

Lecture 23: Sensing Circuits II & Integration

- **Announcements:**
- Project Slide Set #3 due Friday, April 24
- HW#6 online and due Friday, 5/1, at 8 a.m.
- Module 14 on "Sensing Circuits" online
- Module 16 on "Sensing Circuit Non-Idealities & Integration" online

• Reading: Senturia, Chpt. 14

• Lecture Topics:

↳ Detection Circuits

- Velocity Sensing
- Position Sensing

• Reading: Senturia Chpt. 14, 15

• Lecture Topics:

↳ Ideal Op Amps

↳ Op Amp Non-Idealities

↳ MEMS-Transistor Integration

- Mixed
- MEMS-First
- MEMS-Last

• **Last Time:**

- Working through velocity sensing
- Now, continue with this ...

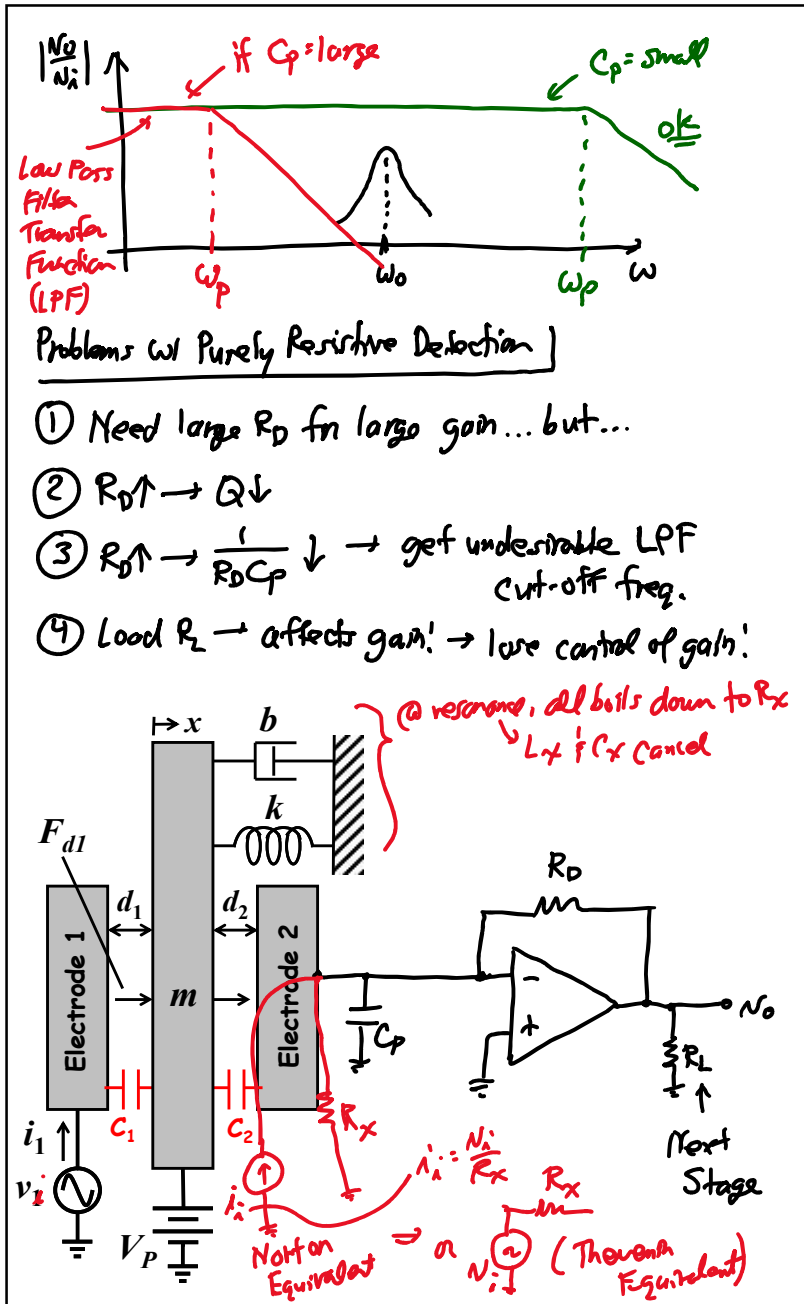
** The Problem is actually much bigger!*

Now, we get:

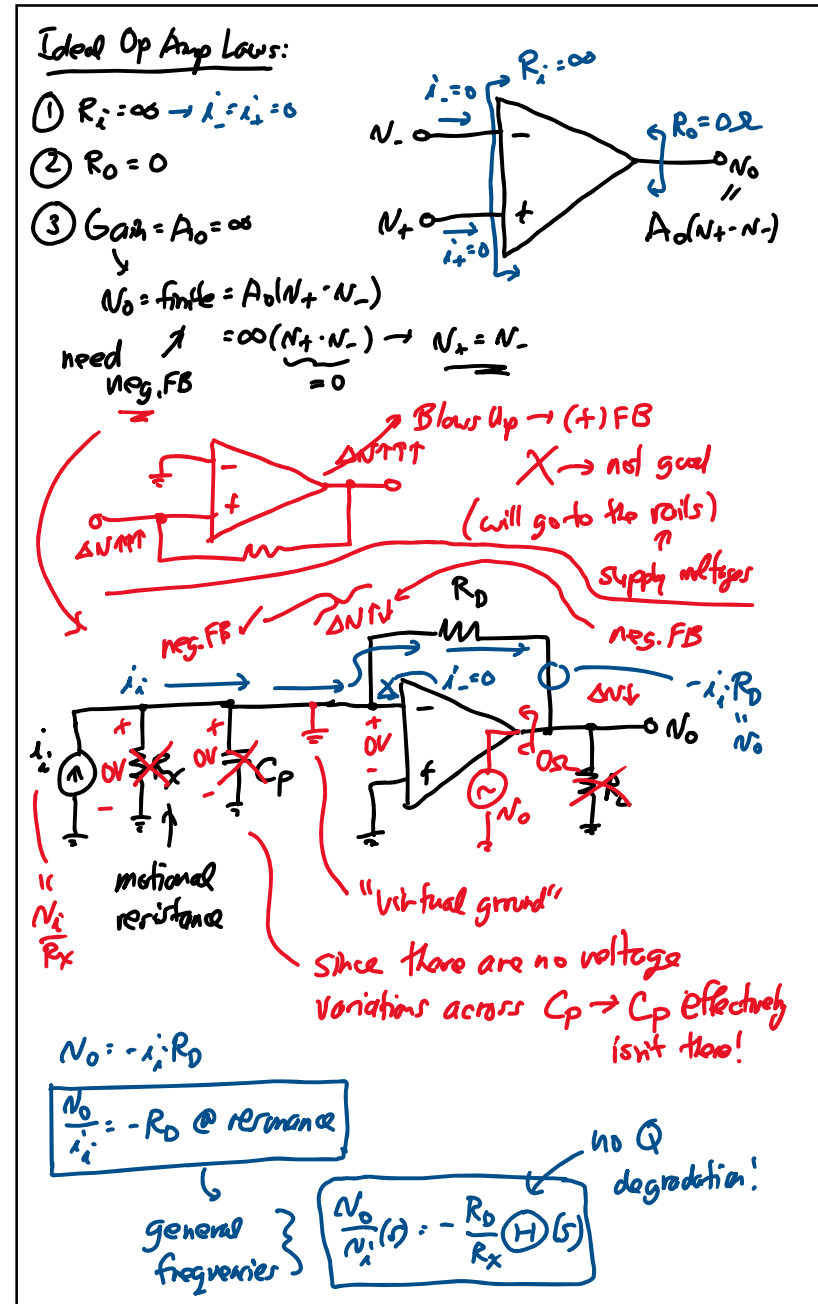
$$\frac{N_o}{N_i}(s) \sim \frac{R_D \parallel R_L}{R_x + R_D \parallel R_L} \cdot \frac{1}{1 + \frac{s}{\omega_p}} \cdot \Theta(s, \omega_o, Q')$$

$$\omega_p = \frac{1}{(R_x \parallel R_D \parallel R_L) C_p}$$

↑
from mechanical device



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