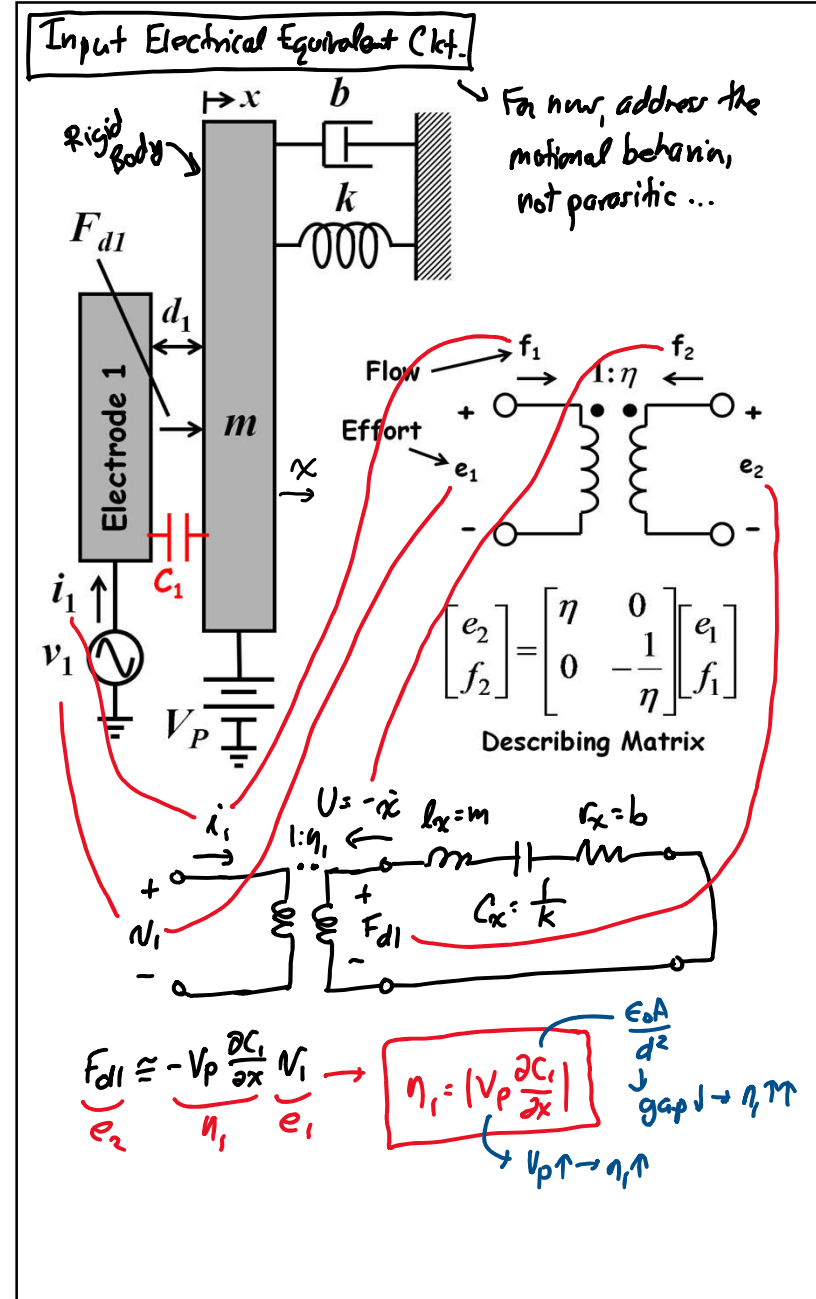


Lecture 21: Equivalent Circuits II

- **Announcements:**
- Project Slide Set #2 due Friday, April 17
- HW#6 online soon
- Module 13 on "Equivalent Circuits II" online
- Module 15 on "Gyros, Noise, & MDS" online
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- Reading: Senturia, Chpt. 6, Chpt. 14
- Lecture Topics:
 - ↳ Input Modeling
 - Force-to-Velocity Equiv. Ckt.
 - Input Equivalent Ckt.
 - ↳ Current Modeling
 - Output Current Into Ground
 - Input Current
 - Complete Electrical-Port Equiv. Ckt.
 - ↳ Impedance & Transfer Functions
-
- Reading: Senturia, Chpt. 14, Chpt. 16, Chpt. 21
- Lecture Topics:
 - ↳ Gyroscopes
- Reading: Senturia, Chpt. 14
- Lecture Topics:
 - ↳ Detection Circuits
 - Velocity Sensing
 - Position Sensing
-
- Last Time: Output current into ground
- Now, continue towards a complete equivalent circuit



Output Current Into Ground

Want this dt. model.

$[q = CV]$
 $i = \frac{dq}{dt} = C \frac{dV}{dt} + V \frac{dC}{dt}$
 ↑ electronics ↑ MEMS

$C_2 = f(t)$ ↑ time

$i_2 = C_2 \frac{dV_2(t)}{dt} + V_2(t) \frac{dC_2(x,t)}{dt}$

$[V_2(t) = -V_P] \Rightarrow i_2 = -V_P \frac{dC_2}{dt} = -V_P \frac{\partial C_2}{\partial x} \frac{\partial x}{\partial t}$

In phasor form: $I_2(j\omega) = -V_P \frac{\partial C_2}{\partial x} (j\omega X)$

$I_2(j\omega) = -j\omega V_P \frac{\partial C_2}{\partial x} X$
 ↑ motional current

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$I_2(j\omega) = -j\omega V_P \frac{\partial C_2}{\partial x} X = -V_P \frac{\partial C_2}{\partial x} \dot{x}$
 ↑ 90° phase lag ↑ (+) (+) → $I_2 = (-)$ when $x = (+)$ ✓
 ↑ velocity

velocity \dot{x} same as f_2

$f_2 = -\frac{1}{\eta_2} f_1 \Rightarrow f_1 = -\eta_2 f_2$

$[f_1 = I_2, f_2 = \dot{x}] \Rightarrow I_2 = -\eta_2 \dot{x}$
 $\therefore \eta_2 = |V_P \frac{\partial C_2}{\partial x}|$

Flow f_1 f_2

Effort e_1 e_2

Describing Matrix

$$\begin{bmatrix} e_2 \\ f_2 \end{bmatrix} = \begin{bmatrix} \eta & 0 \\ 0 & -\frac{1}{\eta} \end{bmatrix} \begin{bmatrix} e_1 \\ f_1 \end{bmatrix}$$

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Input Current Expression

Get $I_1(j\omega)$:

$$i_1(t) = C_1(x,t) \frac{dV_1(t)}{dt} + V_1(t) \frac{dC_1(x,t)}{dt}$$

$V_1(t) = v_1 - V_P$

$$i_1 = C_1 \frac{dx}{dt} + [v_1 - V_P] \frac{\partial C_1}{\partial x} \frac{\partial x}{\partial t}$$

$$\therefore I_1(j\omega) = j\omega C_1 V_1 + j\omega V_1 \frac{\partial C_1}{\partial x} X - j\omega V_P \frac{\partial C_1}{\partial x} X$$

Feedthrough Current (under the first term)
Motional Current due to motion! (under the second and third terms)

V₁(t) is a total voltage (with a note: cap + lower case)

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@DC: $x = \frac{F_{dl}}{k} = -\frac{1}{k} V_P \left(\frac{\partial C_1}{\partial x} \right) V_1$

@ resonance: $x = \frac{Q F_{dl}}{jk} = -\frac{Q}{jk} V_P \frac{\partial C_1}{\partial x} V_1 = X$

Thus: (@ resonance) ω_0 $\tau 90^\circ \text{ lag}$

$$I_1(j\omega) = j\omega_0 C_1 V_1 + j\omega_0 \left(V_P \frac{\partial C_1}{\partial x} \right)^2 \frac{Q}{jk} V_1$$

$$= j\omega_0 C_1 V_1 + \omega_0 \frac{Q}{k} \eta_{e1}^2 V_1$$

90° phase-shifted from V_1 (under the first term)
In phase ω/N_1 (under the second term)

This is a capacitor in shunt w/ the input!
This is an effective resistance seen "looking into electrode 1"

Motional Resistance:

$$R_{x1} = \frac{V_1}{I_1} = \frac{k}{\omega_0 Q \eta_{e1}^2} = \frac{m \omega_0}{Q \eta_{e1}^2} = \frac{b}{\eta_{e1}^2} = R_{x1}$$

"motion"

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Input Impedance Info Part 1

$z_i = \frac{N_i}{I_i} = ?$
 $z_x = j\omega l_x + \frac{1}{j\omega c_x} + r_x$

$z_i = \frac{N_i}{I_i} = \frac{e_1}{f_1}$
 $z_i = \frac{N_i}{I_i} = \frac{e_2}{f_2}$

$$\begin{bmatrix} e_2 \\ f_2 \end{bmatrix} = \begin{bmatrix} \eta & 0 \\ 0 & -\frac{1}{\eta} \end{bmatrix} \begin{bmatrix} e_1 \\ f_1 \end{bmatrix} \Rightarrow \left. \begin{aligned} e_2 &= \eta e_1 + e_1 = \frac{e_2}{\eta} \\ f_2 &= -\frac{1}{\eta} f_1 \rightarrow f_1 = -\eta f_2 \end{aligned} \right\}$$

$$\frac{e_1}{f_1} = \frac{e_2}{\eta} \left(\frac{1}{-\eta f_2} \right) = -\frac{1}{\eta^2} \frac{e_2}{f_2} = \frac{N_i}{I_i} = z_i' = -\frac{1}{\eta_{e1}^2} \frac{F_{d2}}{(-x_2)} \rightarrow *$$

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$* \rightarrow \frac{N_i}{I_i} = -\frac{1}{\eta_{e1}^2} \frac{F_{d2}}{(-x_2)} = \frac{1}{\eta_{e1}^2} z_x$
 $z_x = j\omega l_x + \frac{1}{j\omega c_x} + r_x$

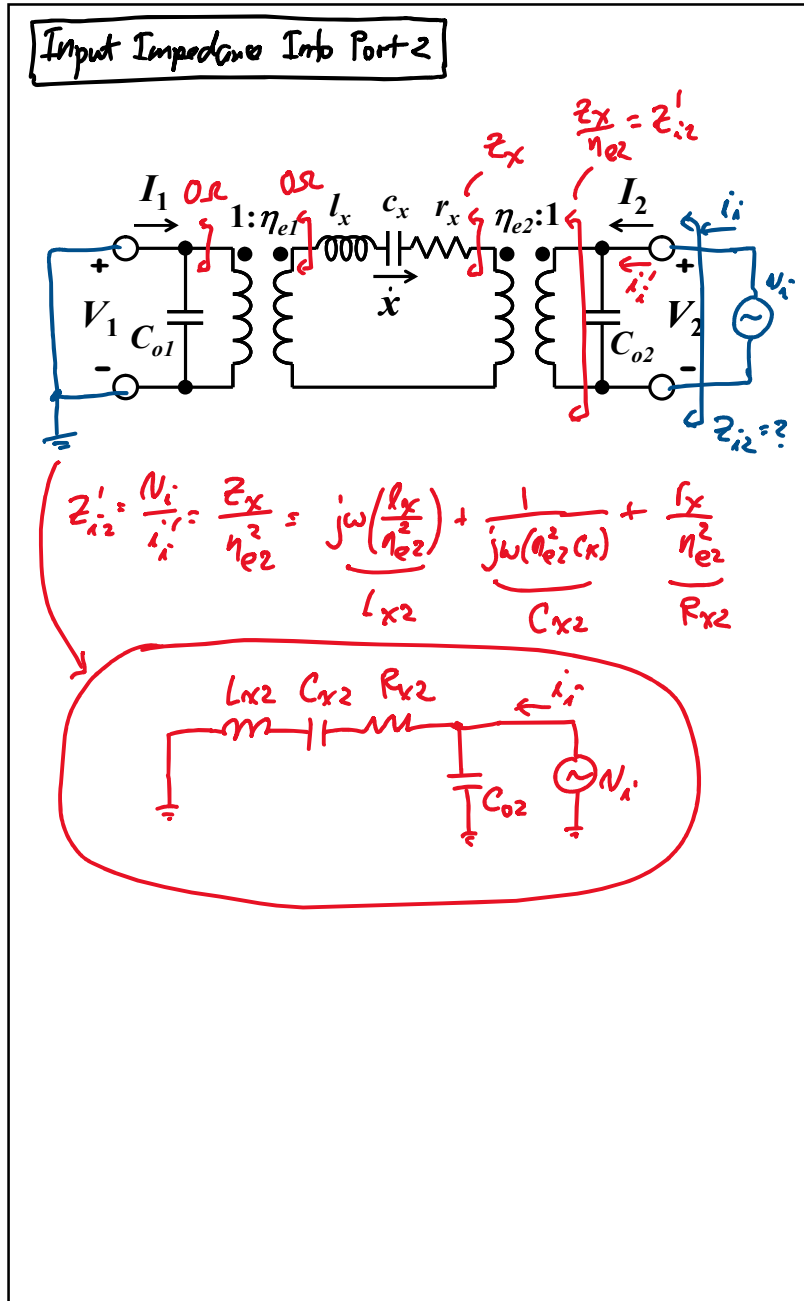
$z_i' = \frac{1}{\eta_{e1}^2} (j\omega l_x + \frac{1}{j\omega c_x} + r_x)$
 $= \underbrace{j\omega \left(\frac{l_x}{\eta_{e1}^2} \right)}_{L_{x1}} + \underbrace{\frac{1}{j\omega (\eta_{e1}^2 c_x)}}_{C_{x1}} + \underbrace{\frac{r_x}{\eta_{e1}^2}}_{R_{x1}} = \frac{b}{\eta_{e1}^2} \checkmark$

Purely Electrical Equivalent Ckt.

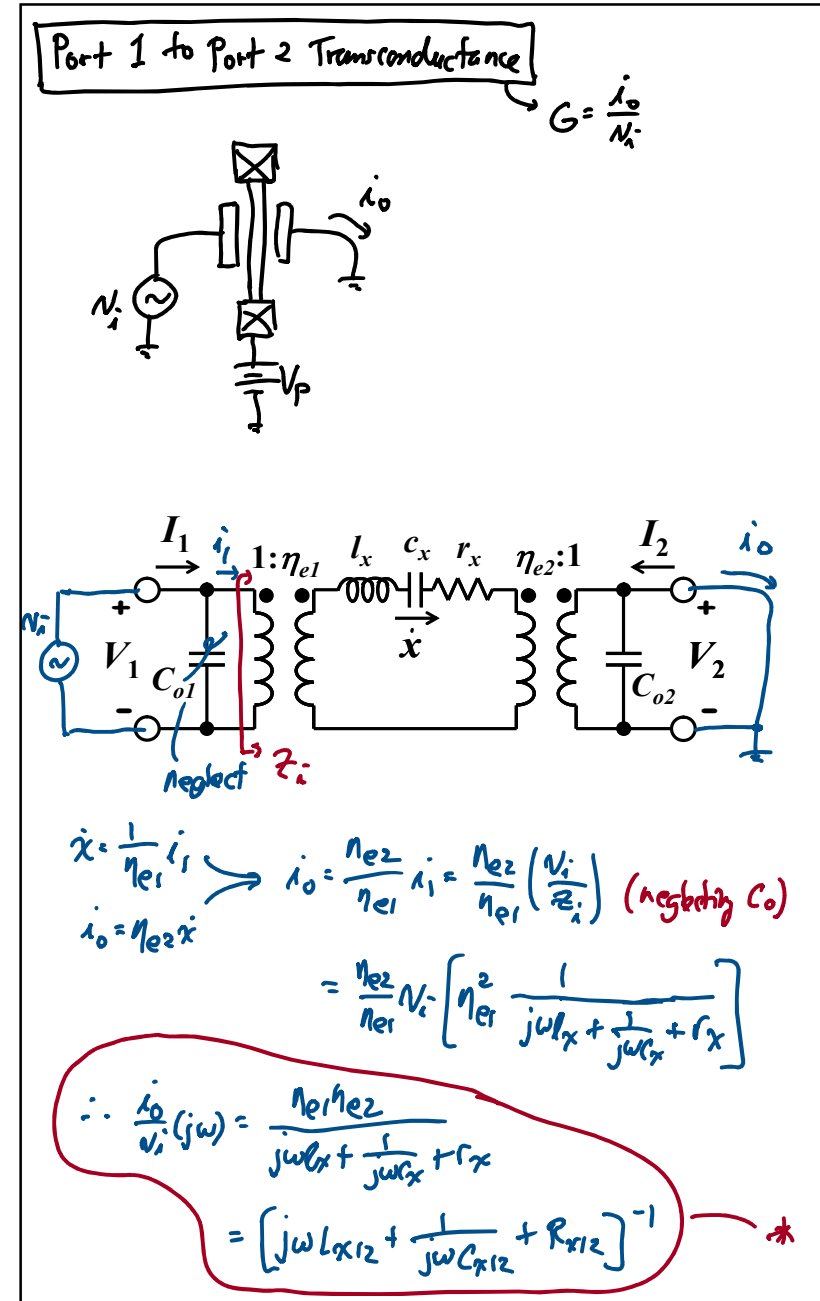
Xformer Inspection Analysis

$\frac{z_L}{\eta^2}$ $\eta^2 z_L$

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$L_{x12} = \frac{L_x}{n_{e1}n_{e2}}, C_{x12} = n_{e1}n_{e2}C_x, R_{x12} = \frac{R_x}{n_{e1}n_{e2}}$

Separate freq. response + magnitude:

* $\frac{i_o(s)}{v_i(s)} = \frac{1}{sL_x + \frac{1}{sC_x} + R_x} = \frac{s(\frac{1}{L_x})}{s^2 + \frac{1}{L_x C_x} + s(\frac{R_x}{L_x})}$

$s = j\omega$

$\left[\frac{1}{L_x C_x} = \omega_0^2, Q = \frac{\omega_0 L_x}{R_x} \rightarrow \frac{R_x}{L_x} = \frac{\omega_0}{Q} \right]$

$\frac{i_o(s)}{v_i(s)} = \frac{1}{R_x} \frac{s(\frac{\omega_0}{Q})}{s^2 + s(\frac{\omega_0}{Q}) + \omega_0^2} = \frac{1}{R_x} \textcircled{H}(s)$

Gain Term \uparrow Freq. Shaping Term \rightarrow Bandpass Biquad Resonance magnitude \downarrow

$Q = \frac{\omega_0}{\Delta\omega_{3dB}}$

Can just solve the ckt. @ resonance
 \downarrow
 then multiply the answer by $\textcircled{H}(s)$!
 \downarrow
 w/ Q modification