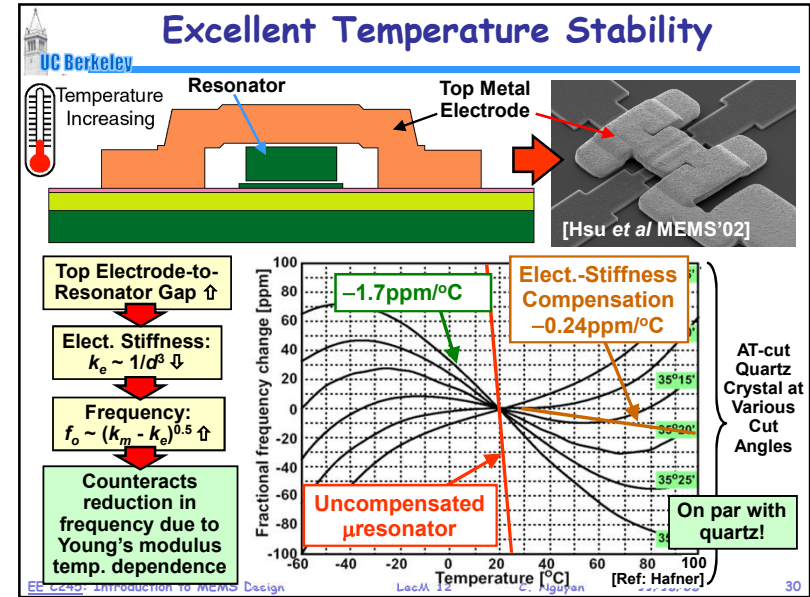
[Hsu et al IEDM 2000]

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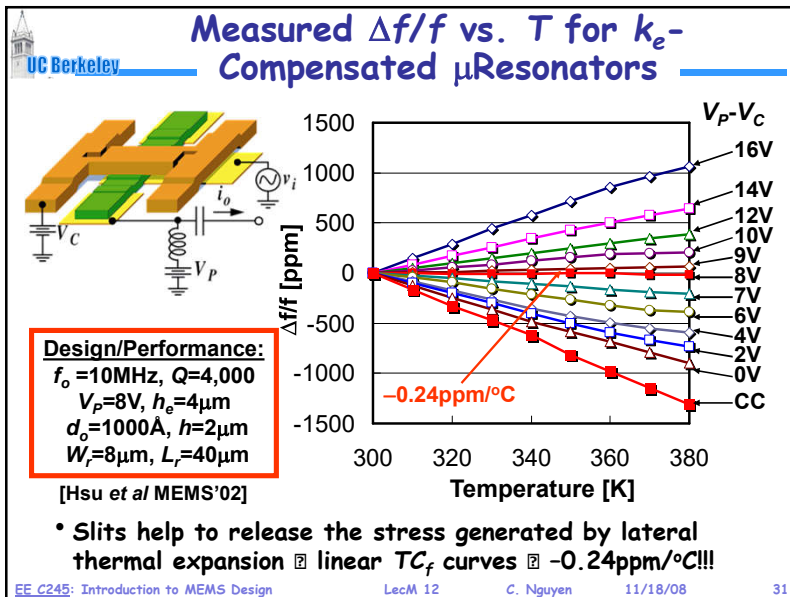
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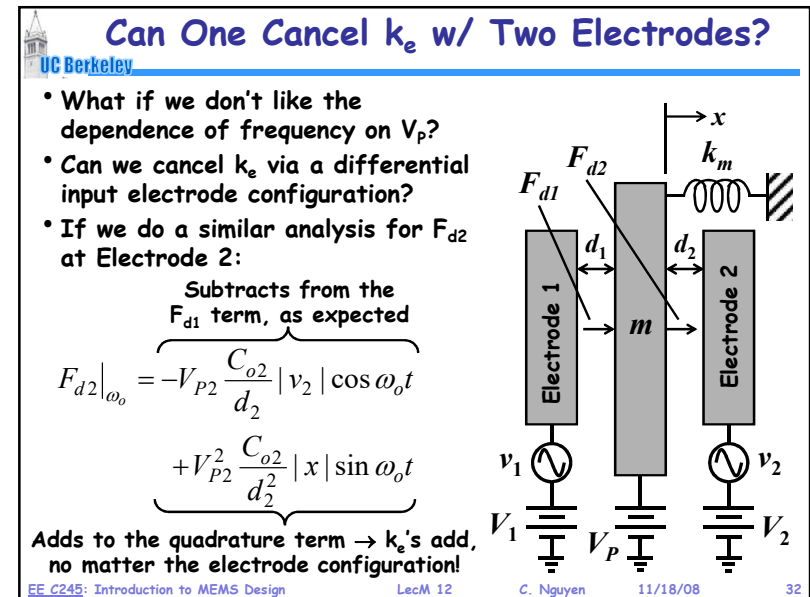
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Problems With Parallel-Plate C Drive

- Nonlinear voltage-to-force transfer function
 - ↳ Resonance frequency becomes dependent on parameters (e.g., bias voltage V_p)
 - ↳ Output current will also take on nonlinear characteristics as amplitude grows (i.e., as x approaches d_0)
 - ↳ Noise can alias due to nonlinearity
- Range of motion is small
 - ↳ For larger motion, need larger gap ... but larger gap weakens the electrostatic force
 - ↳ Large motion is often needed (e.g., by gyroscopes, vibromotors, optical MEMS)

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Electrostatic Comb Drive

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