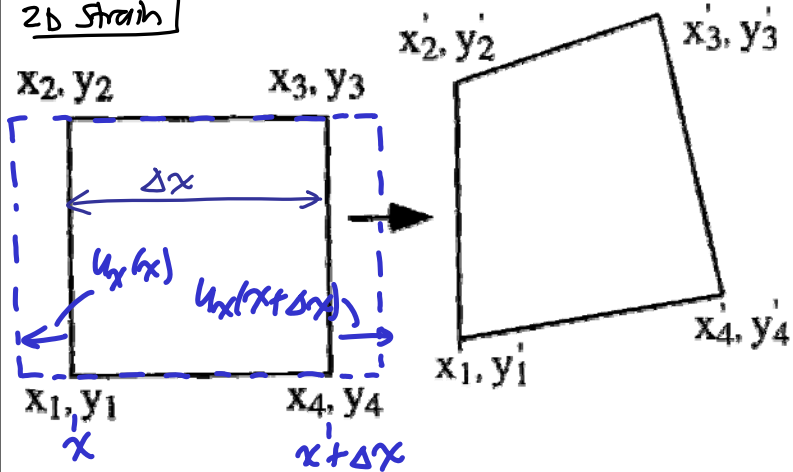


Lecture 13: Mechanics of Materials II

- Announcements:
- HW#4 passed out and online Nov. 2: 7
Oct. 28: 2
- -----
- Reading: Senturia, Chpt. 8
- Lecture Topics:
 - ↳ Stress, strain, etc., for isotropic materials
 - ↳ Thin films: thermal stress, residual stress, and stress gradients
 - ↳ Internal dissipation
 - ↳ MEMS material properties and performance metrics

• Last Time:

2D Strain



In general, motion consists of:

- ① Rigid body displacement (motion of the center of mass)

- ② Rigid body rotation (rotation about the center of mass)

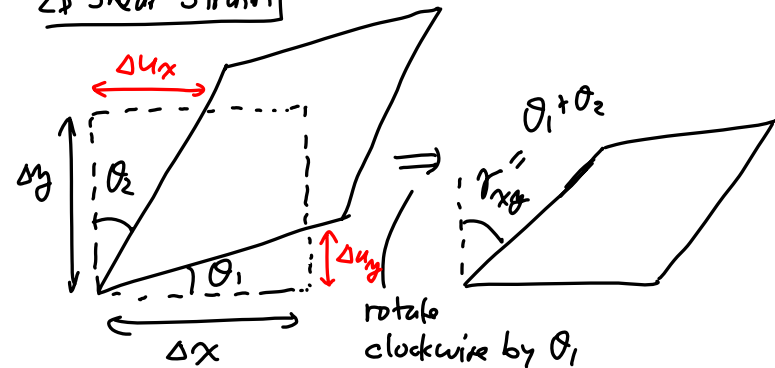
- ③ Deformation relative to displacement & rotation.

⇒ handle by displacement vector → do it an axis at a time

For axial strain in the x-direction:

$$\epsilon_x = \frac{u_x(x + \Delta x) - u_x(x)}{\Delta x} = \frac{\partial u_x}{\partial x}$$

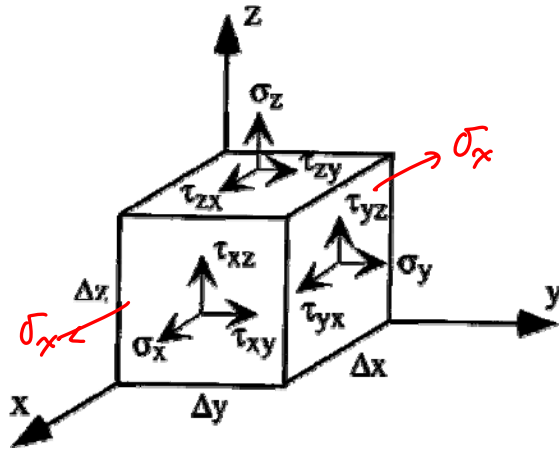
2D Shear Strain



⇒ For shear strain, must remove any rigid body rotation that accompanies the deformation:

$$\gamma_{xy} = \theta_1 + \theta_2 \approx \left(\frac{\Delta u_x}{\Delta y} + \frac{\Delta u_y}{\Delta x} \right) = \left(\frac{\partial u_x}{\partial y} + \frac{\partial u_y}{\partial x} \right)$$

Volume Change for Uniaxial stress



Given an x -directed uniaxial stress, σ_x :
before after application of σ_x

$$\Delta x \rightarrow \Delta x(1 + \epsilon_x)$$

$$\Delta y \rightarrow \Delta y(1 - \nu\epsilon_x)$$

$$\Delta z \rightarrow \Delta z(1 - \nu\epsilon_x)$$

↓ The resulting change in volume ΔV

$$\Delta V = \Delta x \Delta y \Delta z (1 + \epsilon_x)(1 - \nu\epsilon_x)^2 - \Delta x \Delta y \Delta z$$

$$= \Delta x \Delta y \Delta z [(1 + \epsilon_x)(1 - \nu\epsilon_x)^2 - 1]$$

(Assume small strains)

$$\left\{ (1 + m_x)^n \approx 1 + nm_x \right\}$$

$$= \Delta x \Delta y \Delta z \left[\cancel{1} - \epsilon_x - 2\nu\epsilon_x - 2\nu\cancel{\epsilon_x^2} - 1 \right] \text{ "neg!"}$$

$\epsilon_x = \text{small}$

$$\Delta V \approx \Delta x \Delta y \Delta z (1 - 2\nu) \epsilon_x$$

For $\nu = 0.5$ (rubber) \rightarrow no ΔV !

$\nu < 0.5 \rightarrow$ finite ΔV

Isotropic Elasticity in 3D

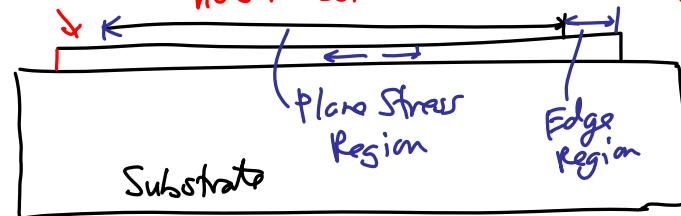
$$\epsilon_x = \frac{1}{E} [\sigma_x - \nu(\sigma_y + \sigma_z)] \quad \gamma_{xy} = \frac{1}{G} \tau_{xy}$$

$$\epsilon_y = \frac{1}{E} [\sigma_y - \nu(\sigma_z + \sigma_x)] \quad \dots$$

Ex:

Important Case: Plane Stress

Thin film \rightarrow deformed @ high temp. @ which there is no stress between the substrate & film



take $T \downarrow \rightarrow$ to room temperature
 \rightarrow get stress!

Plane Stress Region

Get two components: $\sigma_z = 0$

$$\epsilon_x = \frac{1}{E} [\sigma_x - \nu(\sigma_y + 0)]$$

$$\epsilon_y = \frac{1}{E} [\sigma_y - \nu(\sigma_x + 0)]$$

[Symmetry in the xy-plane] $\Rightarrow \sigma_x = \sigma_y = \sigma$

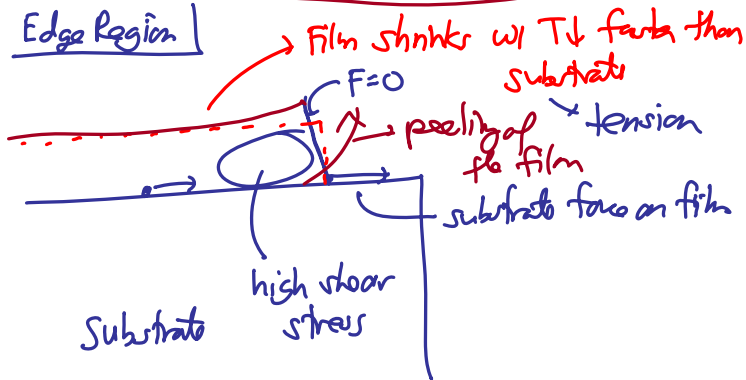
\therefore the in-plane strain components are: $\epsilon_x = \epsilon_y = \epsilon$

$$\epsilon_x = \frac{1}{E} (\sigma - \nu\sigma) = \frac{\sigma}{\left[\frac{E}{(1-\nu)}\right]} = \frac{\sigma}{E'}$$

where

$$E' \equiv \text{Biaxial Modulus} = \frac{E}{1-\nu}$$

Edge Region



Linear Thermal Expansion

\Rightarrow As $T \uparrow \rightarrow$ most solids expand $\rightarrow V \uparrow$

Definition. Linear Thermal Expansion Coefficient

$$\left. \begin{array}{l} \text{Linear Thermal} \\ \text{Expansion Coeff.} \end{array} \right\} \triangleq \alpha_T = \frac{d\epsilon_x}{dT} \quad \begin{array}{l} [\text{kelvin}^{-1}] \\ [\mu\text{strain/K}] \end{array}$$

Remarks:

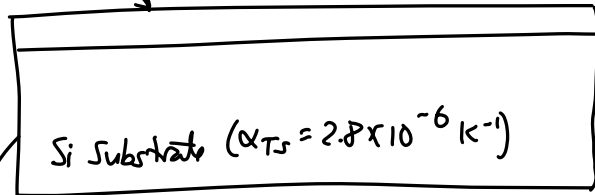
- ① α_T values range: 10^{-6} to 10^{-7}
- ② Can capture the \downarrow using $\mu\text{strain/K}$
- ③ In 3D, get volume thermal expansion coeff.

$$\hookrightarrow \frac{\Delta V}{V} = 3\alpha_T \Delta T$$

- ④ For moderate ΔT 's $\rightarrow \alpha_T \approx \text{constant}$
 \hookrightarrow in actuality, $\alpha_T = f(T)$

Thin Film Thermal Stress

Thin Film (α_{Tf})



Substrate much thicker than the film

Assume:

- ① Film deposited stress free @ T_d
- ② Whole thing cooled to room temp., T_r

What is the thermal mismatch strain?

\Rightarrow substrate much thicker than film \rightarrow substrate dictates the amount of contraction for both

Thermal Strain in Substrate: (in one in-plane dim)

$$\epsilon_s = -\alpha_{Ts} \Delta T, \text{ where } \Delta T = T_d - T_r$$

If the film was not attached to the substrate:

$$\epsilon_{f, \text{free}} = -\alpha_{Tf} \Delta T$$

But since the film is attached to substrate, actual strain in film is

$$\epsilon_{f, \text{attached}} = -\alpha_{Ts} \Delta T$$

Thus:

$$\text{Thermal Mismatch Strain} = \epsilon_{f, \text{mismatch}} = (\alpha_{Tf} - \alpha_{Ts}) \Delta T$$

\hookrightarrow Note that this is biaxial strain:

$$\sigma_{f, \text{mismatch}} = \left(\frac{E}{1-\nu} \right) \epsilon_{f, \text{mismatch}}$$

Ex. Thin film is polyimide $\rightarrow \alpha_{Tf} = 70 \times 10^{-6} \text{K}^{-1}$

\swarrow
deposited @ 250°C , $E = 4 \text{ GPa}$

then cooled to RT = $25^\circ\text{C} \rightarrow \Delta T = 225\text{K}$

$$\epsilon_{f, \text{mismatch}} = (70 - 2.8) \mu (225) = 1.5 \times 10^{-2}$$

$$\sigma_{f, \text{mismatch}} = (46) (1.5 \times 10^{-2}) = \underline{60.5 \text{ MPa}}$$

(+) \therefore tensile

[-] would be compressive