

Lecture 2w: Benefits of Scaling I

Lecture 2: Benefits of Scaling

- Announcements:
- Discussion Section Change?
  - ↳ M 6-7? ~~No!~~ → were not doing anything...
- TA Office Hours: in 481 Cory
- Modules
- The required textbook is the Senturia text.

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• Today:

• Reading: Senturia, Chapter 1

• Lecture Topics:

↳ Benefits of Miniaturization

↳ Examples

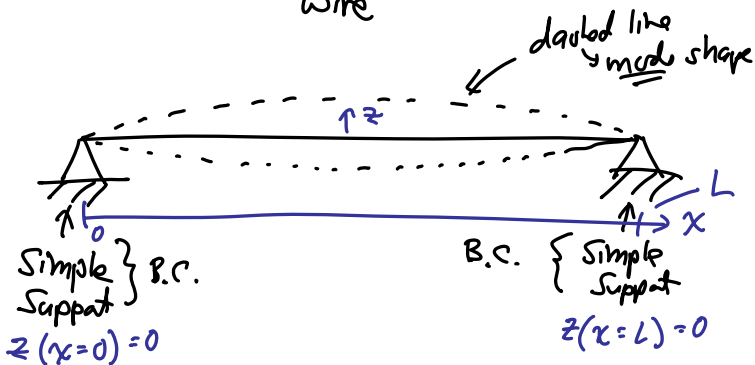
- GHz micromechanical resonators
- Chip-scale atomic clock
- Micro gas chromatograph

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• Start going through module 2

Scaling of Guitar Strings

guitar strings ≡ transversely vibrating stretched wire



Free Body Diagram

vibrating string

acceleration }  $F_{inertial} = ma$

mass per unit length →  $m'dx \frac{\partial^2 z}{\partial t^2}$

$S \frac{\partial z}{\partial x} + \frac{\partial^2 z}{\partial x^2} dx$

$S \frac{\partial z}{\partial x}$

$S \left( \frac{\partial z}{\partial x} + \frac{\partial^2 z}{\partial x^2} dx \right)$

condition for dynamic equilibrium:

$$S \left( \frac{\partial z}{\partial x} + \frac{\partial^2 z}{\partial x^2} dx \right) - S \frac{\partial z}{\partial x} - m'dx \frac{\partial^2 z}{\partial t^2} = 0$$

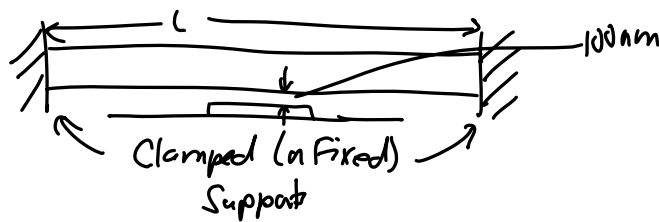
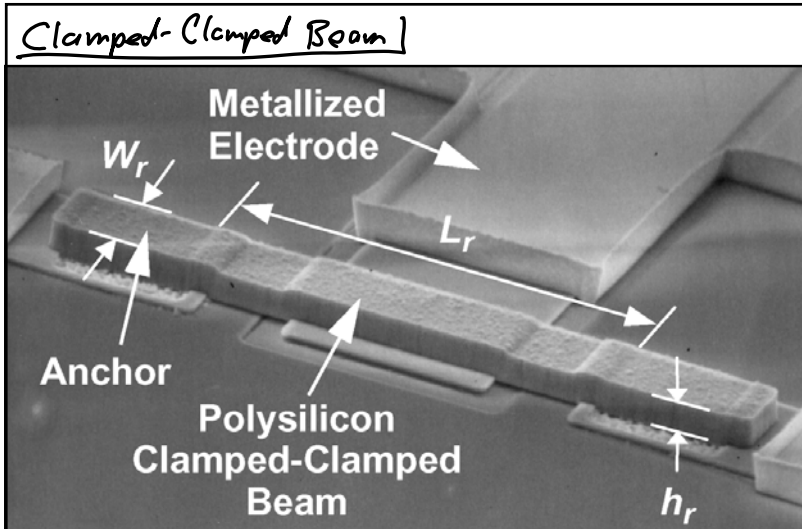
Solve →  $f_n = \frac{n}{2L} \sqrt{\frac{S}{m'}}$

frequency

tension (force per unit cross-sectional area)

mass per unit length

Good approx for a guitar string...



⇒ Eq. for Resonance Freq.:

$$f_0 = \frac{1}{2\pi} \sqrt{\frac{k}{m}} = 1.03 \sqrt{\frac{E}{\rho}} \frac{h}{L^2} \quad (1)$$

← "giga"

where  $E \triangleq$  Young's modulus [GPa]

$\rho \triangleq$  density [kg/m<sup>3</sup>]

$h \triangleq$  thickness [m]

$L \triangleq$  length [m]

Example.  $L=40\mu\text{m}$ ,  $h=2\mu\text{m}$

poly Si →  $E=150\text{ GPa}$ ,  $\rho=2300\text{ kg/m}^3$

$$\therefore f_0 = (1.03) \sqrt{\frac{150\text{G}}{2300}} \frac{2\mu}{(40\mu)^2} \rightarrow \boxed{f_0: 10.4\text{ MHz}}$$

As  $L \downarrow \rightarrow f_0 \uparrow$

acoustic velocity = 8,076 m/s

Scaling

⇒ If we scale all dimensions equally by a scaling factor  $S$ :

$$f_0 \sim \frac{1}{S^2} = \frac{1}{S} \sqrt{\quad} \rightarrow f_0 \uparrow \text{ as we scale to smaller sizes!}$$

If we scale only  $L$ :

$$f_0 \sim \frac{1}{S^2} \rightarrow \text{even faster rise in } f_0!$$

Example.  $L=4\mu \rightarrow \boxed{f_0 = 1.04\text{ GHz!}}$

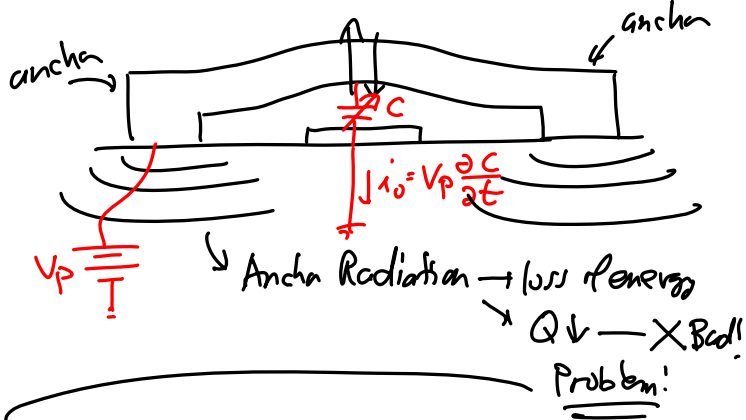
GHz freqs. possible!

Smaller → Faster!

Remarks.

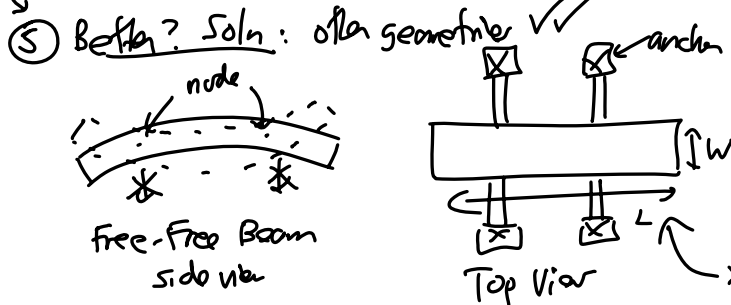
① Eq. (1) not accurate when  $L \approx h \approx w$ .

② When  $L \times h$  (or when it isn't more than  $10 \times h$ ), anchor losses become an issue:

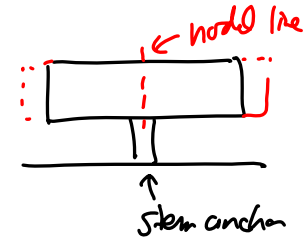
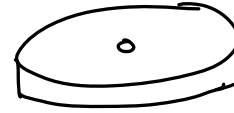


③ Soln: nanodimensions!  $\downarrow$   
 $\downarrow$  problem: power handling

④ Soln: Use an array!



Disk

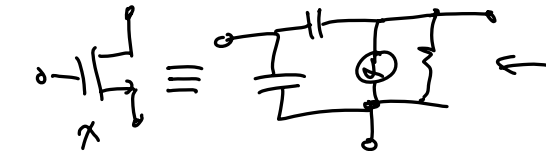


617 w/  $Q's \sim 50,000$   
 $500 \text{ MHz}$

⑥ This device is a glorified LCR:



\* ~~~~~ \*



MOS Transistor Equiv. Ckt.

$\downarrow$  If you can design large ckt. using this, then why not w/ this?

$\downarrow$  You absolutely can design ckt w/ mechanics! (and large ones)