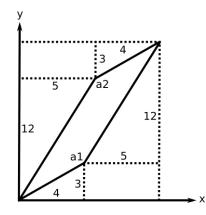
## EECS 16A Designing Information Devices and Systems I Spring 2022 Discussion 5B

## 1. Mechanical Determinants

(a) Compute the determinant of  $\begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix}$ .

(b) Compute the determinant of 
$$\begin{bmatrix} 2 & -3 & 1 \\ 2 & 0 & -1 \\ 1 & 4 & 5 \end{bmatrix}$$
.

(c) We know that the determinant of a matrix represents the multi-dimensional volume formed by the column vectors. Explain geometrically why the determinant of a matrix with linearly dependent column vectors is always 0.



## 2. Mechanical Eigenvalues and Eigenvectors

In each part, find the eigenvalues of the matrix M and the associated eigenvectors.

(a) 
$$\mathbf{M} = \begin{bmatrix} 1 & 0 \\ 0 & 9 \end{bmatrix}$$
  
Do you observe anything?

(b) 
$$\mathbf{M} = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix}$$

(c) Without calculation, determine whether the identity matrix in  $\mathbb{R}^n$  have any eigenvalues  $\lambda \in \mathbb{R}$ . What are the corresponding eigenvectors?

## 3. Steady and Unsteady States

You're given the matrix M:

$$\mathbf{M} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ 0 & 1 & -2 \\ 0 & 0 & 2 \end{bmatrix}$$

which generates the next state of a physical system from its previous state:  $\vec{x}[k+1] = \mathbf{M}\vec{x}[k]$ .

(a) The eigen values of **M** are  $\lambda_1 = 1, \lambda_2 = 2, \lambda_3 = \frac{1}{2}$ . Define  $\vec{x} = \alpha \vec{v}_1 + \beta \vec{v}_2 + \gamma \vec{v}_3$ , a linear combination of the eigenvectors corresponding to the eigen values. For each of the cases in the table, determine if

$$\lim_{n\to\infty}\mathbf{M}^n\vec{x}$$

converges. If it does, what does it converge to?

α	β	γ	Converges?	$\lim_{n\to\infty}\mathbf{M}^n\vec{x}$
0	0	$\neq 0$		
0	$\neq 0$	0		
0	$\neq 0$	eq 0		
$\neq 0$	0	0		
$\neq 0$	0	$\neq 0$		
$\neq 0$	$\neq 0$	0		
$\neq 0$	$\neq 0$	eq 0		

- (b) (**Practice**) Find the eigenspaces associated with the eigenvalues:
  - i. span( $\vec{v}_1$ ), associated with  $\lambda_1 = 1$
  - ii. span( $\vec{v}_2$ ), associated with  $\lambda_2 = 2$
  - iii. span( $\vec{v}_3$ ), associated with  $\lambda_3 = \frac{1}{2}$