

Remote Discussion Section (Starting @ 7:10PM, Berkeley Time)

- M: Manav
- W: Moses, Helen
- What is discussion about?
- Discussion attendance for remote

Icebreaker:

- Share with your breakout room peers your name and what you're looking forward to with in person classes and on campus
- Consider the following **jobs** and **topics** in EECS16B. What kind of connections do you think there are that show what concepts would be encountered in certain careers?

Jobs

- Analog circuit design
- Digital circuit design
- Chip verification
- Control Engineer
- ML engineer
- Graphics/Animation
- CPU design / Architecture design
- Data scientist
- Scientists in Physics, chem, biology
- Software engineer

Topics

- • Compression
  - • filtering
  - • Control systems
  - • Feedback loops
  - • Classification
  - • Sampling (sensor measurements)
  - • Modeling systems that evolve with time.
- ↳ • Linear transformations / coordinate changes
- ↳ • Modeling nonlinear systems with linear systems:  $\dot{y} = Ax$

1. Linear Algebra Review

For the following matrices, find the following properties:

- What is the column space of the matrix?
- What is the null space of the matrix?
- What are the eigenvalues and corresponding eigenspaces for the matrix?

(a)  $\begin{bmatrix} 2 & 4 \\ 0 & 3 \end{bmatrix}$   $\mathbb{R}^2 =$  every vector with 2 entries:  $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$  for any value of  $x_1$  and  $x_2$

Hint:  $\begin{bmatrix} 1 \\ 2 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 2 \\ 4 \end{bmatrix}$

(b)  $\begin{bmatrix} 1 & -2 \\ 2 & -4 \end{bmatrix}$

Colspace  $(\begin{bmatrix} 2 & 4 \\ 0 & 3 \end{bmatrix}) = \mathbb{R}^2$  (columns are linearly independent)

$\begin{bmatrix} 2 \\ 0 \end{bmatrix} \neq \alpha \begin{bmatrix} 4 \\ 3 \end{bmatrix}$

Columns are linearly independent. They're not multiples of each other. The only solution is  $\vec{x} = \vec{0}$ .

(ii) Nullspace  $(\begin{bmatrix} 2 & 4 \\ 0 & 3 \end{bmatrix}) =$  What does this mean? The set of solutions of  $A\vec{x} = \vec{0}$  to  $\begin{bmatrix} 2 & 4 \\ 0 & 3 \end{bmatrix} \vec{x} = \vec{0} \rightarrow$  The set of solutions is  $\{\vec{0}\}$ . Nullspace  $(\begin{bmatrix} 2 & 4 \\ 0 & 3 \end{bmatrix}) = \{\vec{0}\}$

(a) (ii)  $A\vec{x} = \lambda\vec{x}$

polynomial in  $\lambda$

$\det(A - \lambda I) = 0$

$\hookrightarrow$  roots of this polynomial are the eigenvalues

$\det(\begin{bmatrix} 2 & 4 \\ 0 & 3 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix}) = 0$

$\det(\begin{bmatrix} 2-\lambda & 4 \\ 0 & 3-\lambda \end{bmatrix}) = (2-\lambda)(3-\lambda) - 4 \cdot 0 = 0$

$(2-\lambda)(3-\lambda) = 0$

$\lambda_1 = 2, \lambda_2 = 3$

Calculating eigenvectors

$\lambda_1 = 2$

$(A - 2I)\vec{x} = \vec{0}$

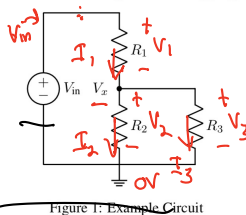
$A\vec{x} = 2\vec{x}$

$\vec{x} = \begin{bmatrix} \alpha \\ 0 \end{bmatrix}$  is an eigenvector for  $\lambda = 2$

Span  $\{\begin{bmatrix} 1 \\ 0 \end{bmatrix}\} \rightarrow$  eigenspace for  $\lambda_1 = 2$

2. KVL/KCL Review

Use Kirchhoff's Laws on the circuit below to find  $V_x$  in terms of  $V_{in}, R_1, R_2, R_3$ .



Review: Read notes 11-20 from 16A

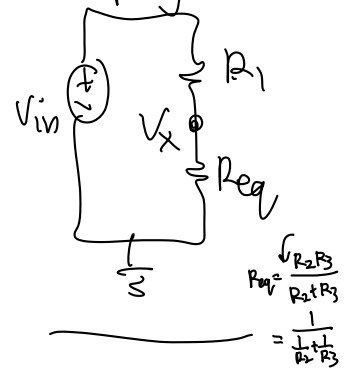
Figure 1: Example Circuit

- Recall Node Voltage Analysis (NVA). Determine  $V_x$  by labeling the circuit and writing equations to solve a system of equations in node voltages.
- In EECS16A, you learned you can simplify analysis by replacing series or parallel resistors with equivalents and memorizing common circuit design blocks. Determine  $V_x$  by leveraging resistor equivalence and recognition of a design block.
- As a check, as  $R_3 \rightarrow \infty$ , what is  $V_x$  for what you found in (a) and (b)? The  $V_x$ 's of each part should approach the same value. What is the name we used for this type of circuit?

NVA

- Label GND  $\checkmark$
- Label node (voltages)
- Label  $V$ 's,  $I$ 's (passive sign convention)
- Write KCL equations at nodes (with unknown voltage)
- Substitute Ohm's Law expressions
- Solve the system

Simplify to:



KCL @  $V_x$ :  $I_1 = I_2 + I_3$

$\frac{V_{in} - V_x}{R_1} = \frac{V_x - 0V}{R_2} + \frac{V_x - 0V}{R_3}$

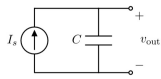
$\frac{V_{in}}{R_1} = V_x \left( \frac{1}{R_2} + \frac{1}{R_2} + \frac{1}{R_3} \right)$

$V_x = \frac{\frac{1}{R_1}}{\frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3}} V_{in}$

3. **Current Sources And Capacitors** (The following problem has been adapted from EECS16A Fall 20 Disc 9A.)

Recall charge has units of Coulombs (C), and capacitance is measured in Farads (F) =  $\frac{\text{Coulomb}}{\text{Volt}}$ . It may also help to note metric prefix examples:  $3\mu\text{F} = 3 \times 10^{-6}\text{F}$ .

Given the circuit below, find an expression for  $v_{\text{out}}(t)$  in terms of  $I_s$ ,  $C$ ,  $V_0$ , and  $t$ , where  $V_0$  is the initial voltage across the capacitor at  $t = 0$ .

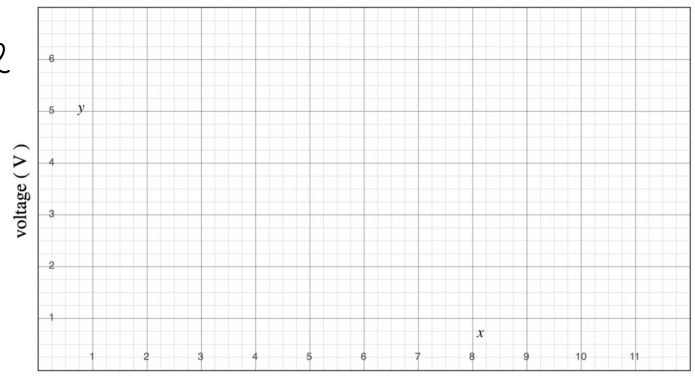


charge  
 $Q = CV \leftarrow \text{voltage}$   
 $I = C \frac{dV}{dt}$

Then plot the function  $v_{\text{out}}(t)$  over time on the graph below for the following conditions detailed below. Use the values  $I_s = 1\text{mA}$  and  $C = 2\mu\text{F}$ .

- (a) Capacitor is initially uncharged  $V_0 = 0$  at  $t = 0$ .
- (b) Capacitor has been charged with  $V_0 = +1.5\text{V}$  at  $t = 0$ .
- (c) **Practice:** Swap this capacitor for one with half the capacitance  $C = 1\mu\text{F}$ , which is initially uncharged  $V_0 = 0$  at  $t = 0$ .

HINT: Recall the calculus identity  $\int_a^b f'(x)dx = f(b) - f(a)$ , where  $f'(x) = \frac{df}{dx}$ .



4. (Take-Home) **Op-Amp Summer**

*Review Golden Rules*

Consider the following circuit (assume the op-amp is ideal):

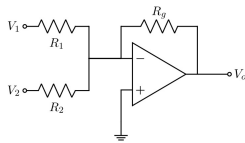


Figure 2: Op-amp Summer

What is the output  $V_o$  in terms of  $V_1$  and  $V_2$ ? You may assume that  $R_1$ ,  $R_2$ , and  $R_f$  are known.