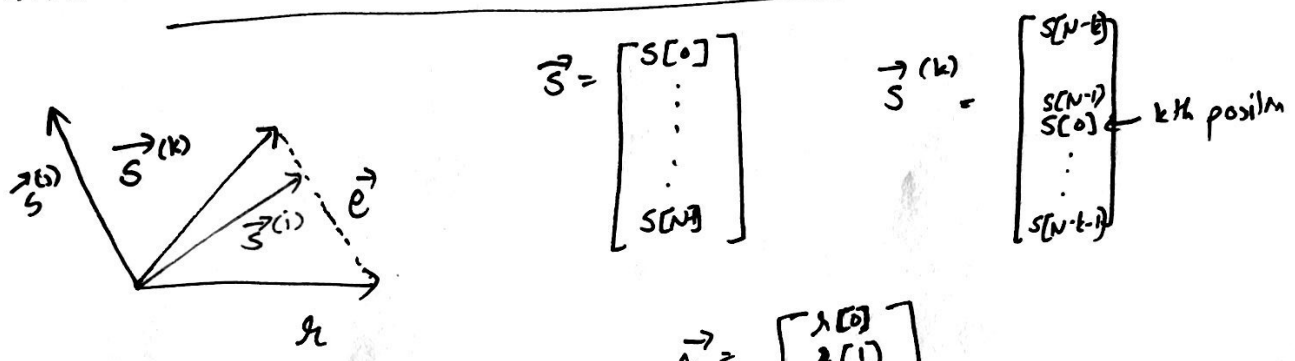


Today:

- Geometric interpretations of correlation and inner product.
- Projections.
- Multiple beacons.
- Trilateration.



$$\vec{e} = \vec{r} - \vec{s}_k$$

$$\vec{r} = \begin{bmatrix} r[0] \\ r[1] \\ \vdots \\ r[N-1] \end{bmatrix}$$

Minimize length ~~is~~ $\|\vec{e}\|$
 Find $k \rightarrow$

$$\begin{aligned} \min_k \|\vec{e}\|^2 &= \|\vec{r} - \vec{s}^{(k)}\|^2 \\ &= (\vec{r} - \vec{s}^{(k)})^T (\vec{r} - \vec{s}^{(k)}) \\ &= \vec{r}^T \vec{r} + \vec{s}^{(k)T} \vec{s}^{(k)} - \vec{r}^T \vec{s}^{(k)} - \vec{s}^{(k)T} \vec{r} \\ &= \|\vec{r}\|^2 + \|\vec{s}\|^2 - 2 \langle \vec{r}, \vec{s}^{(k)} \rangle \end{aligned}$$

\uparrow
 -ve sign.

$$\langle \vec{r}, \vec{s}^{(k)} \rangle = \langle \vec{s}^{(k)}, \vec{r} \rangle$$

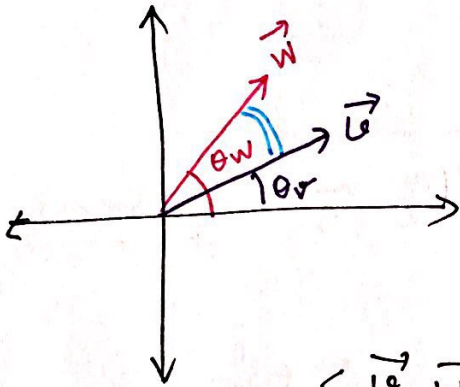
$$\max_k \langle \vec{r}, \vec{s}^{(k)} \rangle$$

Geometric interpretation.

(2)

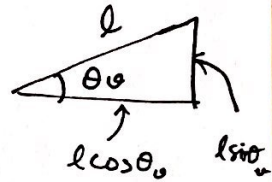
Intuitively $\langle \vec{s}^{(k)}, \vec{x} \rangle$ should be larger if $\vec{s}^{(k)}, \vec{x}$ are close.

2D Geometric.



$$\vec{u} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} \|\vec{u}\| \cos \theta_u \\ \|\vec{u}\| \sin \theta_u \end{bmatrix}$$

$$\vec{w} = \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} \|\vec{w}\| \cos \theta_w \\ \|\vec{w}\| \sin \theta_w \end{bmatrix}$$



$$\langle \vec{u}, \vec{w} \rangle = \langle \vec{w}, \vec{u} \rangle$$

$$= u_1 w_1 + u_2 w_2$$

$$= \|\vec{u}\| \cos \theta_u \cdot \|\vec{w}\| \cos \theta_w + \|\vec{u}\| \sin \theta_u \cdot \|\vec{w}\| \sin \theta_w$$

$$= \|\vec{u}\| \|\vec{w}\| (\cos \theta_u \cos \theta_w + \sin \theta_u \sin \theta_w)$$

$$= \|\vec{u}\| \|\vec{w}\| (\cos (\theta_u - \theta_w))$$

$$= \|\vec{u}\| \|\vec{w}\| (\cos (\theta_w - \theta_u)).$$

$$-1 \leq \cos \theta \leq 1$$

$$\cos \theta = 1$$

$$\cos \frac{\pi}{2} = 0.$$

Properties.

$$\textcircled{1} \langle \vec{x}, \vec{y} \rangle = \langle \vec{y}, \vec{x} \rangle.$$

$$\textcircled{2} \langle \vec{x} + \vec{y}, \vec{z} \rangle = \langle \vec{x}, \vec{z} \rangle + \langle \vec{y}, \vec{z} \rangle$$

$$\textcircled{3} \langle \alpha \vec{x}, \vec{y} \rangle = \alpha \langle \vec{x}, \vec{y} \rangle.$$

$$\textcircled{4} \langle \vec{x}, \vec{x} \rangle \geq 0$$

$$\textcircled{5} \langle \vec{x}, \vec{x} \rangle = 0 \text{ if and only if } \vec{x} = \vec{0}.$$

Cauchy-Schwarz inequality. : CS70.

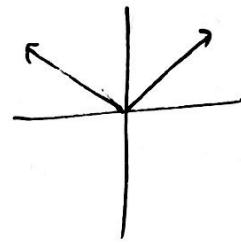
$$|\langle \vec{u}, \vec{w} \rangle| = \|\vec{u}\| \|\vec{w}\| \cos (\theta_u - \theta_w) \leq \|\vec{u}\| \|\vec{w}\|.$$

Minimum Value

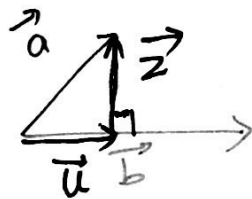
Orthogonality \vec{u}, \vec{w} are orthogonal if $\langle \vec{u}, \vec{w} \rangle = 0$

$\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

$\begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \end{bmatrix}$



Projection \vec{a}, \vec{b} . "Project" \vec{a} onto the subspace spanned by \vec{b}



Find: \vec{u}, \vec{z} such that.

- ① $\vec{u} + \vec{z} = \vec{a}$.
- ② \vec{u} is in the same direction as \vec{b}
 $\vec{u} = \alpha \cdot \vec{b}$
- ③ \vec{z} to be orthogonal to \vec{b} : $\langle \vec{z}, \vec{b} \rangle = 0$

Known: \vec{a}, \vec{b}

Unknown: \vec{u}, \vec{z}



Find: unknown: α

Find co-ordinates of \vec{a} along basis given by \vec{b}, \vec{z}

Co-ord: $\left(\frac{\langle \vec{a}, \vec{b} \rangle}{\|\vec{b}\|^2}, 1 \right)$

$\vec{z} = \vec{a} - \vec{u}$

$\langle \vec{z}, \vec{b} \rangle = 0$

$\Rightarrow \langle \vec{a} - \vec{u}, \vec{b} \rangle = 0$

$\Rightarrow \langle \vec{a}, \vec{b} \rangle - \langle \vec{u}, \vec{b} \rangle = 0.$

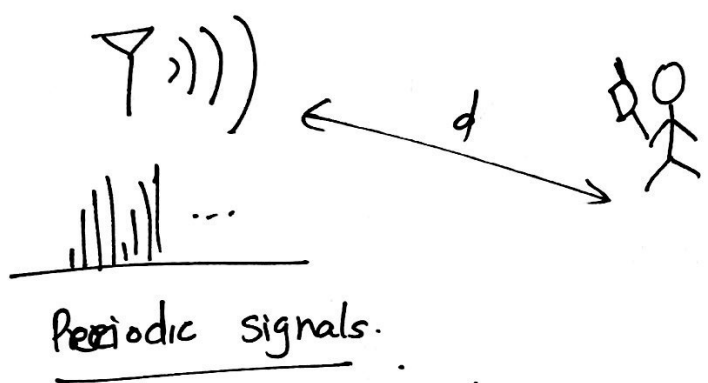
$\Rightarrow \langle \vec{a}, \vec{b} \rangle - \langle \alpha \vec{b}, \vec{b} \rangle = 0.$

$\Rightarrow \langle \vec{a}, \vec{b} \rangle - \alpha \langle \vec{b}, \vec{b} \rangle = 0.$

$\Rightarrow \alpha = \frac{\langle \vec{a}, \vec{b} \rangle}{\langle \vec{b}, \vec{b} \rangle} = \frac{\langle \vec{a}, \vec{b} \rangle}{\|\vec{b}\|^2}$

$\vec{u} = \frac{\langle \vec{a}, \vec{b} \rangle}{\|\vec{b}\|^2} \cdot \vec{b}$

Connecting to localising



Summary.

- Beacon sends periodic signal.
- Use correlation to find the best aligned "shift"
- Transmissiom delay.
- Computz. distance.

Periodic Corr. $\text{corr}_N(\vec{x}, \vec{s})[k] = \sum_{i=0}^{N-1} x[i] \cdot s[i-k] = \langle \vec{x}, \vec{s}^{(k)} \rangle$

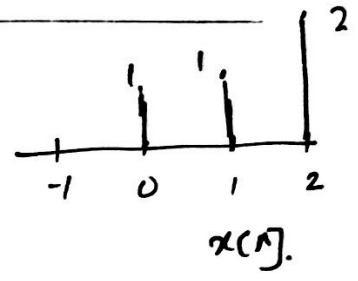
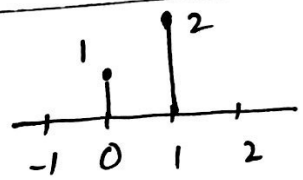
Circular Corr $\text{circcorr}(\vec{x}, \vec{s}) = \sum_{i=0}^{N-1} x[i] s[(i-k)_N]$

matrix-vector multiplication

$$\begin{bmatrix}
 s[0] & s[1] & \dots & s[N-1] \\
 s[N-1] & s[0] & \dots & s[N-2] \\
 \vdots & \vdots & \ddots & \vdots \\
 s[1] & \dots & s[N-1] & s[0]
 \end{bmatrix}
 \begin{bmatrix}
 x[0] \\
 x[1] \\
 \vdots \\
 x[N-1]
 \end{bmatrix}$$

circulant matrix

Linear correlation

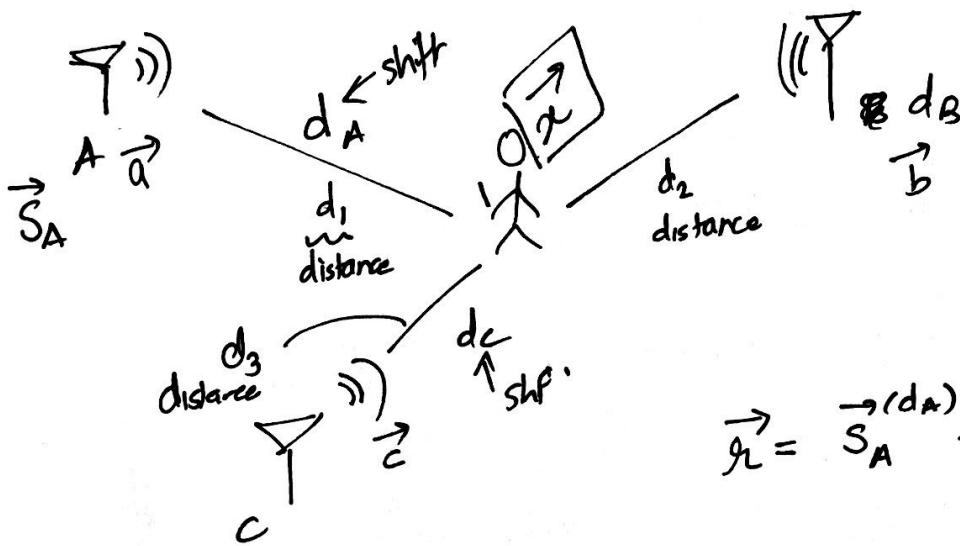


$$\text{corr}(\vec{x}, \vec{y})[k] = \sum_{i=-\infty}^{\infty} x[i] \cdot y[i-k]$$

$$\text{corr}(\vec{x}, \vec{y})[0] = 1 + 2 + 0 = 3.$$

$$\text{corr}(\vec{x}, \vec{y})[1] = 0 + 1 + 4 = 5$$

Multiple beacons



$$\vec{g}_L = \vec{S}_A + \vec{S}_B + \vec{S}_C$$

$$\begin{aligned} \langle \vec{g}_L, \vec{S}_A^{(k)} \rangle &= \langle \vec{S}_A + \vec{S}_B + \vec{S}_C, \vec{S}_A^{(k)} \rangle \\ &= \underbrace{\langle \vec{S}_A, \vec{S}_A^{(k)} \rangle}_{\text{large}} + \langle \vec{S}_B, \vec{S}_A^{(k)} \rangle \\ &\quad + \langle \vec{S}_C, \vec{S}_A^{(k)} \rangle \end{aligned}$$

(small)

$$\begin{aligned} \|\vec{x} - \vec{a}\|^2 = d_1^2 &\rightarrow \|\vec{x}\|^2 - 2\langle \vec{a}, \vec{x} \rangle + \|\vec{a}\|^2 = d_1^2 & \textcircled{1} \\ \|\vec{x} - \vec{b}\|^2 = d_2^2 &\|\vec{x}\|^2 - 2\langle \vec{b}, \vec{x} \rangle + \|\vec{b}\|^2 = d_2^2 & \textcircled{2} \\ \|\vec{x} - \vec{c}\|^2 = d_3^2 &\|\vec{x}\|^2 - \dots = d_3^2 & \textcircled{3} \end{aligned}$$

$$\begin{aligned} \textcircled{2} - \textcircled{1} : 2\langle \vec{x}, \vec{b} \rangle - 2\langle \vec{x}, \vec{a} \rangle &= (d_1^2 - d_2^2) - (\|\vec{a}\|^2 - \|\vec{b}\|^2) \\ \textcircled{3} - \textcircled{1} : 2\langle \vec{x}, \vec{c} \rangle - \dots &= (d_1^2 - d_3^2) - (\|\vec{a}\|^2 - \|\vec{c}\|^2) \end{aligned}$$

$$2 \begin{bmatrix} (\vec{b} - \vec{a})^T \\ (\vec{c} - \vec{a})^T \end{bmatrix} \vec{x} = \begin{bmatrix} \dots \\ \dots \end{bmatrix}$$

Trilateration