
EECS 16B Designing Information Devices and Systems II
Fall 2021 Discussion Worksheet Discussion 9B

The following notes are useful for this discussion: [Note 14](#)

1. Orthonormality and Least Squares

- (a) Let U be an $m \times n$ matrix with orthonormal columns, with $m \geq n$. **Compute $U^T U$. How does this change if $m < n$?**

- (b) Suppose you have a real, square, $n \times n$ orthonormal matrix U (the columns of U are unit norm and mutually orthogonal). You also have real vectors $\vec{x}_1, \vec{x}_2, \vec{y}_1, \vec{y}_2$ such that

$$\vec{y}_1 = U\vec{x}_1$$

$$\vec{y}_2 = U\vec{x}_2$$

Calculate $\langle \vec{y}_1, \vec{y}_2 \rangle = \vec{y}_2^T \vec{y}_1 = \vec{y}_1^T \vec{y}_2$ in terms of $\langle \vec{x}_1, \vec{x}_2 \rangle = \vec{x}_2^T \vec{x}_1 = \vec{x}_1^T \vec{x}_2$.

(c) **Following the previous question, express $\|\vec{y}_1\|_2^2$ and $\|\vec{y}_2\|_2^2$ in terms of $\|\vec{x}_1\|_2^2$ and $\|\vec{x}_2\|_2^2$.**

(d) Suppose you observe data coming from the model $y_i = \vec{a}^\top \vec{x}_i$, and you want to find the linear scale-parameters (each a_i). We are trying to learn the model \vec{a} . You have m data points (\vec{x}_i, y_i) , with each $\vec{x}_i \in \mathbb{R}^n$. Note that \vec{x}_i refers to the i -th vector, not the i -th element of a single vector. Each \vec{x}_i is a different input vector that you take the inner product of with \vec{a} , giving a scalar y_i .

Set up a least squares formulation for estimating \vec{a} , and find the solution to the least squares problem.

(e) Now suppose V is an orthonormal square matrix, and rather than observing $\vec{a}^\top \vec{x}$ directly, we actually observe data points that result from our inputs being transformed by V^\top as follows:

$$\vec{\tilde{x}} = V^\top \vec{x} \quad (1)$$

That is, our model acts on the modified input data $\vec{\tilde{x}}_i$, so the data points we collected are now $(\vec{\tilde{x}}_i, y_i)$. We must now consider the new model:

$$y_i = \vec{a}^\top \vec{\tilde{x}}_i \quad (2)$$

$$= \tilde{a}^\top V^\top \vec{x}_i \quad (3)$$

Set up a least-squares formulation for $\hat{\tilde{a}}$. How is $\hat{\tilde{a}}$ related to \hat{a} ?

(f) Now suppose that we have the matrix

$$\begin{bmatrix} \vec{x}_1^\top \\ \vec{x}_2^\top \\ \vdots \\ \vec{x}_m^\top \end{bmatrix} \triangleq X = U\Sigma V^\top. \quad (4)$$

where U is an $m \times m$ matrix, and V is an $n \times n$ matrix. Here, $\Sigma = \begin{bmatrix} \sigma_1 & 0 & \dots & 0 & 0 & \dots & 0 \\ 0 & \sigma_2 & \dots & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \sigma_n & 0 & \dots & 0 \end{bmatrix}$.

Here we assume that we have more data points than the dimension of our space (that is, $m > n$). Also, the transformation V in part e) is the same V in this factorized representation.

Set up a least squares formulation for estimating \vec{a} and find the solution to the least squares. Is there anything interesting going on?

Note: Don't worry about how we would find U , Σ , V^\top for now; assume that X has the given form and that U and V are orthonormal.

Hint: Start by substituting the factorized representation of X into the answer of the previous part.

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